Recorded at time: 1500041709.397 base_link Broadcaster: /moveit/robot_state_publisher Broadcaster: /my_tf_broadcaster Average rate: 30.302 Hz Average rate: 10.204 Hz Most recent transform: 1500041709.333 (0.064 sec old) Most recent transform: 1500041709.370 (0.027 sec old) Buffer length: 4.950 sec Buffer length: 4.900 sec shoulder_preroll kinect Broadcaster: /moveit/robot_state_publisher Average rate: 30.302 Hz Most recent transform: 1500041709.370 (0.027 sec old) Buffer length: 4.950 sec shoulder Broadcaster: /moveit/robot_state_publisher Average rate: 30.302 Hz Most recent transform: 1500041709.370 (0.027 sec old) Buffer length: 4.950 sec upperarm_preroll Broadcaster: /moveit/robot_state_publisher Average rate: 30.302 Hz Most recent transform: 1500041709.370 (0.027 sec old) Buffer length: 4.950 sec upperarm Broadcaster: /moveit/robot_state_publisher Average rate: 30.302 Hz Most recent transform: 1500041709.370 (0.027 sec old) Buffer length: 4.950 sec lowerarm_preroll Broadcaster: /moveit/robot_state_publisher Average rate: 30.302 Hz Most recent transform: 1500041709.370 (0.027 sec old) Buffer length: 4.950 sec lowerarm Broadcaster: /moveit/robot_state_publisher Average rate: 30.302 Hz Most recent transform: 1500041709.370 (0.027 sec old) Buffer length: 4.950 sec wrist

view_frames Result