

Simulated Annealing

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- Given a list of cities and the distances between each city, find the shortest route where one can visit every city exactly once and return to the starting city.
- Brute Force
 - A brute force solution would be to measure all permutations of the list and find the shortest cost.
 - The downfall of this method is that it would take $O(n!)$ to complete. :(
- Why is this problem so popular?
 - The TSP can be used as an effective way to test how efficient an optimization method is.
- How can we solve the TSP in a timely manner?
 - Random selection and hope that we get lucky.
 - Dynamic Programming.
 - Greedy Algorithm.
 - **Metaheuristics!**

- Procedure designed to select a partial solution that may result in a sufficiently good solution to an optimization problem.
- Most methods can find solutions to optimization problems such that the solution is a small distance from the optimal solution.
- The metaheuristic we chose was Simulated Annealing.

- The algorithm comes from the method of annealing in metallurgy.
- A controlled cooling process.
 - Begins at a high temperature and accepts initial solutions, but as temperature decreases solutions aside from the current best are less likely to be accepted.
 - If δ or the difference between current solution and the proposed solution is positive, we will accept the current solution regardless of the temperature.
 - The acceptance of a solution also relies on the following inequality:

$$e^{-\frac{\delta}{T_{curr}}} > U(0, 1)$$

- Finally, if the current solution is smaller than the best solution, the current solution is the best solution.
- We saw a similar process in the ising model

Algorithm 1 Simulated Annealing Pseudocode

```
1: procedure SIMANNEAL( $m, iter_{max}, T$ )  
2:    $x_{curr} \leftarrow InitialConfig(m)$  ▷ Select some  $x \in S$   
3:    $x_{best} \leftarrow x_{curr}$   
4:   for  $i = 1$  to  $iter_{max}$  do  
5:      $x_{prop} \leftarrow NeighbourConfig(x_{curr})$  ▷ Propose some neighbour configuration  
6:      $temp_{curr} \leftarrow CalcTemp(i, T)$  ▷ Anneal system  
7:     if  $Cost(x_{prop}) \leq Cost(x_{current})$  then  
8:        $x_{curr} \leftarrow x_{prop}$   
9:       if  $Cost(x_{prop}) \leq Cost(x_{best})$  then  
10:         $x_{best} \leftarrow x_{prop}$   
11:       end if  
12:     else if  $\exp\left\{\frac{Cost(x_{curr}) - Cost(x_{prop})}{temp_{curr}}\right\} > Random(0, 1)$  then ▷ Accept upward step?  
13:        $x_{curr} \leftarrow x_{prop}$   
14:     end if  
15:   end for  
16:   return  $x_{best}, Cost(x_{best})$  ▷ Best configuration and associated cost  
17: end procedure
```

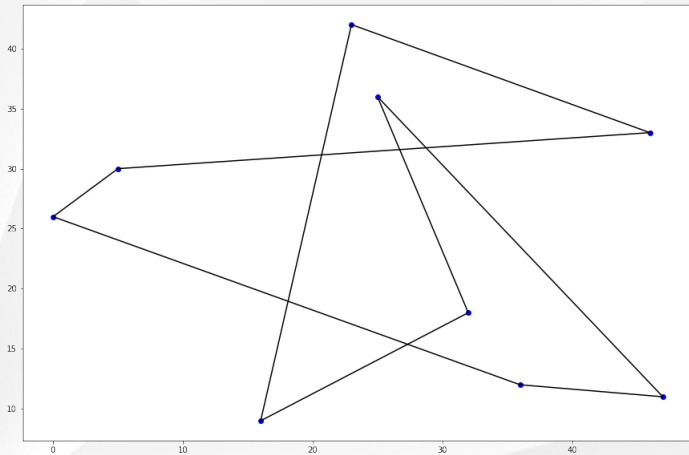


Figure: 1 iteration of SA

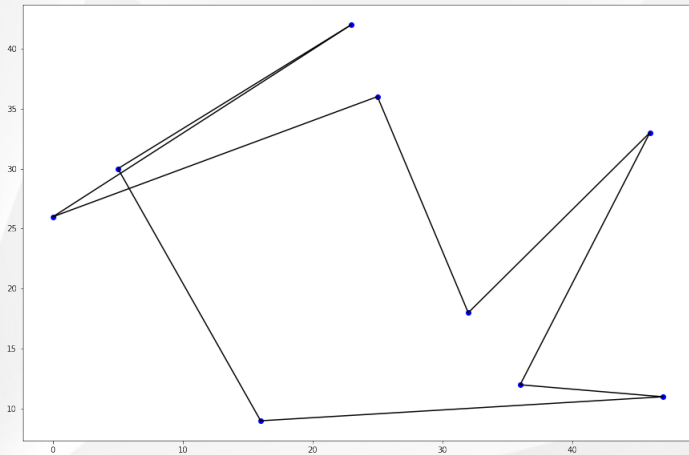


Figure: 10 iterations of SA

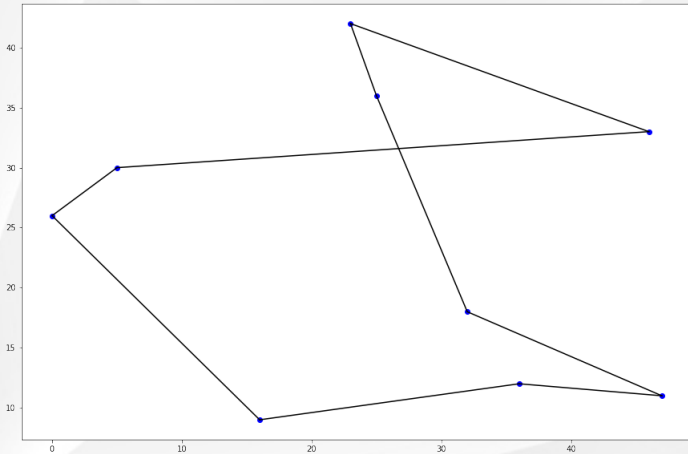


Figure: 100 iterations of SA

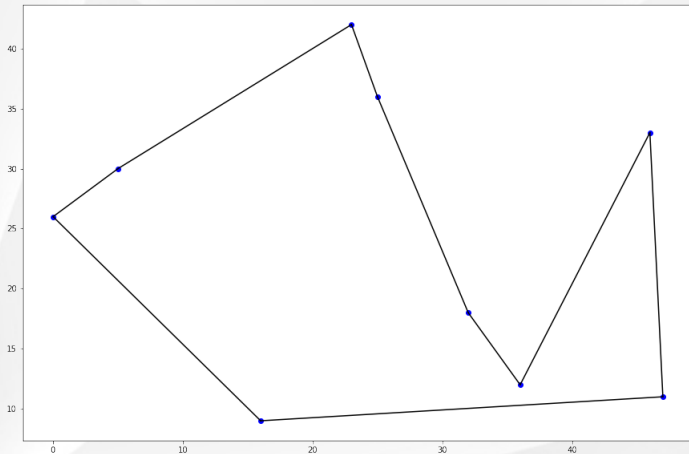


Figure: 1000 iterations of SA

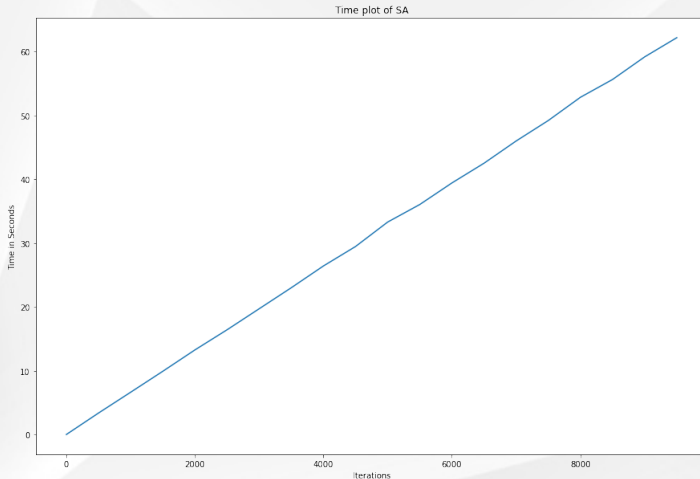


Figure: Time for SA on a nine node TSP

- The idea of SA in parallel has been implemented by many, but we chose to use the implementation done by Czech and Skinderowicz
- Parallel SA works as a team effort

```

1  parfor  $\mathcal{P}_j$ ,  $j = 0, 1, \dots, p - 1$  do
2      Set co-operation mode to regular or rare depending on a test set;
3       $L := (5E)/p$ ; {establish the length of a cooling stage}
4      Create the initial_solution using some heuristics;
5      current_solution $j$  := initial_solution; best_solution $j$  := initial_solution;
6      for  $f := 1$  to 2 do {execute phase 1 and 2}
9          {beginning of phase  $f$ }
7           $T := T_{0,f}$ ; {initial temperature of annealing}
8          repeat {a cooling stage}
9              for  $i := 1$  to  $L$  do
10                 annealing_step $f$ (current_solution $j$ , best_solution $j$ );
11             end for;
12             if ( $f = 1$ ) or (co-operation mode is regular) then  $\{\omega = L\}$ 
13                 co_operation;
14             else {rare co-operation:  $\omega = E$ }
15                 Call co_operation procedure every  $E$  annealing step
16                 counting from the beginning of the phase;
17             end if;
17              $T := \beta_f T$ ; {temperature reduction}
18             until  $a_f$  cooling stages are executed;
18             {end of phase  $f$ }
19         end for;
20 end parfor;
    
```

Figure: Main Algorithm

```
1  procedure annealing_stepf(current_solution, best_solution);  
2    Create new_solution as a neighbor to current_solution  
      (the way this step is executed depends on f);  
3     $\delta := \text{cost}_f(\text{new\_solution}) - \text{cost}_f(\text{current\_solution})$ ;  
4    Generate random  $x$  uniformly in the range (0, 1);  
5    if ( $\delta < 0$ ) or ( $x < e^{-\delta/T}$ ) then  
6      current_solution := new_solution;  
7      if  $\text{cost}_f(\text{new\_solution}) < \text{cost}_f(\text{best\_solution})$  then  
8        best_solution := new_solution;  
9      end if;  
10   end if;  
11 end annealing_stepf;
```

Figure: Step of Annealing

```
1  procedure co_operation;  
2    if  $j = 0$  then Send best_solution0 to process  $\mathcal{P}_1$ ;  
3    else  $\{j > 0\}$   
4      receive best_solution $j-1$  from process  $\mathcal{P}_{j-1}$ ;  
5      if  $\text{cost}_f(\text{best\_solution}_{j-1}) < \text{cost}_f(\text{best\_solution}_j)$  then  
6        best_solution $j$  := best_solution $j-1$ ;  
7        current_solution $j$  := best_solution $j-1$ ;  
8      end if;  
9      if  $j < p - 1$  then Send best_solution $j$  to process  $\mathcal{P}_{j+1}$ ; end if;  
10     end if;  
11  end co_operation;
```

Figure: Main Algorithm

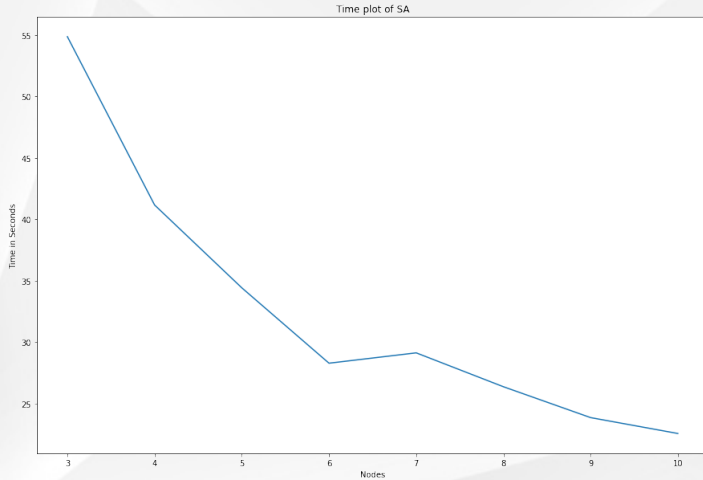


Figure: Parallel Speedup(16)

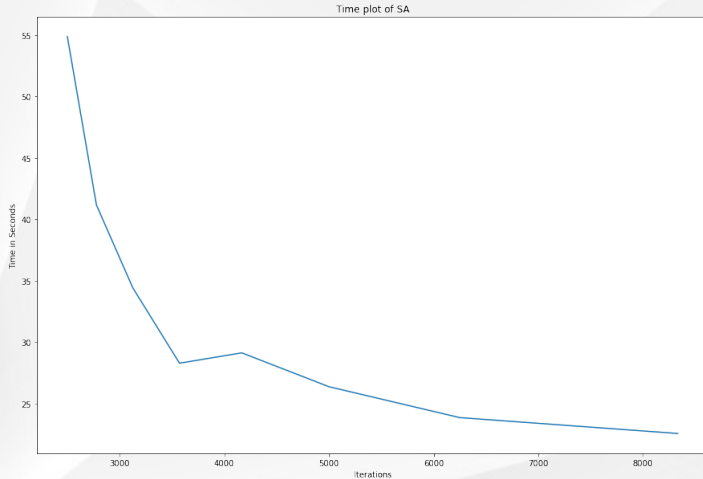


Figure: Iteration Speed Up(16)

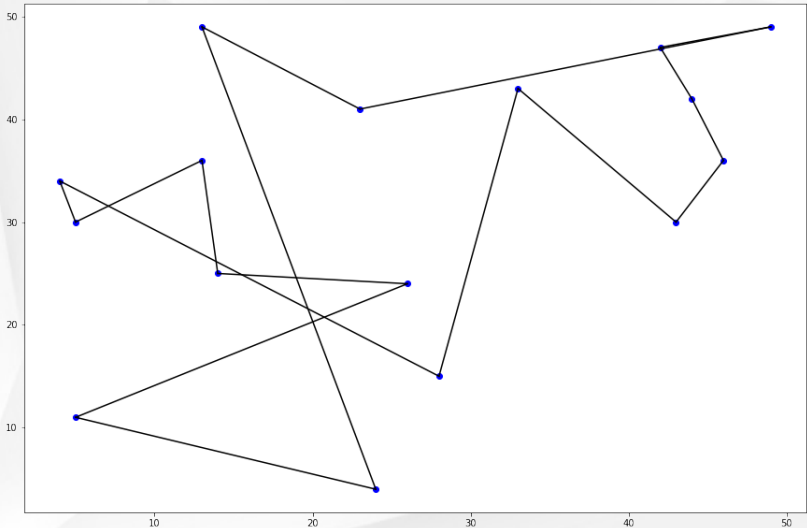


Figure: 16 Node TSP Serial Solution(236)

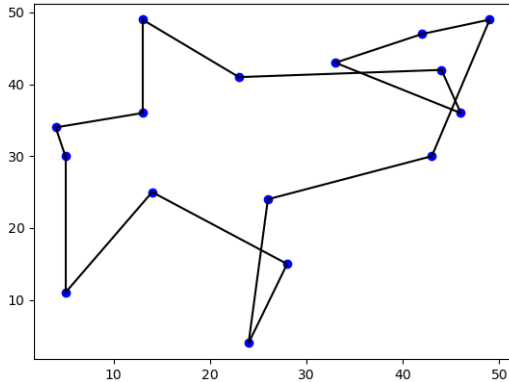


Figure: 16 Node TSP Parallel Solution(236)

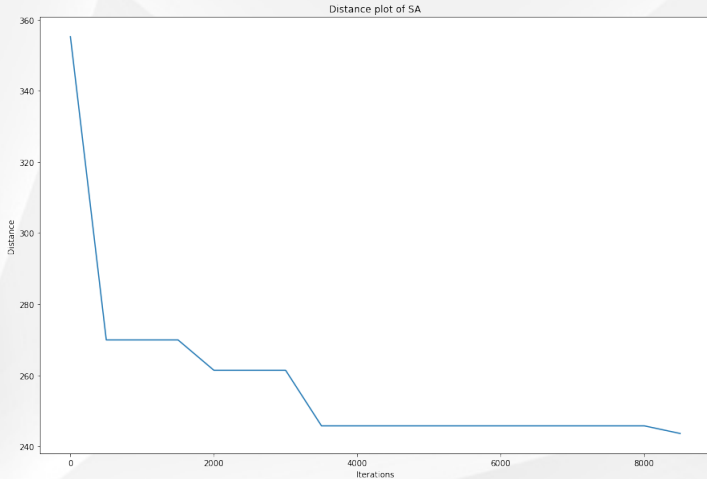


Figure: Distances on 16 node TSP

- We do not fully understand the choice of L , which determines the iterations.
- This algorithm could see improvements in selection of a neighboring solution.
- Python > C
- Stonks only go up.