Recorded at time: 1500302912.320 camera_link Broadcaster: /camera_link_broadcaster Average rate: 25.121 Hz Most recent transform: 1500302912.321 (-0.001 sec old) Buffer length: 4.936 sec base_link Broadcaster: /moveit/robot_state_publisher Broadcaster: /gummi/my_tf_broadcaster Average rate: 30.604 Hz Average rate: 10.204 Hz Most recent transform: 1500302912.302 (0.018 sec old) Most recent transform: 1500302912.260 (0.060 sec old) Buffer length: 4.900 sec Buffer length: 4.967 sec shoulder_preroll kinect Broadcaster: /moveit/robot_state_publisher Average rate: 30.604 Hz Most recent transform: 1500302912.302 (0.018 sec old) Buffer length: 4.967 sec shoulder Broadcaster: /moveit/robot_state_publisher Average rate: 30.604 Hz Most recent transform: 1500302912.302 (0.018 sec old) Buffer length: 4.967 sec upperarm_preroll Broadcaster: /moveit/robot_state_publisher Average rate: 30.604 Hz Most recent transform: 1500302912.302 (0.018 sec old) Buffer length: 4.967 sec upperarm Broadcaster: /moveit/robot_state_publisher Average rate: 30.604 Hz Most recent transform: 1500302912.302 (0.018 sec old) Buffer length: 4.967 sec lowerarm_preroll Broadcaster: /moveit/robot_state_publisher Average rate: 30.604 Hz Most recent transform: 1500302912.302 (0.018 sec old) Buffer length: 4.967 sec lowerarm Broadcaster: /moveit/robot_state_publisher Average rate: 30.604 Hz Most recent transform: 1500302912.302 (0.018 sec old) Buffer length: 4.967 sec wrist

view_frames Result