CS2040S Data Structures and Algorithms

Welcome!

```
Algorithm 1 ICan'tBelieveItCanSort(A[1..n])

for i = 1 to n do

for j = 1 to n do

if A[i] < A[j] then

swap A[i] and A[j]
```

Does this sorting algorithm work correct? If not, can you fix it...

Last Time: Sorting

Sorting algorithms

- BubbleSort
- SelectionSort
- InsertionSort
- MergeSort

Properties

- Running time
- Space usage
- Stability

Today: more sorting!

QuickSort:

- Divide-and-Conquer
- Partitioning
- Duplicates
- Choosing a pivot
- Randomization
- Analysis

Recursive...

```
Step 1:
Divide array into two pieces.
```

```
MergeSort(A, n)

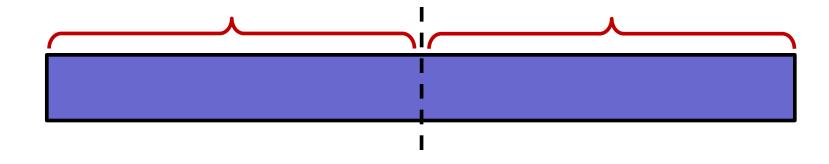
if (n=1) then return;

else:
```

```
X \leftarrow MergeSort(A[1..n/2], n/2);
```

 $Y \leftarrow MergeSort(A[n/2+1, n], n/2);$

return Merge (X,Y, n/2);



Recursive...

Step 2: Recursively sort the two halves.

```
MergeSort(A, n)

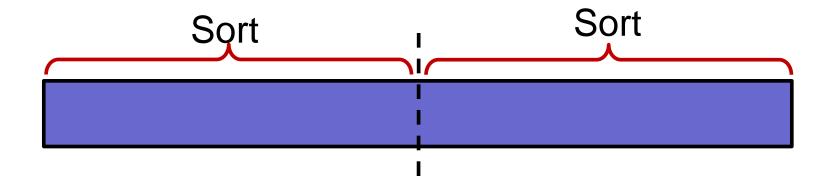
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Recursive...

```
MergeSort(A, n)

if (n=1) then return;

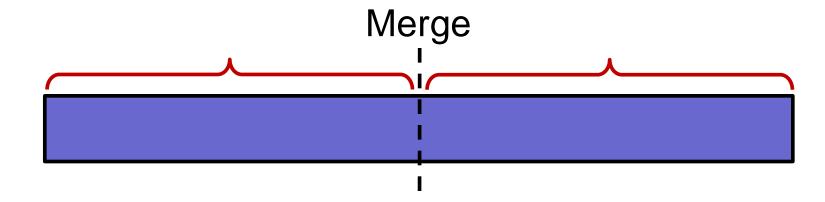
else:
```

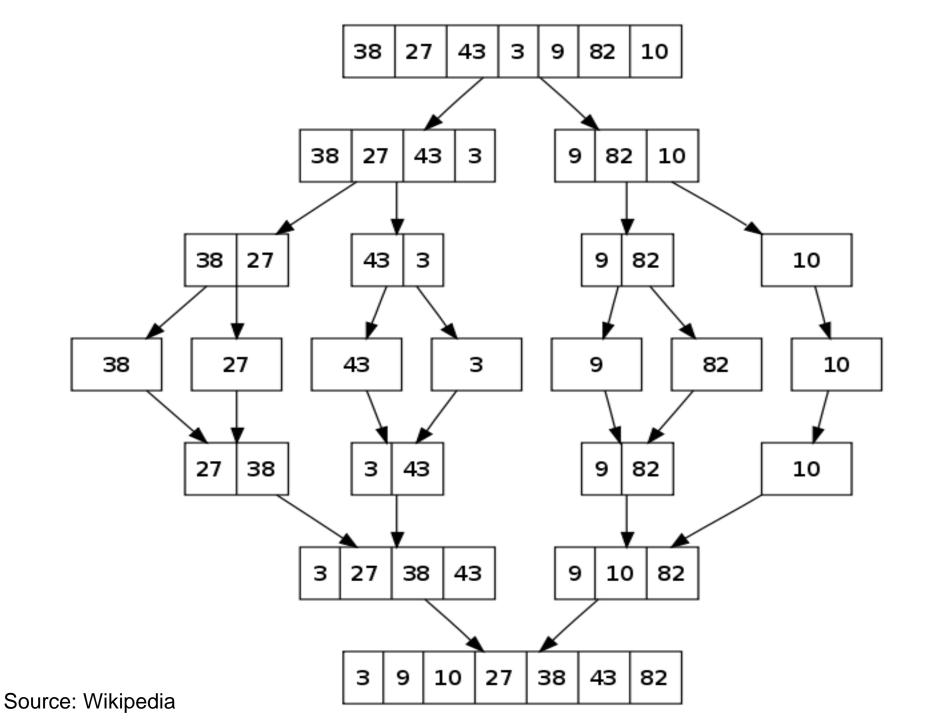
Step 3: Merge the two halves into one sorted array.

 $X \leftarrow MergeSort(A[1..n/2], n/2);$

 $Y \leftarrow MergeSort(A[n/2+1, n], n/2);$

return Merge (X,Y, n/2);

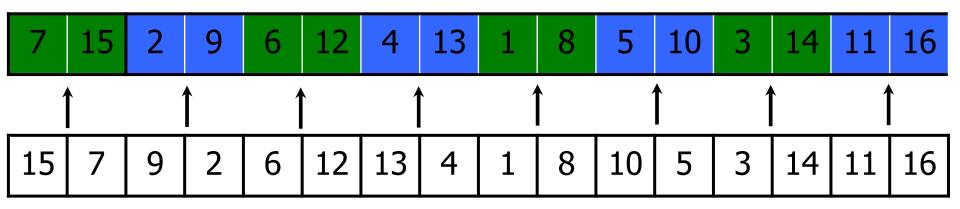


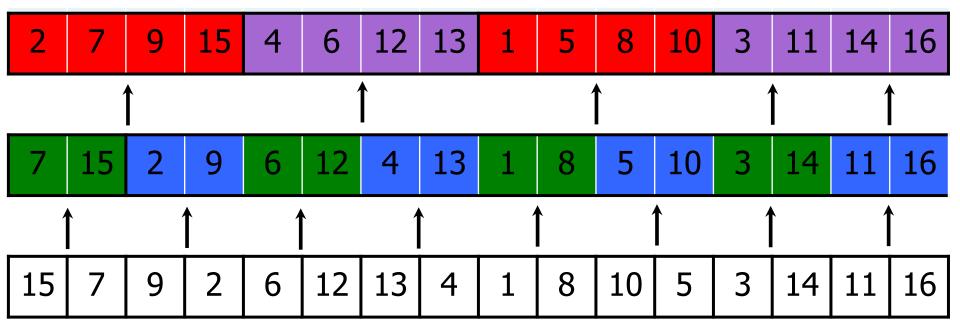


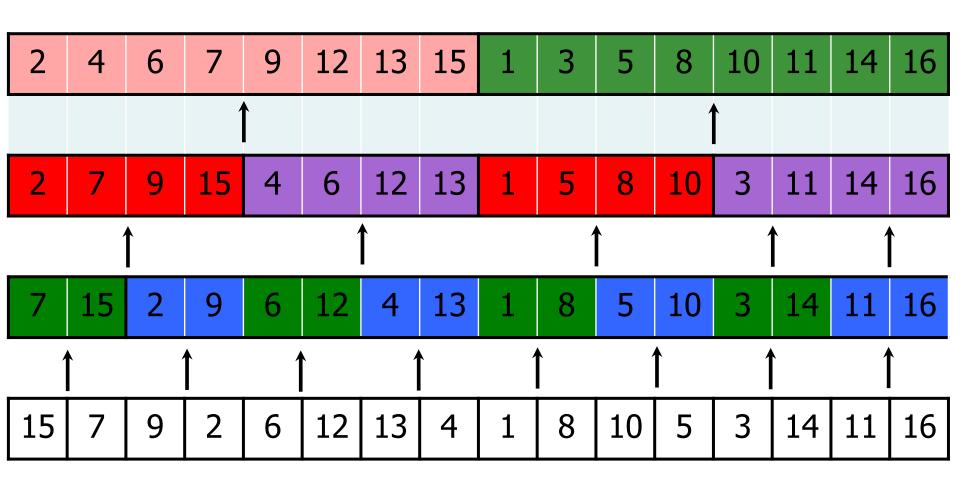
Challenge 1:

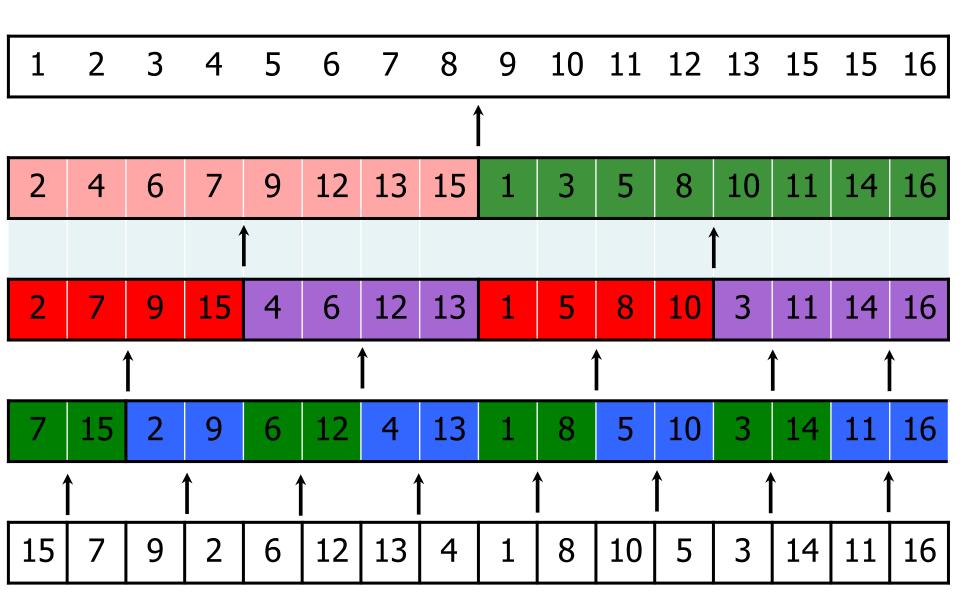
Write an iterative version of MergeSort.

No recursion allowed!









MergeSort

Space usage...

- Need extra space to do merge.
- Merge copies data to new array.

Space Complexity

Question:

How much space is allocated during a call to MergeSort?

Note:

Measure total allocated space.

We will not model *garbage* collection or other Java details.

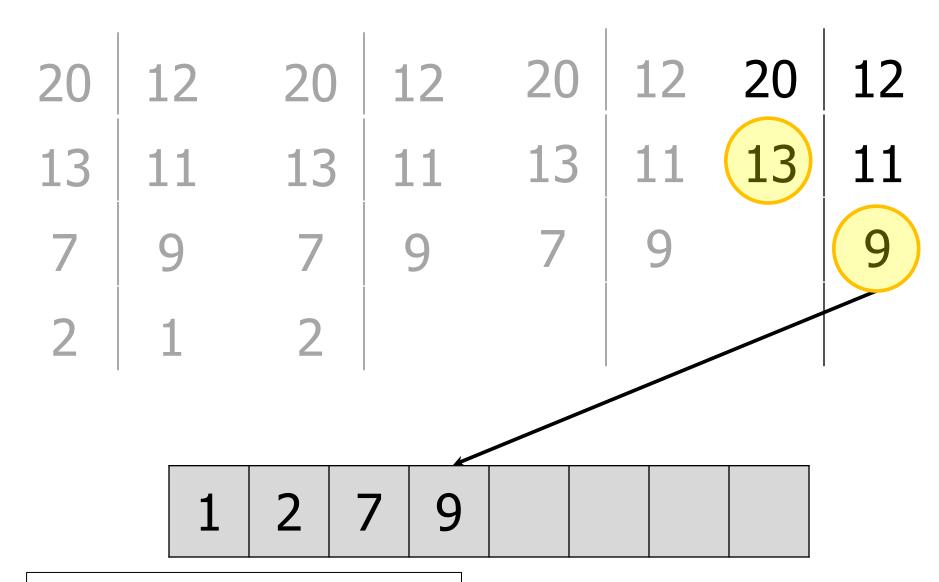
Space Complexity

Question:

How much space is allocated during a call to MergeSort?

Key subroutine: Merge

Merging Two Sorted Lists



Need temporary array of size n.

Let S(n) be the worst-case space allocated for an array of n elements.

$$S(n) = 2S(n/2) + n$$

 $S(n) = ?$

- A. $O(\log n)$
- B. O(n)
- C. O(n log n)
- D. $O(n^2)$
- E. $O(n^2 \log n)$
- F. $O(2^n)$

$$S(n) = 2S(n/2) + n$$

 $S(n) = ?$

- A. O(log n)
- B. O(n)
- \checkmark C. O(n log n)
 - D. $O(n^2)$
 - E. $O(n^2 \log n)$
 - F. O(2ⁿ)

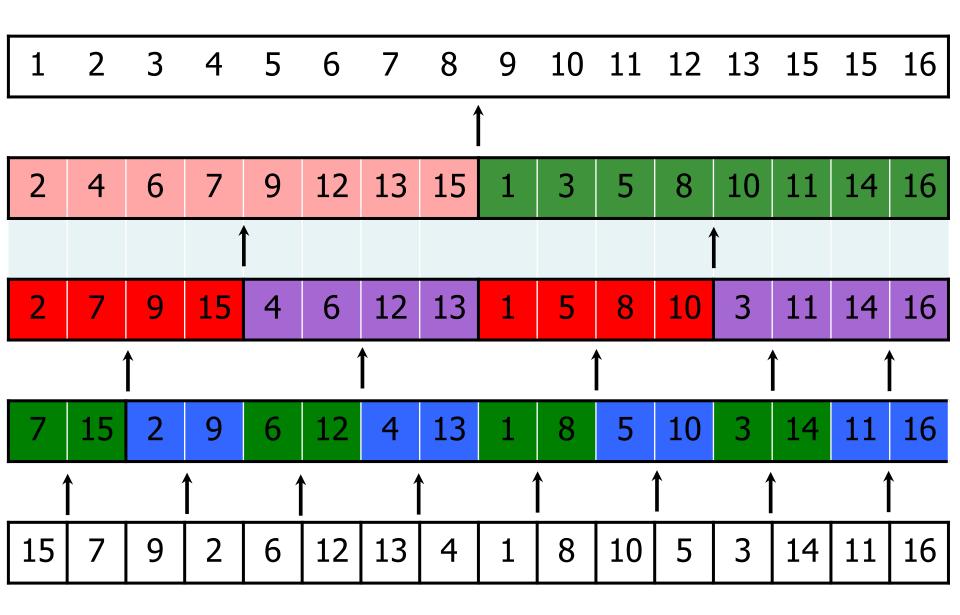
Let S(n) be the worst-case space for an array of n elements.

$$S(n) = \theta(1) \qquad \text{if } (n=1)$$

$$= 2S(n/2) + n \quad \text{if } (n>1)$$

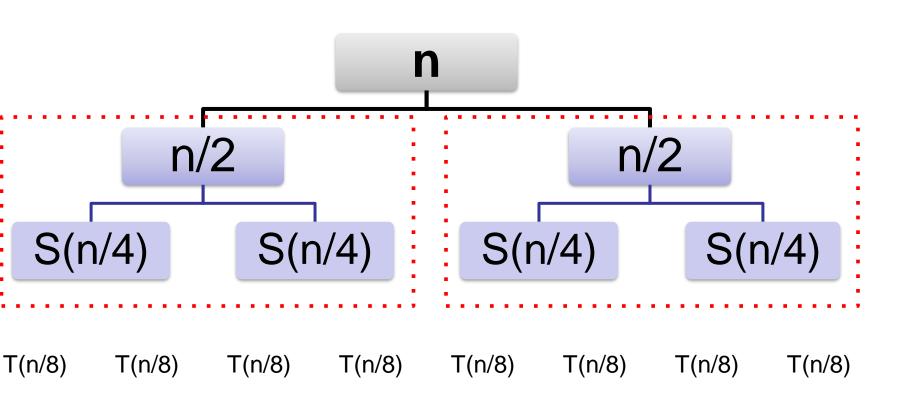
$$= O(n \log n)$$

MergeSort

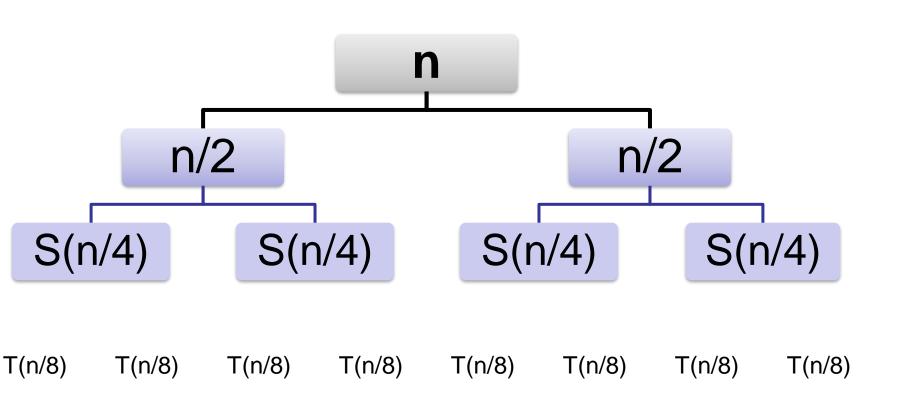


$$S(n) = 2S(n/2) + n$$

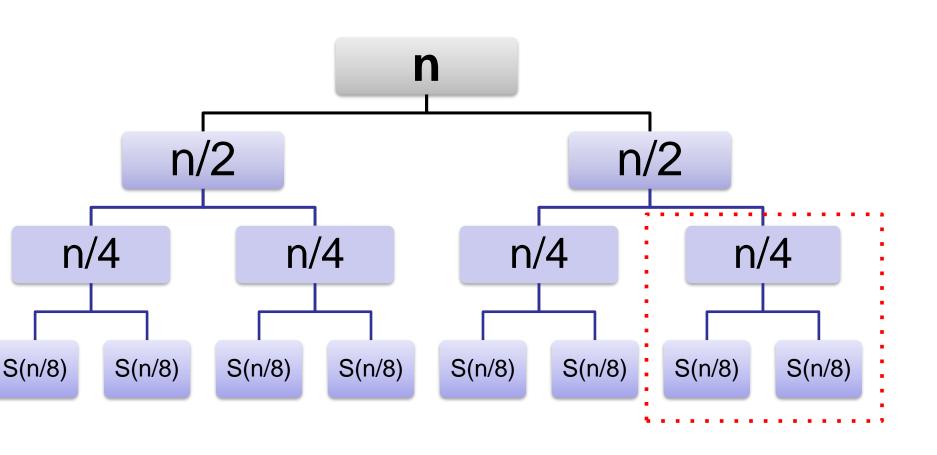
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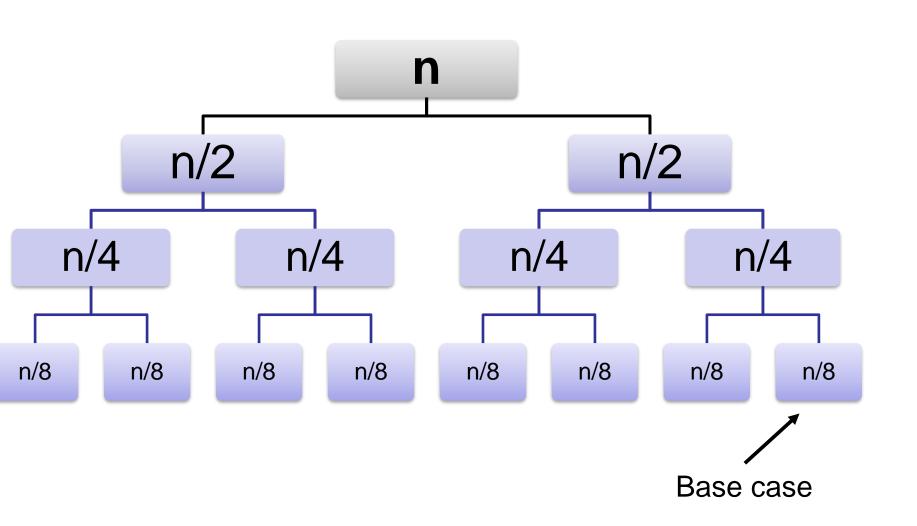
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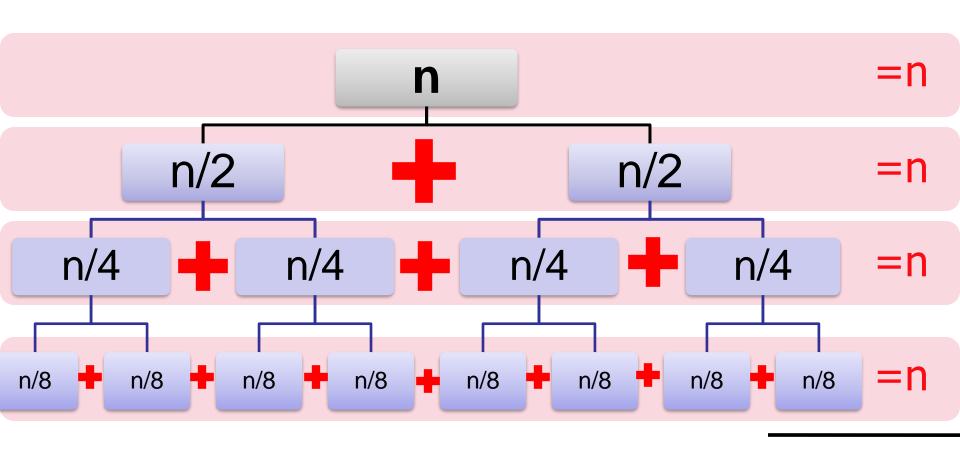
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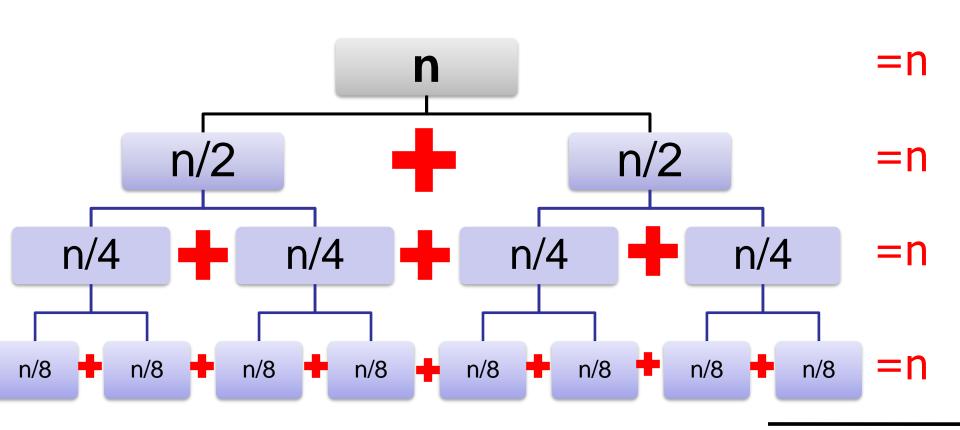
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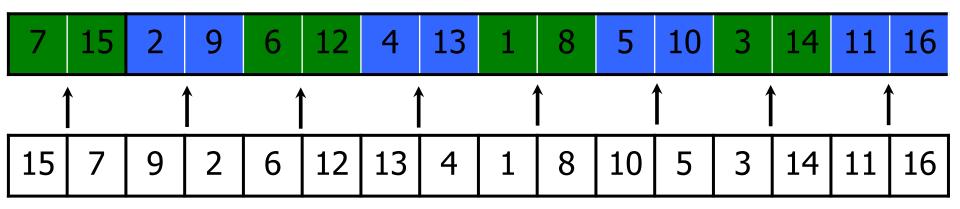
n log n

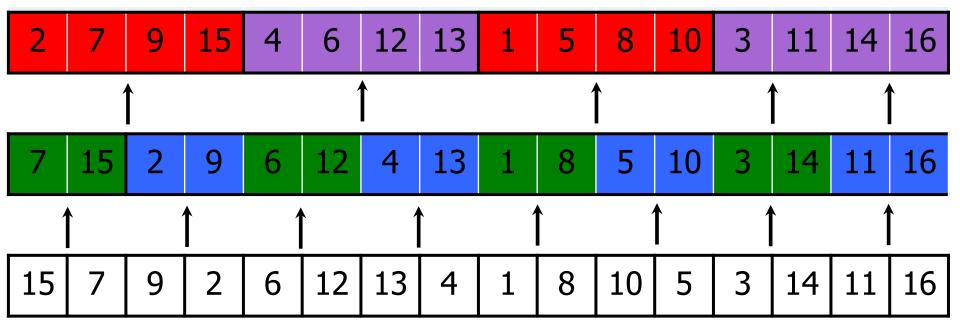
```
S(n) = O(n log n)
MergeSort(A, n)
    if (n=1) then return;
    else:
          X \leftarrow MergeSort(...);
                                 ← - - - - - S(n/2)
          Y \leftarrow MergeSort(...);
                                 <---S(n/2)
    return Merge (X,Y, n/2);
```

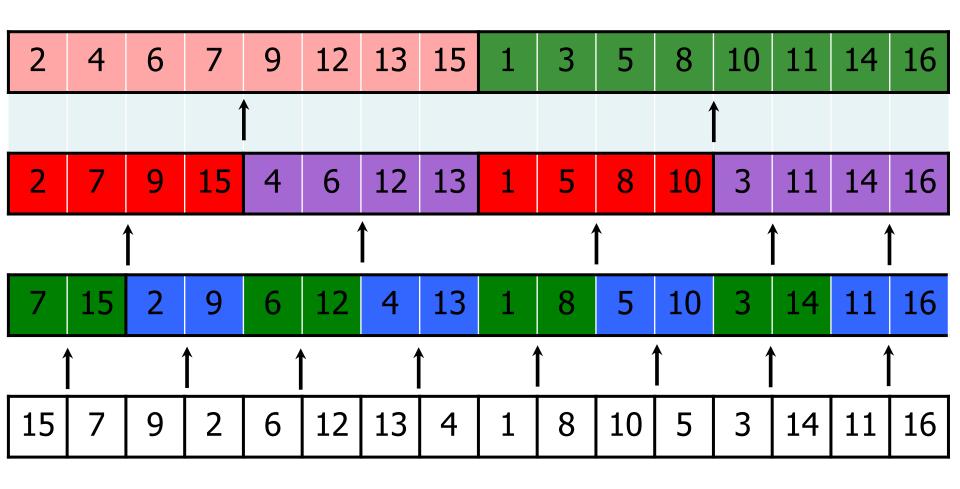
Challenge 2:

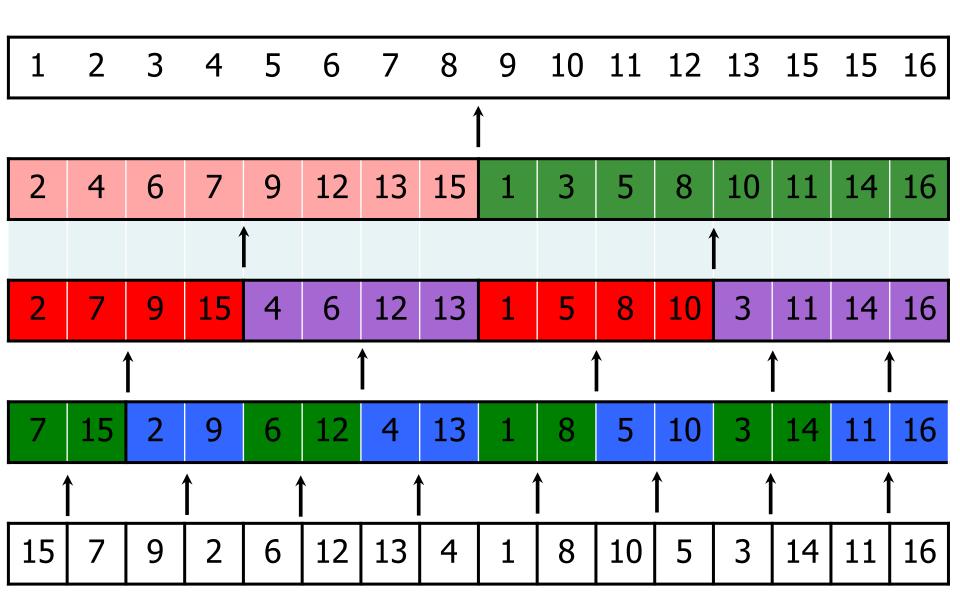
Design a version of MergeSort that minimizes the amount of extra space needed.

Hint: Do not allocate any new space during the recursive calls!

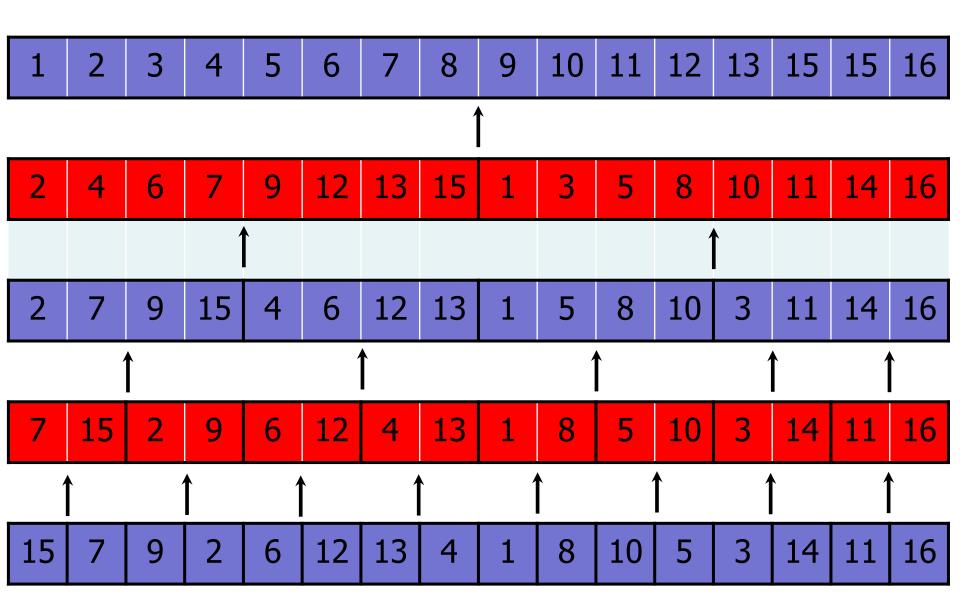








MergeSort: 2 arrays



Use only one temporary array!

MergeSort(A, begin, end, tempArray)

if (begin=end) then return;

else:

mid = begin + (end-begin)/2

MergeSort(A, begin, mid, tempArray);

MergeSort(A, mid+1, end, tempArray);

Merge(A[begin..mid], A[mid+1, end], tempArray);

Copy(tempArray, A, begin, end);

On termination, items in range [begin,end] are sorted in A.

The tempArray is used for workspace.

Merge copies items into tempArray.

We then copy the items back into array A.

```
S(n) = 2S(n/2) + O(1) = O(n)
MergeSort(A, begin, end, tempArray)
     if (begin=end) then return;
     else:
           mid = begin + (end-begin)/2
           MergeSort(A, begin, mid, tempArray);
           MergeSort(A, mid+1, end, tempArray);
           Merge(A[begin..mid], A[mid+1, end], tempArray);
           Copy(tempArray, A, begin, end);
```

Still a problem: can we avoid the extra copying of data? MergeSort(A, begin, end, tempArray) if (begin=end) then return; else: mid = begin + (end-begin)/2MergeSort(A, begin, mid, tempArray); MergeSort(A, mid+1, end, tempArray); Merge(A[begin..mid], A[mid+1, end], tempArray);

Copy(tempArray, A, begin, end);

Idea: switch temporary array at every step!

```
MergeSort(A, B, begin, end)
   if (begin=end) then return;
   else:
```

Initially, both A and B have copies of the unsorted array.

```
mid = begin + (end-begin)/2
MergeSort(B, A, begin, mid);
MergeSort(B, A, mid+1, end);
Merge(A, B, begin, mid, end);
```

-Copy(B, A, begin, end);

Switch the order of A and B at every recursive call.

Today: more sorting!

QuickSort:

- Divide-and-Conquer
- Partitioning
- Duplicates
- Choosing a pivot
- Randomization
- Analysis

History:

- Invented by C.A.R. Hoare in 1960
 - Turing Award: 1980

- Visiting student at Moscow State University
- Used for machine translation (English/Russian)

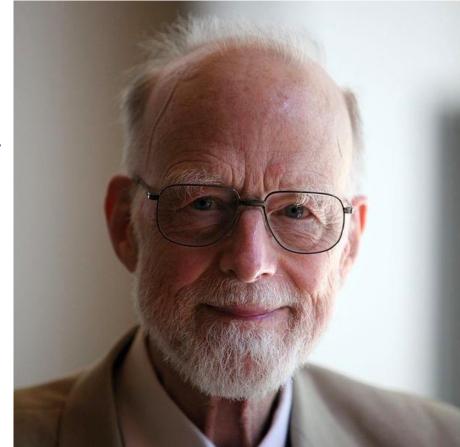


Photo: Wikimedia Commons (Rama)

Hoare

Quote:

"There are two ways of constructing a software design:

One way is to make it <u>so simple</u> that there are obviously no deficiencies, and the other way is to make it <u>so complicated</u> that there are no obvious deficiencies.

The first method is far more difficult."

History:

- Invented by C.A.R. Hoare in 1960
- Used for machine translation (English/Russian)

In practice:

- Very fast
- Many optimizations
- In-place (i.e., no extra space needed)
- Good caching performance
- Good parallelization

QuickSort Today

1960: Invented by Hoare

1979: Adopted everywhere (e.g., Unix qsort)

1993: Bentley & McIlroy improvements

"Engineering a sort function"

Yet in the summer of 1991 our colleagues Allan Wilks and Rick Becker found that a qsort run that should have taken a few minutes was chewing up hours of CPU time. Had they not interrupted it, it would have gone on for weeks. They found that it took n² comparisons to sort an 'organ-pipe' array of 2n integers: 123..nn.. 321.

QuickSort Today

1960: Invented by Hoare

1979: Adopted everywhere (e.g., Unix qsort)

1993: Bentley & McIlroy improvements

"Ok, QuickSort is done," said everyone.



Every algorithms class since 1993:

Punk in the front row:

"But what if we used more pivots?"

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Punk in the front row:

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Professor:

"Doesn't work. I can prove it. Let's get back to the syllabus...."

Punk in the front row:

"Huh... let me try it. Wait a sec, it's faster!"

QuickSort Today

- 1960: Invented by Hoare
- 1979: Adopted everywhere (e.g., Unix qsort)
- 1993: Bentley & McIlroy improvements
- 2009: Vladimir Yaroslavskiy
 - Dual-pivot Quicksort !!!
 - Now standard in Java
 - 10% faster!

QuickSort Today

- 1960: Invented by Hoare
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2012: Sebastian Wild and Markus E. Nebel

- "Average Case Analysis of Java 7's Dual Pivot..."
- Best paper award at ESA

Moral of the story:

- 1) Don't just listen to me. Go try it!
- 1) Even "classical" algorithms change. QuickSort in 5 years may be different than QuickSort I am teaching today.

History:

- Invented by C.A.R. Hoare in 1960
- Used for machine translation (English/Russian)

In practice:

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```
QuickSort(A[1..n], n)

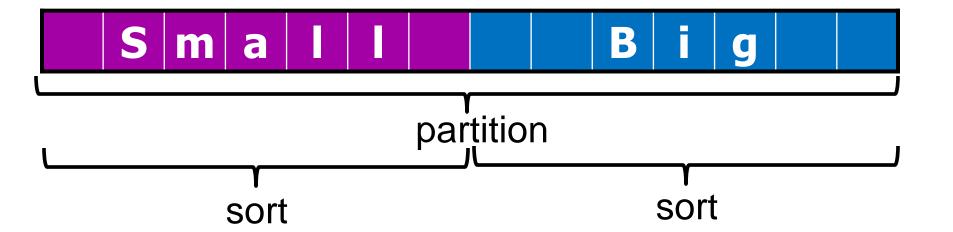
if (n==1) then return;
else

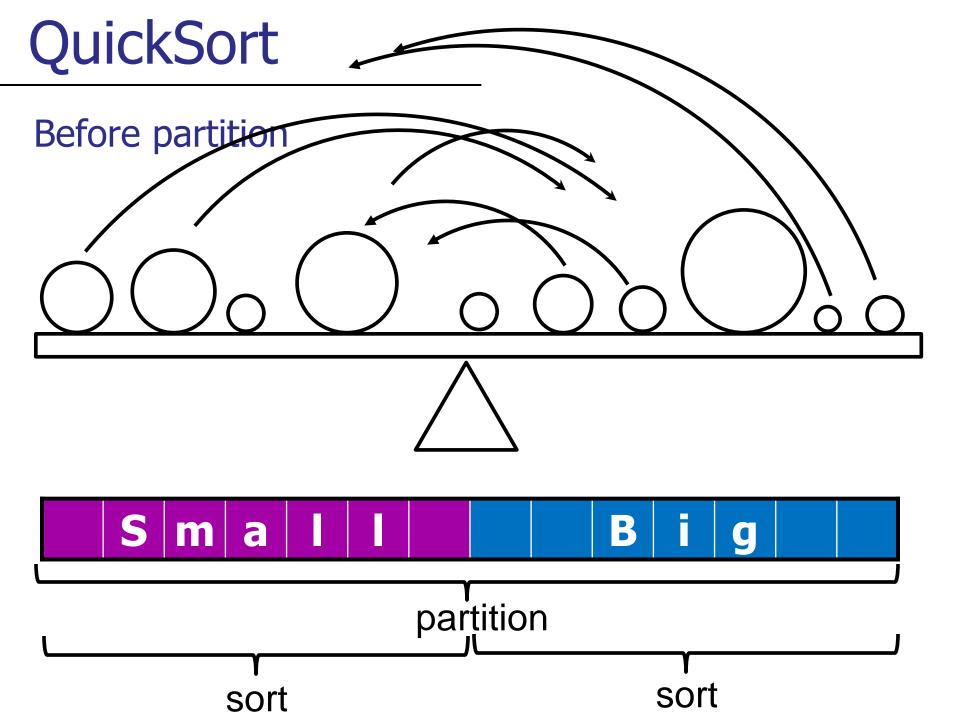
p = partition(A[1..n], n)

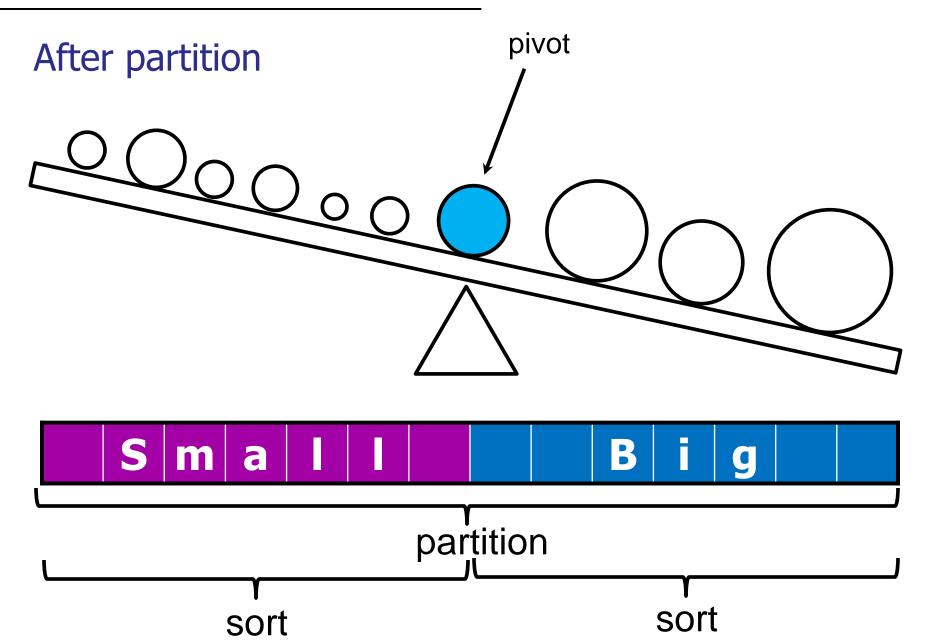
x = QuickSort(A[1..p-1], p-1)

y = QuickSort(A[p+1..n], n-p)
```









```
QuickSort(A[1..n], n)

if (n==1) then return;
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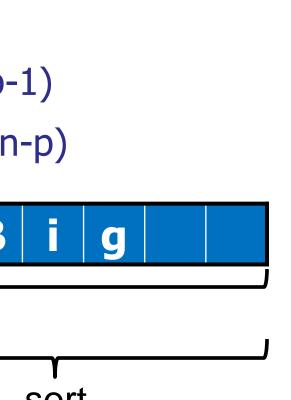
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x = QuickSort(A[1..p-1], p-1)

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```

sort

partition



Given: n element array A[1..n]

1. Divide: Partition the array into two sub-arrays around a *pivot* x such that elements in lower subarray $\le x \le$ elements in upper sub-array.

 $\langle x \rangle \times x$

- 1. Conquer: Recursively sort the two sub-arrays.
- 2. Combine: Trivial, do nothing.

Key: efficient *partition* sub-routine

Three steps:

- 1. Choose a pivot.
- 2. Find all elements smaller than the pivot.
- 3. Find all elements larger than the pivot.

 $\langle x \rangle > x$

Example:

6 3 9 8 4 2

Example:

6 3 9 8 4 2

3 4 2 6 9 8

Example:

```
6
3
9
8
4
2
3
4
2
6
9
8
2
3
4
```

Example:

6 3 9 8 4 2

3 4 2 6 9 8

2 3 4 8 9

Example:

6 3 9 8 4 2

3 4 2 6 9 8

2 3 4 6 8 9

Example:

6 3 9 8 4 2

3 4 2 6 9 8

2 3 4 6 8 9

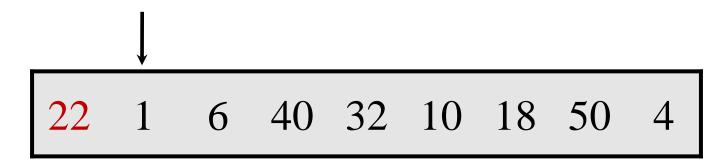
The following array has been partitioned around which element?

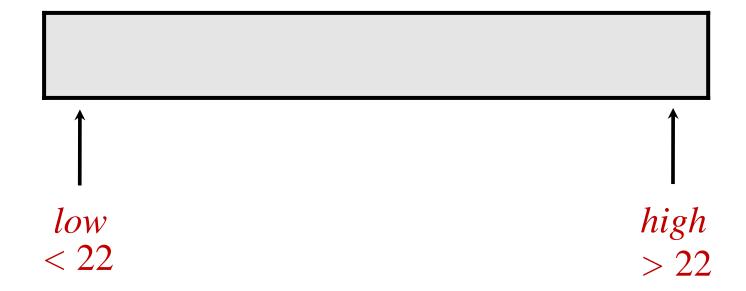
- a. 6
- b. 10
- c. 22
- d. 40
- e. 32
- f. I don't know.

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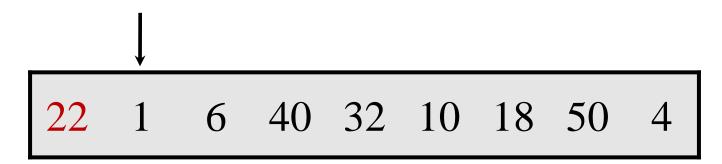
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- b. 10
- **✓**c. 22
 - d. 40
 - e. 32
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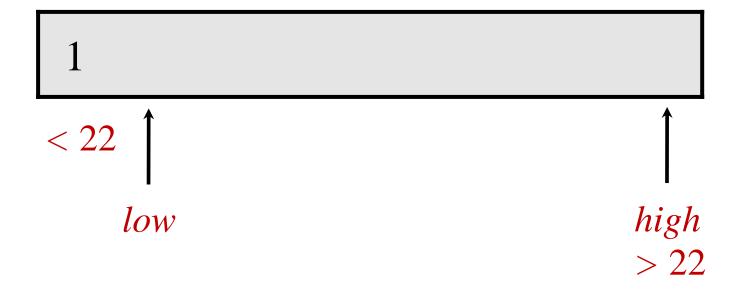
Example: partition around 22



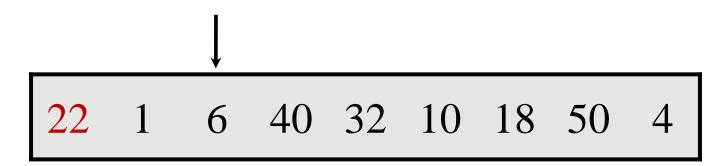


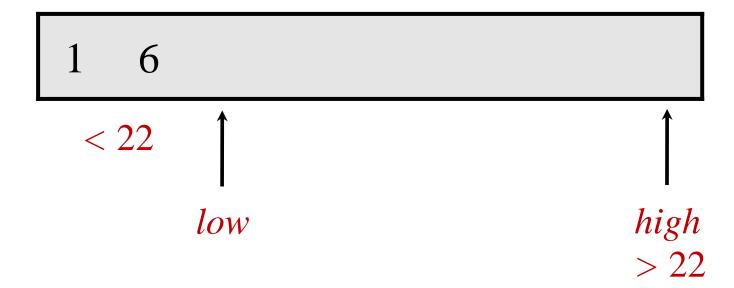
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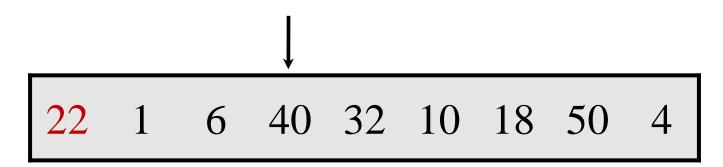


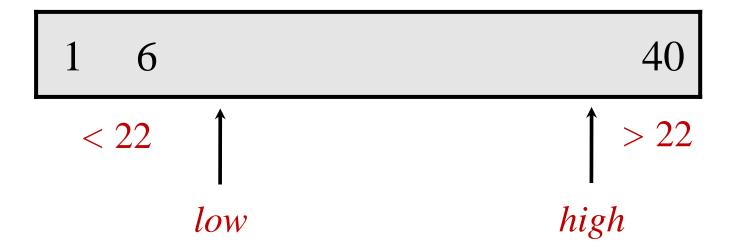
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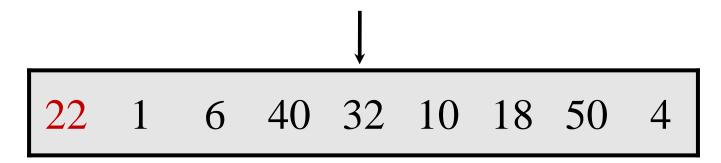


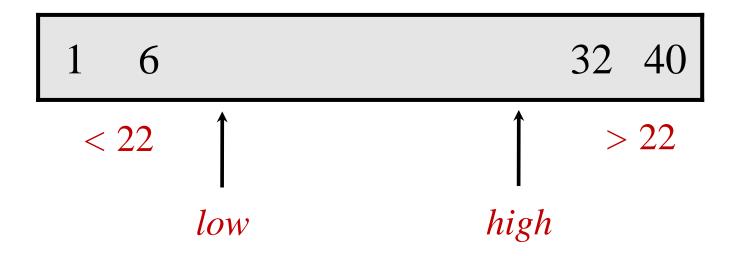
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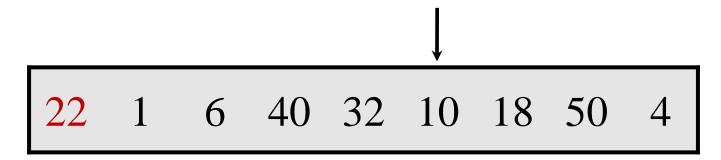


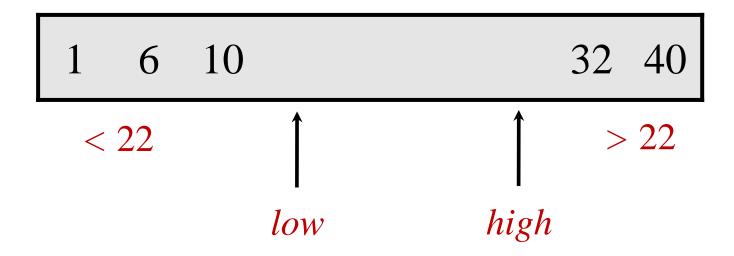
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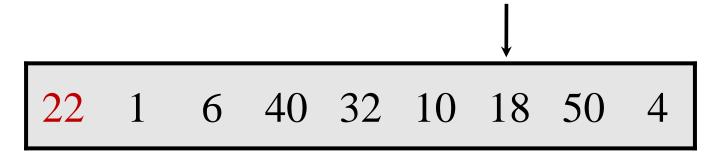


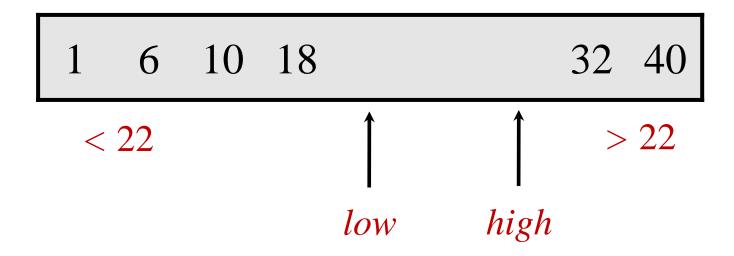
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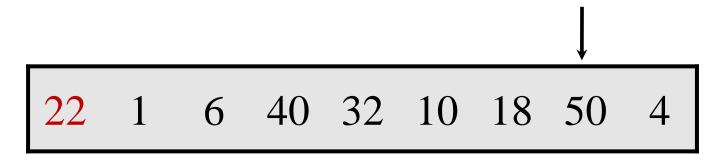


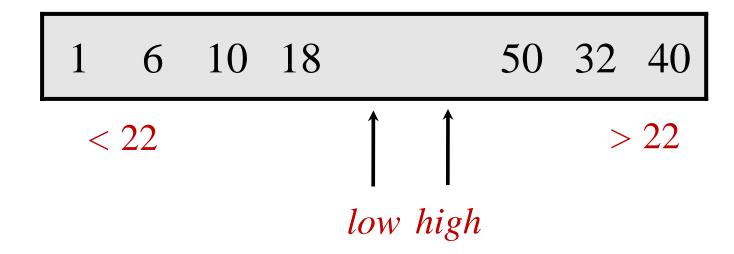
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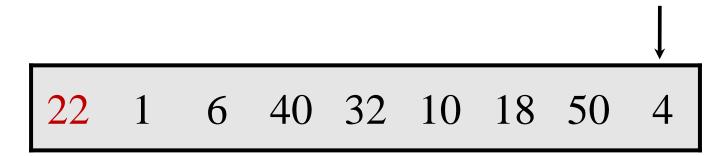


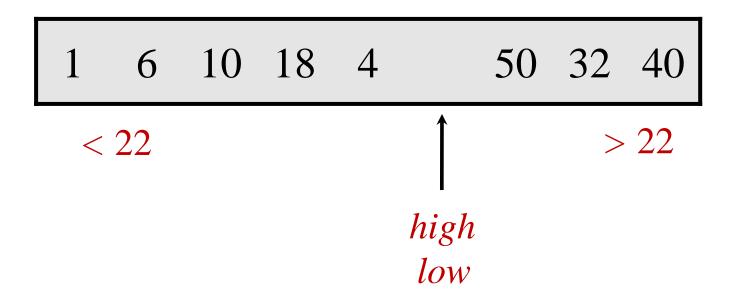
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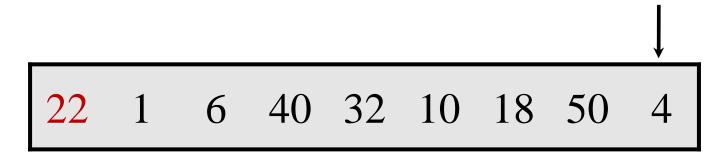


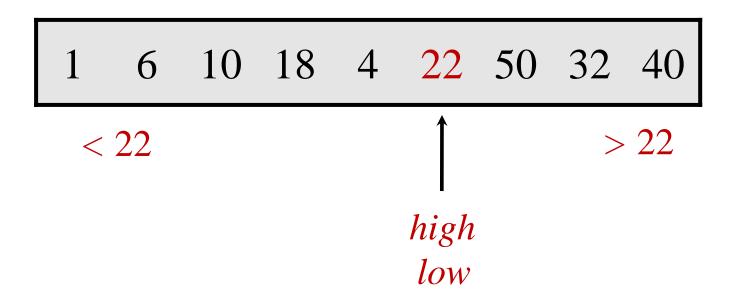
Example: partition around 22





Example: partition around 22





```
partition(A[2..n], n, pivot) // Assume no duplicates
   B = new n element array
   low = 1;
   high = n;
   for (i = 2; i \le n; i++)
       if (A[i] < pivot) then
              B[low] = A[i];
              low++;
       else if (A[i] > pivot) then
              B[high] = A[i];
              high--;
   B[low] = pivot;
    return < B, low >
```

22 1 6 40 32 10 18 50 4 32 40 6 10 18 < 22 > 22 high low

Claim: array B is partitioned around the pivot **Proof**:

Invariants:

- 1. For every i < low : B[i] < pivot
- 2. For every j > high : B[j] > pivot

In the end, every element from A is copied to B.

Then: B[i] = pivot

By invariants, B is partitioned around the pivot.

Example: 22 1 6 40 32 10 18 50

What is the running time of partition?

- 1. $O(\log n)$
- 2. O(n)
- 3. $O(n \log n)$
- 4. $O(n^2)$
- 5. I have no idea.

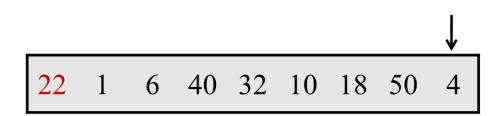
Example: 22 1 6 40 32 10 18 50

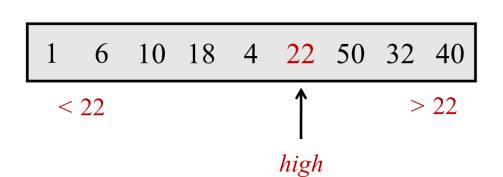
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Any bugs?

Anything that can be improved?

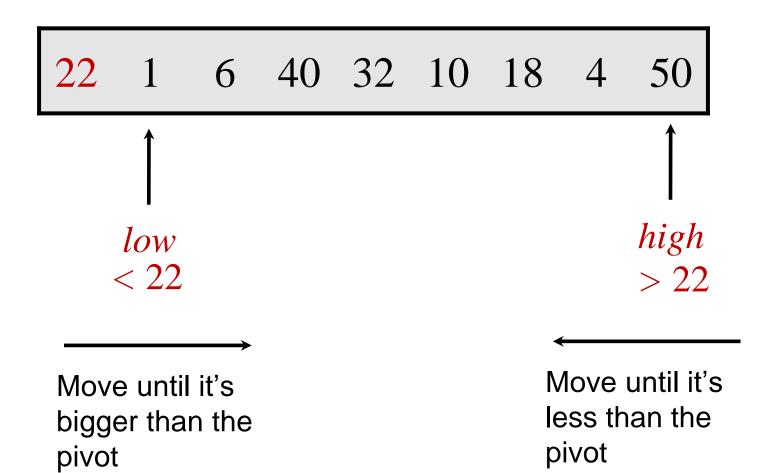


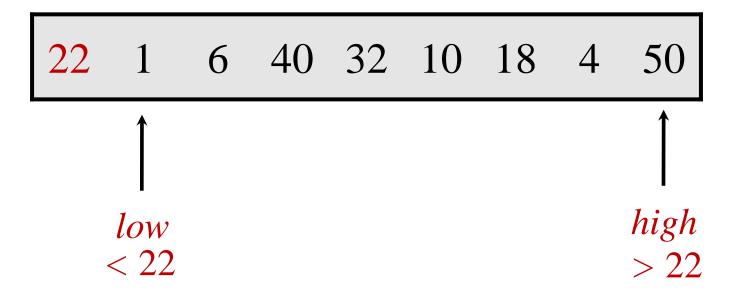


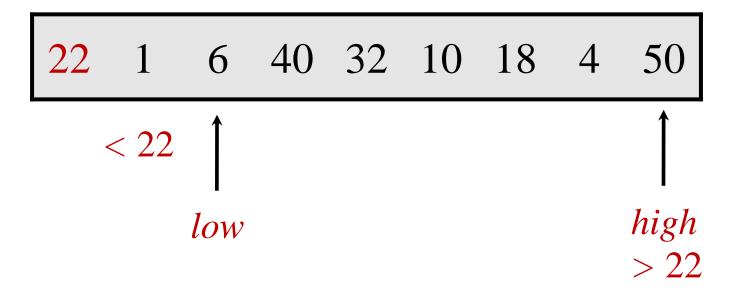
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              high--;
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```

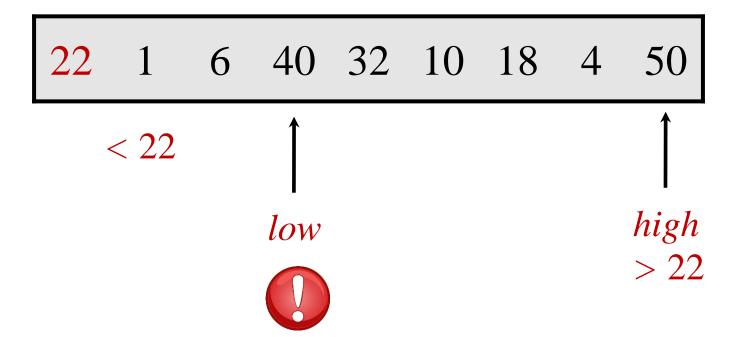
22 1 6 40 32 10 18 50 4 32 40 6 10 18 < 22 > 22 high low

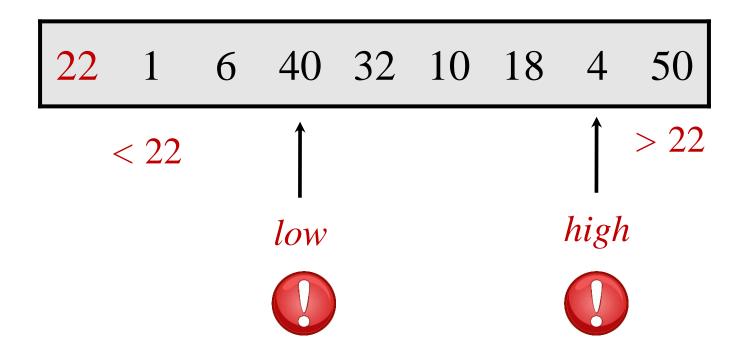
Partitioning an Array "in-place"

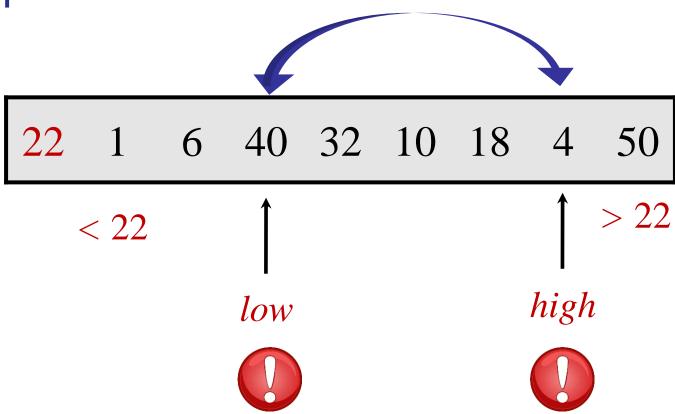


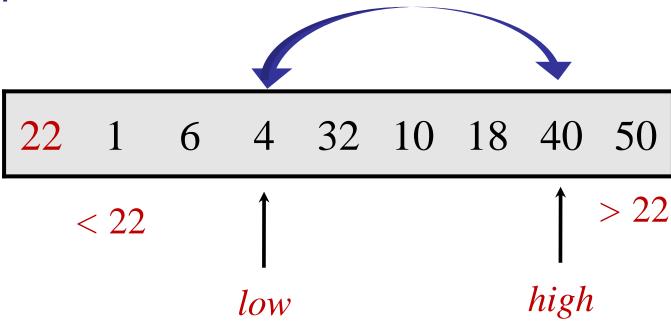


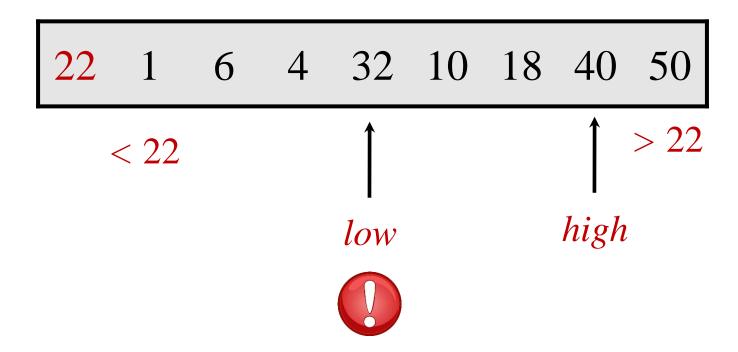


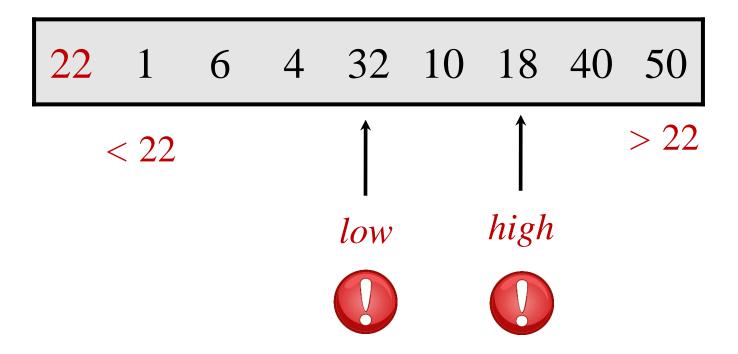


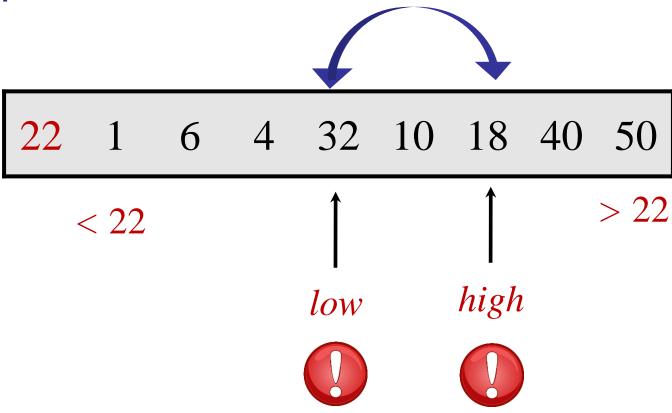


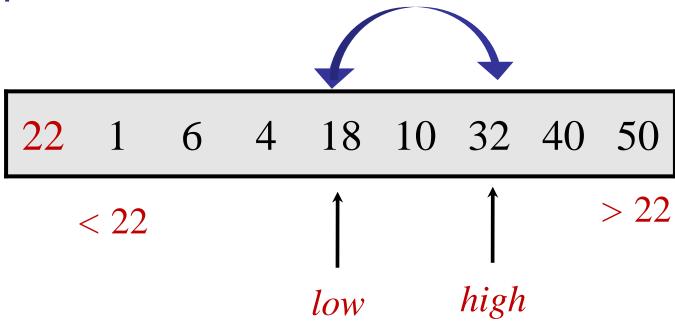


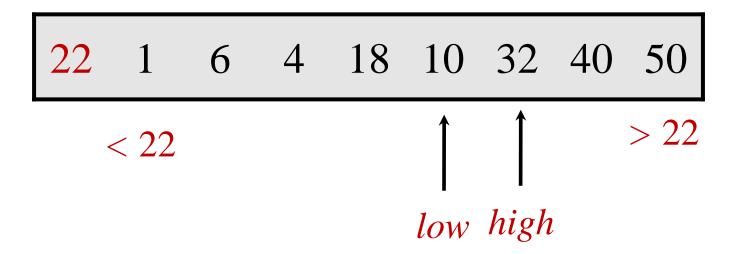


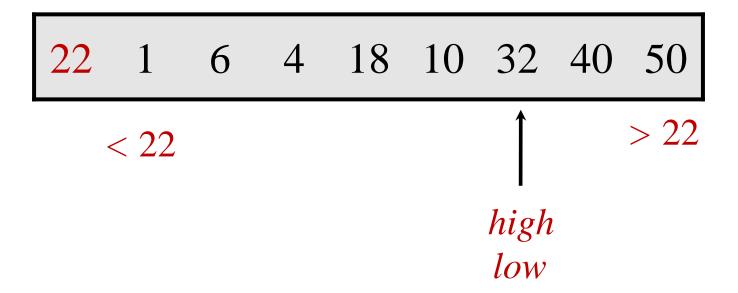


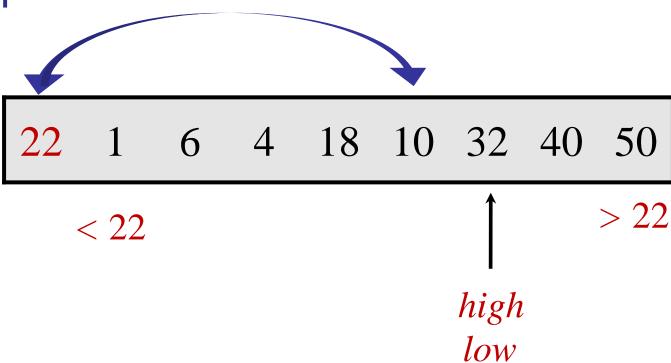


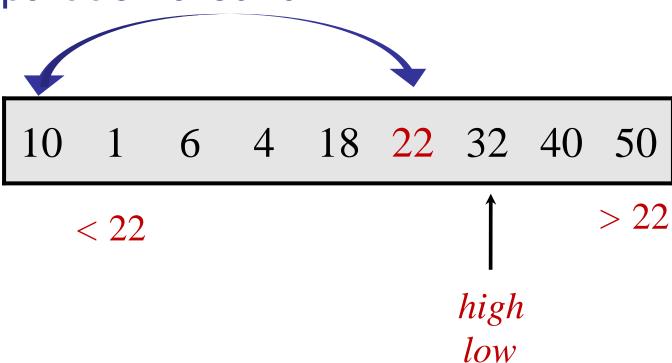












```
partition(A[1..n], n, pIndex)
                                     // Assume no duplicates, n>1
     pivot = A[pIndex];
                                     // pIndex is the index of pivot
                                     // store pivot in A[1]
     swap(A[1], A[pIndex]);
                                     // start after pivot in A[1]
     low = 2;
                                    // Define: A[n+1] = \infty
     high = n+1;
     while (low < high)
             while (A[low] \le pivot) and (low \le high) do low++;
             while (A[high] > pivot) and (low < high) do high - -;
             if (low < high) then swap(A[low], A[high]);
     swap(A[1], A[low-1]);
     return low–1;
```

Pseudocode

VS.

Real Code

QuickSort is notorious for off-by-one errors...

Invariant: A[high] > pivot at the end of each loop.

Proof:

Initially: true by assumption $A[n+1] = \infty$

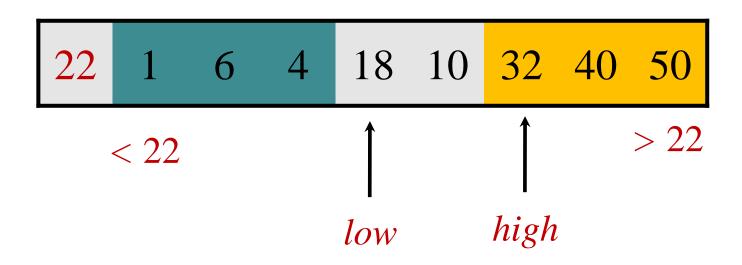
Invariant: A[high] > pivot at the end of each iter: Proof: During loop:

- When exit loop incrementing low: A[low] > pivotIf (low > high), then by **while** condition. If (low == high), then by inductive assumption.
- When exit loop decrementing high:
 A[high] < pivot OR low = high
- If (high == low), then A[high] > pivot
- Otherwise, swap A[high] and A[low]>pivot.

```
partition(A[1..n], n, pIndex)
                                     // Assume no duplicates, n>1
     pivot = A[pIndex];
                                     // pIndex is the index of pivot
                                     // store pivot in A[1]
     swap(A[1], A[pIndex]);
                                    // start after pivot in A[1]
     low = 2;
                                    // Define: A[n+1] = \infty
     high = n+1;
     while (low < high)
             while (A[low] < pivot) and (low < high) do low++;
             while (A[high] > pivot) and (low < high) do high - -;
             if (low < high) then swap(A[low], A[high]);
     swap(A[1], A[low-1]);
     return low–1;
```

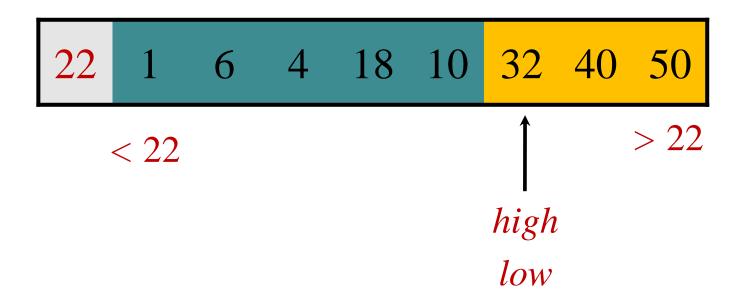
Invariant: At the end of every loop iteration:

for all
$$i >= high$$
, $A[i] > pivot$.
for all $1 < j < low$, $A[j] < pivot$.



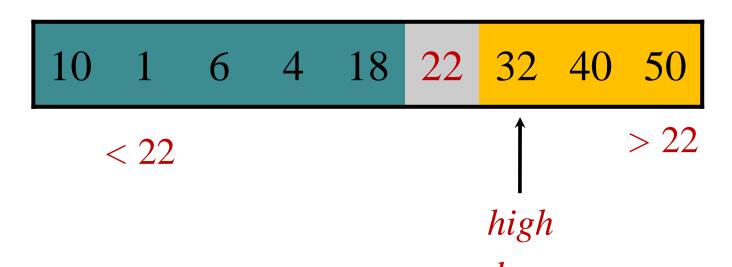
Invariant: At the end of every loop iteration:

for all
$$i >= high$$
, $A[i] > pivot$.
for all $1 < j < low$, $A[j] < pivot$.



Claim: At the end of every loop iteration:

for all
$$i >= high$$
, $A[i] > pivot$.
for all $1 < j < low$, $A[j] < pivot$.



Claim: Array A is partitioned around the pivot

```
partition(A[1..n], n, pIndex)
                                     // Assume no duplicates, n>1
     pivot = A[pIndex];
                                     // pIndex is the index of pivot
                                    // store pivot in A[1]
     swap(A[1], A[pIndex]);
                                    // start after pivot in A[1]
     low = 2;
                                    // Define: A[n+1] = \infty
     high = n+1;
     while (low < high)
             while (A[low] < pivot) and (low < high) do low++;
             while (A[high] > pivot) and (low < high) do high - -;
             if (low < high) then swap(A[low], A[high]);
     swap(A[1], A[low-1]);
     return low–1;
```

```
partition(A[1..n], n, pIndex)
     pivot = A[pIndex];
                                        Running time:
     swap(A[1], A[pIndex]);
     low = 2;
                                              O(n)
     high = n+1;
     while (low < high)
            while (A[low] < pivot) and (low < high) do low++;
            while (A[high] > pivot) and (low < high) do high - -;
            if (low < high) then swap(A[low], A[high]);
     swap(A[1], A[low-1]);
     return low–1;
```

QuickSort

```
QuickSort(A[1..n], n)
    if (n == 1) then return;
    else
          Choose pivot index pIndex.
          p = partition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
```

Sorting, continued

QuickSort

- Divide-and-Conquer
- Partitioning
- Duplicates
- Choosing a pivot
- Randomization
- Analysis

QuickSort

What happens if there are duplicates?

```
QuickSort(A[1..n], n)
    if (n==1) then return;
    else
          Choose pivot index pIndex.
          p = partition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
```

Example:

Example:

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6 6 6 6 6



Example:

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6	6	6	6	6	6
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6	6	6	6	6	6
6	6	6	6	6	6
6	6	6	6	6	6

Example:

U



b







What is the running time on the all 6's array?

6	6	6	6	6	6
6	6	6	6	6	6
6	6	6	6	6	6
6	6	6	6	6	6
6	6	6	6	6	6
6	6	6	6	6	6

Example:

Running time:

 $O(n^2)$

6	6

```
partition(A[1..n], n, pIndex)
                                     // Assume no duplicates, n>1
     pivot = A[pIndex];
                                     // pIndex is the index of pivot
                                     // store pivot in A[1]
     swap(A[1], A[pIndex]);
                                    // start after pivot in A[1]
     low = 2;
                                    // Define: A[n+1] = \infty
     high = n+1;
     while (low < high)
             while (A[low] < pivot) and (low < high) do low++;
             while (A[high] > pivot) and (low < high) do high - -;
             if (low < high) then swap(A[low], A[high]);
     swap(A[1], A[low-1]);
     return low–1;
```

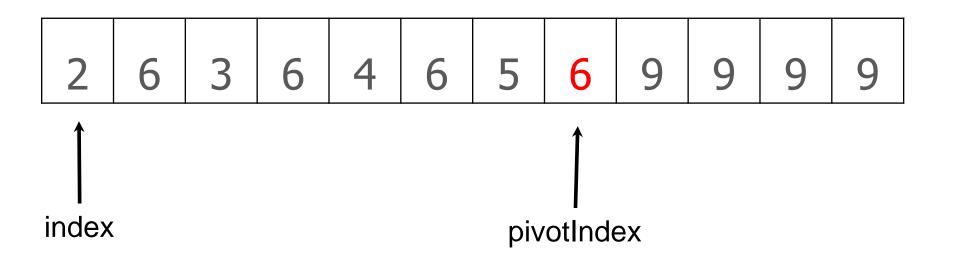
```
QuickSort(A[1..n], n)
    if (n==1) then return;
    else
          Choose pivot index pIndex.
          p = partition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
```

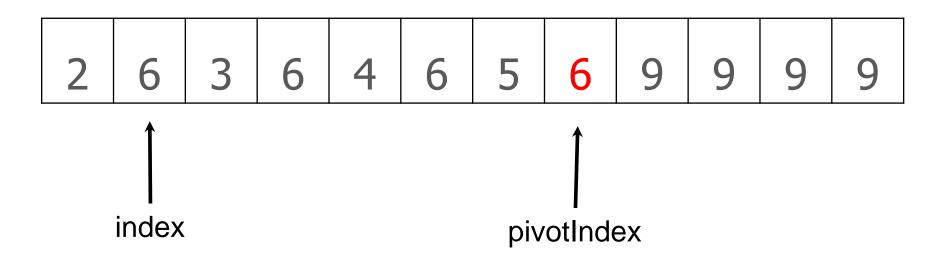
 \boldsymbol{x} \boldsymbol{x} \boldsymbol{x}

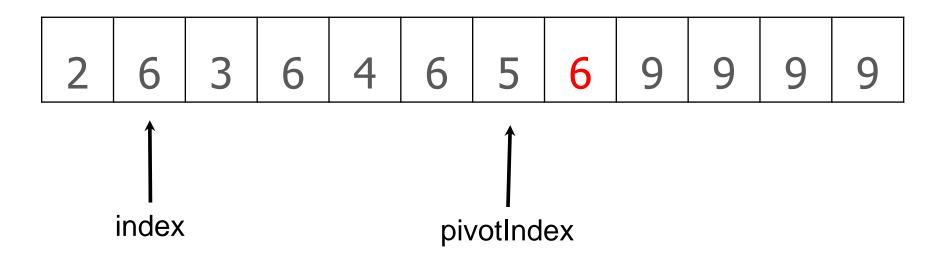
```
QuickSort(A[1..n], n)
    if (n==1) then return;
    else
          Choose pivot index pIndex.
          p = partition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
                     x \quad x \quad x
            < x
                                         > X
```

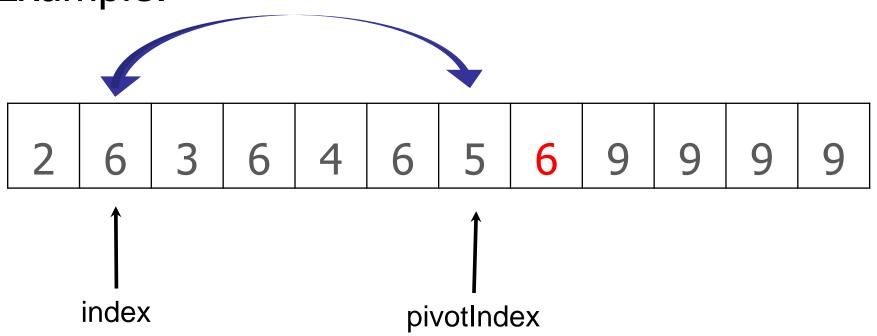
Pivot

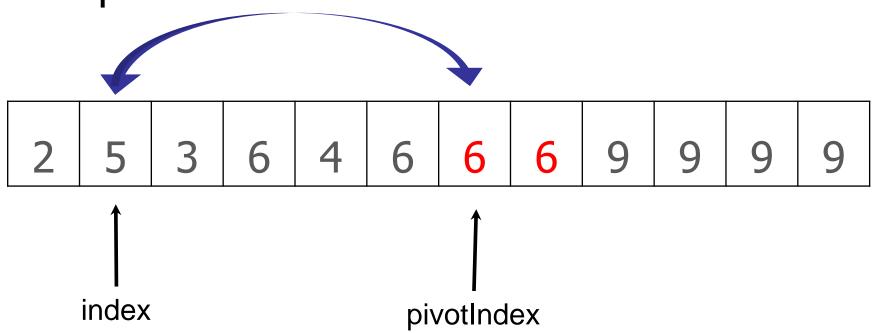
- Option 1: two pass partitioning
 - 1. Regular partition.
 - 2. Pack duplicates.

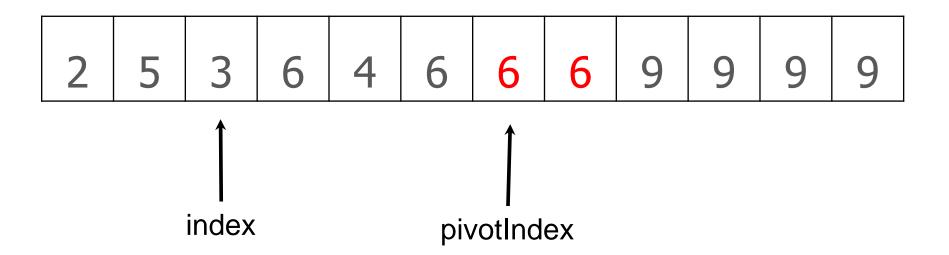


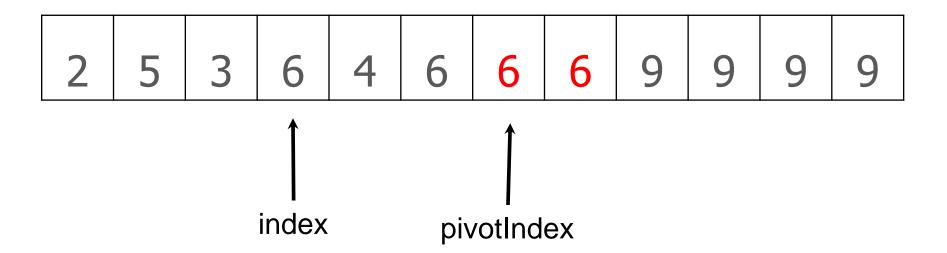


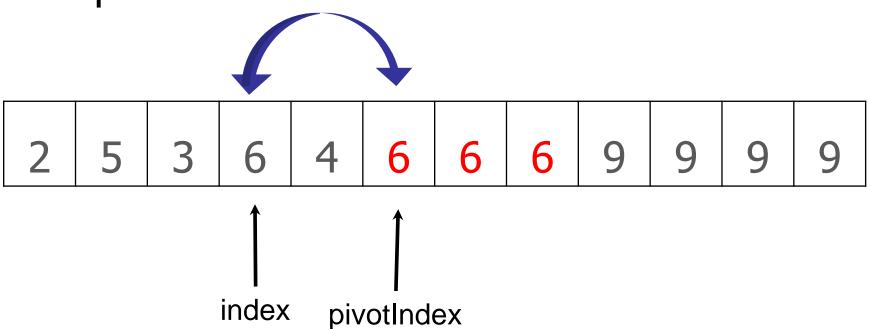


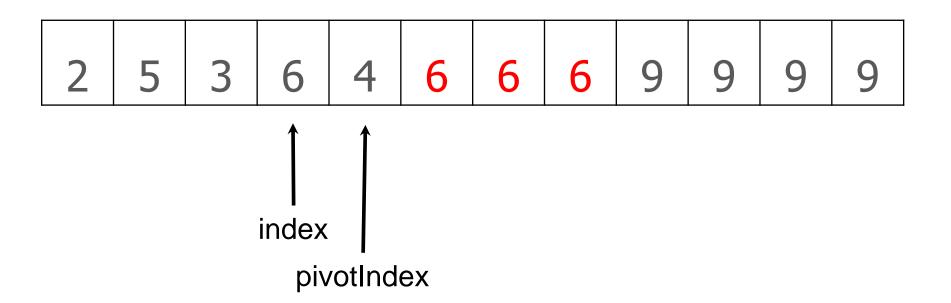


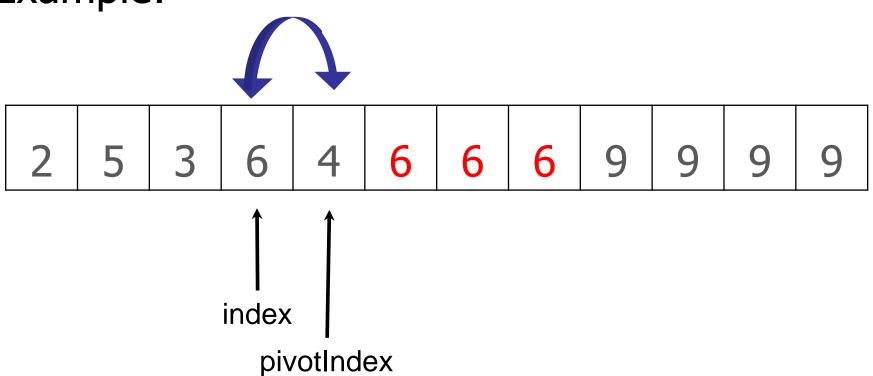


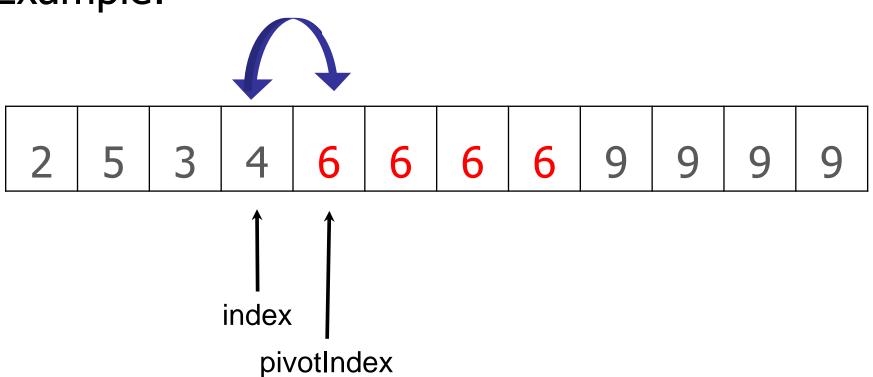


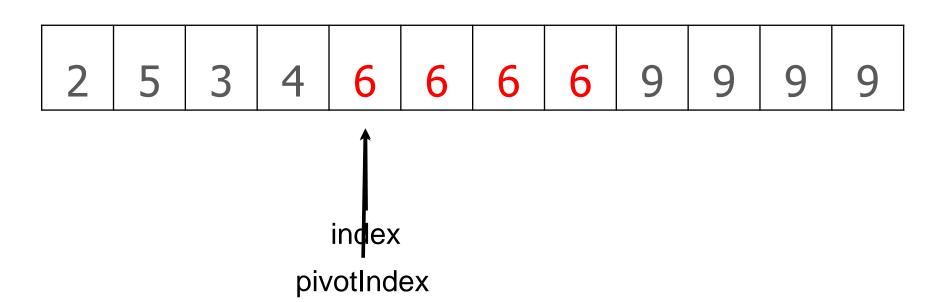










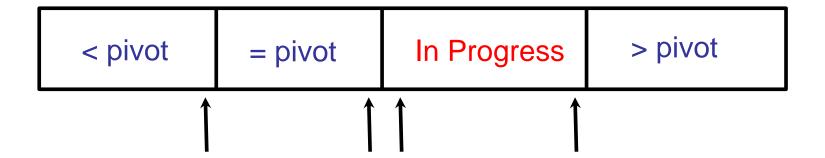


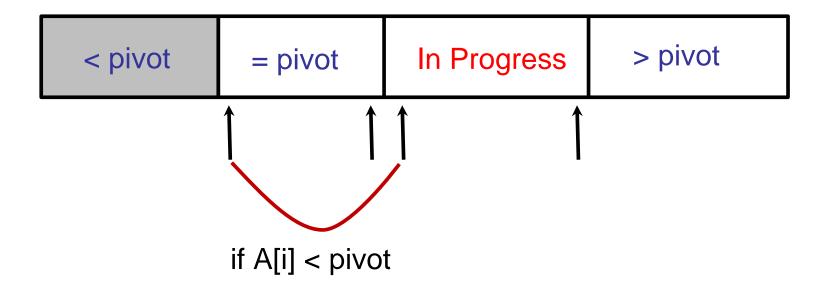
```
QuickSort(A[1..n], n)
    if (n==1) then return;
    else
          Choose pivot index pIndex.
          p = 3wayPartition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
```

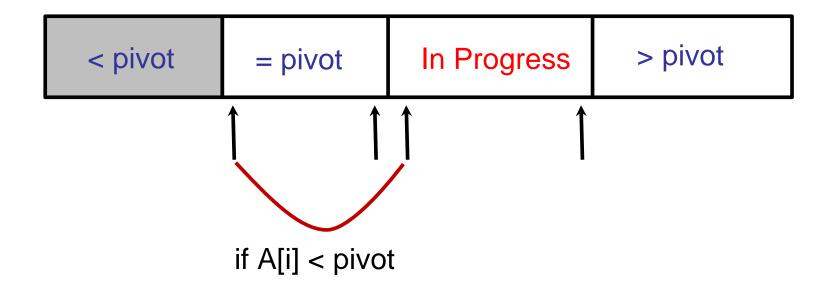
 $\langle x | x | x | x$

- Option 1: two pass partitioning
 - 1. Regular partition.
 - 2. Pack duplicates.

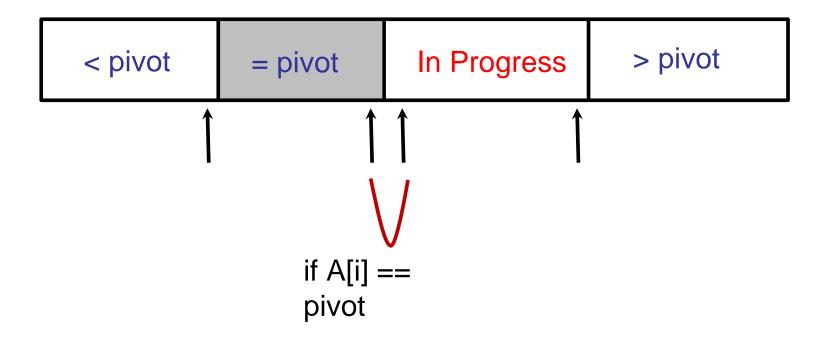
- Option 2: one pass partitioning
 - More complicated.
 - Maintain four regions of the array

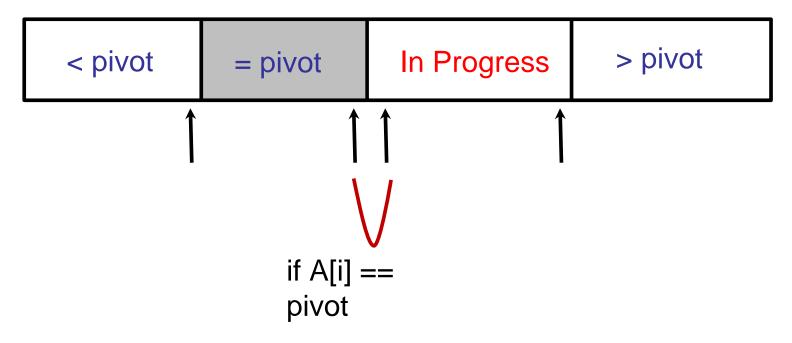






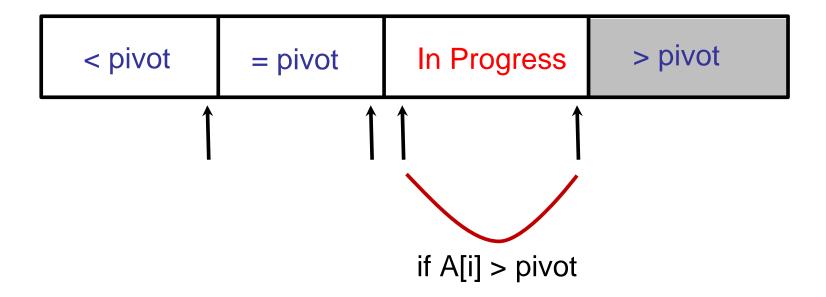
Just swap item at index i with first pivot element

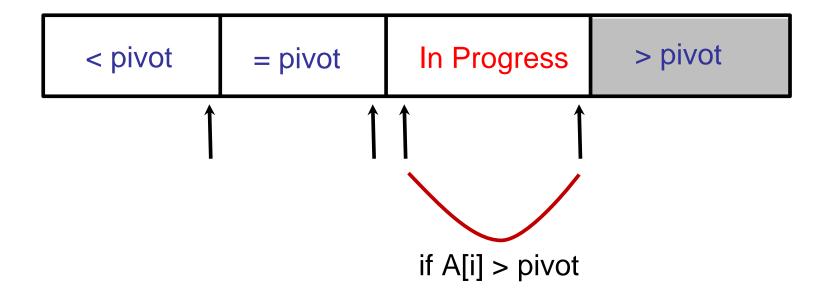




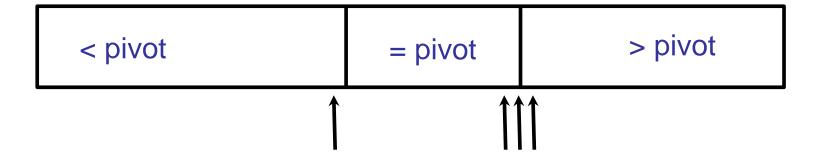
just increment the pivot end index by 1

this "grows" the pivot region





swap element at index i with beginning of the > pivot region



Duplicates

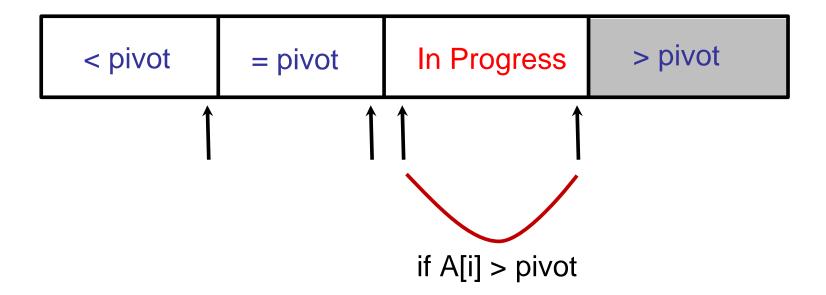
```
QuickSort(A[1..n], n)
    if (n==1) then return;
    else
          Choose pivot index pIndex.
          p = 3wayPartition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
```

 $\langle x | x | x | x$

> X

Is QuickSort stable?

QuickSort is not stable



Sorting, continued

QuickSort

- Divide-and-Conquer
- Partitioning
- Duplicates
- Choosing a pivot
- Randomization
- Analysis

Options:

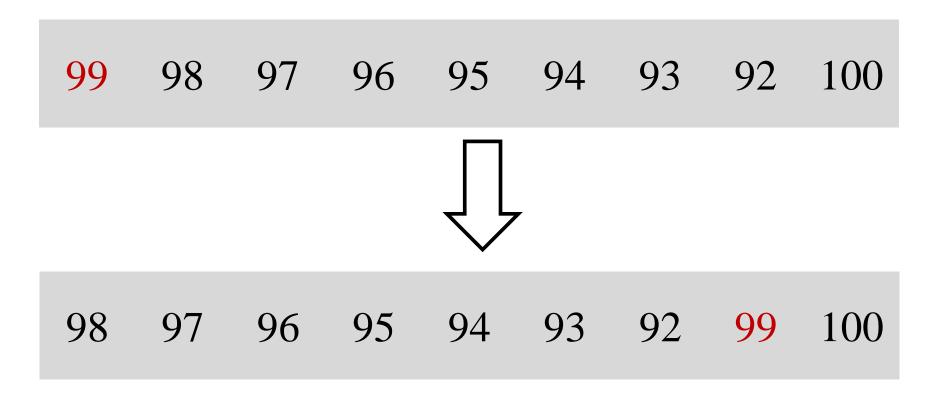
- -first element: A[1]
- -last element: A[n]
- -middle element: A[n/2]
- -median of (A[1], A[n/2], A[n])

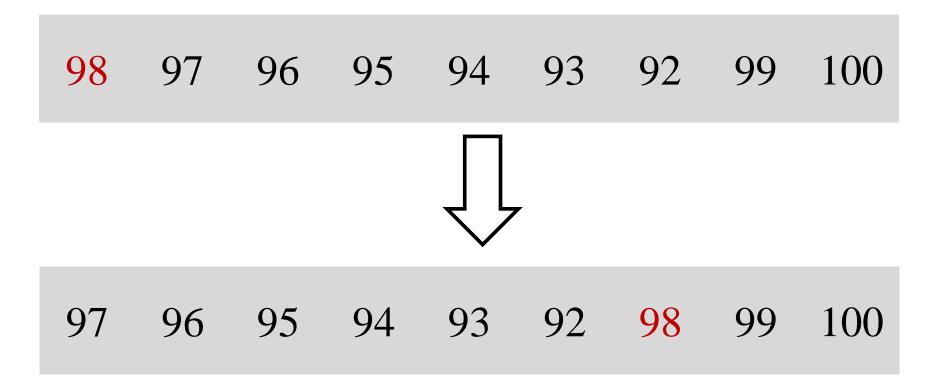
Options:

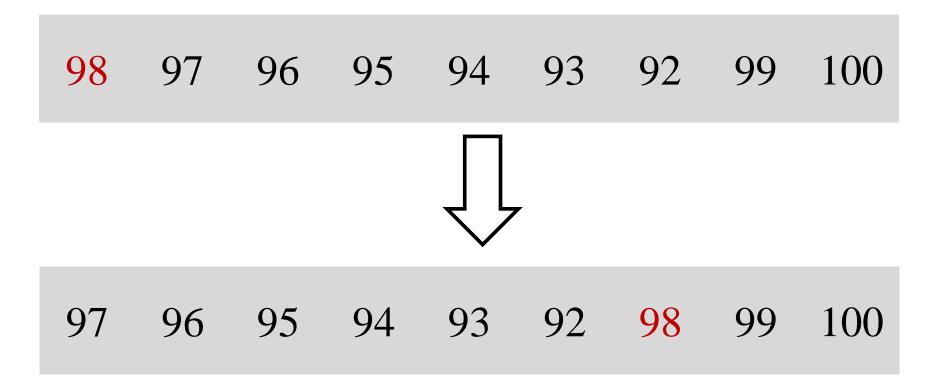
- -first element: A[1]
- -last element: A[n]
- -middle element: A[n/2]
- -median of (A[1], A[n/2], A[n])

In the worst case, it does not matter!

All options are equally bad.





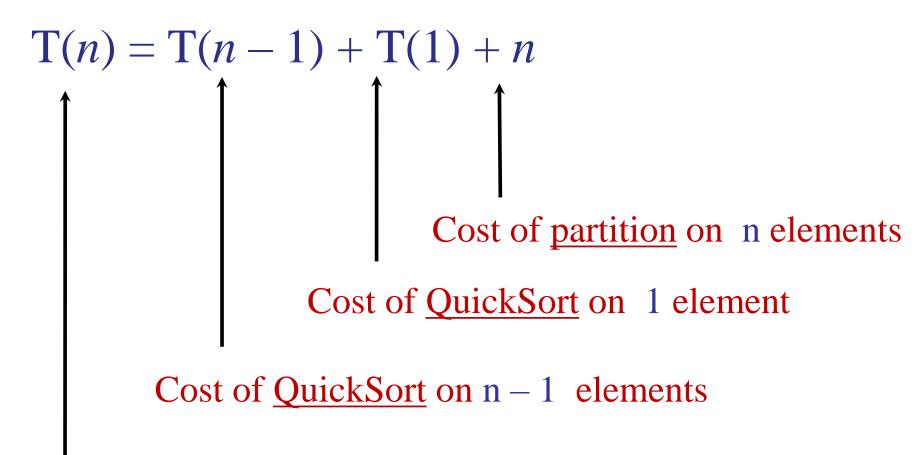


Sorting the array takes n executions of partition.

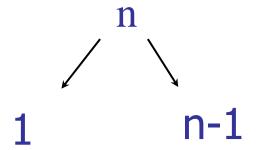
- -Each call to partition sorts one element.
- –Each call to partition of size k takes: ≥ k

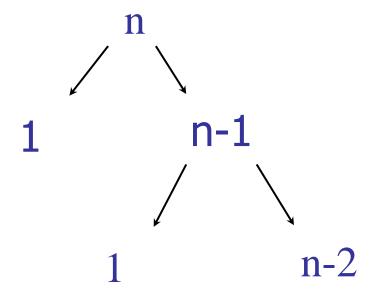
Total:
$$n + (n-1) + (n-2) + (n-3) + ... = O(n^2)$$

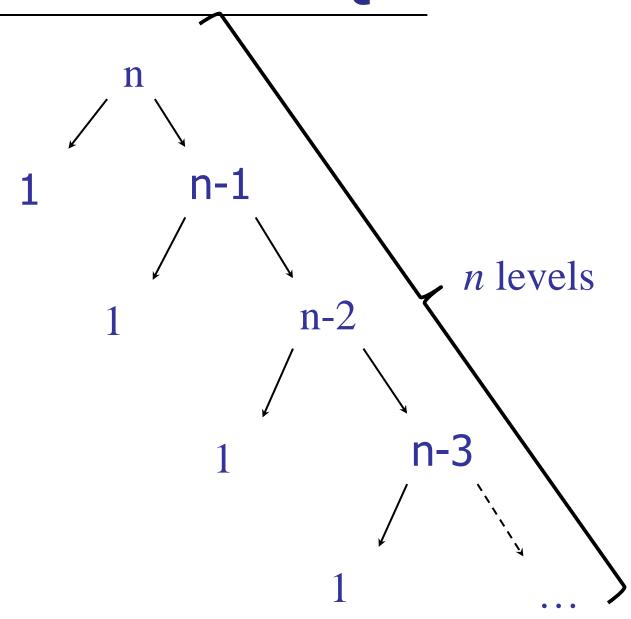
QuickSort Recurrence:

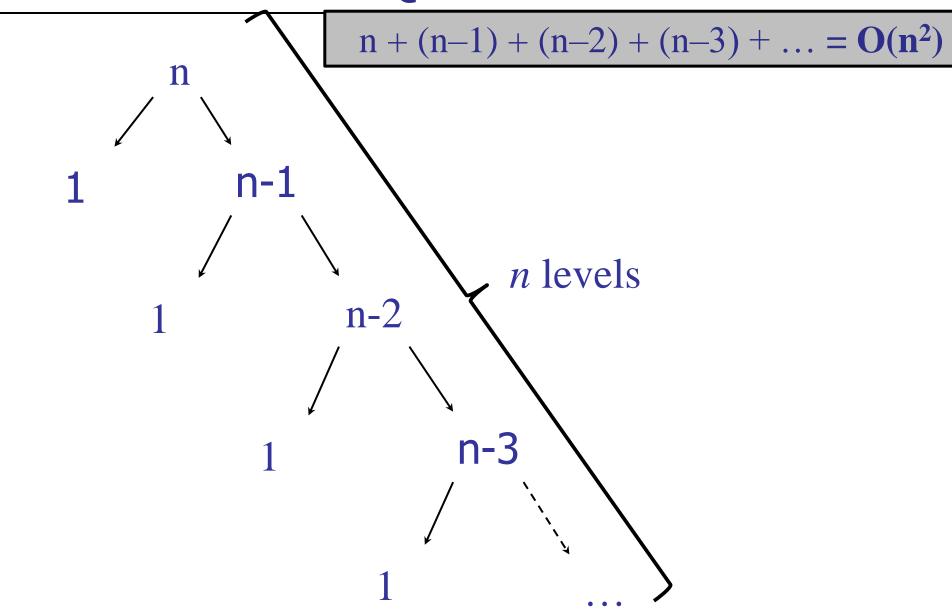


Cost of QuickSort on n elements





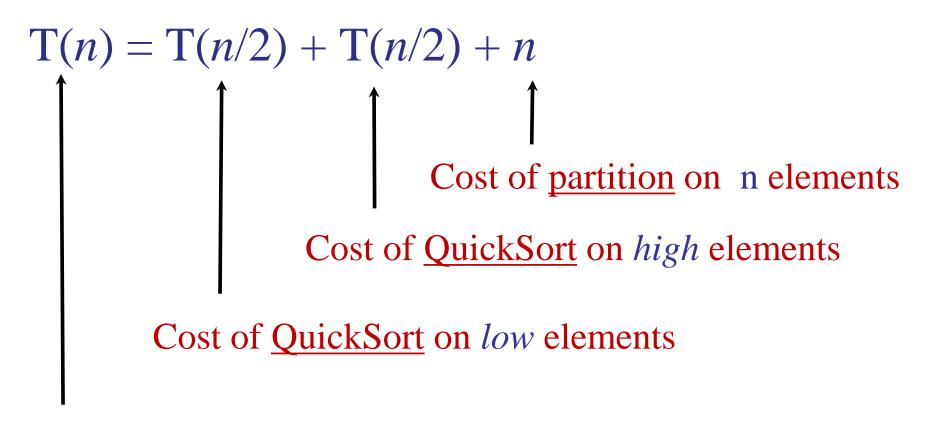




```
QuickSort(A[1..n], n)
    if (n==1) then return;
    else
          Choose pivot index pIndex.
          p = partition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
```

Better QuickSort

What if we chose the *median* element for the pivot?



Cost of QuickSort on n elements

Better QuickSort

If we split the array evenly:

$$T(n) = T(n/2) + T(n/2) + cn$$
$$= 2T(n/2) + cn$$
$$= O(n \log n)$$

QuickSort Summary

- If we choose the pivot as A[1]:
 - Bad performance: $\Omega(n^2)$

- If we could choose the median element:
 - Good performance: $O(n \log n)$

- If we could split the array (1/10): (9/10)
 - _ ??

QuickSort Pivot Choice

Define sets L (low) and H (high):

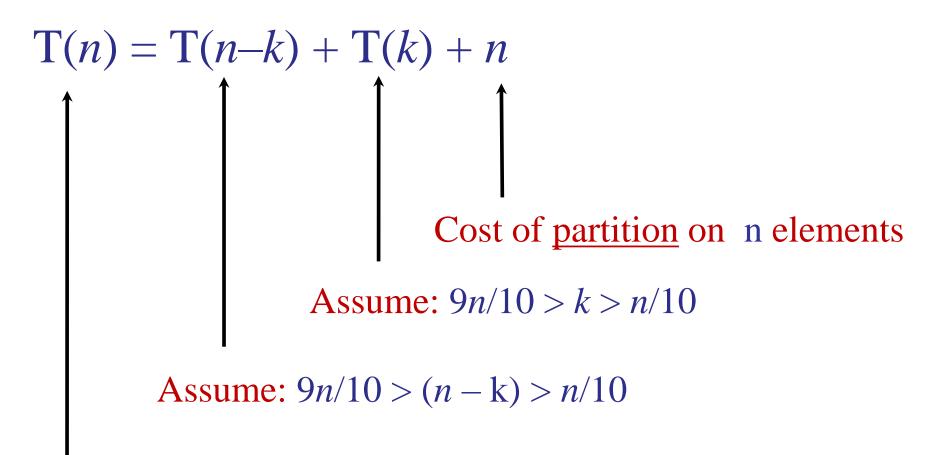
- $L = \{A[i] : A[i] < pivot\}$
- $H = \{A[i] : A[i] > pivot\}$

What if the *pivot* is chosen so that:

- 1. L > n/10
- 2. H > n/10

 $k = \min(|L|, |H|)$

QuickSort with interesting *pivot* choice:



Cost of QuickSort on *n* elements

Tempting solution:

$$T(n) = T(n-k) + T(k) + n$$

 $< T(9n/10) + T(9n/10) + n$
 $< 2T(9n/10) + n$
 $< O(n \log n)$

What is wrong?

Tempting solution:

$$T(n) = T(n-k) + T(k) + n$$

$$< T(9n/10) + T(9n/10) + n$$

$$< 2T(9n/10) + n$$

$$< O(n \log n)$$

$$= O(n^{6.58})$$

Too loose an estimate. We didnt solve the last line properly.

Tempting solution:

$$T(n) = T(n-k) + T(k) + n$$

$$< T(9n/10) + T(9n/10) + n$$

$$< 2T(9n/10) + n$$

$$< O(n \log n)$$

$$= O(n^{6.58})$$

Intuition: Making 2 calls to problem sizes 9/10n leads to more work than O(nlog n)

QuickSort Pivot Choice

Define sets *L* (low) and *H* (high):

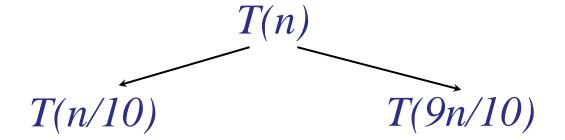
- $L = \{A[i] : A[i] < pivot\}$
- $H = \{A[i] : A[i] > pivot\}$

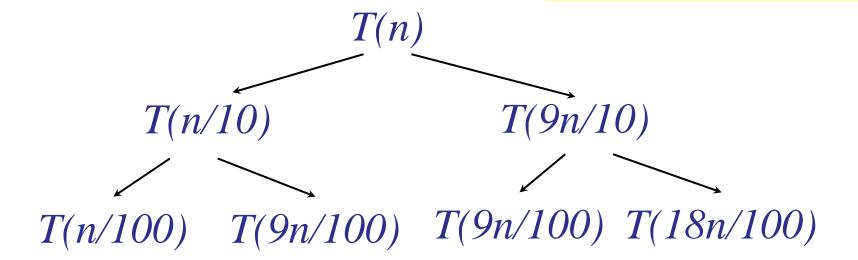
What if the *pivot* is chosen so that:

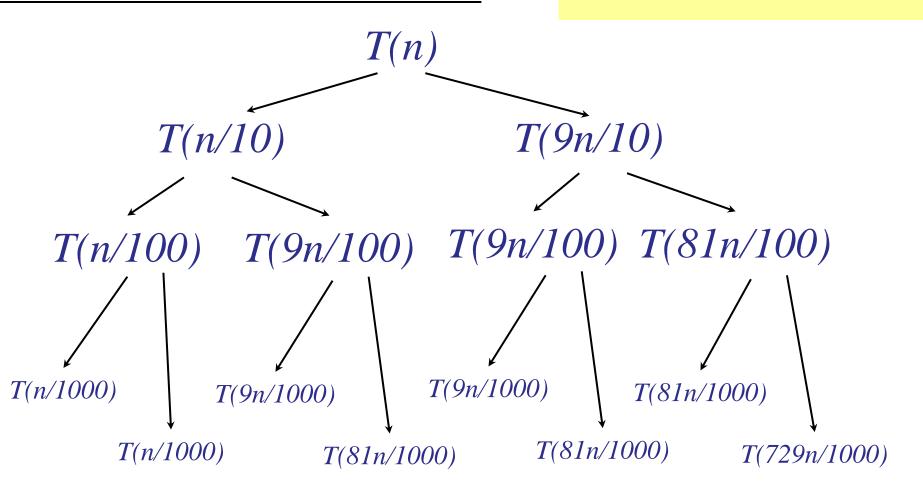
- 1. L = n(1/10)
- 2. H = n(9/10) (or *vice versa*)

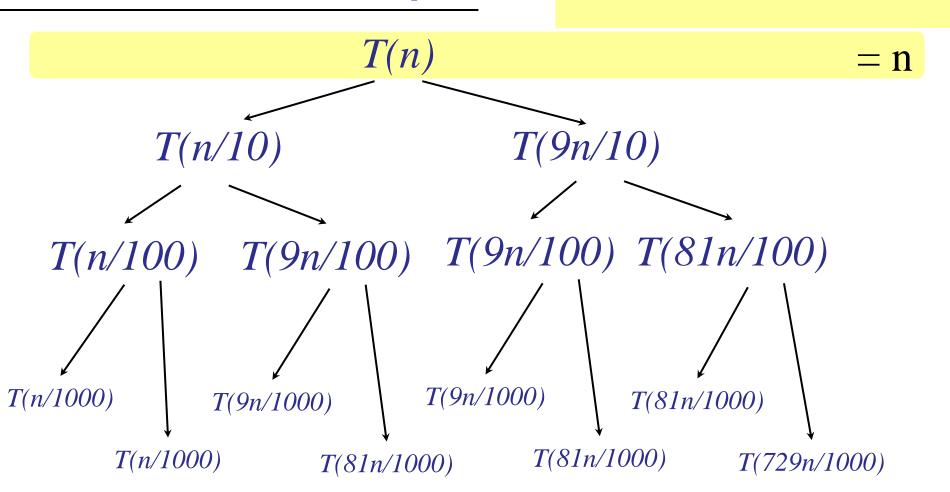
k = n/10

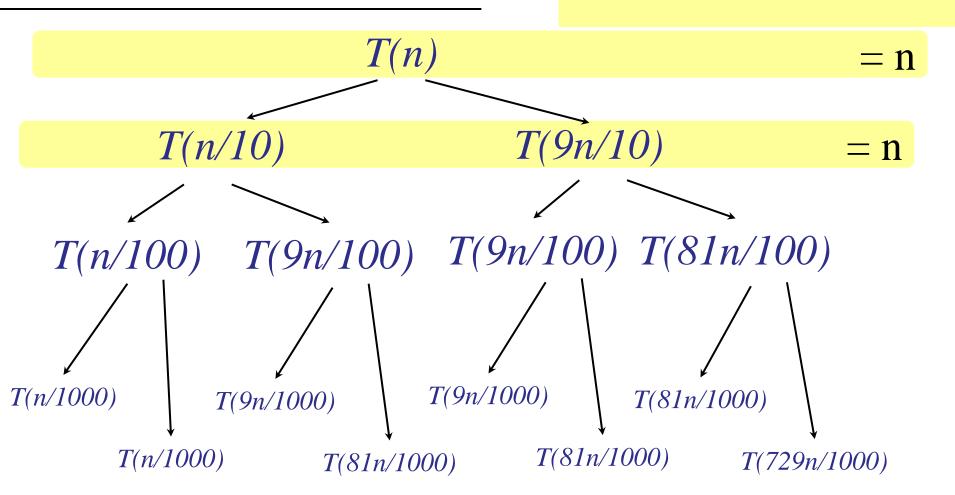
T(n)



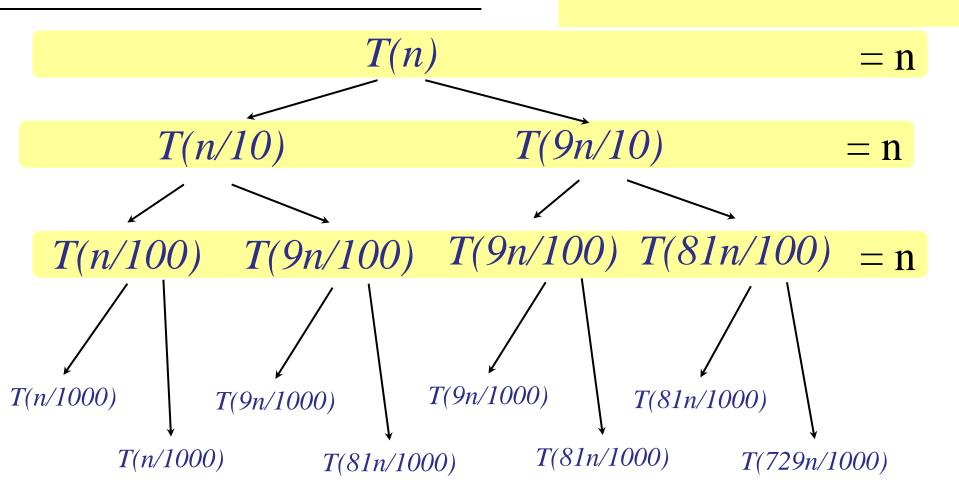




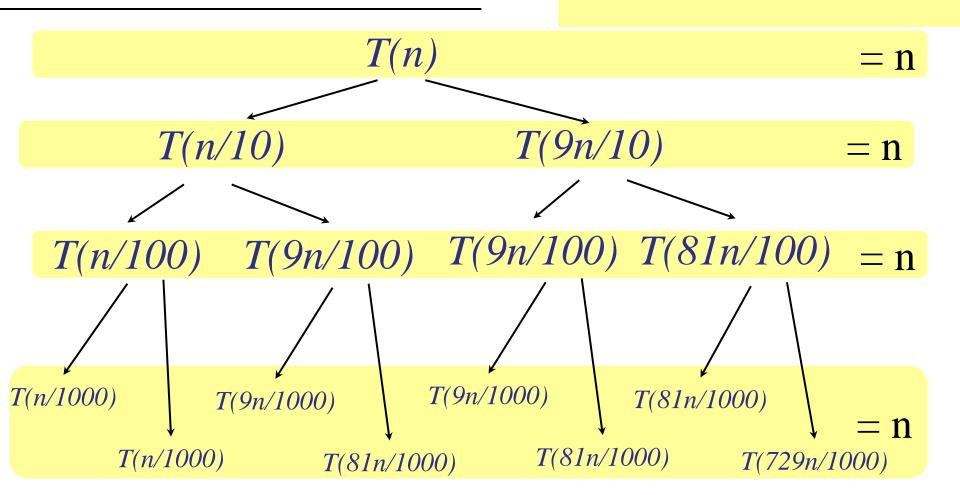




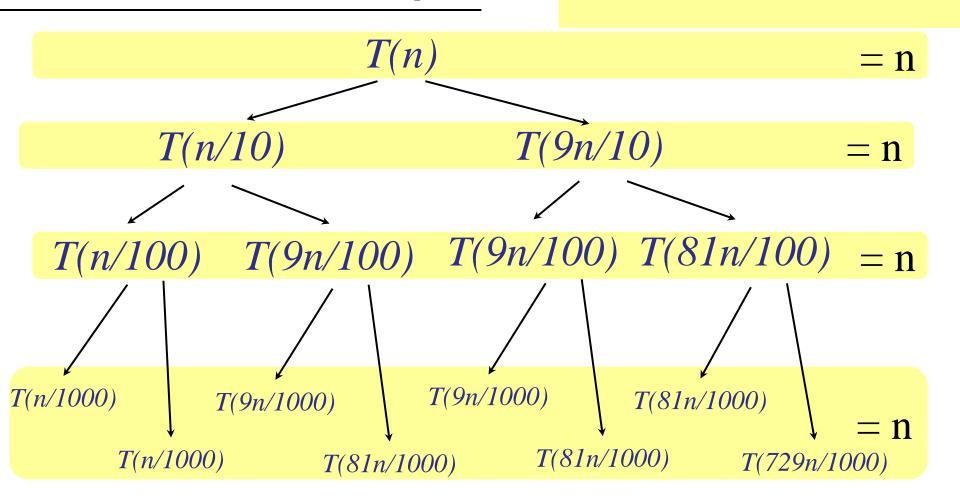
k = n/10



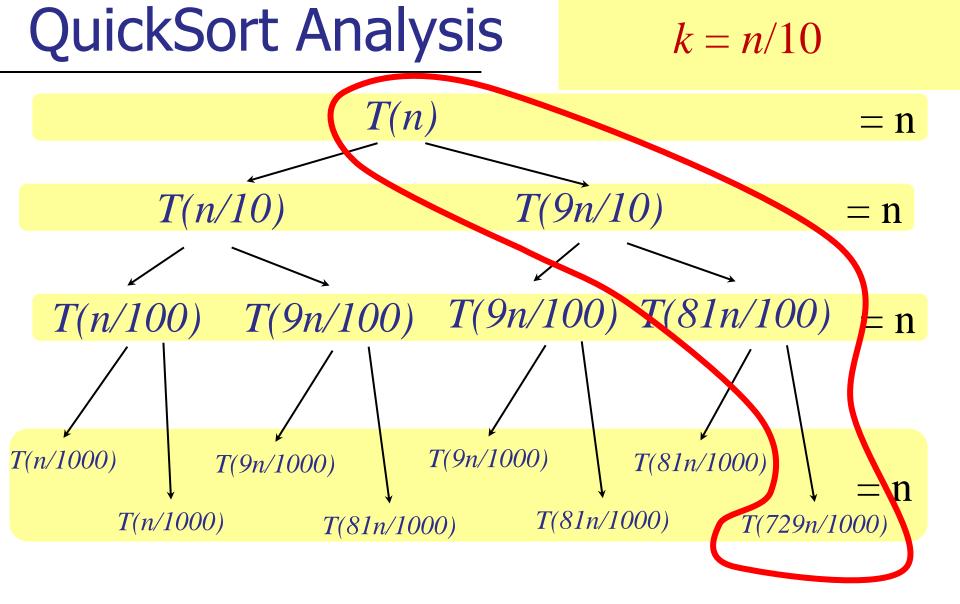
k = n/10



k = n/10



How many levels??



How many levels??

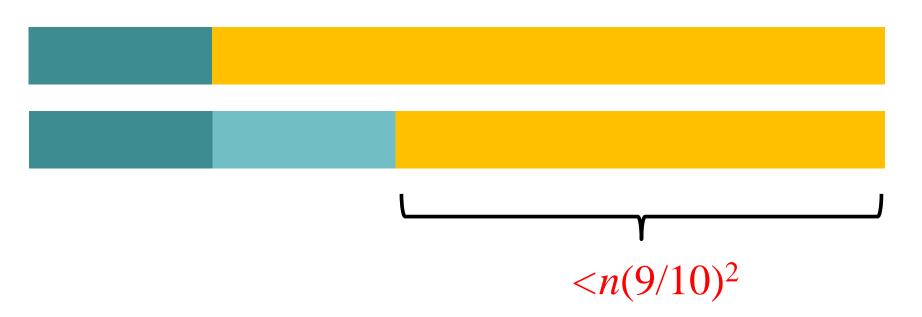
Maximum number of levels:

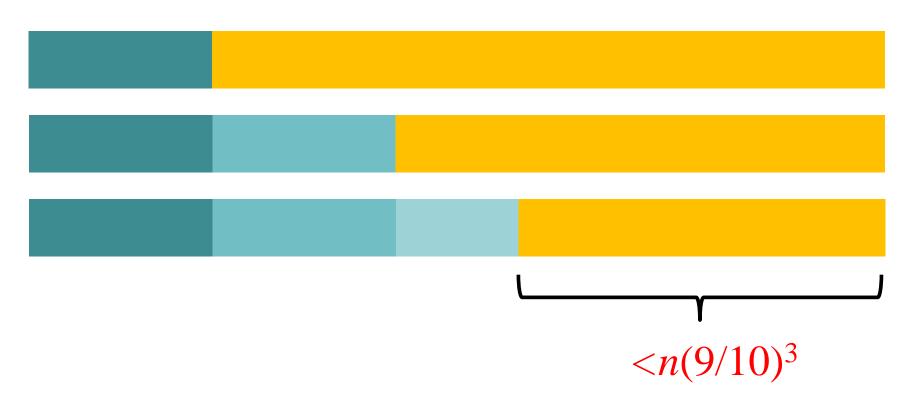
$$1 = n(9/10)^h$$

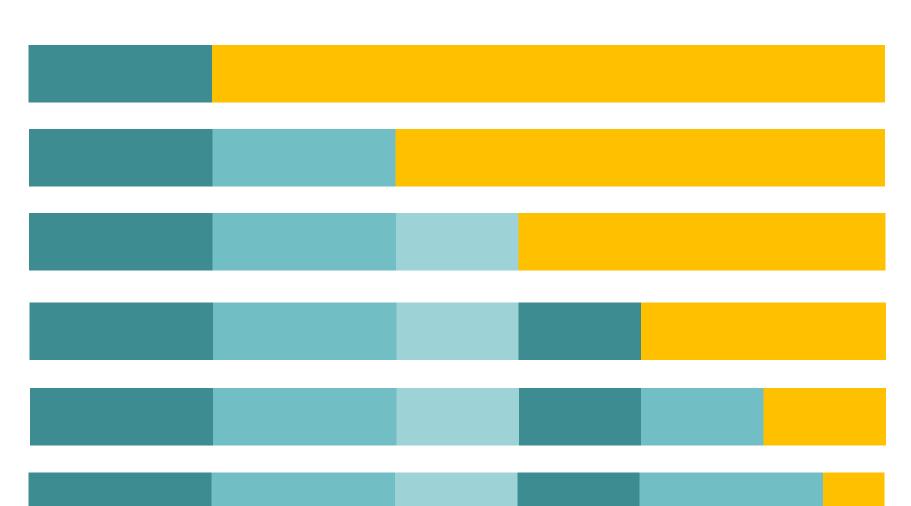
$$(10/9)^h = n$$

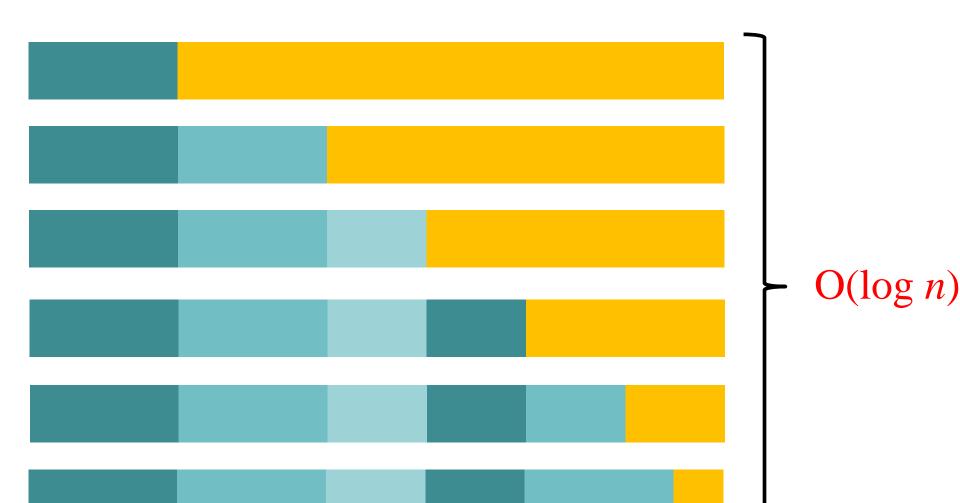
$$h = \log_{10/9}(n) = O(\log n)$$

```
<n(9/10)
```









QuickSort Summary

- If we choose the pivot as A[1]:
 - Bad performance: $\Omega(n^2)$

- If we could choose the median element:
 - Good performance: $O(n \log n)$

- If we could split the array (1/10): (9/10)
 - Good performance: $O(n \log n)$

QuickSort

```
QuickSort(A[1..n], n)
    if (n==1) then return;
    else
          Choose pivot index pIndex.
          p = partition(A[1..n], n, pIndex)
          x = \text{QuickSort}(A[1..p-1], p-1)
          y = QuickSort(A[p+1..n], n-p)
```

QuickSort

Key Idea:

Choose the pivot at random.

Randomized Algorithms:

- Algorithm makes decision based on random coin flips.
- Can "fool" the adversary (who provides bad input)
- Running time is a random variable.

Randomization

What is the difference between:

- Randomized algorithms
- Average-case analysis

Randomization

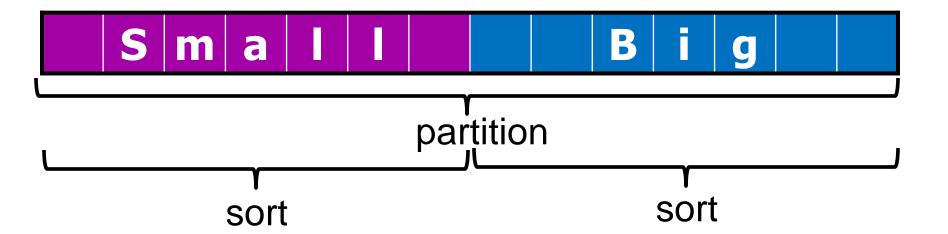
Randomized algorithm:

- Algorithm makes random choices
- For every input, there is a good probability of success.

Average-case analysis:

- Algorithm (may be) deterministic
- "Environment" chooses random input
- Some inputs are good, some inputs are bad
- For most inputs, the algorithm succeeds

```
QuickSort(A[1..n], n)
    if (n == 1) then return;
    else
     pIndex = random(1, n)
     p = 3WayPartition(A[1..n], n, pindex)
     x = QuickSort(A[1..p-1], p-1)
     y = QuickSort(A[p+1..n], n-p)
```



```
ParanoidQuickSort(A[1..n], n)
    if (n == 1) then return;
    else
         repeat
               pIndex = random(1, n)
               p = partition(A[1..n], n, pIndex)
         until p > (1/10)n and p < (9/10)n
         x = QuickSort(A[1..p-1], p-1)
         y = QuickSort(A[p+1..n], n-p)
```

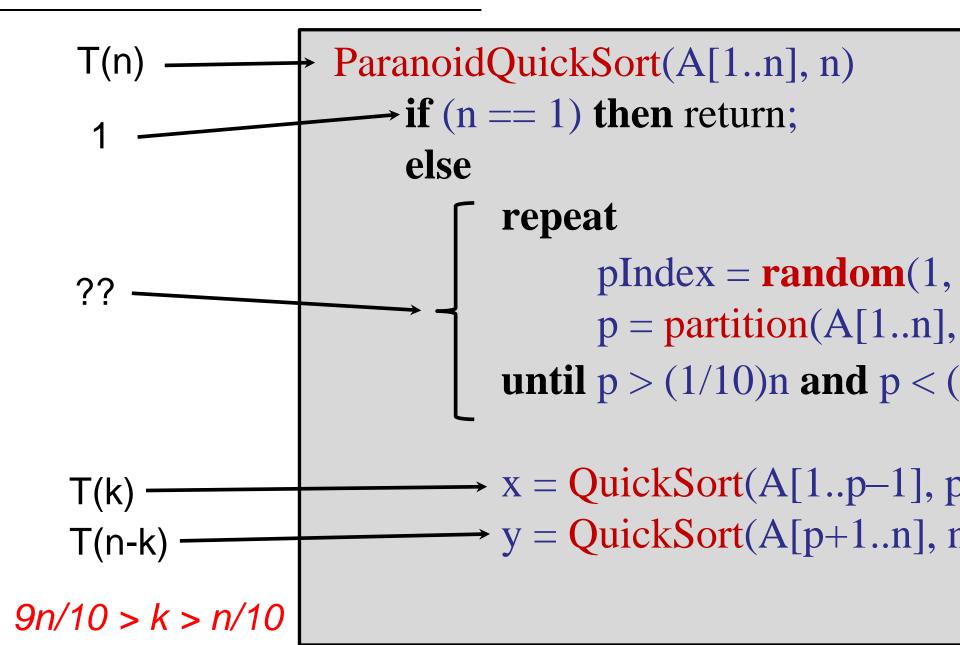
Easier to analyze:

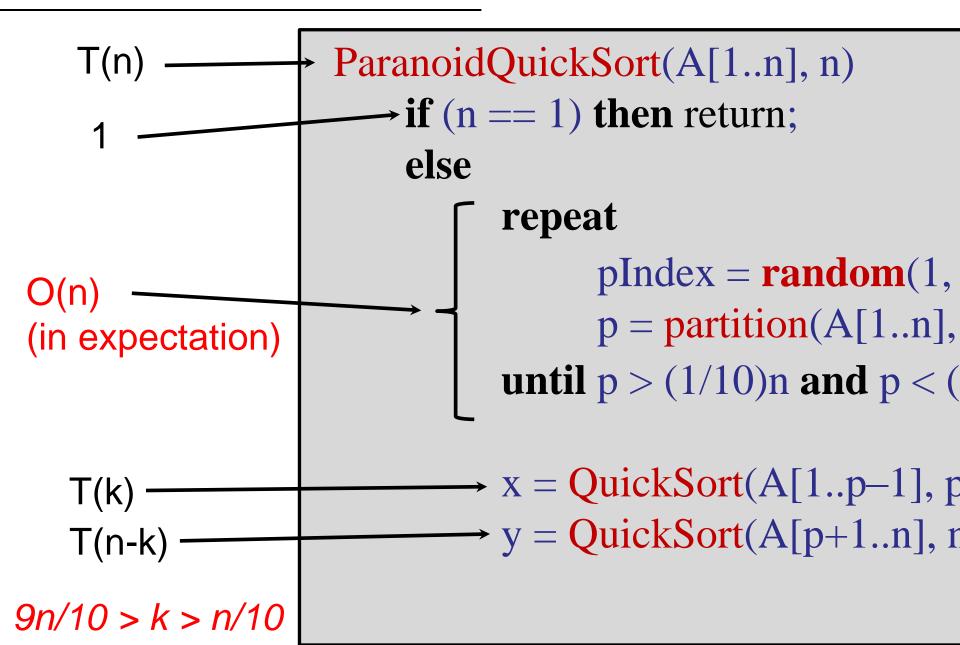
- Every time we recurse, we reduce the problem size by at least (1/10).
- We have already analyzed that recurrence!

Note: non-paranoid QuickSort works too

Analysis is a little trickier (but not much).

```
ParanoidQuickSort(A[1..n], n)
    if (n == 1) then return;
    else
         repeat
               pIndex = random(1, n)
               p = partition(A[1..n], n, pIndex)
         until p > (1/10)n and p < (9/10)
         x = QuickSort(A[1..p-1], p-1)
         y = QuickSort(A[p+1..n], n-p)
```



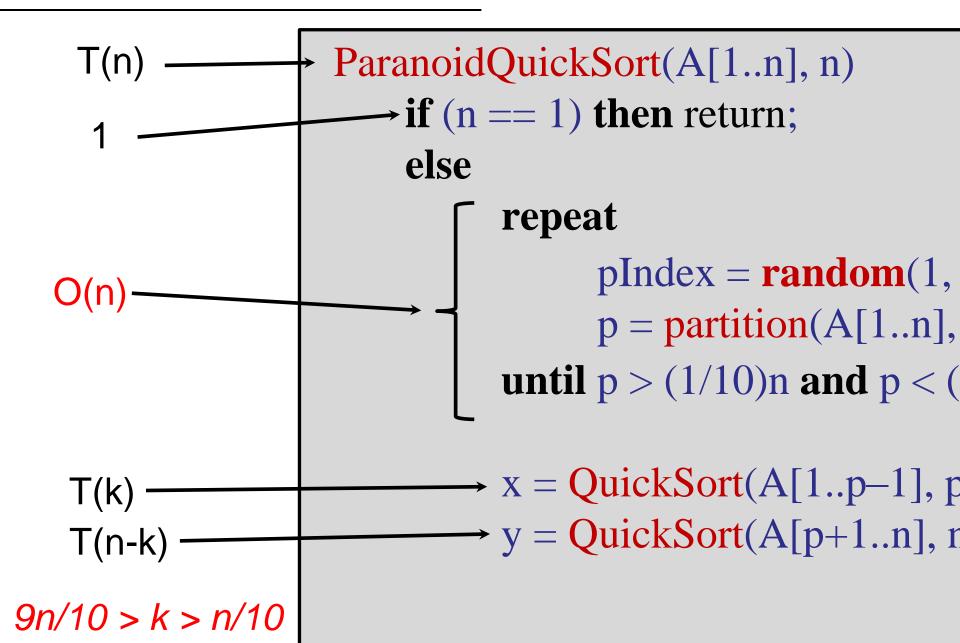


Key claim:

 We only execute the repeat loop O(1) times (in expectation).

Then we know:

```
T(n) \le T(n/10) + T(9n/10) + n(\# iterations of repeat)
= O(n \log n)
```



Summary

QuickSort:

- Divide-and-Conquer
- Partitioning
- Duplicates
- Choosing a pivot
- Randomization

Next Week:

- Probability Theory
- Randomized Analysis
- Ordered Statistics