view\_frames Result Recorded at time: 489.179 world Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (489.179 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (489.179 sec old) Most recent transform: 0.000 (489.179 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base\_laser cpu\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (489.179 sec old) Buffer length: 0.000 sec upper\_base\_link Broadcaster: /robot\_state\_publisher Average rate: 50.205 Hz Most recent transform: 489.150 (0.029 sec old) Buffer length: 4.880 sec torso\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (489.179 sec old) Most recent transform: 0.000 (489.179 sec old) Most recent transform: 0.000 (489.179 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec right\_shoulder\_link head\_pan\_link left\_shoulder\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.205 Hz Average rate: 50.205 Hz Average rate: 50.205 Hz Most recent transform: 489.150 (0.029 sec old) Most recent transform: 489.150 (0.029 sec old) Most recent transform: 489.150 (0.029 sec old) Buffer length: 4.880 sec Buffer length: 4.880 sec Buffer length: 4.880 sec head\_tilt\_link left\_shoulder\_forward\_link right\_shoulder\_forward\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.205 Hz Average rate: 50.205 Hz Average rate: 50.205 Hz Most recent transform: 489.150 (0.029 sec old) Most recent transform: 489.150 (0.029 sec old) Most recent transform: 489.150 (0.029 sec old) Buffer length: 4.880 sec Buffer length: 4.880 sec Buffer length: 4.880 sec neck\_link left shoulder up link right\_shoulder\_up\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (489.179 sec old) Most recent transform: 0.000 (489.179 sec old) Most recent transform: 0.000 (489.179 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec left\_upper\_arm\_link head\_link right\_upper\_arm\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 50.205 Hz Average rate: 50.205 Hz Most recent transform: 0.000 (489.179 sec old) Most recent transform: 489.150 (0.029 sec old) Most recent transform: 489.150 (0.029 sec old) Buffer length: 0.000 sec Buffer length: 4.880 sec Buffer length: 4.880 sec antenna\_link left\_elbow\_link right\_elbow\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (489.179 sec old) Most recent transform: 0.000 (489.179 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left\_lower\_arm\_link right\_lower\_arm\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.205 Hz Average rate: 50.205 Hz Most recent transform: 489.150 (0.029 sec old) Most recent transform: 489.150 (0.029 sec old) Buffer length: 4.880 sec Buffer length: 4.880 sec left\_wrist\_link right\_wrist\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (489.179 sec old) Most recent transform: 0.000 (489.179 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left\_hand\_link right\_hand\_link