1. Force Plates

FP1	FP2	FP3	dimension			unit
Force			Fx	Fy	Fz	[N]
Moment			Mx	My	Mz	[N.mm]
СоР		Cx	Су	Cz	[mm]	

2. Model Outputs

Left	Right	dimension			unit
CentreOfMass		X	Y	Z	[mm]
CentreOfMassFloor		X	Y	Z	[mm]
H	ŒD	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
F	EL	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
Т	RX	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LAbsAnkleAngle	RAbsAnkleAngle	X	Y	Z	[deg]
LAnkleAngles	RAnkleAngles	X	Y	Z	[deg]
LAnkleForce	RAnkleForce	X	Y	Z	[N/kg]
LAnkleMoment	RAnkleMoment	X	Y	Z	[N.mm/kg]
LAnklePower	RAnklePower	X	Y	Z	[W/kg]
LCL	RCL	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LElbowAngles	RElbowAngles	X	Y	Z	[deg]
LElbowForce	RElbowForce	X	Y	Z	[N/kg]
LElbowMoment	RElbowMoment	X	Y	Z	[N.mm/kg]

LElbowPower	RElbowPower	X	Y	Z	[W/kg]
LFE	RFE	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LFO	RFO	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LFootProgressAngles	RFootProgressAngles	X	Y	Z	[deg]
LGroundReactionForce	RGroundReactionForce	X	Y	Z	[N/kg]
LGroundReactionMoment	RGroundReactionMoment	X	Y	Z	[N.mm/kg]
LHN	RHN	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LHU	RHU	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LHeadAngles	RHeadAngles	X	Y	Z	[deg]
LHipAngles	RHipAngles	X	Y	Z	[deg]
LHipForce	RHipForce	X	Y	Z	[N/kg]
LHipMoment	RHipMoment	X	Y	Z	[N.mm/kg]
LHipPower	RHipPower	X	Y	Z	[W/kg]
LKneeAngles	RKneeAngles	X	Y	Z	[deg]
LKneeForce	RKneeForce	X	Y	Z	[N/kg]
LKneeMoment	RKneeMoment	X	Y	Z	[N.mm/kg]
LKneePower	RKneePower	X	Y	Z	[W/kg]
LNeckAngles	RNeckAngles	X	Y	Z	[deg]
LNeckForce	RNeckForce	X	Y	Z	[N/kg]
LNeckMoment	RNeckMoment	X	Y	Z	[N.mm/kg]
LNeckPower	RNeckPower	X	Y	Z	[W/kg]
LNormalisedGRF	RNormalisedGRF	X	Y	Z	[]
LPelvisAngles	RPelvisAngles	X	Y	Z	[deg]
LRA	RRA	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]

LShoulderAngles	RShoulderAngles	X	Y	Z	[deg]
LShoulderForce	RShoulderForce	X	Y	Z	[N/kg]
LShoulderMoment	RShoulderMoment	X	Y	Z	[N.mm/kg]
LShoulderPower	RShoulderPower	X	Y	Z	[W/kg]
LSpineAngles	RSpineAngles	X	Y	Z	[deg]
LTI	RTI	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LTO	RTO	RX	RY	RZ	[deg]
		TX	TY	TZ	[mm]
		SX	SY	SZ	[mm]
LThoraxAngles	RThoraxAngles	X	Y	Z	[deg]
LWaistForce	RWaistForce	X	Y	Z	[N/kg]
LWaistMoment	RWaistMoment	X	Y	Z	[N.mm/kg]
LWaistPower	RWaistPower	X	Y	Z	[W/kg]
LWristAngles	RWristAngles	X	Y	Z	[deg]
LWristForce	RWristForce	X	Y	Z	[N/kg]
LWristMoment	RWristMoment	X	Y	Z	[N.mm/kg]
LWristPower	RWristPower	X	Y	Z	[W/kg]

3. Trajectories

Left	Right		dimensio	unit	
C7		X	Y	Z	[mm]
T10		X	Y	Z	[mm]
CLAV		X	Y	Z	[mm]
STRN		X	Y	Z	[mm]
RBAK		X	Y	Z	[mm]
LFHD	RFHD	X	Y	Z	[mm]
LBHD	RBHD	X	Y	Z	[mm]
LSHO	RSHO	X	Y	Z	[mm]
LUPA	RUPA	X	Y	Z	[mm]
LELB	RELB	X	Y	Z	[mm]

LFRM	RFRM	X	Y	Z	[mm]
LWRA	RWRA	X	Y	Z	[mm]
LWRB	RWRB	X	Y	Z	[mm]
LFIN	RFIN	X	Y	Z	[mm]
LASI	RASI	X	Y	Z	[mm]
LPSI	RPSI	X	Y	Z	[mm]
LTHI	RTHI	X	Y	Z	[mm]
LKNE	RKNE	X	Y	Z	[mm]
LTIB	RTIB	X	Y	Z	[mm]
LANK	RANK	X	Y	Z	[mm]
LHEE	RHEE	X	Y	Z	[mm]
LTOE	RTOE	X	Y	Z	[mm]