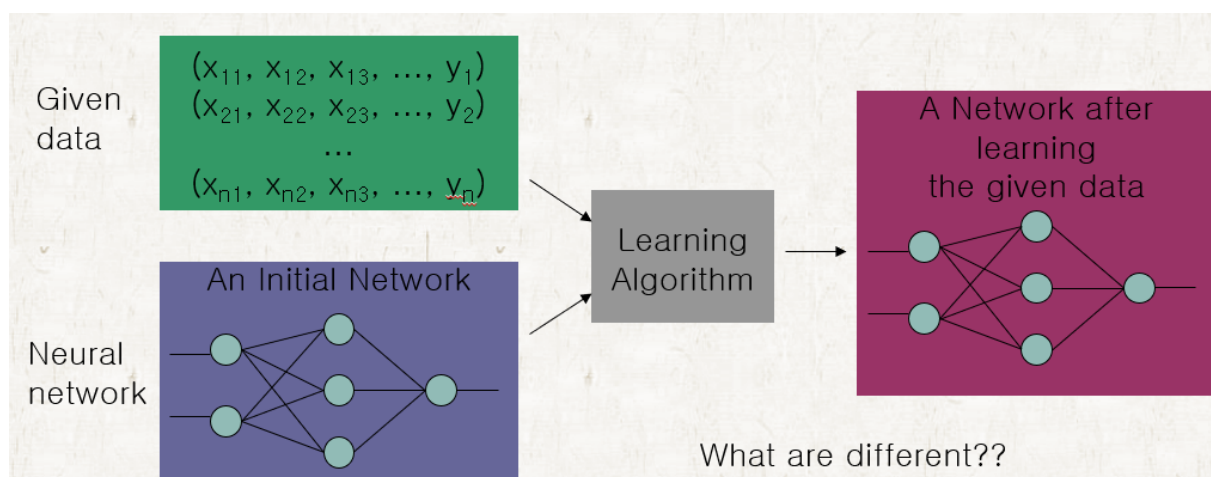


Neural Networks-Learning Algorithm(Back Propagation)

Learning Algorithm(1)

Preparation for Learning

- Given input -output data of the target function to learn
- Given structure of network(#of nodes in hidden layers)
- **Randomly initialized weights**



학습할때마다 w값은 다르다!!

Learning Algorithm(2)

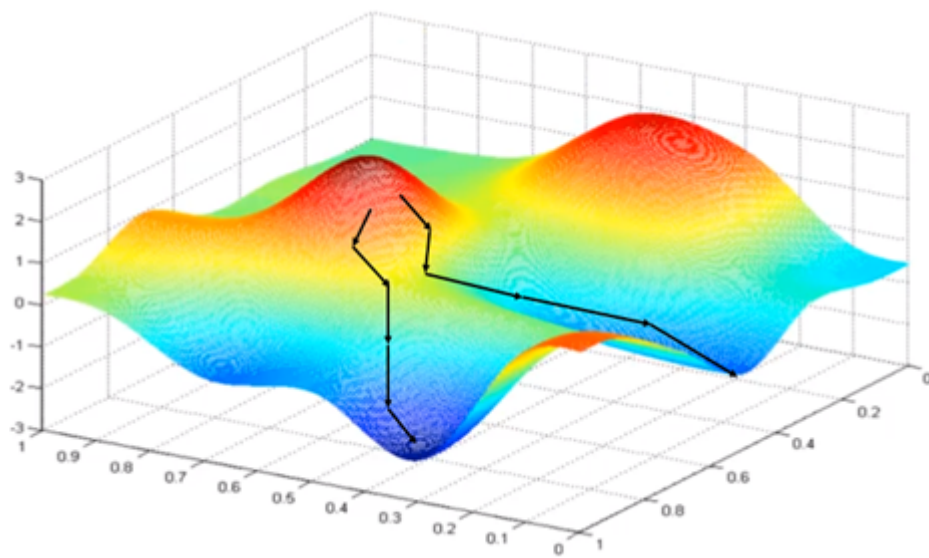
Basic Idea of Learning

- Find weights $w=(w_1, w_2, \dots, w_n)$ so that
 $NN(w, t)=t$ for all (x, t)
- Find weights $w=(w_1, w_2, \dots, w_n)$ which minimize Error function

$$E(\mathbf{w}) = \sum_{(x,t) \in \text{Data}} (t - NN(\mathbf{w}, x))^2 \quad \mathbf{w} = (w_1, w_2, \dots, w_n)$$

Learning Algorithm(3)

Learning with Gradient Descend Method



Randomly choose an initial solution, w_0^0, w_1^0

Repeat

$$w_0^{t+1} = w_0^t - \eta \left. \frac{\partial E}{\partial w_0} \right|_{w_0=w_0^t, w_1=w_1^t}$$

$$w_1^{t+1} = w_1^t - \eta \left. \frac{\partial E}{\partial w_1} \right|_{w_0=w_0^t, w_1=w_1^t}$$

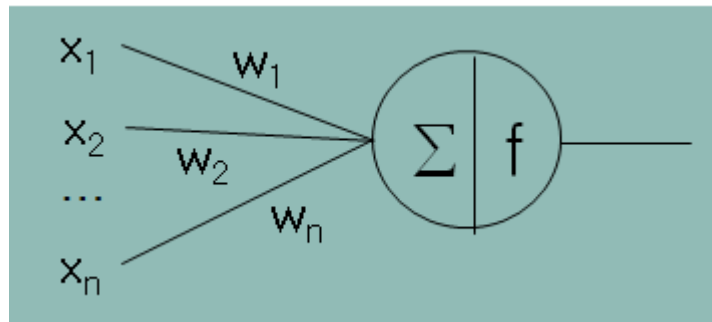
Until stopping condition is satisfied

#Gradient descent method는 추가적으로 다룰 예정

Error Back Propagation(1)

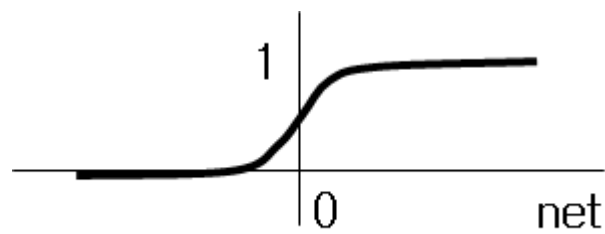
Error Back Propagation

- ANN learning algorithm based on gradient descent method
- Using derivatives to change the weights so that the error is minimized
- Hard limit(step function) is not differentiable → Sigmoid

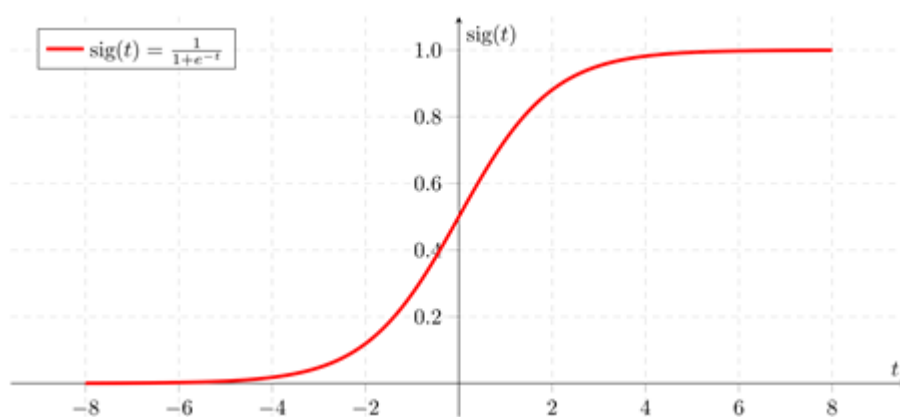


Gradient descent method를 사용하여 w 값을 update하는건데 미분해서 0이 나오면 update의 의미가 없다.

$$\text{net} = x_1w_1 + x_2w_2 + x_3w_3 + \dots + x_nw_n$$



Sigmoid function



$$\begin{aligned}
 y' &= \left(\frac{1}{1 + e^{-x}} \right)^2 e^{-x} \\
 &= \left(\frac{1}{1 + e^{-x}} \right) \left(\frac{e^{-x}}{1 + e^{-x}} \right) \\
 &= \left(\frac{1}{1 + e^{-x}} \right) \left(\frac{1 + e^{-x} - 1}{1 + e^{-x}} \right) \\
 &= \left(\frac{1}{1 + e^{-x}} \right) \left(1 - \frac{1}{1 + e^{-x}} \right) \\
 &= y(1 - y)
 \end{aligned}$$

Error Back Propagation(3)

Basic Idea

- Given input-target pairs and output of NN

$$\begin{aligned}
 D_1 &= (x_{11}, x_{12}, \dots, x_{1d}, t_{11}, t_{12}, \dots, t_{1m}) \\
 D_2 &= (x_{21}, x_{22}, \dots, x_{2d}, t_{21}, t_{22}, \dots, t_{2m}) \\
 &\vdots \\
 D_N &= (x_{N1}, x_{N2}, \dots, x_{Nd}, t_{N1}, t_{N2}, \dots, t_{Nm})
 \end{aligned}$$

$$\begin{aligned}
 &(o_{11}, o_{12}, \dots, o_{1m}) \\
 &(o_{21}, o_{22}, \dots, o_{2m}) \\
 &\vdots \\
 &(o_{N1}, o_{N2}, \dots, o_{Nm})
 \end{aligned}$$

$\underbrace{\hspace{10em}}$
 inputs

$\underbrace{\hspace{10em}}$
 targets

$\underbrace{\hspace{10em}}$
 Outputs of NN

- Minimize the error

$$E(\mathbf{w}) = \sum_{n=1}^N E_n(\mathbf{w}) \quad \text{where} \quad E_n(\mathbf{w}) = \frac{1}{2} \sum_{k=1}^m (t_{nk} - o_{nk})^2$$

Error func에있는 아래첨자 n 은 데이터개수다.

- Remember

$$\frac{\partial E}{\partial w} = \frac{\partial}{\partial w} \sum_{d=1}^N E_d = \sum_{d=1}^N \frac{\partial}{\partial w} E_d$$

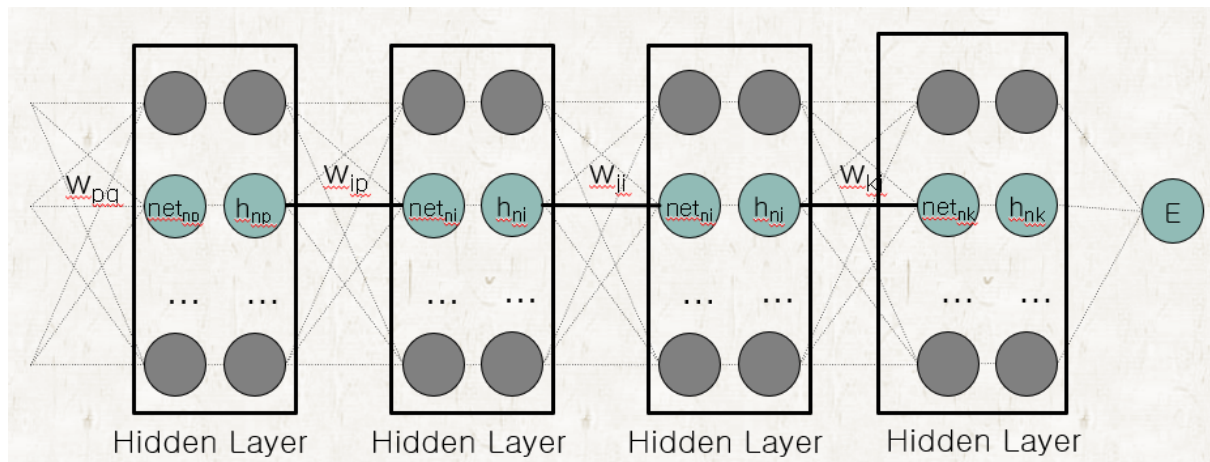
- So, we need to evaluate :

$$\frac{\partial}{\partial w} E_d$$

Algorithm(1)

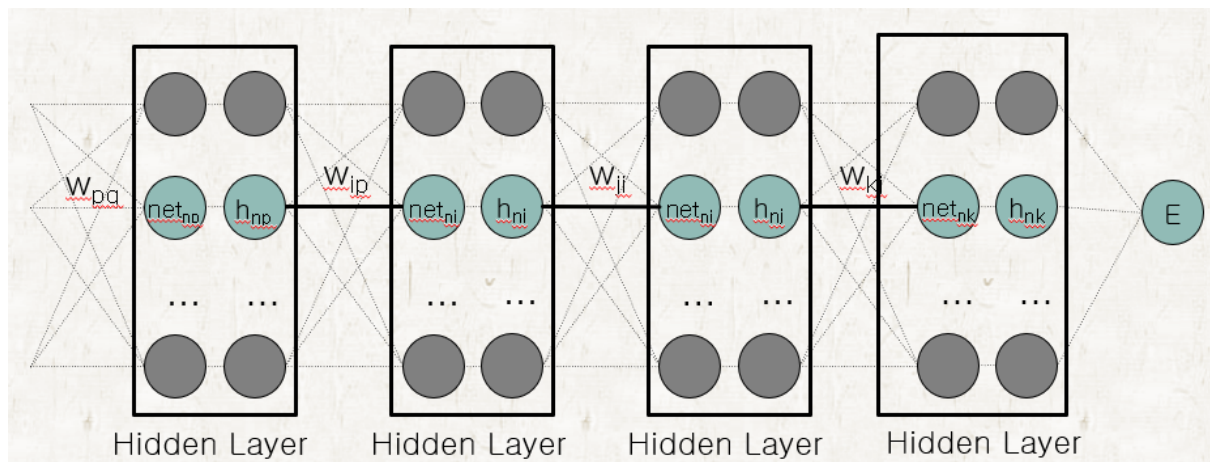
Weights between deep layers

- For $D_n=(x_{n1},x_{n2},\dots,x_{nd},t_{n1},t_{n2},\dots,t_{nm})$



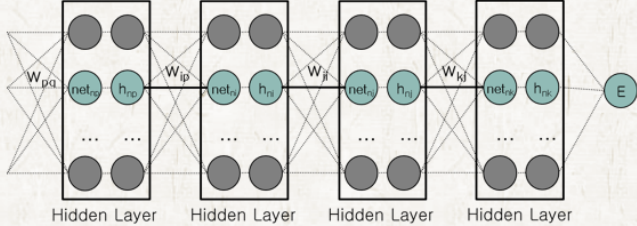
Algorithm(2)

Weights between deep layers



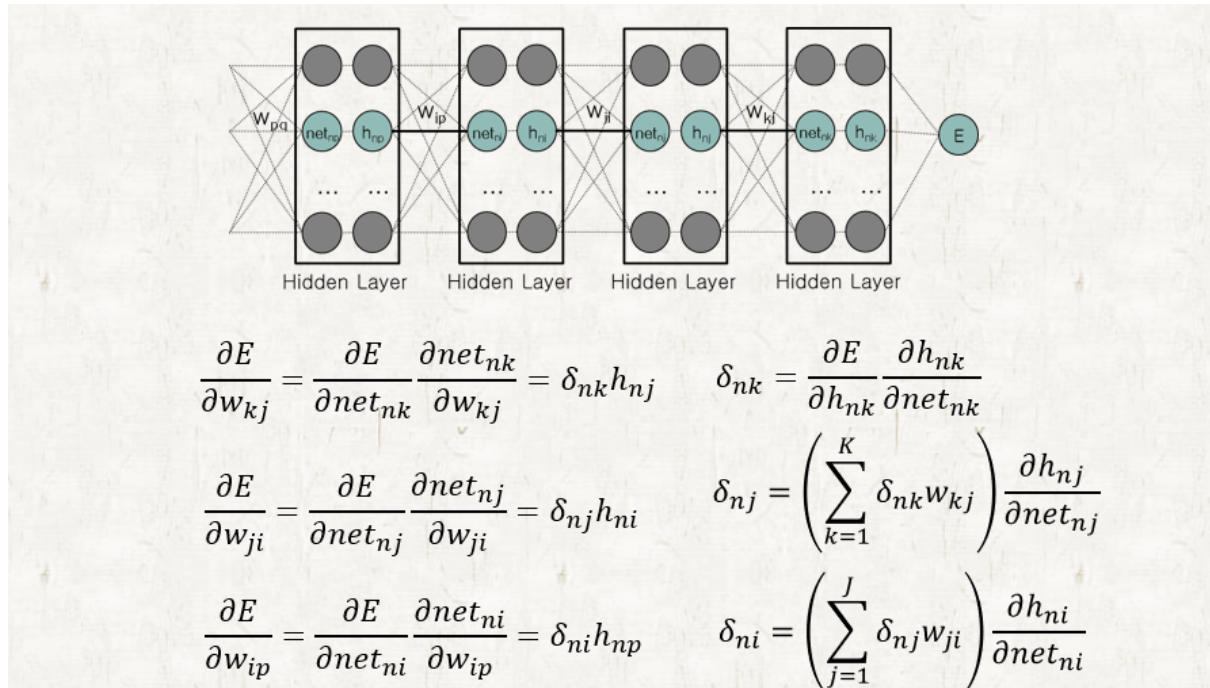
$$\begin{aligned}\frac{\partial E}{\partial w_{kj}} &= \frac{\partial E}{\partial net_{nk}} \frac{\partial net_{nk}}{\partial w_{kj}} = \delta_{nk} h_{nj} & \delta_{nk} &= \frac{\partial E}{\partial net_{nk}} \\ \frac{\partial E}{\partial w_{ji}} &= \frac{\partial E}{\partial net_{nj}} \frac{\partial net_{nj}}{\partial w_{ji}} = \delta_{nj} h_{ni} & \delta_{nj} &= \frac{\partial E}{\partial net_{nj}} \\ \frac{\partial E}{\partial w_{ip}} &= \frac{\partial E}{\partial net_{ni}} \frac{\partial net_{ni}}{\partial w_{ip}} = \delta_{ni} h_{np} & \delta_{ni} &= \frac{\partial E}{\partial net_{ni}}\end{aligned}$$

Algorithm(3)

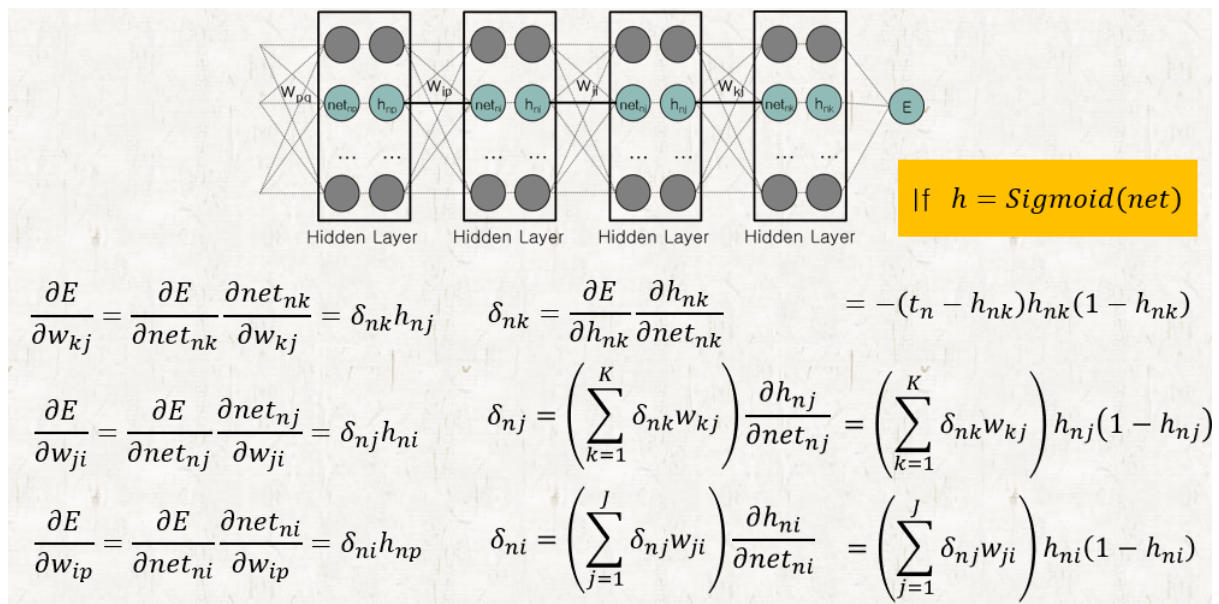


$$\begin{aligned}\delta_{nk} &= \frac{\partial E}{\partial net_{nk}} = \frac{\partial E}{\partial h_{nk}} \frac{\partial h_{nk}}{\partial net_{nk}} & \delta_{nj} &= \frac{\partial E}{\partial net_{nj}} = \frac{\partial E}{\partial h_{nj}} \frac{\partial h_{nj}}{\partial net_{nj}} & \delta_{ni} &= \frac{\partial E}{\partial net_{ni}} = \frac{\partial E}{\partial h_{ni}} \frac{\partial h_{ni}}{\partial net_{ni}} \\ & & &= \left(\sum_{k=1}^K \frac{\partial E}{\partial net_{nk}} \frac{\partial net_{nk}}{\partial h_{nj}} \right) \frac{\partial h_{nj}}{\partial net_{nj}} & &= \left(\sum_{j=1}^J \frac{\partial E}{\partial net_{nj}} \frac{\partial net_{nj}}{\partial h_{ni}} \right) \frac{\partial h_{ni}}{\partial net_{ni}} \\ & & &= \left(\sum_{k=1}^K \delta_{nk} w_{kj} \right) \frac{\partial h_{nj}}{\partial net_{nj}} & &= \left(\sum_{j=1}^J \delta_{nj} w_{ji} \right) \frac{\partial h_{ni}}{\partial net_{ni}}\end{aligned}$$

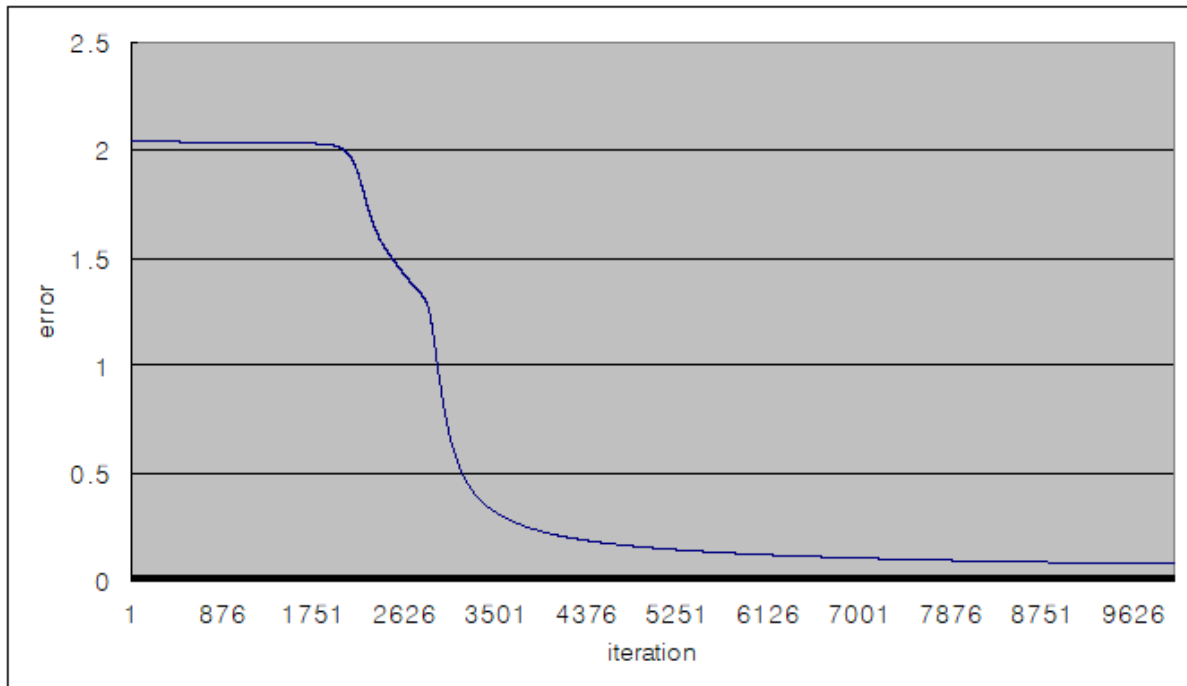
Algorithm(4)



Algorithm(5)



Example of Error Back Propagation



Neural Network의 사용목적

>unknown data를 잘 맞추기 위해서

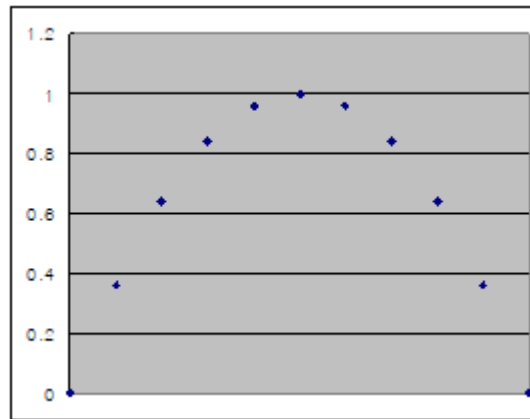
Error가 작다고 무조건 좋은게 아니다(:'overfitting)

overfitting이란? 말그대로 오버피팅 너무 과하게 training data를 학습한것—>training data의 노이즈 까지 학습하는경우

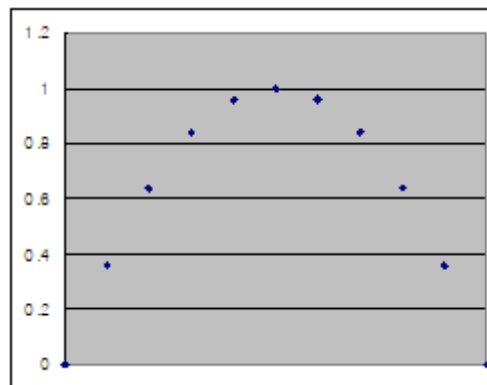
Neural Network의 사용목적은 unknown data를 잘 맞추기 위해서였다. 즉, training data의 패턴을 잘 학습해야 가능하다. —>Generalization

NN은 unknown data를 어떻게 맞추나?

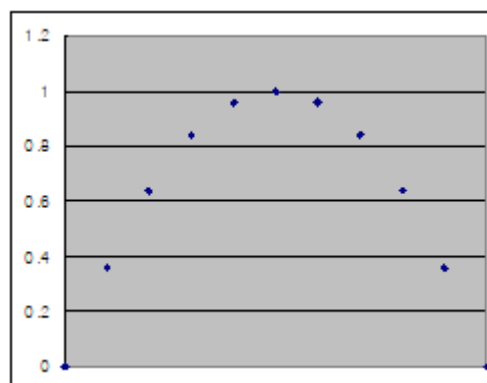
>> interpolation을 통해(non-linear)



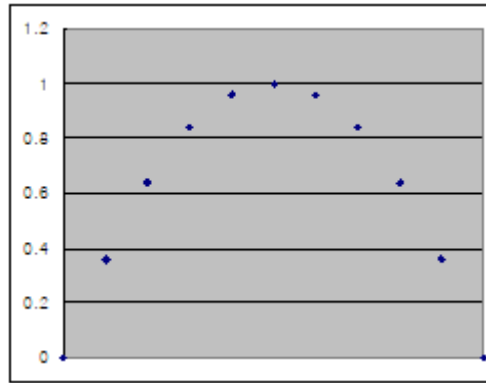
이것은 Training data



1번



2번



Which one is better??

1번이 좋다@@

3번은 overfitting

Generalization and Overfitting

1. Find the optimal number of neurons
2. Find the optimal number of training iterations
3. Use regularization
4. Use more training data>>현실적으로 문제를 해결할 정도로 많은 data를 모으기는 힘들다.