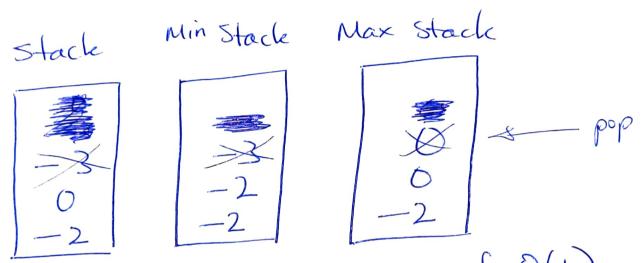
· For this problem, we need to define another Stack w/ the minimum/maximum & in the order of the values pushed/popped



- . This way, we can have runtime of O(1) Since we are comparing the pushed value w/ the previous min/max value, at the Cost of O(n) space.
- · Here, we create a parallel data structure.
- · This problem is less algorithmic and has more to do w/ using OOP and designing data structure.

## Alternative Approacles

"Iterate through entire stack, pop every element and push them back in to check the values and return the min/max. -> O(n), O(1)

· O(log n), O(n) can be achieved using heap or BST, and a hash table.

Class Max Stack (object): def \_\_init\_\_ (self): Self. stack = [] Self. maxes = [] det push (self, val): Self. Stack. append (val) # IF the max value from the maxes stack is greater, add that to stack otherwise, push that value that is greater than the max if self, maxes and self, maxes [-1] > val=: self. maxes. append (self. maxes [-1]) else: self, maxes, append (val) def pop(self): self. maxes:

Self. maxes. pop() } # Need to make

Sure we also pop val

from naxes stack if self maxes: return self, stack. popl) det max (self): return self, maxes [-1]

8.6 7/8/22

Then for each depth, store the children node
to a queue, store the elements
in the queue to a list and append
that to the result. Do this until
all nodes are processed.

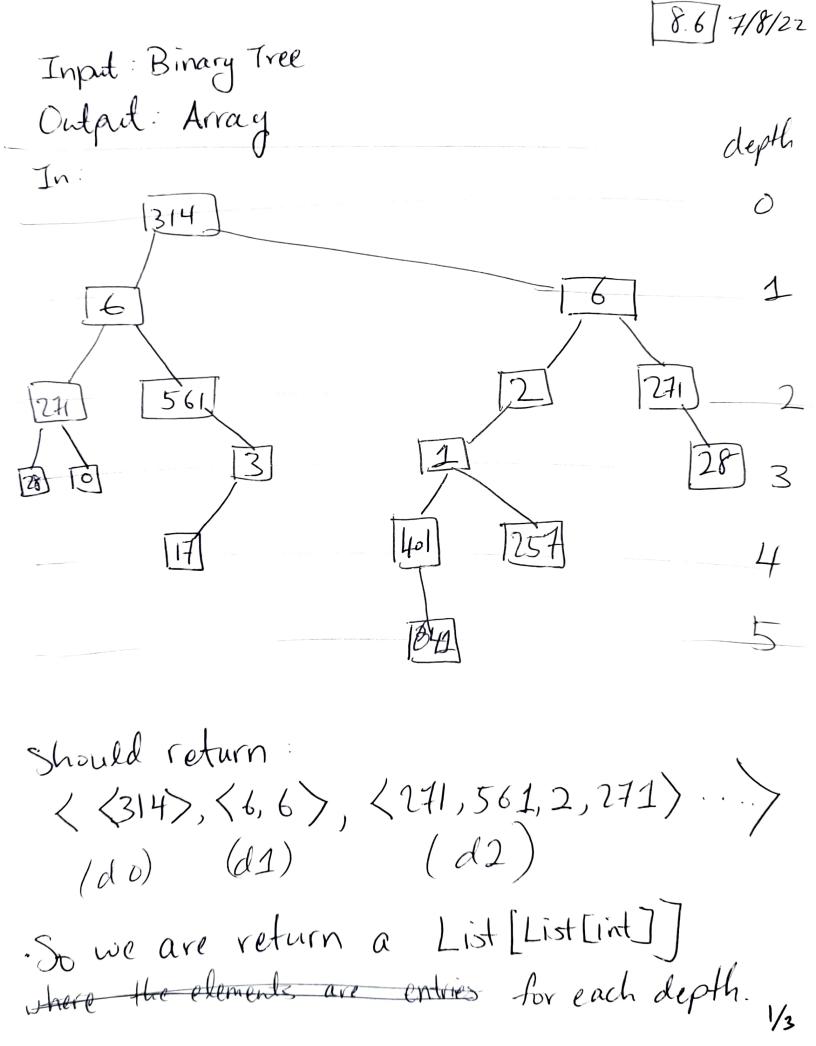
queue
[9,20]
[15,7]

result
[[3]]
[[3],[9,20]]
[[3],[9,20],[15,7]]

det binary-tree\_depth\_order(tree Binary TreeNede) -> List[List[int]]: result : List [List[int]] = [] if not tree: return result -Queue = Curr-depth nodes = [tree] While curr-depth\_nodes: nodes\_at\_depth = [] for node in cur-depth\_nodes: append a nodes in the nodes-at-depth append (node) derth to result append (nodes\_at\_depth) the result next\_depth = [] for node in curr-depth-nodes: for child in (node, left, noderight): Process the nodes in the it child: next depth append (child) next depth curr-depth-nodes = [] #empty the queue

# prepare the next queue for node in next-depth: Curr-depth-nodes.append (node)

return result



· I don't know how the bin tree like.	e input lookes
Bin Tree will Look like.	
class Node(object):  def_ind_(self, the def  self. date = data  self. left = left  self. right = right	Nove ata, left=None, right=
and the prinputs:  root = Node('a')  root. left = Node('b')  root. left, left = Node('d')  root.right = Node('c')	(b) (c) (d)

(3min)

· So the problem is asking for a class that has a method for getting the depth and for each depth, append all the values into a list and append to another list to return the list of values. The

Boundary/edge cases:

Co Since His a binary tree, at each depth the max amount of elem is 2 depth.

D'How can I use queue in this?

What is the Naire Approach?

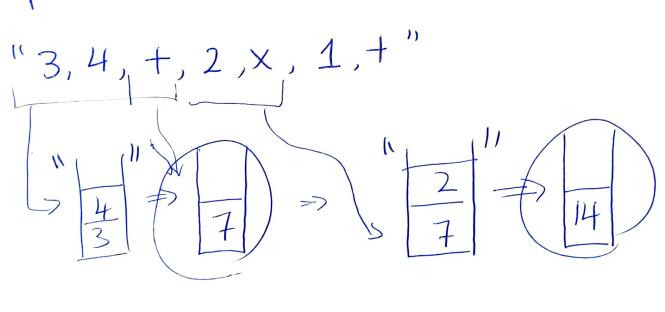
-Maybe I can append to a list of the max amount of elem, checking each branch. Where node, left # null; the temp-list append (node eith)

and then result. append (temp-list)

\_3 Since we are dieche all branches = 0 (2 max (depth)) time
25 Since we are dieche all branches = 0 (depth) space 3

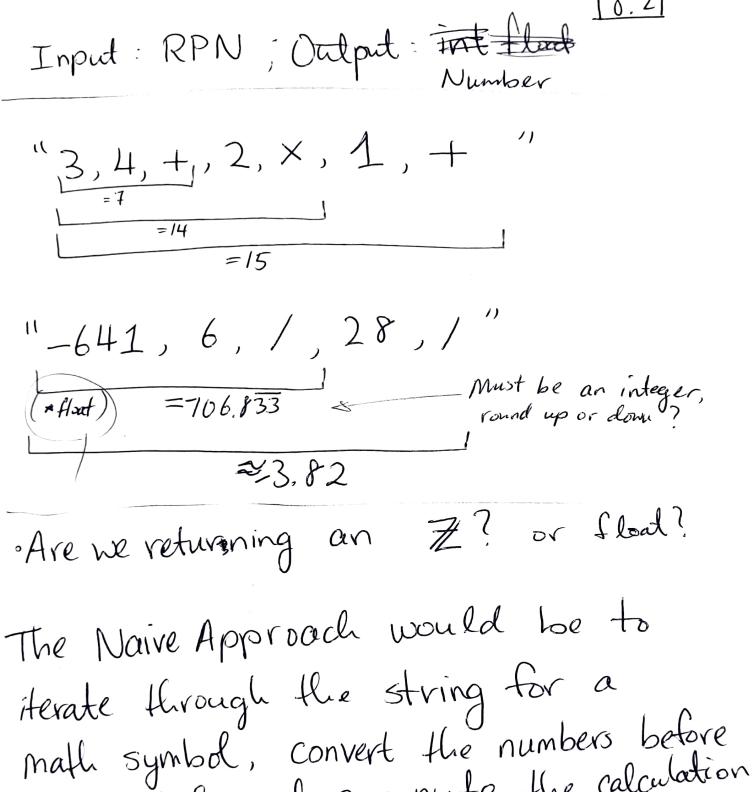
## Evaluation

Sthe design was similar but not correct. When doing the computation, I had to observe the A and B by popping them and do the computation. Then push the value back into the list.



15

\* For each number value (not operators) we convert and push/append as integer.



math symbol, convert the numbers before the symbol and compute the calculation. We can take that number value and traverse the string until next math symbol or rend. We can do this recursively. (000), 0(1)

13min 6 We might be able to use stacks to store the computed value and compute again when there is a symbol. To compute & in accordance to the symbol, we might have to use a dictionary. This can reduce the time but use extra memory (O(1), O(n))"3,4,+,2x ZOMin