

Computational Dynamics Homework5 Numerical Initial Value Problems

April 5, 2020

Number 2

```
# First find the values that h ensure Stability
# Adams_Basthforth
using SymPy
using Plots
import LinearAlgebra
@vars lambda
(sigma,z,zx,zy,theta, h) = symbols("sigma z zx zy theta h",real=true)

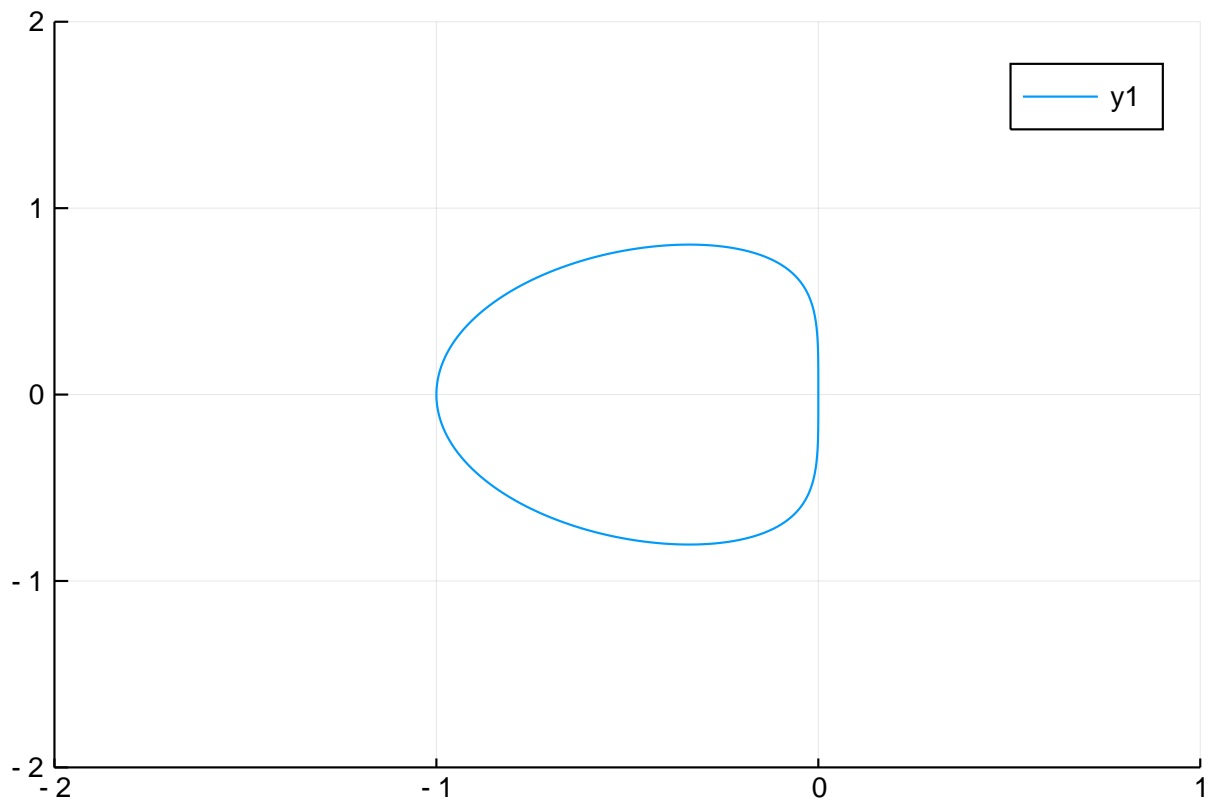
eq1 = sigma^2 - sigma*(1+3/2*z)+1/2*z
eq1 = eq1 |> subs(sigma=>cos(theta) + sin(theta)*1im)
eq1 = eq1 |> subs(z=>zx + zy*1im)
eq2 = real(eq1)
eq3 = imag(eq1)

zsolution = solve([eq2, eq3],[zx,zy])

Dict{Any,Any} with 2 entries:
  zx => 2.0*(cos(theta)^2 - 2.0*cos(theta) + 1.0)/(3.0*cos(theta) - 5.0)
  zy => 2.0*(cos(theta) - 2.0*sin(theta))/(3.0*cos(theta) - 5.0)

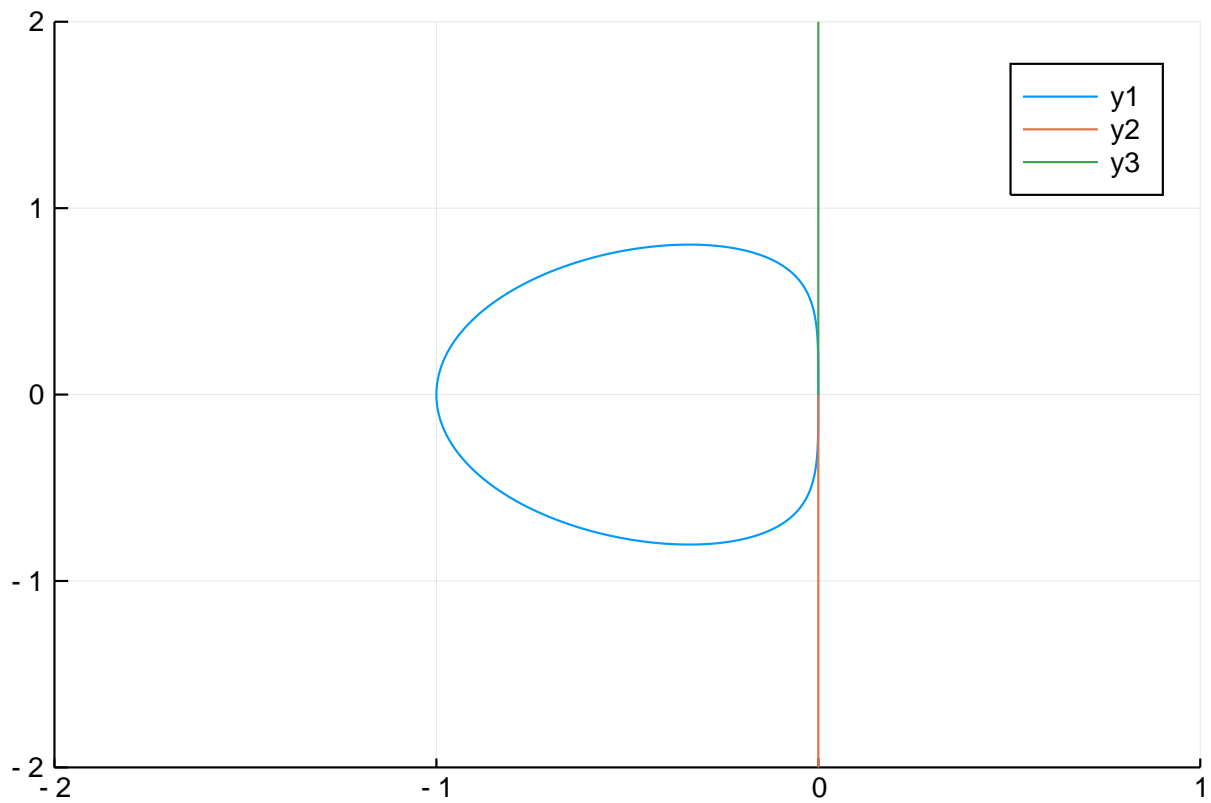
z_x = lambdify(zsolution[zx])
z_y = lambdify(zsolution[zy])
theta = collect(0:2*pi/100:2*pi)

plot(z_x, z_y, 0, 2*pi,xlims = (-2,1),ylims = (-2,2))
```



```
A = [0 1;-1 0]
lamda1 = LinearAlgebra.eigvals(A)[1]
lamda2 = LinearAlgebra.eigvals(A)[2]

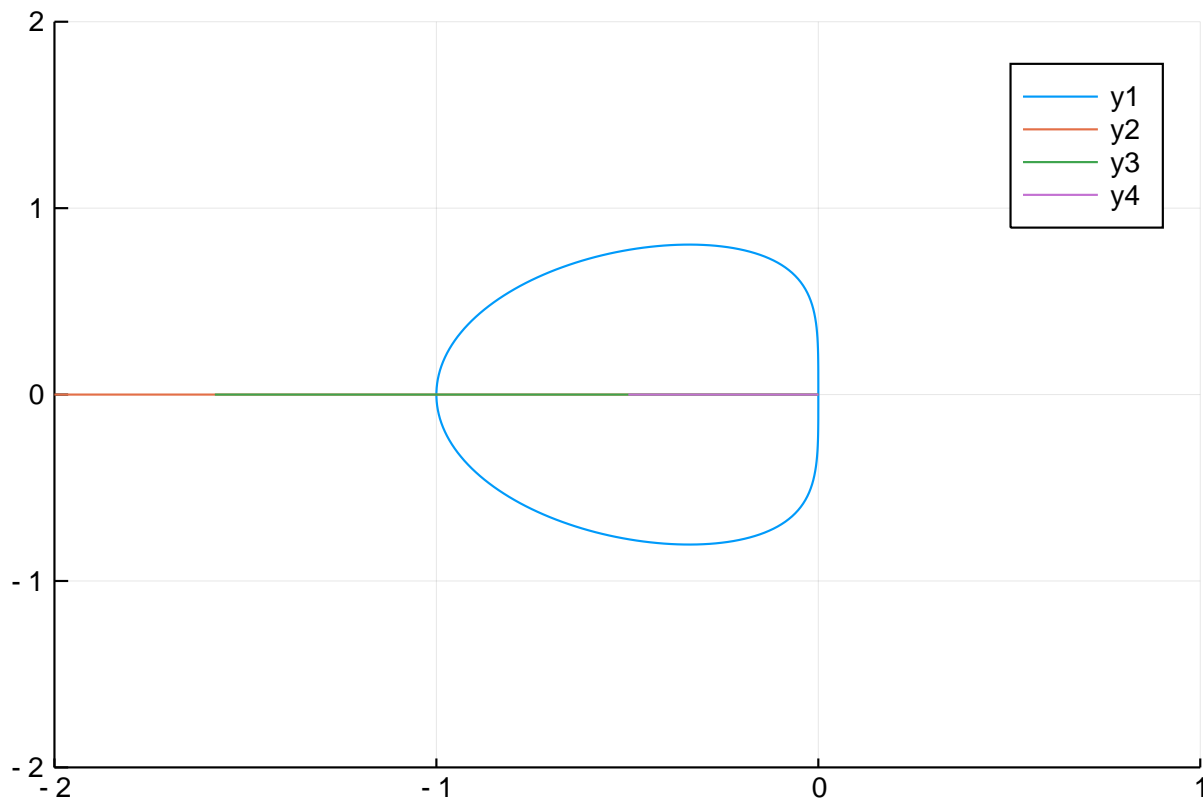
hvals = collect(0:.01:5)
plot!(real(hvals*lamda1),imag(hvals*lamda1))
plot!(real(hvals*lamda2),imag(hvals*lamda2))
```



```

plot(z_x, z_y, 0, 2*pi, xlims = (-2,1), ylims = (-2,2))
A2 = [0 1 0; 0 0 1; -23 -304 -732]
lamda3 = LinearAlgebra.eigvals(A2)[1]
lamda4 = LinearAlgebra.eigvals(A2)[2]
lamda5 = LinearAlgebra.eigvals(A2)[3]
plot!(real(hvals*lamda3), imag(hvals*lamda3))
plot!(real(hvals*lamda4), imag(hvals*lamda4))
plot!(real(hvals*lamda5), imag(hvals*lamda5))

```



Now I'm going to try to find the max h value analytically for Adams_Basthforth

```

a= 1
b = -(1+(3/2*z))
c = 1/2*z
root1 = -b+sqrt(b^2-4*a*c)/2/a |> subs(z=>h*lambda)
root2 = -b-sqrt(b^2-4*a*c)/2/a |> subs(z=>h*lambda)
h_Boundary1 = solve(root1,h)[1]
h_Boundary2 = solve(root2,h)[1]
# The time step h must be smaller than h_Boundary for Adams Basthforth
# CASE 1
hmax_Adams_Basthforth1 = h_Boundary2 |> subs(lambda=>lamda1) |> LinearAlgebra.norm

0.3463292355306104

# CASE 2
hmax_Adams_Basthforth2 = h_Boundary2 |> subs(lambda=>lamda3) |> LinearAlgebra.norm

0.0004733960771775613

```

NOW WE NEED TO COMPUTE THESE METHODS NUMERICALLY I'll start with the Adams Basthforth

Start with IVP (x_0 given) I'll use euler's to get the second point

```

function Adams_Basthforth(tf,A,h,x0)
    f(t,x) = A*x
    x_nPlus1(t_n,x_n,t_nMinus1,x_nMinus1) = x_n + 3/2*h*f(t_n,x_n) -
1/2*h*f(t_nMinus1,x_nMinus1)
    x = fill(NaN,oftype(1,tf/h+1),length(x0))
    x[1,:] = x0
    x[2,:] = x0 + h*f(0,x[1,:])
    for i = 3:oftype(1,tf/h+1)
        x[i,:] = x_nPlus1(0,x[i-1,:],0,x[i-2,:])
    end
end

```

```

        end
        return x
    end

# check the system of 2 equations with built in stuff
##
import DifferentialEquations

function ode2(dz,z,p,t)
    dz[1] = z[2]
    dz[2] = -z[1]
end

tspan = (0.0,5.)
z0 = [1.;1.]
prob = DifferentialEquations.ODEProblem(ode2,z0,tspan)
sol1 = DifferentialEquations.solve(prob)


# now do implicit midpoint method
##

function ImplicitMidPoint(A, tf, h, x0; tol = 1e-4, iterMax = 1000 )
    f(t,x) = A*(x)
    time = 0:h:tf
    n = length(time)
    p = length(x0)

    x = fill(NaN,n,p)

    # Initial Condition
    x[1,:] .= x0

    # 1 Euler Step (first guess)
    y = x[1,:] + h*f(time[1],x[1,:])

    # Implicit Midpoint for multiple steps
    for i = 1:n-1
        flag = 0
        iter = 0
        while flag == 0
            iter += 1

            ynew = x[i,:] + h*f(time[i]+h/2,1/2*(x[i,:]+y))

            residual = LinearAlgebra.norm( y - ynew)
            y = ynew

            if residual <= tol
                flag = 1
            elseif iter >= iterMax
                flag = -1
                error("Error: failed to converge")
            end
        end
    end
end

```

```

        x[i+1,:] = y
    end
end
return x,time
end

## check the system of 3 equations with built in stuff
##

function ode3(dz,z,p,t)
    A2 = [0 1 0 ; 0 0 1; -23 -304 -372]
    dz[1] = z[2]
    dz[2] = z[3]
    dz[3] = -23*z[1] -304*z[2] -372*z[3]

end

tspan = (1.,5.)
z0 = [-10.;10.;-7.5]
prob = DifferentialEquations.ODEProblem(ode3,z0,tspan)
sol3 = DifferentialEquations.solve(prob)

##
# Now we'll test them

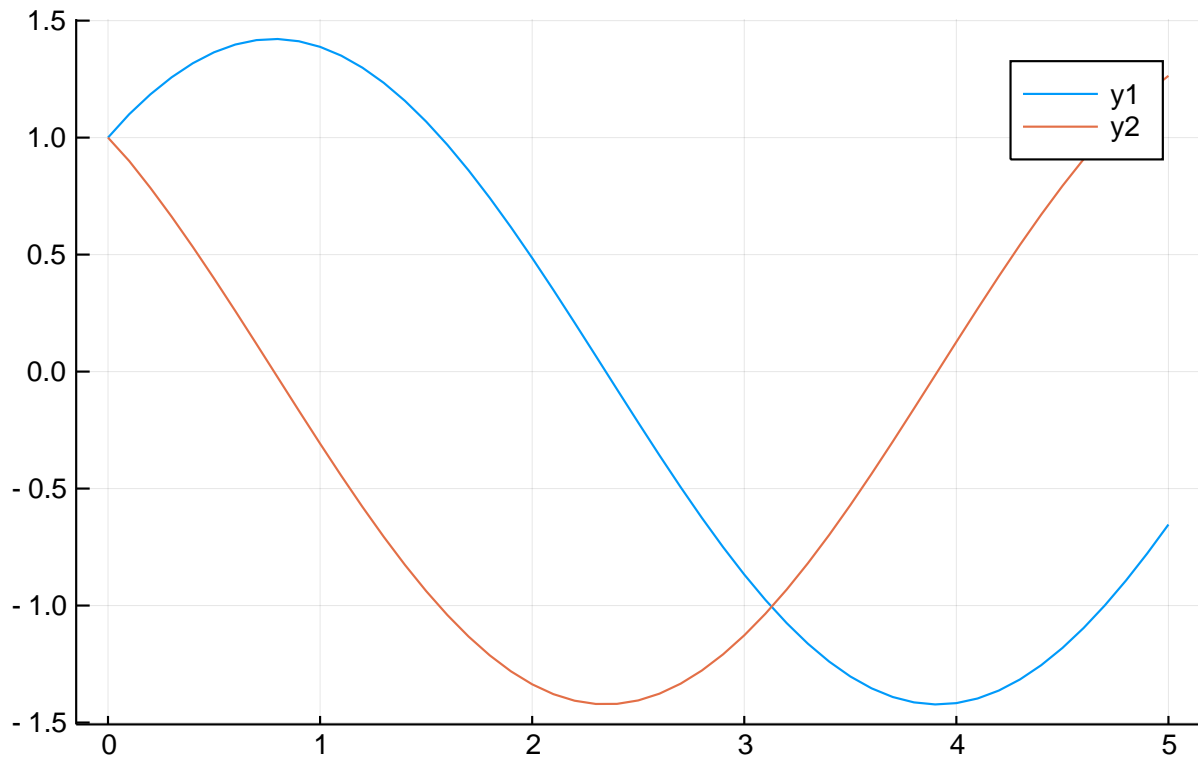
A = [0 1;-1 0]
x0 = [1.;1.]
h = .1
t0 = 0
tf = 5

## Adams_Basthforth Test
xvals = Adams_Basthforth(tf,A,h,x0)

tvals = collect(0:h:tf)
plot(tvals,xvals[:,1])
plot!(tvals,xvals[:,2])
title!("Case 1: Adams Basthforth: Stable Case")

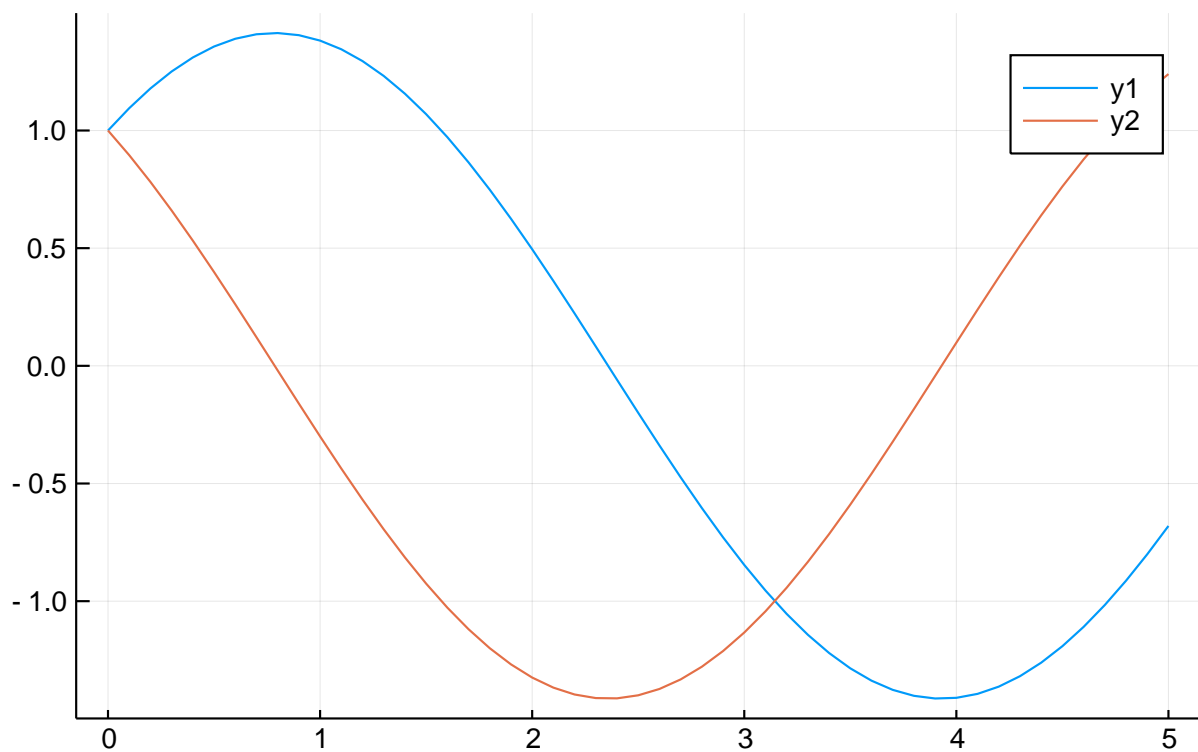
```

Case 1: Adams Bashforth: Stable Case



```
## ImplicitMidPoint
x,Time = ImplicitMidPoint(A, tf, h, x0)
plot( Time, x)
title!("Case 1: Implicit Midpoint: Stable Case")
```

Case 1: Implicit Midpoint: Stable Case

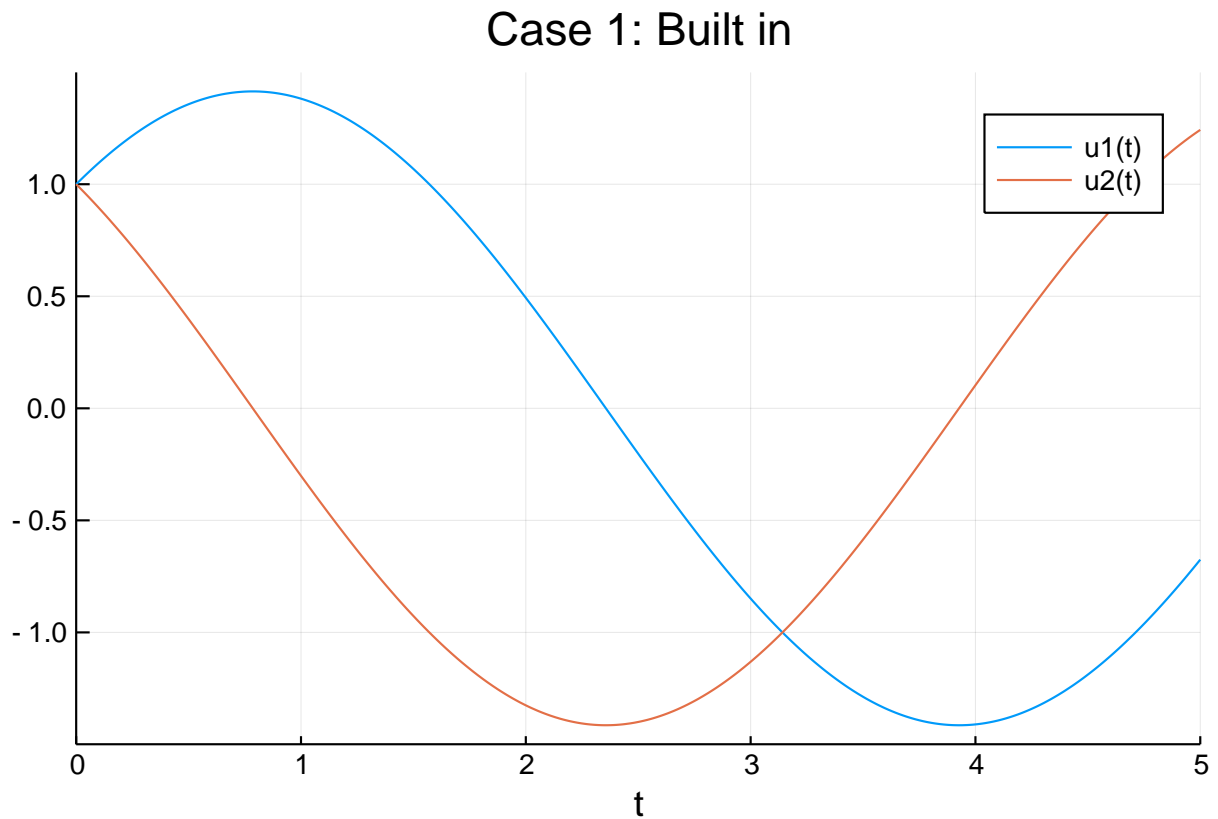


#DifferentialEquations.jl algorithm which which picks the best solver to use.

```

plot(sol1, vars = (0,1))
plot!(sol1, vars = (0,2))
title!("Case 1: Built in")

```



Now we'll test the system of 3 equations

```

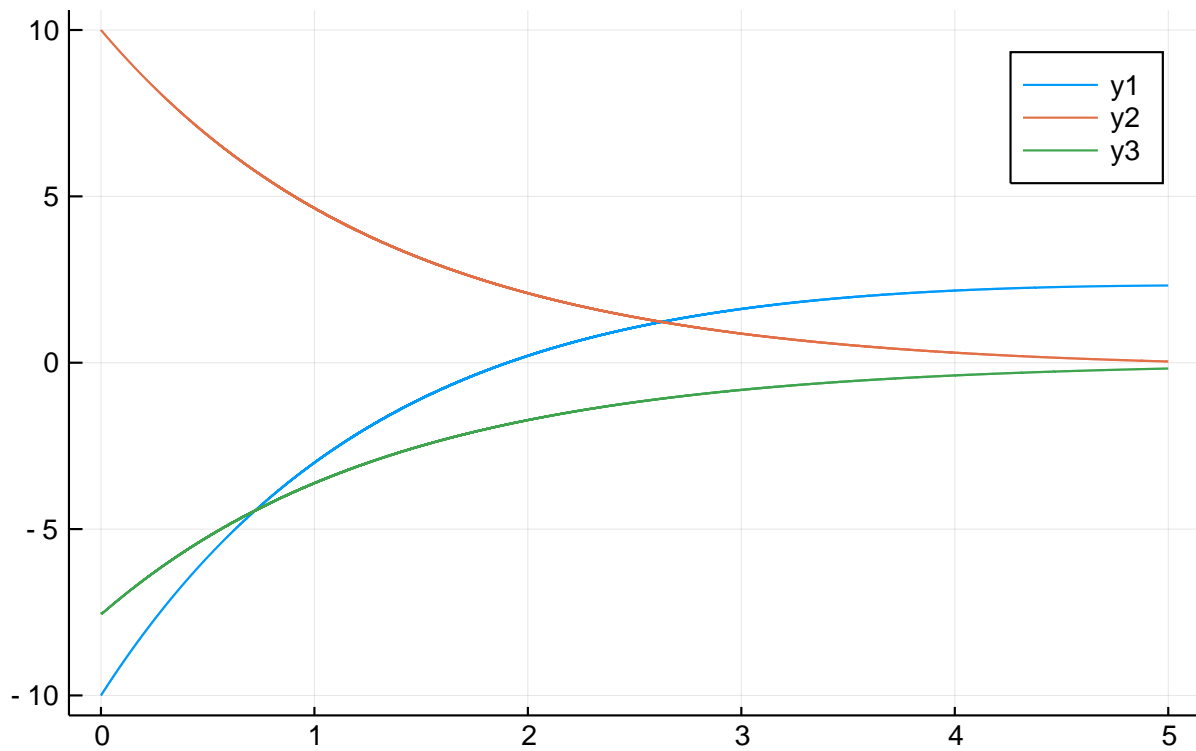
A2 = [0 1 0 ; 0 0 1; -23 -304 -372]
x02 = [-10.; 10.; -7.5]
h2 = .0001

##
# Adams_Basthforth
xvals = Adams_Basthforth(tf,A2,h2,x02)

tvals = collect(0:h2:tf)
plot(tvals,xvals[:,1])
plot!(tvals,xvals[:,2])
plot!(tvals,xvals[:,3])
title!("Case 2: Adams Basthforth: Stable Case")

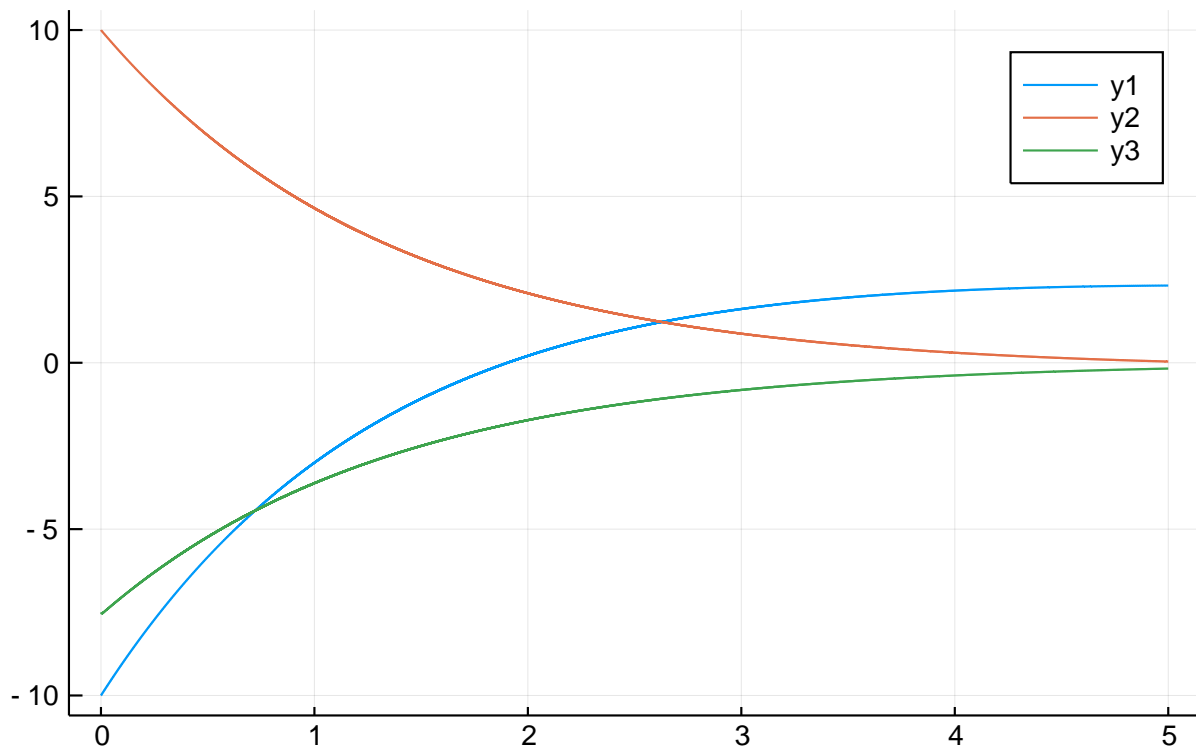
```


Case 2: Adams Bashforth: Stable Case



```
# ImplicitMidPoint method
x,Time = ImplicitMidPoint(A2, tf, h2, x02)
plot( Time, x)
title!("Case 2: Implicit Midpoint: Stable Case")
```

Case 2: Implicit Midpoint: Stable Case

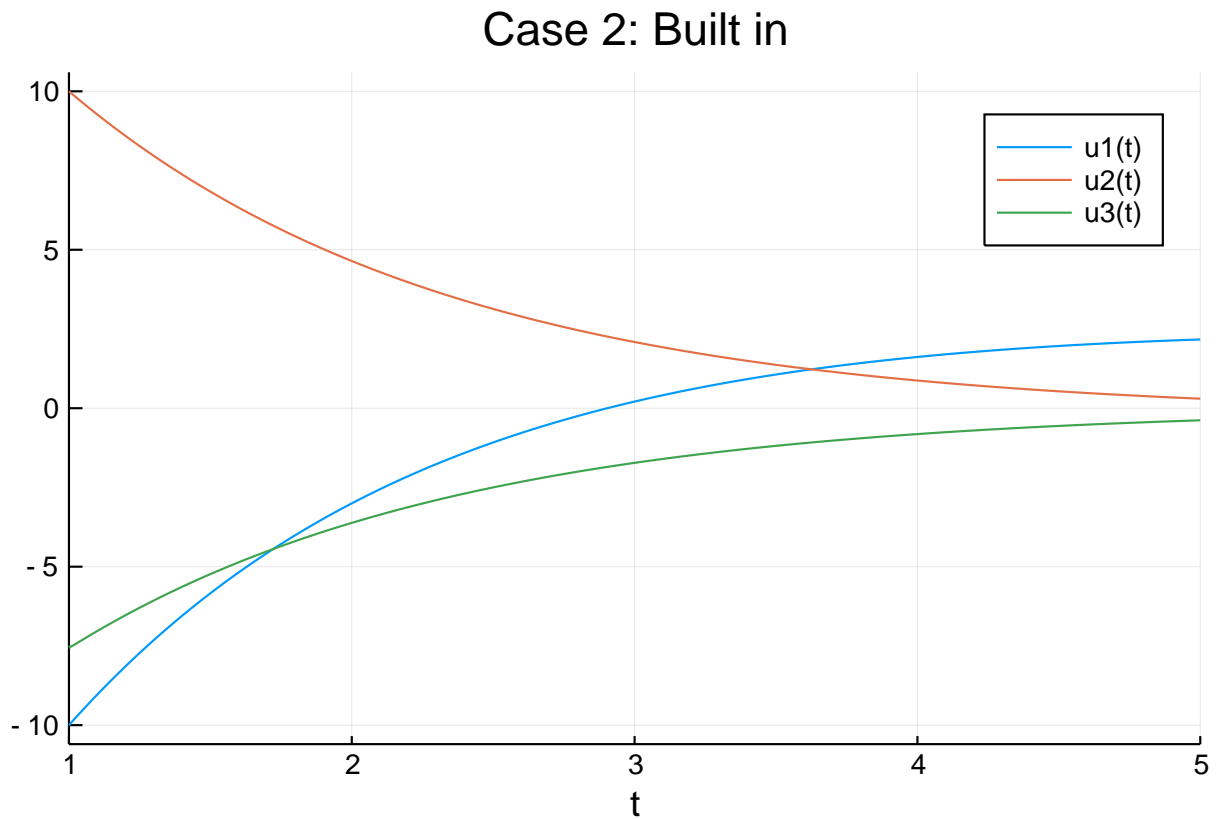


```
# Built in stuff
```

```

plot(sol3, vars = (0,1))
plot!(sol3, vars = (0,2))
plot!(sol3, vars = (0,3))
title!("Case 2: Built in")

```



Ok! Now lets test the boundary case! I couldnt figure out how to solve it analytically so I did it with guess and check

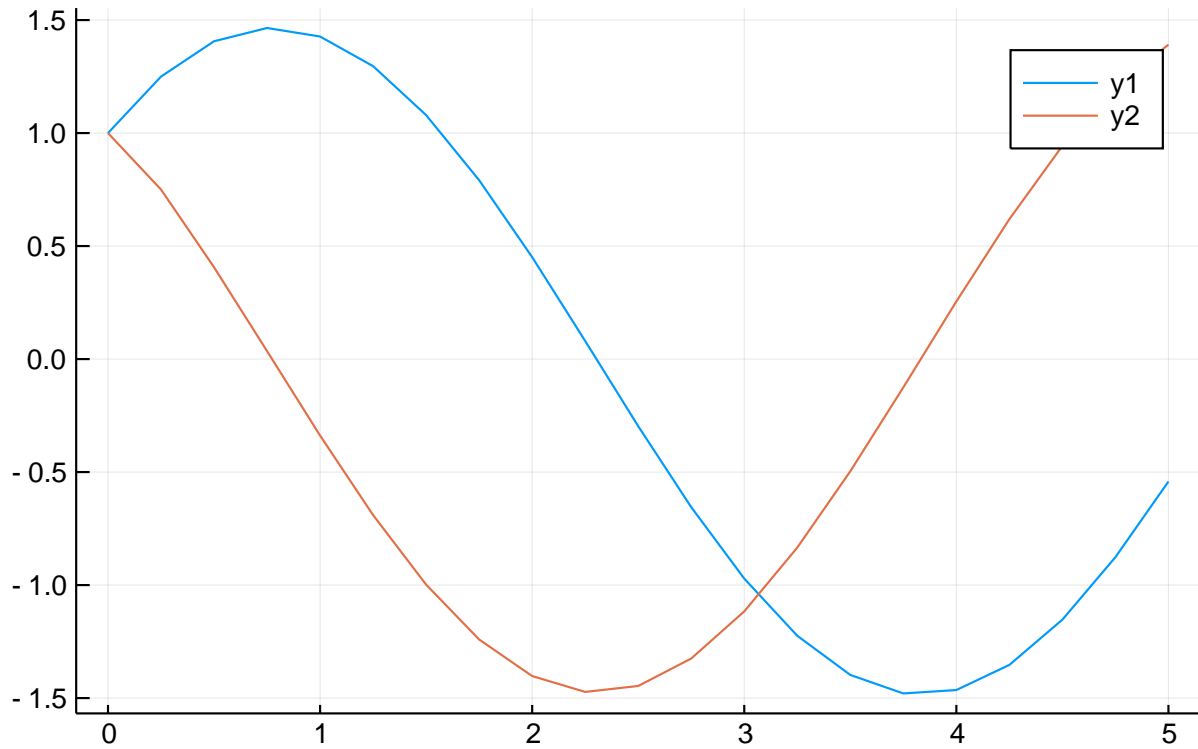
```

# by testing hmax for adams bathforth is .25 for case 1
## Adams_Basthforth Test
xvals = Adams_Basthforth(tf,A,.25,x0)

tvals = collect(0:.25:tf)
plot(tvals,xvals[:,1])
plot!(tvals,xvals[:,2])
title!("Case 1: Adams Basthforth: Boundary Case")

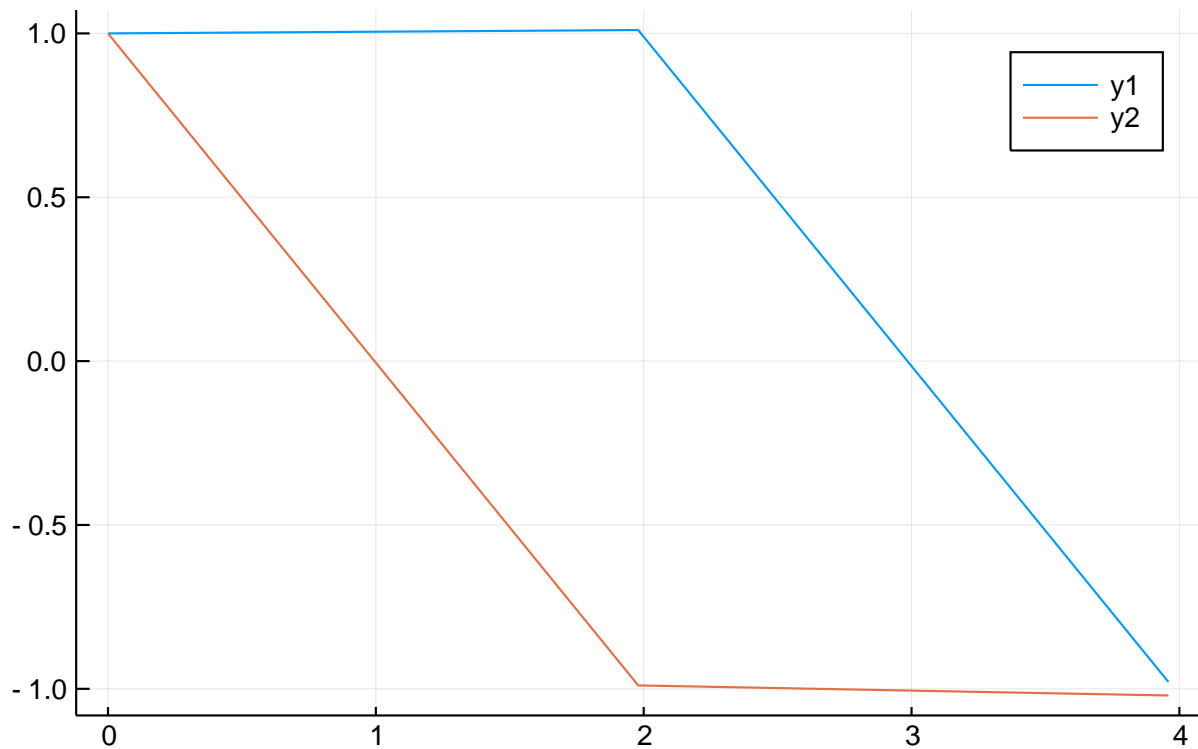
```

Case 1: Adams Bashforth: Boundary Case



```
# by testing hmax for Implicit MidPoint is 1.9796 for case 1
x,Time = ImplicitMidPoint(A, tf, 1.9796, x0)
plot( Time, x)
title!("Case 1: Implicit Midpoint: Boundary Case")
```

Case 1: Implicit Midpoint: Boundary Case



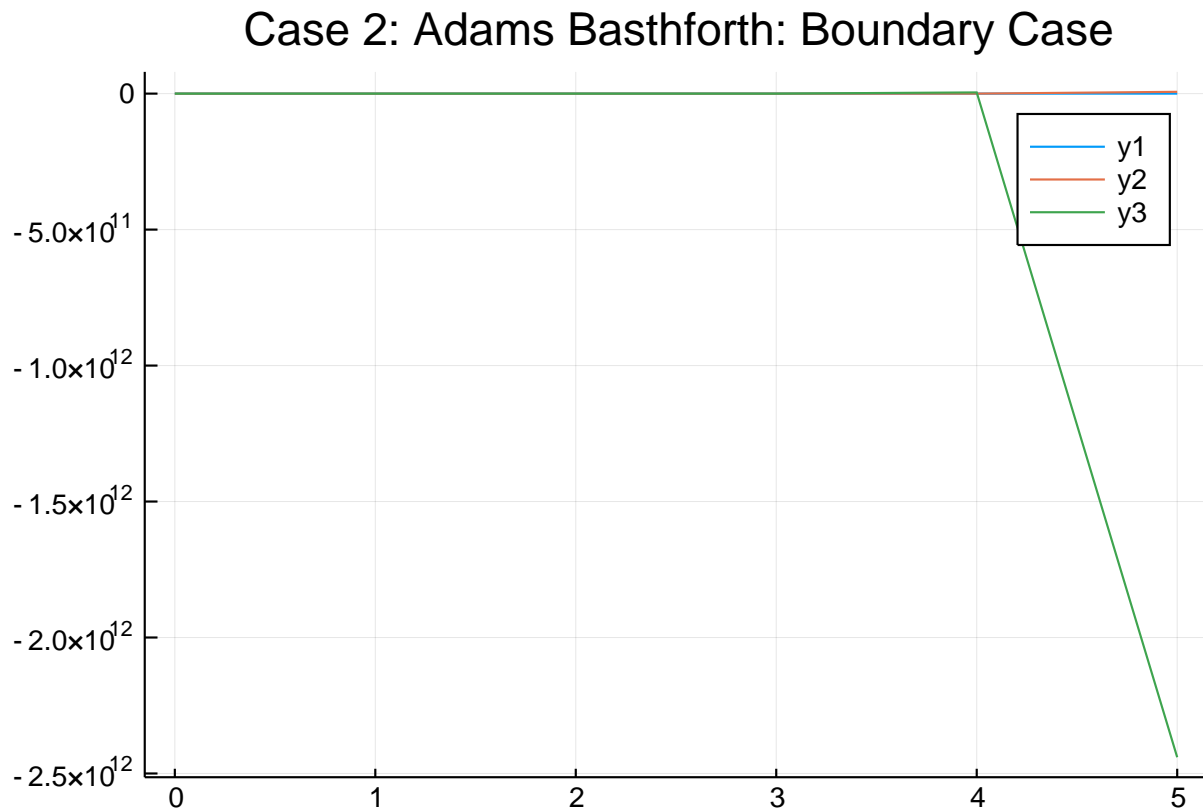
```
# by testing hmax for adams bashforth is 1 for case 2
```

```

# Adams_Basthforth
xvals = Adams_Basthforth(tf,A2,1.,x02)

tvals = collect(0:1:tf)
plot(tvals,xvals[:,1])
plot!(tvals,xvals[:,2])
plot!(tvals,xvals[:,3])
title!("Case 2: Adams Basthforth: Boundary Case")

```

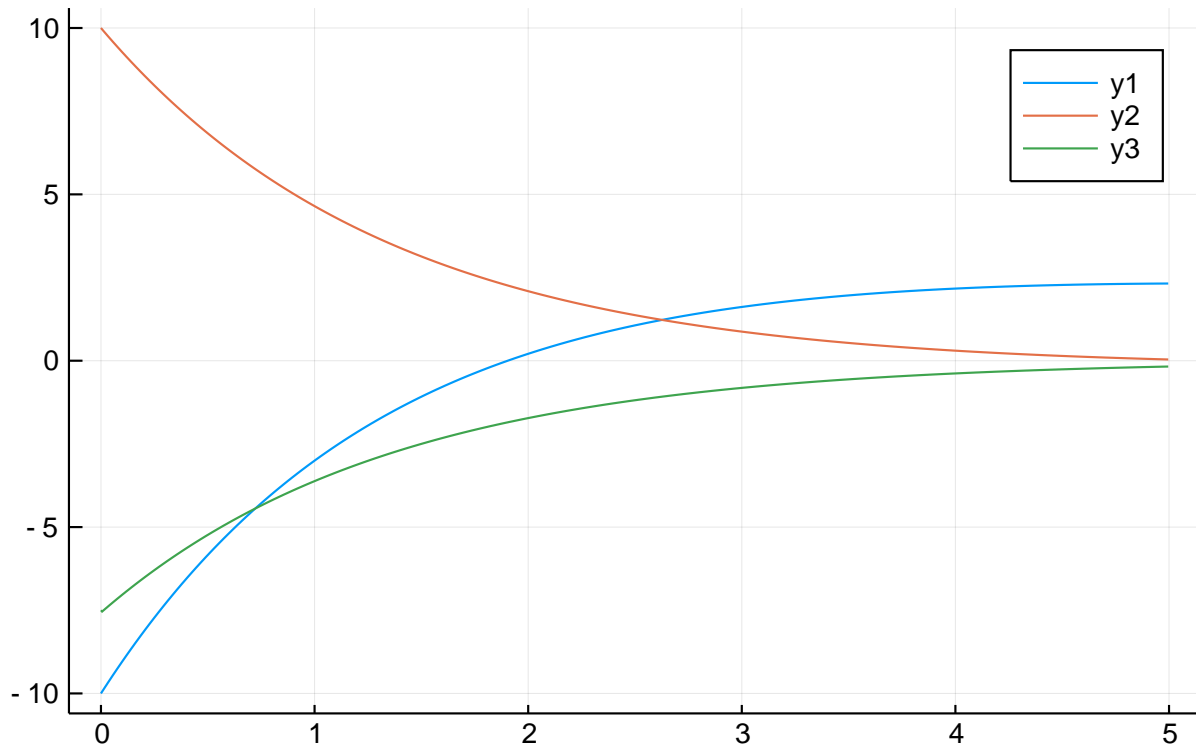


```

# by testing hmax for Implicit MidPoint is 0.0053494 for case 2
# ImplicitMidPoint method
x,Time = ImplicitMidPoint(A2, tf, .0053494, x02)
plot( Time, x)
title!("Case 2: Implicit Midpoint: Boundary Case")

```

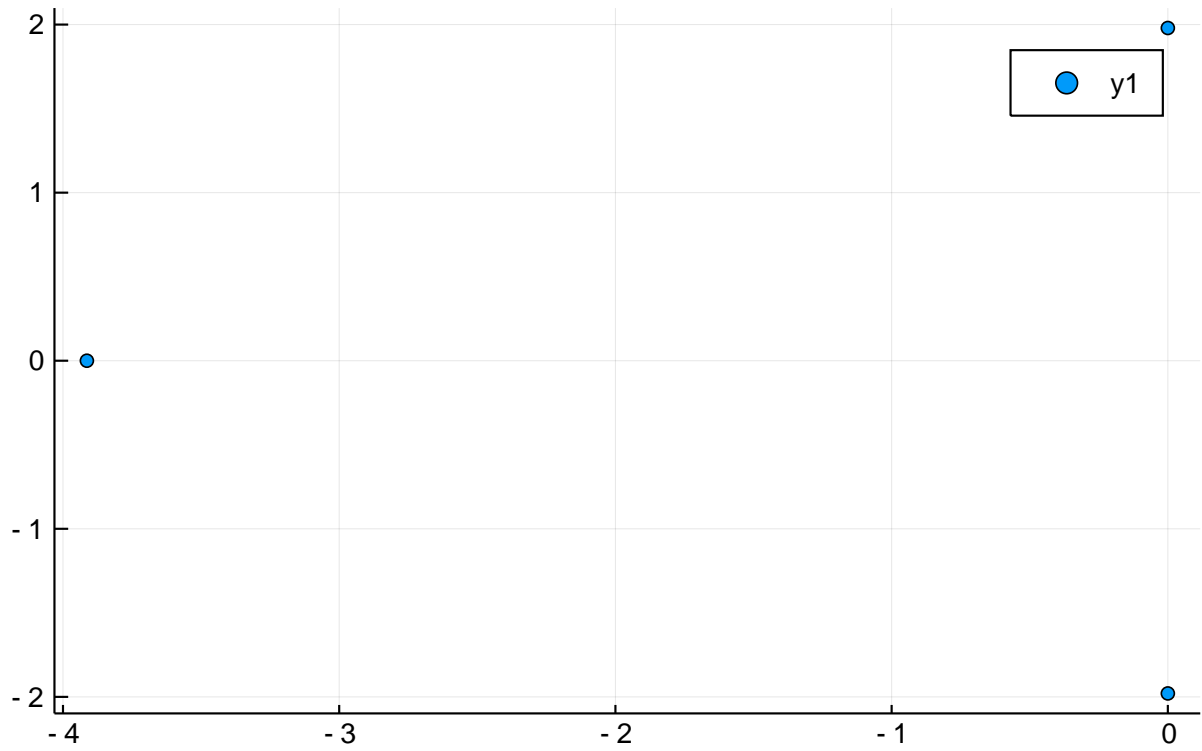
Case 2: Implicit Midpoint: Boundary Case



Now I am going to plot $h \cdot \lambda$ for the largest values of h possible to try to get at least a few points of the stability curve.... I know Its not great but Its what I've got right now...

```
scatter(real([lamda3*.0053494,lamda1*1.9796,lamda2*1.9796]),imag([lamda3*.0053494,lamda1*1.9796,lamda2*1.9796]),  
        title!("ImplicitMidPoint"))
```

ImplicitMidPoint



```
scatter(real([lamda3*1,lamda1*.25,lamda2*.25]),imag([lamda3*1,lamda1*.25,lamda2*.25]))  
title!("Adams Basthforth")
```

Adams Basthforth

