

## Software timer with incorrect update of variable Timer

```
// Timer for millis() approach.
unsigned long Timer;

// Interrupt Service Routine to toggle pin
void TogglePin13()
{
    // Set pin 12 on to indicate start of ISR
    bitSet(PORTB, 4);
    // if pin 13 is one,
    if (bitRead(PINB, 5))
    {
        // Clear pin 13
        bitClear(PORTB, 5);
    }
    else
    {
        // set pin 13.
        bitSet(PORTB, 5);
    } // end of if

    // Clear pin 12 on to indicate end of ISR
    bitClear(PORTB, 4);
} // End of TogglePin13.

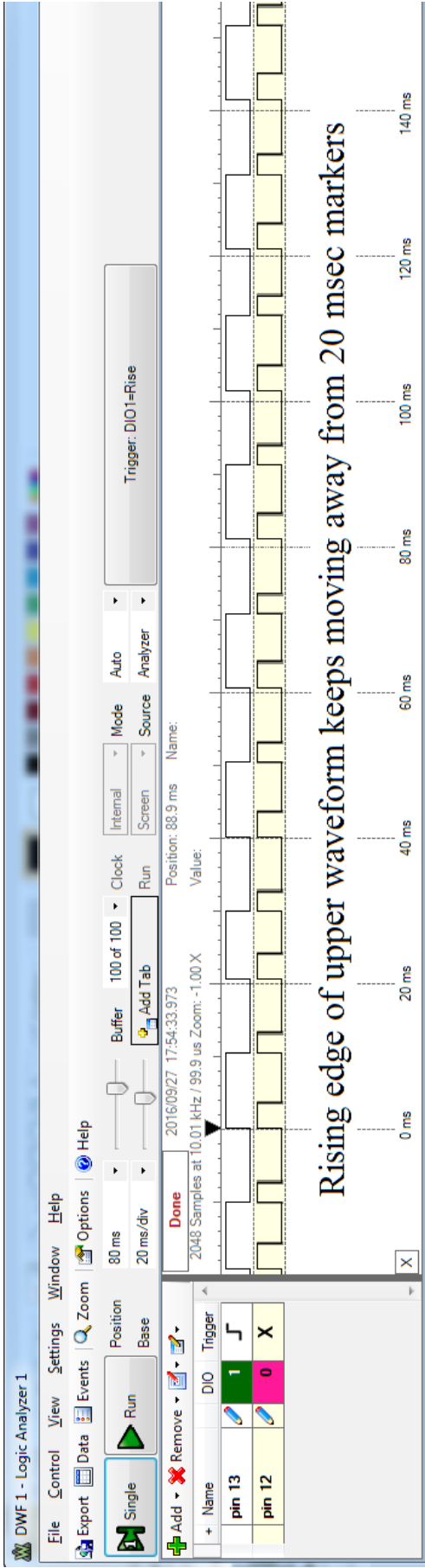
// Configure System, run at startup
void setup()
{
    pinMode(13, OUTPUT); // 13 an output.

    // Timer based on millis()
    Timer = millis();
} // End of setup.

// Main loop is constantly run.
void loop()
{
    // Timer using millis() call.
    if( millis()-Timer >= 10 ) // check of 10 milliseconds
    {
        TogglePin13(); // Then toggle pin 13,

        Timer = millis(); // Incorrect update of timer.
    }

    // Time consuming loop.
    for (int m = 0; m < 1000; m++)
    {
        for (int k = 0; k < 32000; k++)
        {
            int j = k * k + 5; // Calculation to use time.
        }
    }
} // End of loop.
```



Software timer with more accurate update of variable Timer

```
// Timer for millis() approach.
unsigned long Timer;

// Interrupt Service Routine to toggle pin
void TogglePin13()
{
    // Set pin 12 on to indicate start of ISR
    bitSet(PORTB, 4);
    // if pin 13 is one,
    if (bitRead(PINB, 5))
    {
        // Clear pin 13
        bitClear(PORTB, 5);
    }
    else
    {
        // set pin 13.
        bitSet(PORTB, 5);
    } // end of if

    // Clear pin 12 on to indicate end of ISR
    bitClear(PORTB, 4);
} // End of TogglePin13.

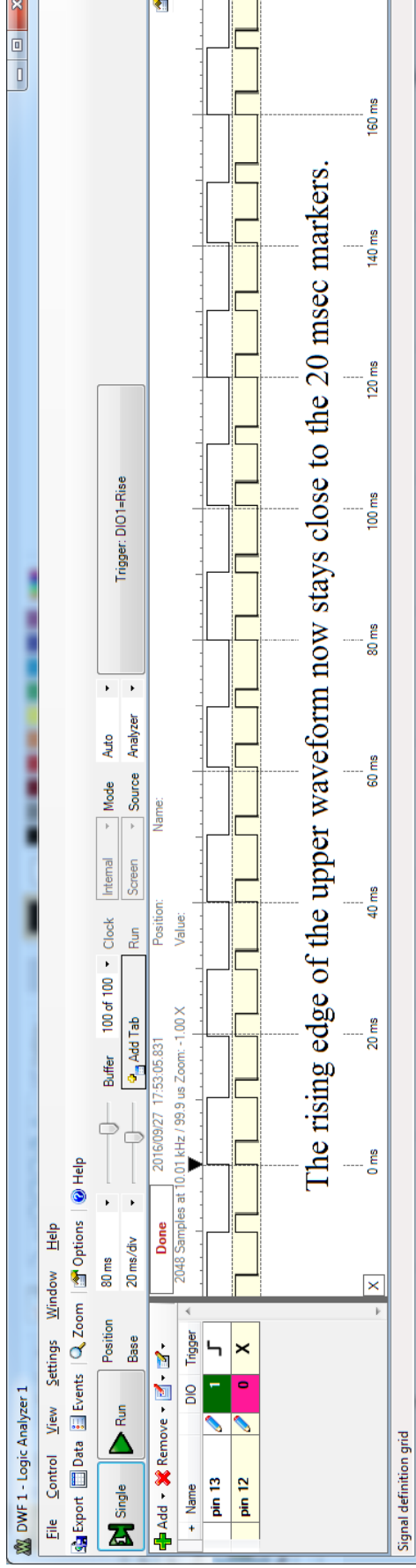
// Configure System, run at startup
void setup()
{
    pinMode(13, OUTPUT); // 13 an output.

    // Timer based on millis()
    Timer = millis();
} // End of setup.

// Main loop is constantly run.
void loop()
{
    // Timer using millis() call.
    if( millis()-Timer >= 10 ) // check of 10 milliseconds
    {
        TogglePin13(); // Then toggle pin 13,

        Timer += 10; // Correct update of timer.
    }

    // Time consuming loop.
    for (int m = 0; m < 1000; m++)
    {
        for (int k = 0; k < 32000; k++)
        {
            int j = k * k + 5; // Calculation to use time.
        }
    }
} // End of loop.
```



## Hardware based 10 millisecond interval

```
// 10 millisecond time interval implemented by hardware.
#include <TimerOne.h>

// Interrupt Service Routine to toggle pin
void TogglePin13()
{
    // Set pin 12 on to indicate start of ISR
    bitSet(PORTB, 4);
    // if pin 13 is one,
    if (bitRead(PINB, 5))
    {
        // Clear pin 13
        bitClear(PORTB, 5);
    }
    else
    {
        // set pin 13.
        bitSet(PORTB, 5);
    } // end of if

    // Clear pin 12 on to indicate end of ISR
    bitClear(PORTB, 4);
} // End of TogglePin13.

// Configure System, run at startup
void setup()
{
    pinMode(13, OUTPUT); // 13 an output.
    // Timer1 based system
    Timer1.initialize(10000);
    Timer1.attachInterrupt(TogglePin13);
} // End of setup.

// Main loop is constantly run.
void loop()
{
    // Nothing to do since all is handled by hardware.

    // Time consuming loop.
    for (int m = 0; m < 1000; m++)
    {
        for (int k = 0; k < 32000; k++)
        {
            int j = k * k + 5; // Calculation to use time.
        }
    }
} // End of loop.
```

