Binary Search Tree (BST)

Searching Items in Lists

- Searching & removing an item from a list
 - Search if 14 is in the list.
 - Delete 3 from the list.

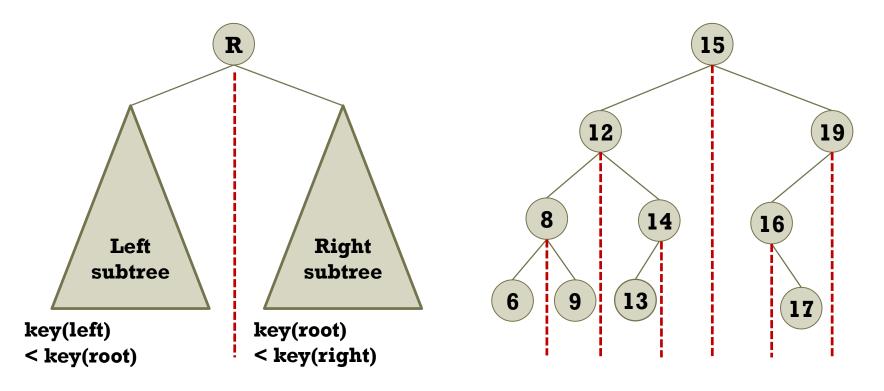


- The time complexity of searching and deletion is O(n).
 - This is **too slow** if the number of items are huge.

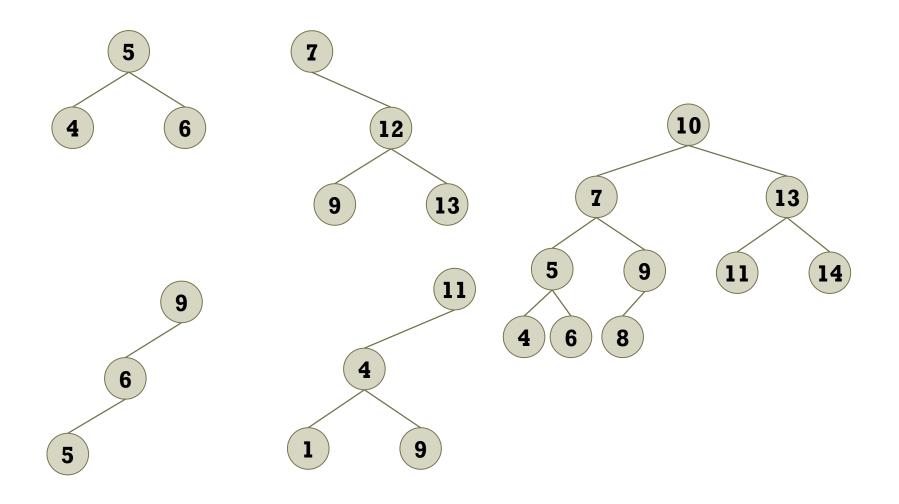
- Q) How to improve time complexity of searching and deleting an element?
- A) Use a Binary Search Tree (BST).

What is Binary Search Tree (BST)?

- A binary tree that is empty or each node satisfies the following conditions.
 - Every element has a key, and there are no duplicate keys.
 - key(left subtree) < key(root node) < key(right subtree)



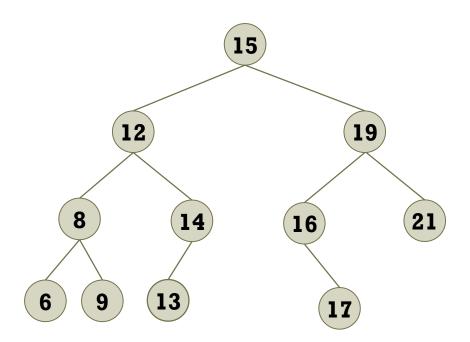
Examples of BST



Properties of BST

Properties

- The operations for searching, insertion, and deletion are bound by O(h), where h is the height is the BST.
- The inorder traversal of BST can generate a sorted list.



Inorder traversal: 6 8 9 12 13 15 16 17 19 21

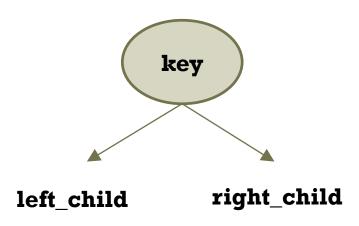
Implementation of BST

■ Node representation in BST

left_child key right_child

```
typedef int Key;

typedef struct _BSTNode
{
    Key key;
    struct _BSTNode * left_child;
    struct _BSTNode * right_child;
} BSTNode;
```



Implementation of BST

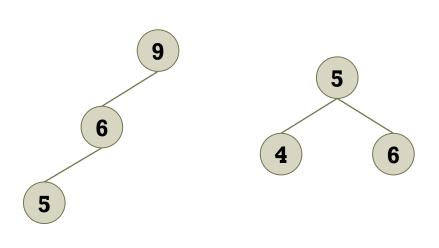
Operations

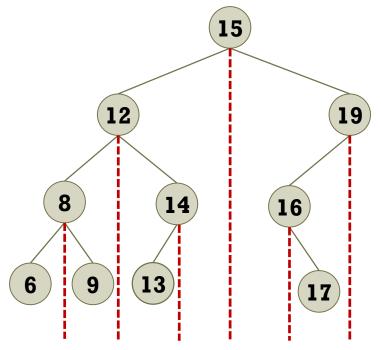
```
// Create a new node.
BSTNode * CreateNode(Key key);
// Destroy a node.
void DestroyNode(BSTNode * node);
// Verify whether the tree is a binary search tree or not.
bool Verify(BSTNode* root);
// Search an item in BST.
BSTNode* Search(BSTNode* root, Key key);
// Insert an item to BST.
void Insert(BSTNode* root, Key key);
// Remove an item from BST.
void Remove(BSTNode* node, Key key);
// Traverse BST (the inorder travsal is a sorted list.)
void Traverse(BSTNode* root);
// Clear a tree.
void ClearTree(BSTNode* root);
```

Verifying BST

Description

- 1. Check the following conditions for every node.
 - 1.1. The key of the current node should be greater than the keys of all nodes in its left subtree.
 - 1.2. The key of the current node should be less than the keys of all nodes in its right subtree.
- Are they binary search trees?





Verifying BST

Algorithm

Check the minimum and maximum conditions for each node.

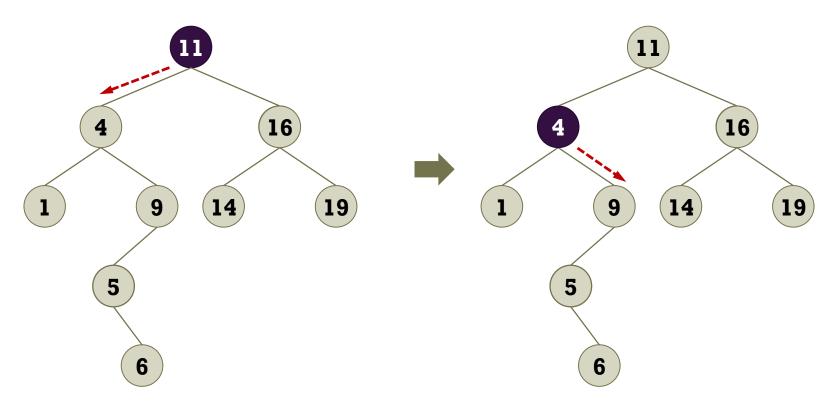
```
// Initialize the minimum and maximum as INT_MIN and INT_MAX
// for 32 bits, -2147483648 ~ +2147483647
bool Verify(BSTNode* root, int min, int max)
{
    if (root != NULL)
        // Return false if this node violates the min/max constraints.
         if (root->key < min || root->key > max)
              return false;
         else
              // Check the subtrees with the min/max constraints.
              return Verify(root->left child, min, root->key) &&
                     Verify(root->right child, root->key, max);
    else
         return true; // an empty tree is BST.
}
```

Description

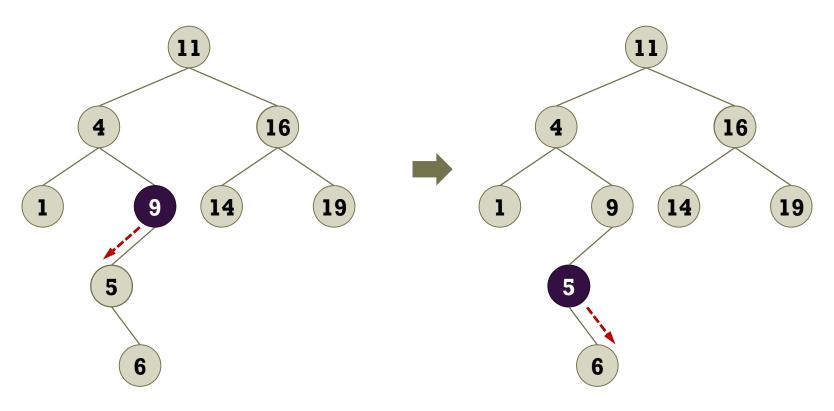
- 1. Begin by examining the root node.
 - 1.1. If the node is NULL, the element does not exist.
- 2. Compare the key of the root with the element.
 - 2.1 If the element is equal to the key, the element is found.
 - 2.2 If the element is less than the key, **search a left subtree**.
 - 2.3 If the element is greater than the key, search a right subtree.
- 3. Repeat steps 1-2 until the element is found or the root is NULL.

■ Animation: https://visualgo.net/en/bst

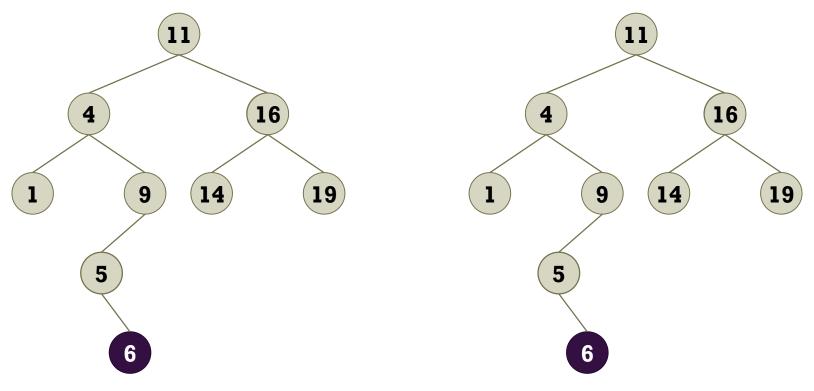
- Searching 6 in BST
 - Compare 6 with 11. Because 6 < 11, traverse a left subtree.
 - Compare 6 with 4. Because 6 > 4, traverse a right subtree.



- Searching 6 in BST
 - Compare 6 with 9. Because 6 < 9, traverse a left subtree.
 - Compare 6 with 5. Because 6 > 5, traverse a right subtree.



- Searching 6 in BST
 - Compare 6 with 6. Finally, 6 is found.
 - If searching 7, traverse a right subtree. Because the node is NULL, 7 does not exist in BST.



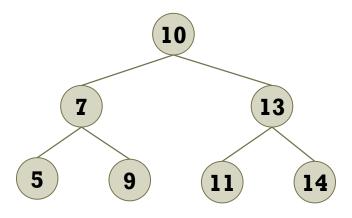
13

The element 6 is found!

The element 7 does not exist.

■ Algorithm: Recursive version

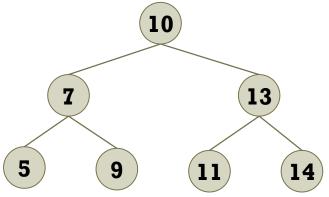
```
BSTNode* Search(BSTNode* root, Key key)
{
    if (root == NULL || root->key == key) return root;
    else if (root->key > key)
        return Search(root->left_child, key);
    else
        return Search(root->right_child, key);
}
```



How to search 9?

■ Algorithm: Iterative version

```
BSTNode* Search(BSTNode* root, Key key)
{
    BSTNode* cur = root;
    while (cur != NULL) {
        if (cur->key == key) break;
        else if (cur->key > key)
            cur = cur->left_child;
        else
            cur = cur->right_child;
    }
    return cur;
}
```



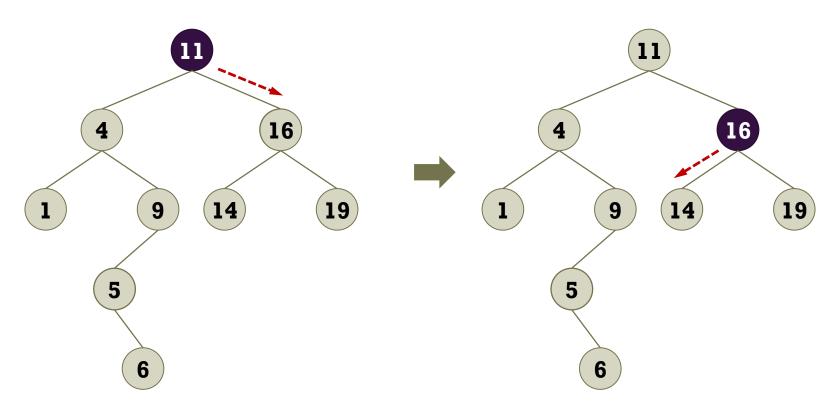
How to search 12?

Description

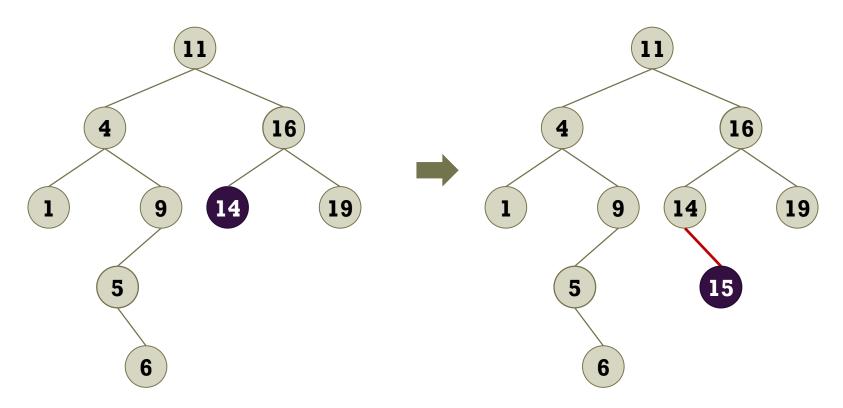
- 1. Begin by examining the root node.
 - 1.1. If the node is NULL, the element is inserted at this position.
- 2. Compare the key of the root with the element.
 - 2.1 If the element is equal to the key, **return an error**.
 - 2.2 If the element is less than the key, **search a left subtree**.
 - 2.3 If the element is greater than the key, search a right subtree.
- 3. Repeat steps 1-2 until the element is found or the root is NULL.

■ Similar to searching an element in the BST, it finds a position to be inserted.

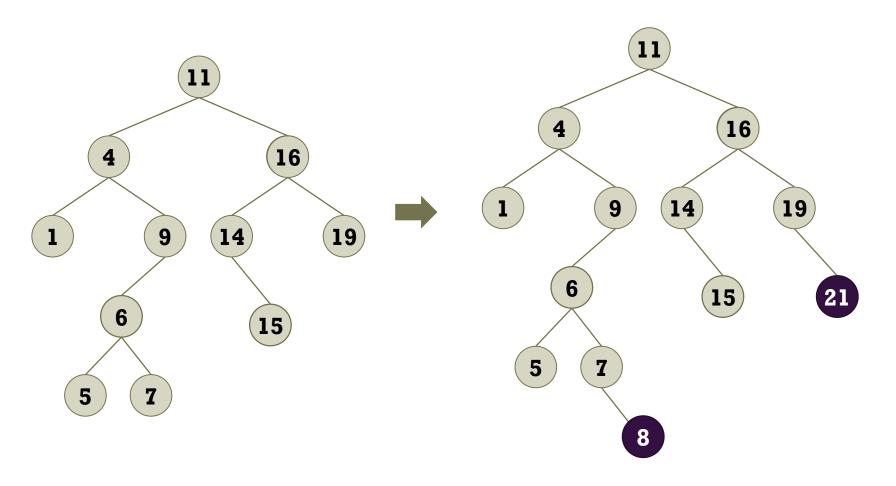
- Inserting 15 to BST
 - Compare 15 with 11. Because 15 > 10, traverse a right subtree.
 - Compare 15 with 16. Because 15 < 16, traverse a left subtree.



- Inserting 15 to BST
 - Compare 15 with 14. Because 15 > 14, traverse a right subtree.
 - Because the node is NULL, 15 is inserted at this position.



■ Inserting 21 and 8 to BST in sequence



■ Algorithm: Recursive version

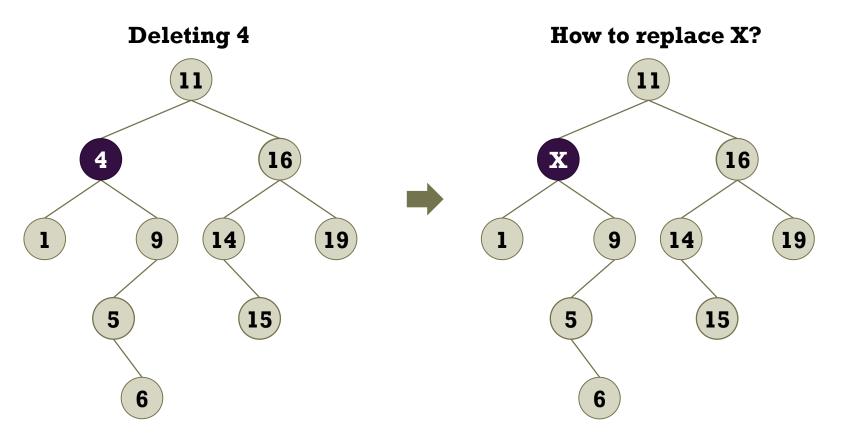
```
void Insert(BSTNode* root, Key key)
{
    if (root->key == key) exit(1);
    else if (root->key > key) {
         // Insert a new node for a left child.
         if (root->left child == NULL)
              CreateLeftSubtree(root, key);
         else
              Insert(root->left child, key);
    else {
         // Insert a new node for a right child.
         if (root->right child == NULL)
              CreateRightSubtree(root, key);
         else
              Insert(root->right child, key);
```

■ Animation: https://visualgo.net/en/bst

■ Algorithm: Iterative version

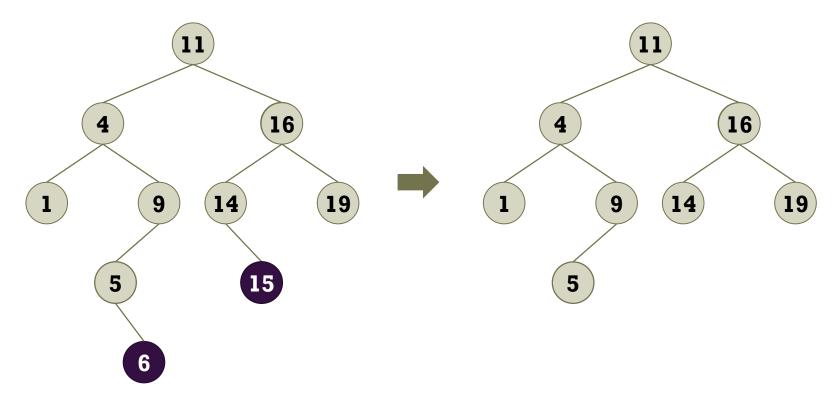
```
void Insert(BSTNode* root, Key key)
{
    BSTNode* cur = root;
    while (cur != NULL) {
         if (cur->key == key) exit(1);
         else if (cur->key > key) {
              // Insert a new node for a left child.
              if (cur->left child == NULL) {
                   CreateLeftSubtree(cur, key);
                   break;
              } else
                   cur = cur->left child;
         else {
              // Insert a new node for a right child.
              if (cur->right child == NULL) {
                   CreateRightSubtree(cur, key);
                   break:
              } else
                   cur = cur->right child;
```

- When removing a node from BST, it is important to maintain the inorder sequence of the nodes.
 - The heights of the subtree need to be changed by at most one.



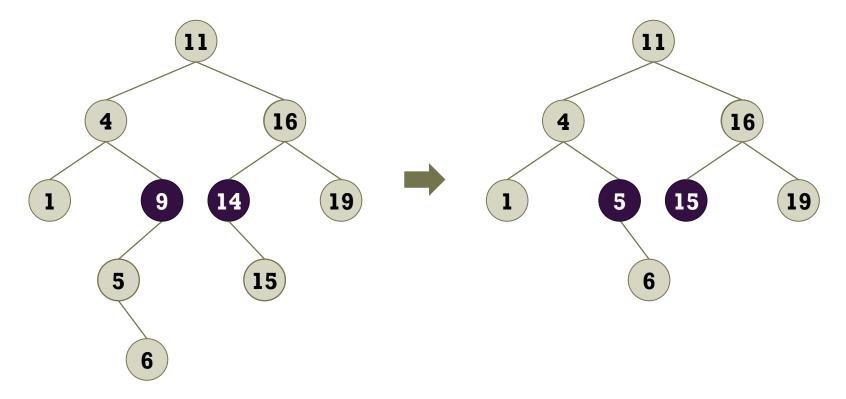
- Case 1: Deleting a node with no children
 - Simply remove the node from the tree.

■ Deleting 6 and 15 from BST

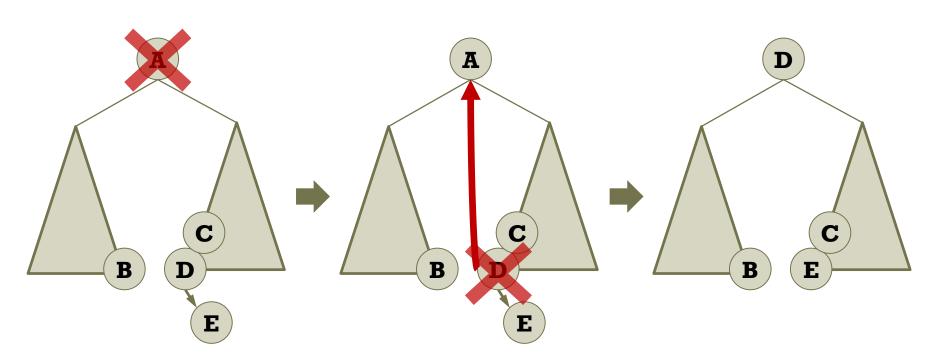


- Case 2: Deleting a node with one child
 - Remove the node and replace it with its child node.

■ Deleting 9 and 14 from BST

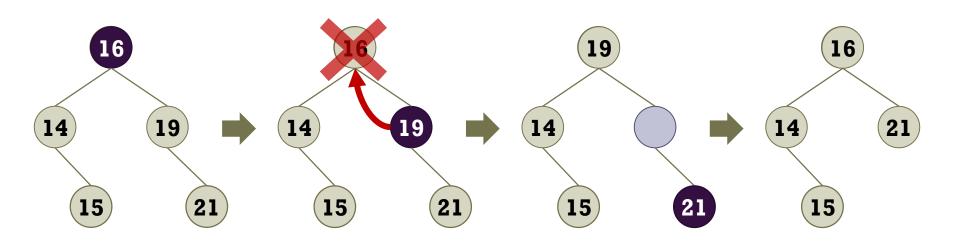


- Case 3: Deleting a node with two children
 - Choose either its **inorder predecessor node** or **successor node** as a replacement node.
 - Inorder predecessor: The largest in the left subtree
 - Inorder successor: The smallest in the right subtree

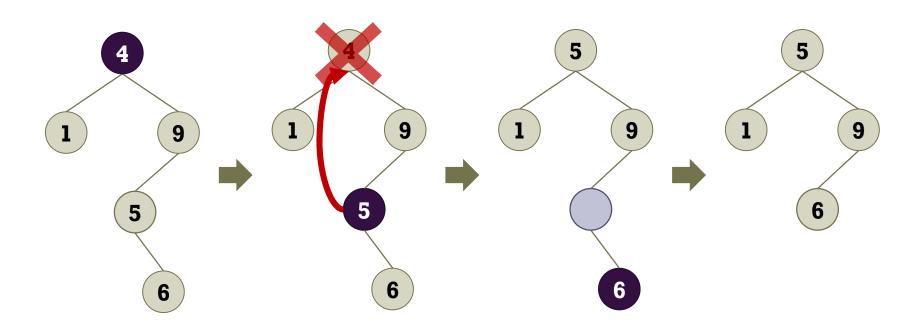


- Case 3: Deleting a node with two children
 - Choose its inorder successor node as a replacement node.
 - When a node is removed, the successor is the left-most node of its right child node.

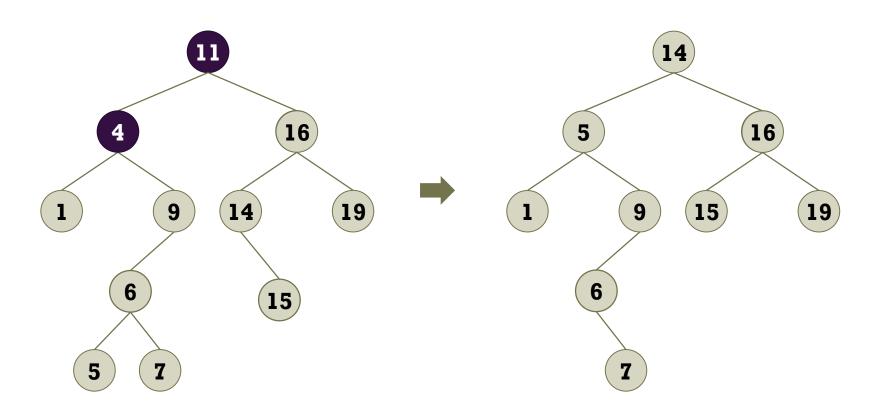
- Deleting 16 from BST
 - The replacement node is updated by **the right child node** of the successor node.



- Deleting 4 from BST
 - The replacement node is updated by **the left child node** of the successor node.



■ Deleting 4 and 11 from BST in sequence



■ Algorithm

■ Handle three possible cases for removing an element in BST.

```
void Remove(BSTNode* root, Key key)
{
    BSTNode* cur = root, * parent = NULL;

    // Find the current node and its parent node.
    while (cur != NULL && cur->key != key) {
        parent = cur; // Update the parent node.
        if (cur->key > key)
            cur = cur->left_child;
        else
            cur = cur->right_child;
    }
}
```

■ Animation: https://visualgo.net/en/bst

- Case 1: Deleting a node with no children
 - Simply remove the node from the tree.

```
if (cur == NULL) exit(1);

if (cur->left_child == NULL && cur->right_child == NULL) {
    if (parent != NULL) {
        // Remove the current node depending on its position.
        if (parent->left_child == cur)
            parent->left_child = NULL;
        else
            parent->right_child = NULL;
    }
    else
        cur = NULL; // The current node is the root.
}
```

- Case 2: Deleting a node with one child
 - Remove the node and replace it with its child node.

```
else if (cur->left child == NULL || cur->right child == NULL) {
    BSTNode* child;
    // Replace a node with its child node.
    if (cur->left child != NULL)
         child = cur->left child;
    else
         child = cur->right child;
    // Replace the child node of its parent node.
    if (parent != NULL) {
         if (parent->left child == cur)
              parent->left child = child;
         else
              parent->right child = child;
```

- Case 3: Deleting a node with two children
 - Choose the successor node as a replacement node.

```
else {
         BSTNode* succ parent = cur, *succ = cur->right child;
         // Find the successor (left-most node of the current node.)
         while (succ->left child != NULL) {
              succ_parent = succ;
              succ = succ->left child;
         // If the successor has a child, update its the child node.
         if (succ parent->right child == succ)
              succ parent->right child = succ->right child;
         else
              succ parent->left child = succ->right child;
         cur->key = succ->key;
         cur = succ; // Remove the successor.
    DestroyNode(cur);
}
```

Summary of Binary Search Tree

- Time complexity of BST
 - The operations for searching, insertion, and deletion are bound by O(h), where h is the height of BST.

Algorithm	Average case	Worst case
Searching	$O(\log n)$	0 (n)
Insertion	$O(\log n)$	0 (n)
Deletion	$O(\log n)$	0 (n)

 \blacksquare where *n* is the number of nodes in BST.

■ How to maintain a balanced tree?