# Directed Acyclic Graph Conversion to Tree with Two Edge Types

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Due to the adoption of the Directed Acyclic Graph (DAG) as a standard in many workflows (e.g. Common Workflow Language), it is useful to have an algorithm capable of converting DAGs into trees, which is the data structure jobTree uses to model job hierarchy. Since standard trees, with one type of edge, are incapable of storing the complexity that can arise from a DAG, we will use a special type of tree that has 2 types of edges and is used by **jobTree**, a scheduling system used by UCSC's Computational Genomics Lab.

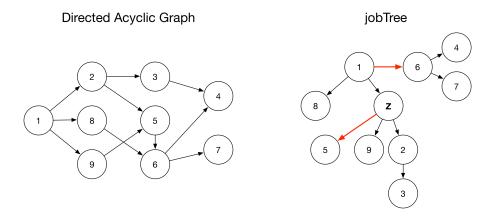


Figure 1: An example of a DAG reshaped as a tree. The black arrows in the tree correspond to 'child' jobs (collectively children) and the red arrows correspond to 'follow-on' jobs, which are only run after all of a given node's children and their descendants have run. **Z** represents a pseudo-node that has no function outside of scheduling jobs.

# 1 Algorithm

### 1.1 Setup

## 1.2 Creating Pseudonodes to Remove Multiple Parents

```
while \exists \geq 1 node with multiple parents do
    Let X be a node with multiple parents whose predecessors each have
     only one parent;
    Let \mathbf{Y} be the most recent common ancestor of \mathbf{X}'s parents.;
    if Y' has a follow-on then
        Y is the node on a path from Y' to X that is connected to Y' by
          a sequence of follow-on edges.;
    else
     \mathbf{Y} is \mathbf{Y}
    \mathbf{end}
    Make new child of \mathbf{Y}, \mathbf{Z};
    \mathbf{for} \ each \ edge \ incident \ to \ \mathbf{\textit{Y}} \ that \ is \ on \ the \ path \ to \ \mathbf{\textit{Z}} \ \mathbf{do}
        Delete (Y, incident node);
        Attach (Z, incident node);
    \mathbf{end}
    for each incoming edge of X do
     Delete edge
    end
    Add follow-on edge (\mathbf{Z}, \mathbf{X})
end
```

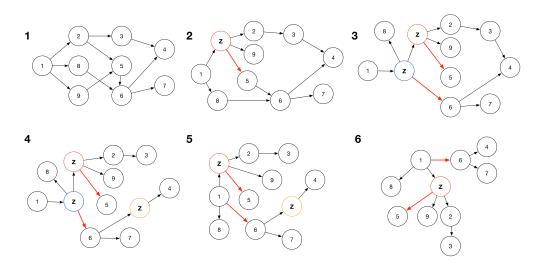


Figure 2: DAG to Tree Conversion