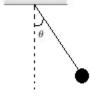
Mechanical pendulum: a study of the small oscillations approximation

In this notebook we show an important result in classical mechanics: the simple gravity pendulum and use Python to compute its period of oscillation, comparing the complete solution and the simple one.

Consider the classical pendulum with no friction force and subjected only to the force of gravity:



where the sphere is a puntiform particle with mass m, the line is a rigid and inextensible cable. The angle between the pendulum and the vertical line is θ . The differential equation satisfied by this system (using Newton's second law of motion) is:

where
$$x$$
 is the arc length of the pendulum trajectory. Note that this is a second order non-linear differential

 $m\frac{d^2x}{dt^2} = -mg\sin\left(\frac{x}{L}\right),$

equation which are hard to solve analytically. So, to attempt a easier solution, we consider the small oscillations approximation: $\sin(\alpha) \approx \alpha$, for $\alpha << 1$ radians. In this approximation the differential equation is transformed to: $\frac{d^2x}{dt^2} = -g\frac{x}{L}.$

lapsed for a complete cycle. For the simple gravity pendulum it is given by: $T_0 = 2\pi \sqrt{\frac{L}{a}}$. But one can ask: if the pendulum does not satisfies the small oscillations approximation? So what happens

But one can ask: if the pendulum does not satisfies the small oscillations approximation? So what happe if the angle
$$\theta>1$$
 radians? In Sears and Zemansky, Young and Freedman, volume 2, Physics book [2] we

2.4

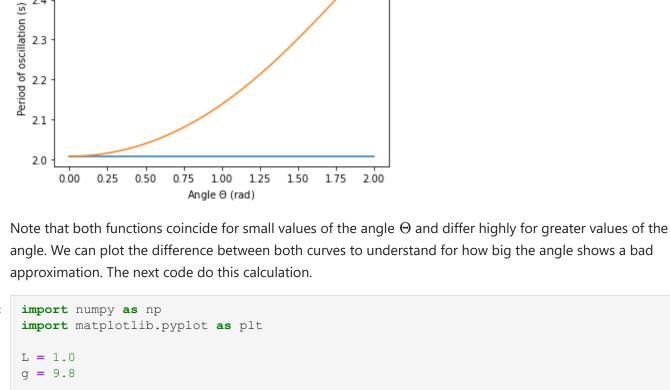
2.3

found the answer: the period of oscillation is written as an infinite series of the angle: $T_n = 2\pi\sqrt{rac{L}{g}}\left[1+rac{1}{2^2}{
m sin}^2\left(rac{\Theta}{2}
ight) + rac{1\cdot 3^2}{2^2\cdot 4^2}{
m sin}^4\left(rac{\Theta}{2}
ight) + \cdots
ight]$

Now
$$\Theta$$
 is the maximum angle of the pendulum. We consider in this notebook the approximation up to four order (named T_4 , the 4th power of the sine function) because the next term is a 6th power of the sine function, which can be neglected. We compute the period of a pendulum with $L=1$ m length and

function, which can be neglected. We compute the period of a pendulum with L=1 m length and $q=9.8~\mathrm{m/s^2}$ for various angles starting from small values and going to higher ones. We also compare the calculations with the simple pendulum approximation. In [4]: import numpy as np import matplotlib.pyplot as plt

```
L = 1.0
g = 9.8
small = open('Small period.txt','w')
four = open('Four order period.txt','w')
for i in range (0,201):
    Theta = 0.01*i
    Tsmall = 2*np.pi*np.sqrt(L/g)
    Tfour = 2*np.pi*np.sqrt(L/g)*(1 + (1/4)*(np.sin(Theta/2))**2 
                                   + (9/64)*(np.sin(Theta/2))**4)
    four.write(str(Tfour))
    four.write('\n')
    small.write(str(Tsmall))
    small.write('\n')
small.close()
four.close()
small = np.loadtxt('Small period.txt')
four = np.loadtxt('Four order period.txt')
x = np.arange(0, 2.01, 0.01)
ysmall = small[:]
yfour = four[:]
plt.plot(x,ysmall,x,yfour)
plt.xlabel(r'Angle $\Theta$ (rad)')
plt.ylabel('Period of oscillation (s)')
plt.legend(['Small approximation','Four order term'],loc=0)
plt.show()
 2.5
         Small approximation
         Four order term
```



dif = open('difference.txt','w') for i in range (0,201): Theta = 0.01*iTsmall = 2*np.pi*np.sqrt(L/g)Tfour = 2*np.pi*np.sqrt(L/g)*(1 + (1/4)*(np.sin(Theta/2))**2

```
+ (9/64) * (np.sin(Theta/2)) **4)
     difference = abs(Tsmall-Tfour)/Tsmall
     dif.write(str(difference))
     dif.write('\n')
 dif.close()
 dif = np.loadtxt('difference.txt')
 x = np.arange(0, 2.01, 0.01)
 y = dif[:]
plt.plot(x,y)
 plt.xlabel(r'Angle $\Theta$ (rad)')
plt.ylabel('Percentual difference of periods (%)')
plt.show()
  0.25
Percentual difference of periods (%)
  0.20
  0.15
  0.10
  0.05
  0.00
                                1.00
        0.00
             0.25
                   0.50
                          0.75
                                      1.25
                                            1.50
                                                  1.75
                                                        2.00
```

The above picture show that for angles greater than 0.50 radians the approximation starts turning bad. For

Solving the transcendetal equation to find the bound value of angle Suppose we want to find the angle that the approximation above is better than 1% accurate. It is means that the relative absolute difference: $|T_0-T_4|/T_0=0.01$, where T_0 and T_4 are the equations mentioned before. Using the expressions derived before we find that the relative absolute difference is given by: $rac{1}{2^2} \sin^2\left(rac{\Theta}{2}
ight) + rac{1.3^2}{2^2 \, 4^2} \sin^4\left(rac{\Theta}{2}
ight) = 0.01.$

Angle Θ (rad)

example, near $\Theta=0.75$ radians the percentual error is 5 %, approximately.

def func(Theta, error): **return** (1/4) * (np.sin(Theta/2)) **2 \ + (9/64) * (np.sin(Theta/2)) **4 - error res = root(func, 0.01, args=(0.01)) #First the function, second the initial solution

This is a bisquared equation, which can be solved analytically using the formulas for second order

equations. But, we want to solve this using regular methods of equation solving within Python. Next code

```
print(relativeerror)
 #Print the result in grads
 print('The result in grads is: %s' % str(res.x*180/np.pi))
 [0.39829584]
 [0.00978459]
The result in grads is: [22.82067064]
So, as we can see in the code, the angle \Theta=0.39829584 radians gives us a relative error of 1 % if we use
the small approximation instead of the four order approximation for the period. This relative error is rather
small and with a simple conversion we find that \Theta=22,8^{\circ}. For angles smaller than this, the relative error
is pretty small and can be neglected, showing that the small oscillations approximation works fine for
\Theta < 22,8^{\circ}.
Final remarks
In this notebook we briefly present the gravity pendulum and its small oscillations approximation. We show
```

shows this in more details.

import numpy as np

#Check the result

from scipy.optimize import root

+ (9/64)*(np.sin(res.x/2))**4

print(res.x) #Result of the root finding

relativeerror = (1/4)*(np.sin(res.x/2))**2

 (T_4) . We showed that, for $\Theta < 22, 8^\circ$ is a good approximation based on our calculations. We did not improved the terms on T_n using up to fourth order only. Increasing more terms will only gives an result with a better accuracy in the third decimal case or less. We invite the reader to do that calculation for higher order terms. This can be achieved by some modifications of this notebook. The reader will see that the difference between our results and with a higher order terms is quite small. But the most important feature of this notebook is not the result itself, but the construction. It shows to the reader that we can use Python as a simple programming languagen for many physics simulations and

the results comparing the period of the pendulum for small approximations (T_0) and up to four order term

calculations. Here we used Python to solve and study a tipical mechanics problem that is not convered treated in the usual physics courses in the way did here and we wanted to cover the absence with this notebook. Hope you enjoyed it! Any doubts, critics, suggestions or other informations email me: jvfrossard@gmail.com

Bibliography

See you in the next calculations!

[1] BOYCE, William E.; DIPRIMA, Richard C.; MEADE, Douglas B. Elementary differential equations. John

Wiley & Sons, 2017.

[2] YOUNG, Hugh D.; FREEDMAN, Roger A.; FORD, Albert Lewis. Sears and Zemansky's University Physics. Pearson Education, vol 2, 2006.