

Classification: Linear Models

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Some contents adopted from Stanford CS221, Percy Liang.

Road Map

Linear predictors

Learning objective

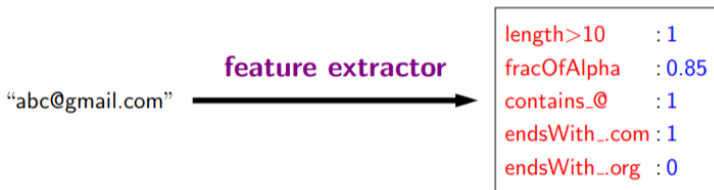
Optimization

Feature Extraction

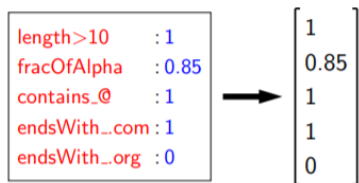
Example task: Predict y , whether a string x is an email address.

Question: What properties of x might be relevant for predicting y ?

Feature extraction: Given input x , produce a set of (feature name, feature value) pairs.



Linear Classifier



For an input x , its **feature vector** is:

$$\phi(x) = [\phi(x)_1, \phi(x)_2, \dots, \phi(x)_D].$$

In practice, we usually use \mathbf{x} to denote the feature vector of input after feature extraction, i.e., $\mathbf{x} = \phi(x)$.

Linear Classifier

length>10	:-1.2
fracOfAlpha	:0.6
contains_@	:3
endsWith_.com	:2.2
endsWith_.org	:1.4
...	

For each feature j , have real number w_j representing contribution of the feature to prediction.

Linear Classifier

length>10	:-1.2	length>10	:1
fracOfAlpha	:0.6	fracOfAlpha	:0.85
contains_@	:3	contains_@	:1
endsWith_.com	:2.2	endsWith_.com	:1
endsWith_.org	:1.4	endsWith_.org	:0

Figure 1: Left: Weight vector \mathbf{w} . Right: Feature vector $\phi(\mathbf{x})$.

Prediction score: The weighted sum of features.

$$\mathbf{w}^T \cdot \mathbf{x} = \sum_j^D \mathbf{w}_j \mathbf{x}_j \quad (1)$$

Example:

$$-1.2(1) + 0.6(0.85) + 3(1) + 2.2(1) + 1.4(0) = 4.51$$

Linear Classifier

Weight vector $\mathbf{w} \in \mathbb{R}^D$.

Feature vector $\mathbf{x} \in \mathbb{R}^D$.

For binary classification, the linear classifier $f_{\mathbf{w}}$ is:

$$f_{\mathbf{w}}(\mathbf{x}) = \text{sign}(\mathbf{w}^T \cdot \mathbf{x}) = \begin{cases} +1, & \text{if } \mathbf{w}^T \cdot \mathbf{x} > 0 \\ -1, & \text{if } \mathbf{w}^T \cdot \mathbf{x} < 0 \\ ?, & \text{if } \mathbf{w}^T \cdot \mathbf{x} = 0 \end{cases} \quad (2)$$

Linear Classifier: Geometric intuition

Example:

$$\mathbf{w} = [2, -1]$$

$$\phi(\mathbf{x}) = \{[2, 0], [0, 2], [2, 4]\}$$

Linear Classifier: Geometric intuition

A binary classifier $f_{\mathbf{w}}$ defines a **hyperplane** with a normal vector \mathbf{w} .

($\mathbb{R}^2 \rightarrow$ the hyperplane is a line; $\mathbb{R}^3 \rightarrow$ the hyperplane is a plane)

Linear Classifier: Geometric intuition

Please note that, the complete definition of a linear classifier is:

$$f_{\mathbf{w}}(\mathbf{x}) = \textit{sign}(\mathbf{w}^T \cdot \mathbf{x} + b), \quad (3)$$

where b is the offset parameter.

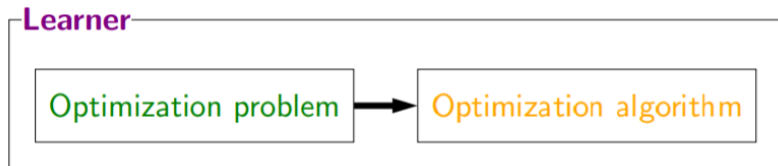
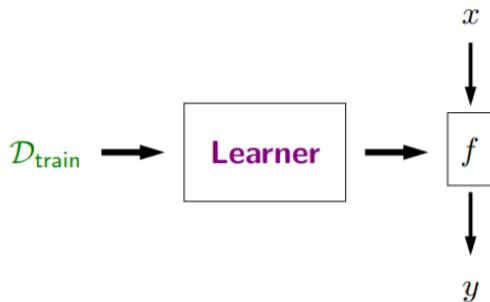
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Linear Classifier: Overall Framework



Linear Classifier: Loss Function

Definition: **Loss function.**

A loss function $L(x, y, \mathbf{w})$ quantifies how *unhappy* you would be if you use \mathbf{w} to make a prediction on x when the correct output is y .

Our goal is to find the best parameters \mathbf{w} that can minimize the loss function.

Linear Classifier: Score and Margin

Predicted label: $y' = f_{\mathbf{w}}(x) = \text{sign}(\mathbf{w}^T \cdot \mathbf{x})$

Ground-truth label: y

Example: $\mathbf{w} = [2, -1]$, $\mathbf{x} = [2, 0]$, $y = -1$

Definition: **Prediction score**.

The prediction score on an example (x, y) is $\mathbf{w}^T \cdot \mathbf{x}$, i.e., how confident we are in prediction.

Definition: **Margin**.

The margin on an example (x, y) is $(\mathbf{w}^T \cdot \mathbf{x})y$, i.e., how correct we are.

Linear Classifier: Score and Margin

When does a binary classifier mis-classify an example?

margin less than 0

margin greater than 0

score less than 0

score greater than 0

Linear Classifier: Loss function

Definition: **Zero-One loss**.

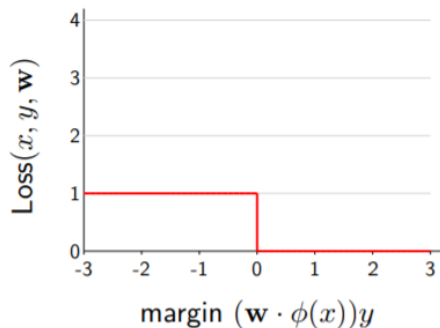
$$L_{0-1}(x, y, \mathbf{w}) = \mathbb{1}[y' \neq y] \quad (4)$$

$$= \mathbb{1}[f_{\mathbf{w}}(x) \neq y] \quad (5)$$

$$= \mathbb{1}[(\mathbf{w}^T \cdot \mathbf{x})y \leq 0] \quad (6)$$

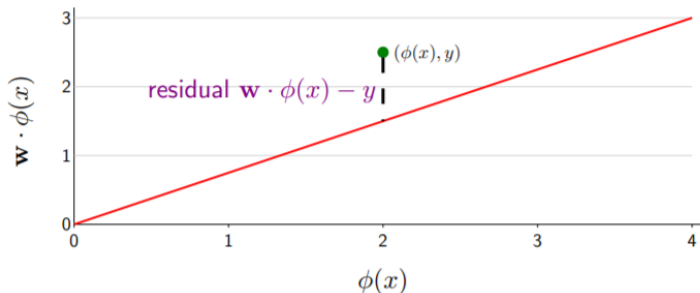
Here $\mathbb{1}$ is the indicator function, where $\mathbb{1}[True] = 1$ and $\mathbb{1}[False] = 0$.

Linear Classifier: Loss function



$$L_{0-1}(x, y, \mathbf{w}) = \mathbb{1}[(\mathbf{w}^T \cdot \mathbf{x})y \leq 0]$$

Linear Classifier \rightarrow Linear Regression



Definition: **Residual**.

The residual is $(\mathbf{w}^\top \cdot \mathbf{x}) - y$, the amount by which prediction $f_{\mathbf{w}}(\mathbf{x}) = \mathbf{w}^\top \cdot \mathbf{x}$ deviates from the target y .

- Define classification errors as regression errors.

Linear Regression: Squared loss

Definition: **Squared loss**.

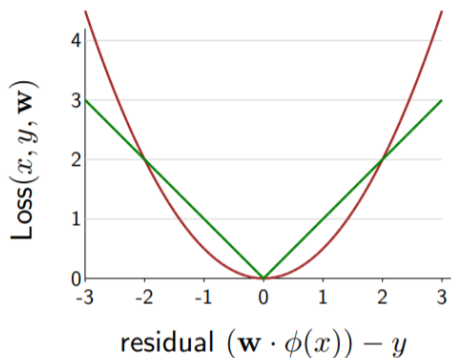
$$L_{\text{quared}}(x, y, \mathbf{w}) = (y' - y)^2 \quad (7)$$

$$= (\mathbf{w}^T \cdot \mathbf{x} - y)^2 \quad (8)$$

Example: $\mathbf{w} = [2, -1]$, $\mathbf{x} = [2, 0]$, $y = -1$

$L_{\text{quared}}(x, y, \mathbf{w}) = ?$

Linear Regression: Losses



$$L_{\text{squared}}(x, y, \mathbf{w}) = (\mathbf{w}^T \cdot \mathbf{x} - y)^2 \times \frac{1}{2}$$

$$L_{\text{absdev}}(x, y, \mathbf{w}) = |\mathbf{w}^T \cdot \mathbf{x} - y|$$

Loss Minimization

So far: for one instance, $L(x, y, \mathbf{w})$ is easy to minimize.

How to set \mathbf{w} to make *global* trade-offs?

- Not every instance can be happy.
- Try to make more instances happy.

Definition: **Training loss**.

$$L_{train}(\mathcal{D}_{train}, \mathbf{w}) = \frac{1}{|\mathcal{D}_{train}|} \sum_{(x,y) \in \mathcal{D}_{train}} L(x, y, \mathbf{w}) \quad (9)$$

The learning objective:

$$\min_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w}) \quad (10)$$

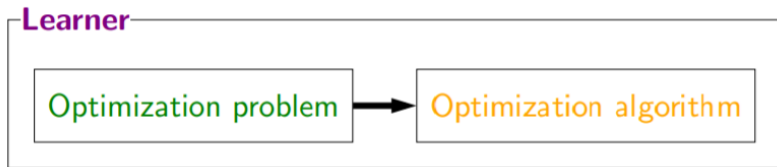
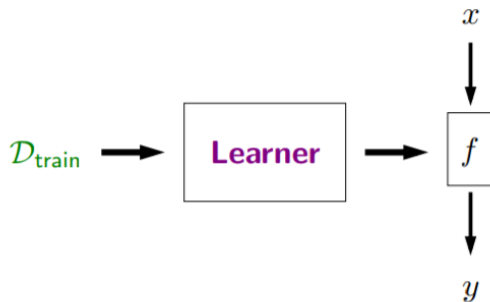
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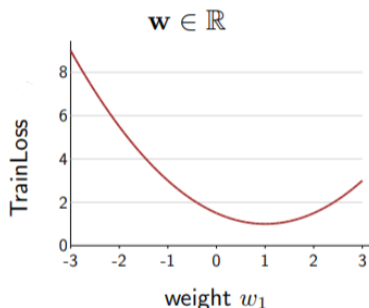
Linear Classifier: Optimization



Linear Classifier: Optimization

The learning objective:

$$\min_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w})$$



$$\mathbf{w} \in \mathbb{R}^2$$

Linear Classifier: Optimization

The learning objective:

$$\min_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w})$$

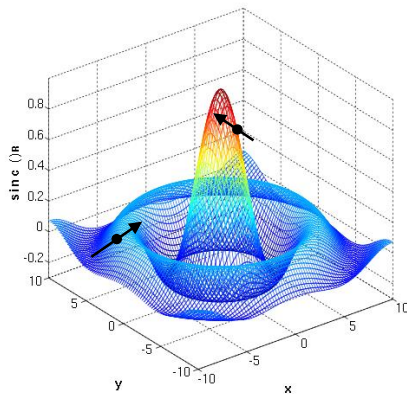
How to optimize it?

- Analytic solution (not always applicable).
- A more general solution is needed.
- **Gradient descent.**
 - An iterative algorithm.
 - At each iteration, find the fastest direction of moving \mathbf{w} that decreases L_{train} .
 - Move \mathbf{w} towards that direction.
 - Repeat the above two steps until reaching a stable \mathbf{w} .

Gradient

Definition: **Gradient**.

The gradient $\nabla_{\mathbf{w}} L_{\text{train}}$ is the direction that *increases* the training loss the most.



Gradient Descent

Algorithm Gradient Descent

Initialize \mathbf{w} ;

for $t = 1, 2, \dots, T$ **do**

$\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w})$

end

η : step size

T : number of iterations

Gradient Descent

Algorithm Gradient Descent

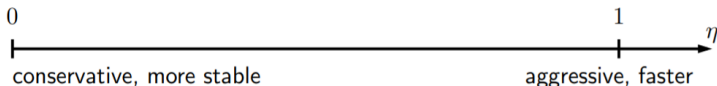
Initialize \mathbf{w} ;

for $t = 1, 2, \dots, T$ **do**

$\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w})$

end

How to choose the step size η ?



Common strategies:

- Constant: e.g., $\eta = 0.01$.
- Decreasing: e.g., $\eta = 0.1/t$.

Gradient Descent

Algorithm Gradient Descent

Initialize \mathbf{w} ;
for $t = 1, 2, \dots, T$ **do**
 $\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w})$
end

Example: Least squares regression

$$L_{train}(\mathcal{D}_{train}, \mathbf{w}) = \frac{1}{|\mathcal{D}_{train}|} \sum_{(x,y) \in \mathcal{D}_{train}} (\mathbf{w}^T \cdot \mathbf{x} - y)^2$$

$$\nabla_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w}) = \frac{1}{|\mathcal{D}_{train}|} \sum_{(x,y) \in \mathcal{D}_{train}} 2(\mathbf{w}^T \cdot \mathbf{x} - y) \mathbf{x}$$

Gradient Descent

Algorithm Gradient Descent

Initialize \mathbf{w} ;

for $t = 1, 2, \dots, T$ **do**

$\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w})$

end

Gradient descent is slow!

- Each iteration requires going over all training examples.
- Costly when the dataset is large (which is common nowadays).

Stochastic Gradient Descent

Algorithm Stochastic Gradient Descent

Initialize \mathbf{w} ;

for $t = 1, 2, \dots, T$ **do**

for $(x, y) \in \mathcal{D}_{train}$ **do**

$\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} L(x, y, \mathbf{w})$

end

end

The key idea: It's not about quality, it's about quantity.

Linear Classifier: Summary

- Linear predictor (model architecture):

$$f_{\mathbf{w}}(x) \text{ based on } \mathbf{w}^T \cdot \phi(x).$$

- Learning objective (goal):

$$\min_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w}).$$

- Optimization (train the model towards the goal):

$$\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} L_{train}(\mathcal{D}_{train}, \mathbf{w})$$