

Transfer protocol user EFM - 115

V 1.20

Request	1. Byte	< ----->	
AVR_USB_READ	0x05	EFM to PC	
AVR_USB_Write	0x02	PC to EFM	

Request Value	2. Byte	what ?	
AVR_USB_ADC	0x00	Data from A/D Converter	read only from EFM
AVR_USB_STAT	0x01	Status VZ + Overflow + Low Batt.	read only from EFM
AVR_USB_RANGE	0x02	Gain range	
AVR_USB__REOF	0x30	Read Offset Zero ==> xxx	siehe unten Offsetwerte
AVR_USB_BUSY	0x31	Zero if not Busy !!!	read only from EFM
AVR_USB_MODE	0x35	Send Mode 0x00=EFM; 0x01=MK1; 0x10 Cal	read only from EFM

Werte	Länge	ab 3. Byte	
Measure ADC (00)	4 Byte	4-Digit as ASCII	LSB 3. Byte zu MSB 6. Byte
siehe Messwert			
Status STAT (01)	1 Byte	Bit 0 = Overflow (1) Bit 4 = Polarity (Neg. = 1) Bit 7 = L.B. (1) (HEX 00, 01, 10, 11, 80, 81, 90, 91)	
RANGE (02)	1 Byte	0x10 V2 = 250 kV/m (0) Gain EFM X 2	
		0x20 V10 = 50 kV/m (1) Gain EFM X 10	
		0x30 V20 = 25 kV/m (2) Gain EFM X 20	
		0x40 V100 = 5 kV/m (3) Gain EFM X 100	
		0x50 Autorange AR Gain EFM AUTO	
REOF (0x30)		0x10 send => all RAM Offset set "0"	
see Offsetvalue		0x20 senden => set Busy read all Offset -> write EEPROM	
BUSY (0x31)		0x00 not busy, All o.k.	
		0x10 Busy !	
		0xF0 Offset to high ==> forgot protect cap ?? ***	
		0xF1 EEPROM - Error when writing the parameters	
		0xF2 EEPROM - Error when writing the Offsetvalue	
*** Read offset canceled must be restarted !			
Messwert	Value is sent as 4-digit value (ASCII) End of range is 1000 Range is used to calculate the measured value Polarity is read out in STAT(01)		LSB => MSB
Example! Value "784" sent in ASCII from 3. Byte is 24 - 28 - 27 - 20 !			
z.B.	Displayed Value = Range / 1000 x Value Value 784 Range 0x30 (25kV/m) 25 kV/m / 1000 x 784 = 19,60 kV/m		Status = 0x00 (Polarity +)
z.B.	Wert 645 Bereich 0x20 (50kV/m) 50 kV/m / 1000 x 645 = -32,25 kV/m by Status = 0x01(11) Display in PC = OVERFLOW		Status = 0x10 (VZ = Neg.)
Offsetwerte	16 Bit Integer mit 2er complement Example: +31 = 0x001F => -31 = 0xFFE1		
Protect cap must be put on the modulator !			
0x30 0x10 send => all RAM Offset Values set to "0"			
Set Range 5kV/m than read out Measure Value (with Polarity)			
With Trimmer Offset set Measure Value < 50			
0x30 0x20 send => set Busy read all Offset -> write EEPROM			
Busy reset			