Announcements

P6, H10 assigned

Final exam

Final exam will cover *all* material covered in course – i.e., all compiler phases

Focus will be on after-midterm material

There will be some questions on special topics 100 minutes exam, similar in format to midterm

Optimization Frameworks

Roadmap

Last time:

- Optimization overview
 - Soundness and completeness
- Simple optimizations
 - Peephole
 - LICM

This time:

- More Optimization
- Analysis frameworks

Outline

Review Dominators
Introduce some more advanced concepts

- Static single assignment (SSA)
- Dataflow propagation

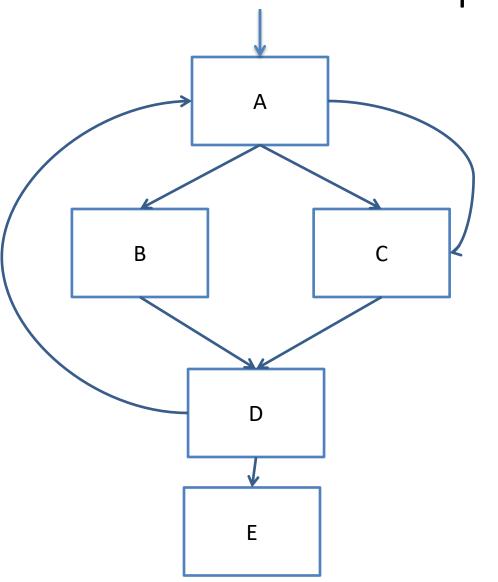
DOMINATOR REVIEW

Dominator terms

Domination (A dominates B):

- to reach block B, you must have gone through block A
 Strict Domination (A strictly dominates B)
- A dominates B and A is not B
 Immediate Domination (A immediately dominates B)
- A immediately dominates B if A dominates B and has no intervening dominators

Dominator example



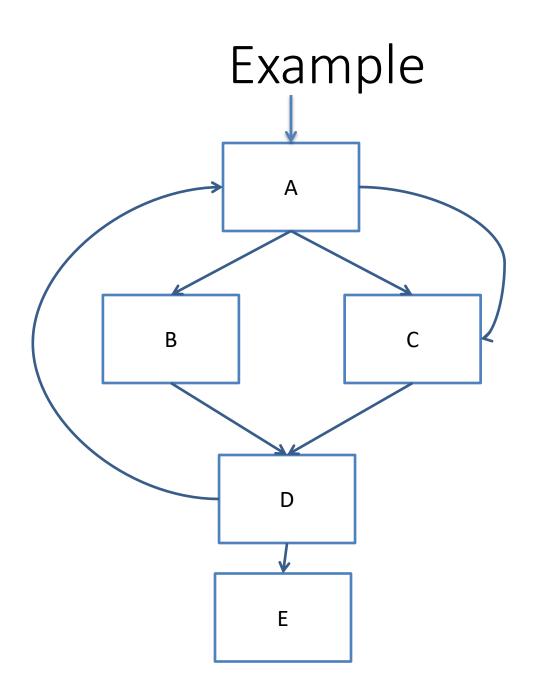
Dominance frontier

Definition:

For a block **x**, the dominance frontier of x is the set of nodes **Y** such that

- x dominates an immediate predecessor of Y
- x does not strictly dominate Y

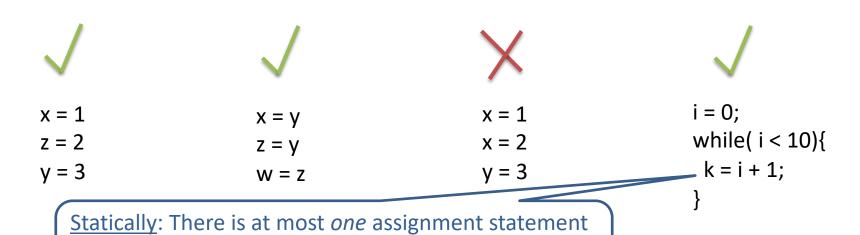




STATIC SINGLE ASSIGNMENT

Goal of SSA Form

Build an intermediate representation of the program in which each variable is assigned a value in at most 1 program point:



that assigns to k

Dynamically: k can be assigned to multiple times

Conversion

We'll make new variables to carry over the effect of the original program



Benefits of SSA Form

There are some obvious advantages to this format for program analysis

- Easy to see the live range of a given variable x assigned to in statement s
 - The region from "x = ...;" until the last use(s) of x before x is redefined
 - In SSA form, from " $x_i = ...$;" to all uses of x_i , e.g., "... = $f(..., x_i, ...)$;"
- Easy to see when an assignment is useless
 - We have "x_i = ...;" and there are no uses of x_i in any expression or assignment RHS
 - "'x_i = ...;' is a useless assignment"
 - "'x_i = ...;' is dead code"

In other words, some deleast easily recorded

information is pre-computed, or at

Warning 1: Dead code = useless assignments + unreachable code

Optim At "if (b < 4)", b is only reached by "b = 2;"
Therefore, the else branch is unreachable (dead), and can be removed

Helps

Dead-Code Elip

```
if (q < 12) {
else (
  if (b < 4) [
  } else {
return 2;
```

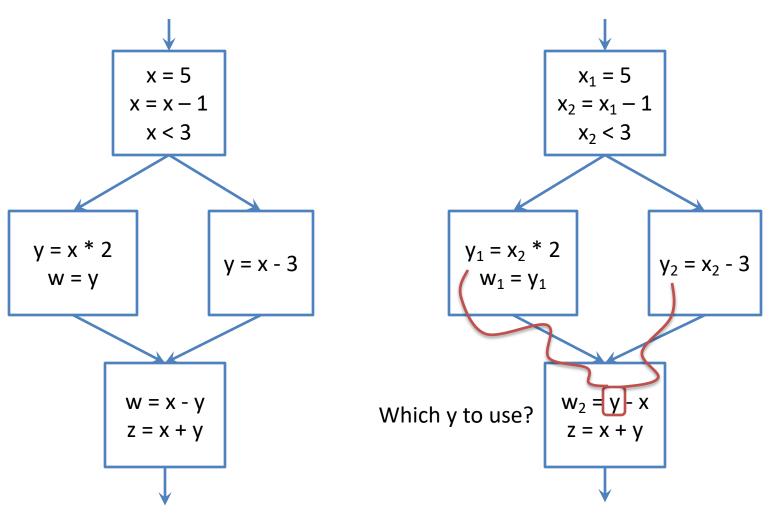
```
int a_1 = 9;
int b_1 = 2;
if (g_1 < 12) {
  a_2 = 1;
} else {
  if (b_1 < 4) {
   a_3 = 2;
  } else {
   a_4 = 3;
  a_5 = \phi (a_3, a_4);
a_6 = \phi(a_2, a_5);
b_2 = a_6;
return 2;
```

Optimizations Where SSA Helps

Constant-propagation/constant-folding

```
int a = 30; 6
int b = 9; (a / 5);
int c;
c = h2; 4; true
if (crue10) {
    c = 2; - 10; 2
}
return 4; 260 4 a);
```

What About Conditionals?



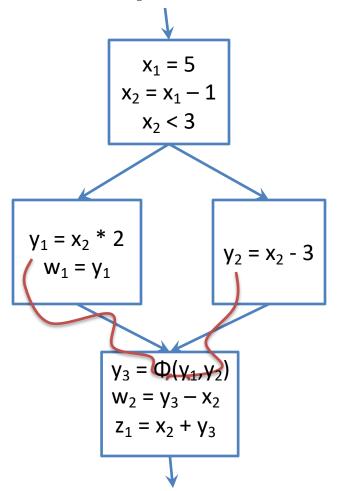
Phi Functions (ϕ)

We introduce a special symbol Φ at such points of confluence

Φ's arguments are all the instances of variable y that might be the most recently assigned variant of y

Returns the "correct" one Do we need a Φ for x?

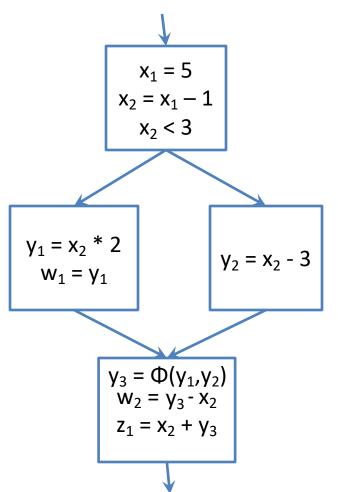
- No!



Computing Phi-Function Placement

Intuitively, we want to figure out cases where there are multiple assignments that can reach a node

To be safe, we can place a Φ function for each assignment at every node in the *dominance frontier*



Pruned Phi Functions

This criterion causes a bunch of useless Φ functions to be inserted

 Cases where the result is never used "downstream" (useless)

Pruned SSA is a version where useless Φ nodes are suppressed

DATAFLOW ANALYSIS

Dataflow framework idea

Many analyses can be formulated as how data is transformed over the control flow graph

Propagate static information from:

- the beginning of a single basic block
- the end of a single basic block
- The join points of multiple basic blocks

Dataflow framework idea

Meet Lattice

Transfer function

 How data is propagated from one end of a basic block to the other

Meet operation

Means of combining lattice between blocks

Dataflow analysis direction

Forward analysis

 Start at the beginning of a function's CFG, work along the control edges

Backwards analysis

 Start at the end of a function's CFG, work against the control edges

Continuously propagate values until there is no change

Reaching definitions <u>Transfer function:</u> $\lambda S.(S - \{ < p_i, x > \}) \cup \{ < p_i, x > \}$ Before p1: Ø After p1: $\{ \langle p1, x \rangle \}$ p1: x = 1; Before p2: {<p1, x>, ...} After p2: {<p2, x>, ...} p2: x = 2; Before p3: $\{ < p2, x >, ... \}$ After p3: $\{ < p2, x >, < p3, y >, ... \}$

<u>Data</u>: sets of cprogram-point, variable> pairs

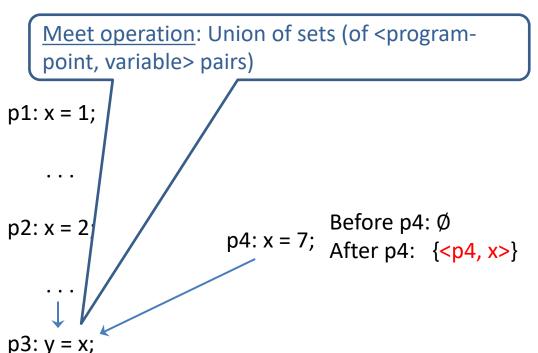
Note: for expository purposes, it is convenient to assume we have a statement-level CFG rather than a basic-block-level CFG.

Reaching definitions

Before p1: Ø After p1: {<p1, x>}

Before p2: {<p1, x>, ...} After p2: {<p2, x>, ...}

Before p3: {<p2, x>, <p4,x>, ...} After p3: {<p2, x>, <p3, y>, <p4,x>,...}



Note: for expository purposes, it is convenient to assume we have a statement-level CFG rather than a basic-block-level CFG.

Reaching definitions: Why is it useful?

Answers the question "Where could this variable have been defined?"

```
Before p1: Ø
After p1: {<p1, x>}

Before p2: {<p1, x>, ...}

After p2: {<p2, x>, <p4,x>, ...}

Before p3: {<p2, x>, <p4,x>, ...}

After p3: {<p2, x>, <p4,x>, ...}

P1: x = 1;

...

p2: x = 2;

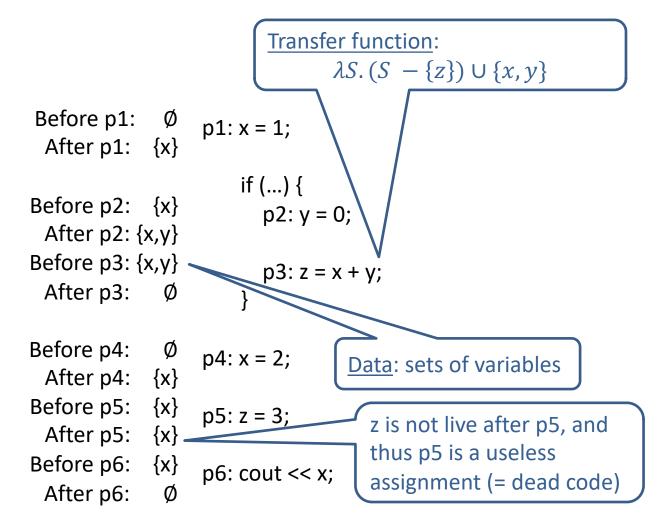
p4: x = 7;

After p4: {<p4, x>}

After p3: {<p2, x>, <p4,x>, ...}

p3: y = x;
```

Live Variables



The end: or is it?

Covered a broad range of topics

- Some formal concepts
- Some practical concepts

What we skipped

- Linking and loading
- Interpreters
- Register allocation
- Performance analysis / Proofs