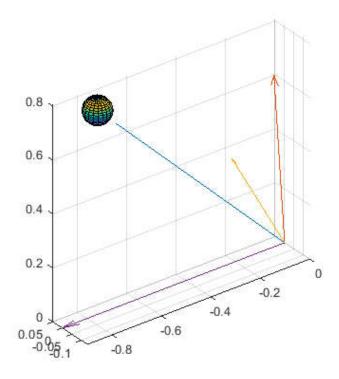
```
clc; close all;
% a_s=deg2rad(158.454753); %Azimuth
% alpha=deg2rad(90-18.259991); %Elevation=90-Zenith
% I_x=cos(alpha)*sin(a_s);
% I_y=-cos(alpha)*cos(a_s);
% I_z=sin(alpha);
LTH=11; %Local Hour
LTM=15/60;
Lat=32.32;
Long=-106.74;
delT=-7; %Time zone of Las Cruces
t=[datetime('today')];
N=day(t,'dayofyear');
X=deg2rad((360*(N-1))/365.242);
EoT=229.2*(0.000075+(0.001868*cos(X))-(0.032077*sin(X))-(0.014615*cos(2*X))-(0.04089*sin(2*X)))
LSTM=15*delT; %Conversion to deg
ST=LTH+(((4*(LSTM-Long))+EoT)/60)+LTM;
del=0.006918-0.399912*cos(X)+0.070257*sin(X)-0.006758*cos(2*X)+0.00907*sin(2*X)-0.002679*cos(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.00148*sin(3*X)+0.0014*sin(3*X)+0.0014*sin(3*X)+0.0014*sin(3*X)+0.0014*sin(
hour_angle=deg2rad(15*(ST-12))
zenith s=acos((cos(deg2rad(Lat))*cos(del)*cos(hour angle))+(sin(deg2rad(Lat))*sin(del)))
decl=asin((0.39795*cos(0.98563*(deg2rad(N-173)))))
azimuth=sign(hour_angle)*abs(acos(((cos(zenith_s)*sin(deg2rad(Lat)))-sin(del))/(sin(zenith_s)*cos(deg2rad(Lat)))))
azimuth_deg=rad2deg(azimuth)
% phy_prime=(asin((cos(del)*sin(hour_angle))/sin(zenith_s)))
Altitude=90-rad2deg(zenith_s)
% if cos(hour_angle)>=(tan(del)/tan(deg2rad(Lat)))
%
           gamma_s=180-rad2deg(phy_prime)
% else
          gamma s=180+rad2deg(phy prime)
% end
Hh=10*0.0254;
Ht=72.5*0.0254;
R=72.5*0.0254;
d=sqrt((R^2)+(Ht-Hh)^2);
atr=atan((Ht-Hh)/R);
atr_deg=rad2deg(atr)
betahs=rad2deg((atr+deg2rad(Altitude))/2)
%Right Mirror X=72.*0.0254 Y=0
Y=0;
X=72.5*0.0254;
Z=0;
r = -X/sqrt((X^2)+(Y^2)+((Ht-Hh)^2)) %heliostat position w/r to receiver;
r_y=-Y/sqrt((X^2)+(Y^2)+((Ht-Hh)^2)) %heliostat position w/r to receiver;
r_z=(Ht)/sqrt((X^2)+(Y^2)+((Ht-Hh)^2))%heliostat position w/r to receiver;
r_{vec}=[r_x,r_y,r_z]
s_x=(-\cos(hour_angle)*\sin(deg2rad(Lat))*\cos(decl))+(\cos(deg2rad(Lat))*\sin(decl));
s y=sin(hour angle)*cos(decl);
s z=(cos(hour angle)*sin(deg2rad(Lat))*cos(decl))+(cos(deg2rad(Lat))*sin(decl));
s_{vec}=[s_x,s_y,s_z]
 m_x = ((abs(s_z + r_z))/(s_z + r_z))^*(s_x + r_x)^*(1/(s_x + r_x)^2) + ((s_y + r_y)^2) + ((s_z + r_z)^2)); 
m_y = ((abs(s_z+r_z))/(s_z+r_z))*(s_y+r_y)*(1/(s_x+r_x)^2)+((s_y+r_y)^2)+((s_z+r_z)^2));
 \label{eq:mz}  \mbox{$m_z$=(abs(s_z+r_z))*(1/(sqrt((s_x+r_x)^2)+((s_y+r_y)^2)+((s_z+r_z)^2)));} 
m_{vec}=[m_x,m_y,m_z]
origin=[-1,0,0]
ANGLE_X=90-(rad2deg(acos(dot(s_vec,origin))))
theta=acos((s_x*m_x)+(s_y*m_y)+(s_z*m_z))
quiver3(0,0,0,r_x,r_y,r_z)
```

```
hold on
quiver3(0,0,0,s_x,s_y,s_z)
hold on
\verb"quiver3"(0,0,0,m_x,m_y,m_z")
hold on
quiver3(0,0,0,origin_x,origin_y,origin_z)
hold on
[x,y,z]=sphere;
axis equal
r_r=0.05;
X_r=x*r_r;
Y_r=y*r_r;
Z_r=z*r_r;
surf(X_r+r_x,Y_r+r_y,Z_r+r_z)
EoT =
         1.41014298955139
del =
        0.391301907126079
hour_angle =
       -0.159827902341764
zenith_s =
         0.223387736823318
decl =
         0.396795536421729
azimuth =
        -0.726276009410768
azimuth_deg =
         -41.6125501008406
Altitude =
         77.2008254850447
atr_deg =
          40.7636052009412
betahs =
```

58.9822153429929

r\_x = -0.757409961600577 r\_y = 0 r\_z = 0.757409961600577 r\_vec = 0 0.757409961600577 -0.757409961600577 s\_vec = -0.160230796923711 -0.146783140310057 0.813414547979883 m\_vec = -0.269365458404951 -0.0430869133791753 0.461101863846291 origin = -1 0 0 ANGLE\_X = 9.22029274897612 theta = 1.13232926289255



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