view_frames Result Recorded at time: 1500209392.192 base_link Broadcaster: /my_tf_broadcaster Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1500209392.171 (0.021 sec old) Most recent transform: 1500209392.106 (0.086 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec kinect shoulder_preroll Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1500209392.171 (0.021 sec old) Buffer length: 4.900 sec shoulder Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1500209392.171 (0.021 sec old) Buffer length: 4.900 sec upperarm_preroll Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1500209392.171 (0.021 sec old) Buffer length: 4.900 sec upperarm Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1500209392.171 (0.021 sec old) Buffer length: 4.900 sec lowerarm_preroll Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1500209392.171 (0.021 sec old) Buffer length: 4.900 sec lowerarm Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1500209392.171 (0.021 sec old)

wrist

Buffer length: 4.900 sec