



## Introduction

This application note is intended for system designers who require a hardware implementation overview of the development board features such as the power supply, the clock management, the reset control, the boot mode settings and the debug management. It shows how to use the low-density, medium-density, high-density, and connectivity line STM32F10xxx product families and describes the minimum hardware resources required to develop an STM32F10xxx application.

Detailed reference design schematics are also contained in this document with descriptions of the main components, interfaces and modes.

## Glossary

- **Low-density devices** are STM32F101xx, STM32F102xx and STM32F103xx microcontrollers where the Flash memory density ranges between 16 and 32 Kbytes.
- **Medium-density devices** are STM32F101xx, STM32F102xx and STM32F103xx microcontrollers where the Flash memory density ranges between 64 and 128 Kbytes.
- **High-density devices** are STM32F101xx and STM32F103xx microcontrollers where the Flash memory density ranges between 256 and 512 Kbytes.
- **Connectivity line devices** are STM32F105xx and STM32F107xx microcontrollers.

# Contents

<b>1</b>	<b>Power supplies</b>	<b>6</b>
1.1	Introduction	6
1.1.1	Independent A/D converter supply and reference voltage	6
1.1.2	Battery backup	7
1.1.3	Voltage regulator	7
1.2	Power supply schemes	7
1.3	Reset & power supply supervisor	8
1.3.1	Power on reset (POR) / power down reset (PDR)	8
1.3.2	Programmable voltage detector (PVD)	9
1.3.3	System reset	9
<b>2</b>	<b>Clocks</b>	<b>11</b>
2.1	HSE OSC clock	11
2.1.1	External source (HSE bypass)	11
2.1.2	External crystal/ceramic resonator (HSE crystal)	12
2.2	LSE OSC clock	12
2.2.1	External source (LSE bypass)	13
2.2.2	External crystal/ceramic resonator (LSE crystal)	13
2.3	Clock security system (CSS)	13
<b>3</b>	<b>Boot configuration</b>	<b>14</b>
3.1	Boot mode selection	14
3.2	Boot pin connection	14
3.3	Embedded Boot Loader mode	15
<b>4</b>	<b>Debug management</b>	<b>16</b>
4.1	Introduction	16
4.2	SWJ debug port (serial wire and JTAG)	16
4.3	Pinout and debug port pins	16
4.3.1	SWJ debug port pins	16
4.3.2	Flexible SWJ-DP pin assignment	17
4.3.3	Internal pull-up and pull-down resistors on JTAG pins	17
4.3.4	SWJ debug port connection with standard JTAG connector	18

<b>5</b>	<b>Recommendations</b>	<b>19</b>
5.1	Printed circuit board	19
5.2	Component position	19
5.3	Ground and power supply ( $V_{SS}$ , $V_{DD}$ )	19
5.4	Decoupling	19
5.5	Other signals	20
5.6	Unused I/Os and features	20
<b>6</b>	<b>Reference design</b>	<b>21</b>
6.1	Description	21
6.1.1	Clock	21
6.1.2	Reset	21
6.1.3	Boot mode	21
6.1.4	SWJ interface	21
6.1.5	Power supply	21
6.2	Component references	22
<b>7</b>	<b>Revision history</b>	<b>26</b>

List of tables

Table 1. Boot modes. . . . . 14

Table 2. Debug port pin assignment. . . . . 17

Table 3. SWJ I/O pin availability . . . . . 17

Table 4. Mandatory components . . . . . 22

Table 5. Optional components . . . . . 22

Table 6. Reference connection for all packages. . . . . 24

Table 7. Document revision history . . . . . 26



## List of figures

Figure 1.	Power supply overview . . . . .	6
Figure 2.	Power supply scheme. . . . .	8
Figure 3.	Power on reset/power down reset waveform . . . . .	8
Figure 4.	PVD thresholds. . . . .	9
Figure 5.	Reset circuit . . . . .	10
Figure 6.	External clock . . . . .	11
Figure 7.	Crystal/ceramic resonators. . . . .	11
Figure 8.	External clock . . . . .	12
Figure 9.	Crystal/ceramic resonators <sup>(2)</sup> . . . . .	12
Figure 10.	Boot mode selection implementation example . . . . .	14
Figure 11.	Host-to-board connection . . . . .	16
Figure 12.	JTAG connector implementation . . . . .	18
Figure 13.	Typical layout for $V_{DD}/V_{SS}$ pair . . . . .	20
Figure 14.	STM32F103ZE(T6) microcontroller reference schematic. . . . .	23

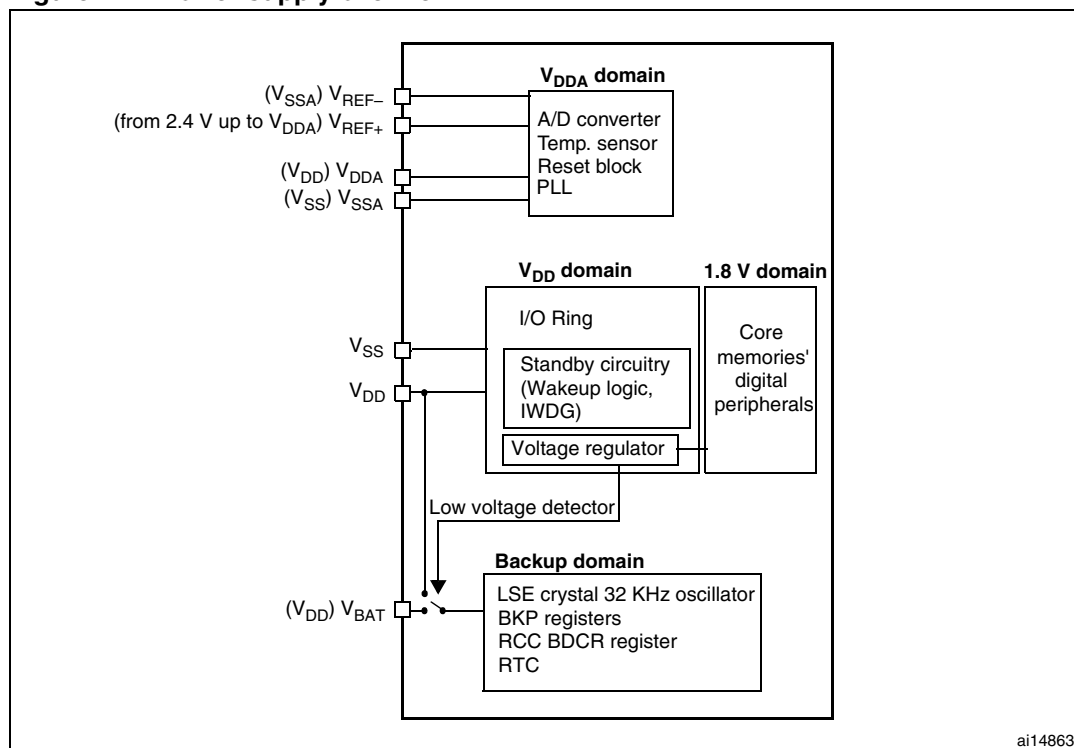
# 1 Power supplies

## 1.1 Introduction

The device requires a 2.0 V to 3.6 V operating voltage supply ( $V_{DD}$ ). An embedded regulator is used to supply the internal 1.8 V digital power.

The real-time clock (RTC) and backup registers can be powered from the  $V_{BAT}$  voltage when the main  $V_{DD}$  supply is powered off.

**Figure 1. Power supply overview**



*Note:*  $V_{DDA}$  and  $V_{SSA}$  must be connected to  $V_{DD}$  and  $V_{SS}$ , respectively.

### 1.1.1 Independent A/D converter supply and reference voltage

To improve conversion accuracy, the ADC has an independent power supply that can be filtered separately, and shielded from noise on the PCB.

- the ADC voltage supply input is available on a separate  $V_{DDA}$  pin
- an isolated supply ground connection is provided on the  $V_{SSA}$  pin

When available (depending on package),  $V_{REF-}$  must be tied to  $V_{SSA}$ .

#### On 100-pin and 144-pin packages

To ensure a better accuracy on low-voltage inputs, the user can connect a separate external reference voltage ADC input on  $V_{REF+}$ . The voltage on  $V_{REF+}$  may range from 2.4 V to  $V_{DDA}$ .

### On packages with 64 pins or less

The  $V_{REF+}$  and  $V_{REF-}$  pins are not available, they are internally connected to the ADC voltage supply ( $V_{DDA}$ ) and ground ( $V_{SSA}$ ).

#### 1.1.2 Battery backup

To retain the content of the Backup registers when  $V_{DD}$  is turned off, the  $V_{BAT}$  pin can be connected to an optional standby voltage supplied by a battery or another source.

The  $V_{BAT}$  pin also powers the RTC unit, allowing the RTC to operate even when the main digital supply ( $V_{DD}$ ) is turned off. The switch to the  $V_{BAT}$  supply is controlled by the power down reset (PDR) circuitry embedded in the Reset block.

If no external battery is used in the application, it is highly recommended to connect  $V_{BAT}$  externally to  $V_{DD}$ .

#### 1.1.3 Voltage regulator

The voltage regulator is always enabled after reset. It works in three different modes depending on the application modes.

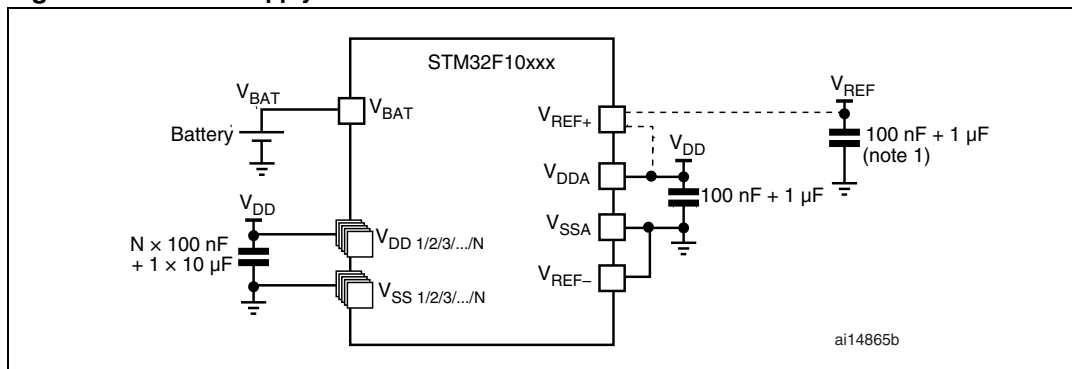
- in Run mode, the regulator supplies full power to the 1.8 V domain (core, memories and digital peripherals)
- in Stop mode, the regulator supplies low power to the 1.8 V domain, preserving the contents of the registers and SRAM
- in Standby mode, the regulator is powered off. The contents of the registers and SRAM are lost except for those concerned with the Standby circuitry and the Backup domain.

## 1.2 Power supply schemes

The circuit is powered by a stabilized power supply,  $V_{DD}$ .

- Caution:
  - If the ADC is used, the  $V_{DD}$  range is limited to 2.4 V to 3.6 V
  - If the ADC is not used, the  $V_{DD}$  range is 2.0 V to 3.6 V
- The  $V_{DD}$  pins must be connected to  $V_{DD}$  with external decoupling capacitors (eleven 100 nF Ceramic capacitor + one Tantalum or Ceramic capacitor (min. 4.7  $\mu$ F typ. 10  $\mu$ F)).
- The  $V_{BAT}$  pin can be connected to the external battery (1.8 V <  $V_{BAT}$  < 3.6 V). If no external battery is used, it is recommended to connect this pin to  $V_{DD}$  with a 100 nF external ceramic decoupling capacitor.
- The  $V_{DDA}$  pin must be connected to two external decoupling capacitors (100 nF Ceramic + 1  $\mu$ F Tantalum or Ceramic).
- The  $V_{REF+}$  pin can be connected to the  $V_{DDA}$  external power supply. If a separate, external reference voltage is applied on  $V_{REF+}$ , a 100 nF and a 1  $\mu$ F capacitors must be connected on this pin. In all cases,  $V_{REF+}$  must be kept between 2.4 V and  $V_{DDA}$ .
- Additional precautions can be taken to filter analog noise:
  - $V_{DDA}$  can be connected to  $V_{DD}$  through a ferrite bead.
  - The  $V_{REF+}$  pin can be connected to  $V_{DDA}$  through a resistor (typ. 47  $\Omega$ ).

**Figure 2. Power supply scheme**



- Optional. If a separate, external reference voltage is connected on  $V_{REF+}$ , the two capacitors (100 nF and 1  $\mu$ F) must be connected.
- $V_{REF+}$  is either connected to  $V_{DDA}$  or to  $V_{REF}$ .
- N is the number of  $V_{DD}$  and  $V_{SS}$  inputs.

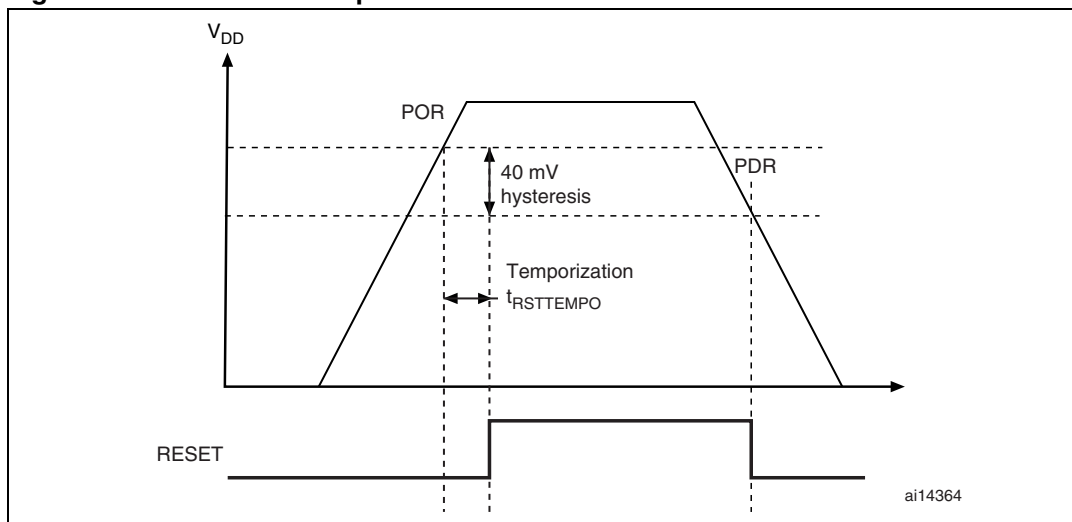
### 1.3 Reset & power supply supervisor

### 1.3.1 Power on reset (POR) / power down reset (PDR)

The device has an integrated POR/PDR circuitry that allows proper operation starting from 2 V.

The device remains in the Reset mode as long as  $V_{DD}$  is below a specified threshold,  $V_{POR/PDR}$ , without the need for an external reset circuit. For more details concerning the power on/power down reset threshold, refer to the electrical characteristics in the low-density, medium-density, high-density, and connectivity line STM32F10xxx datasheets.

**Figure 3. Power on reset/power down reset waveform**





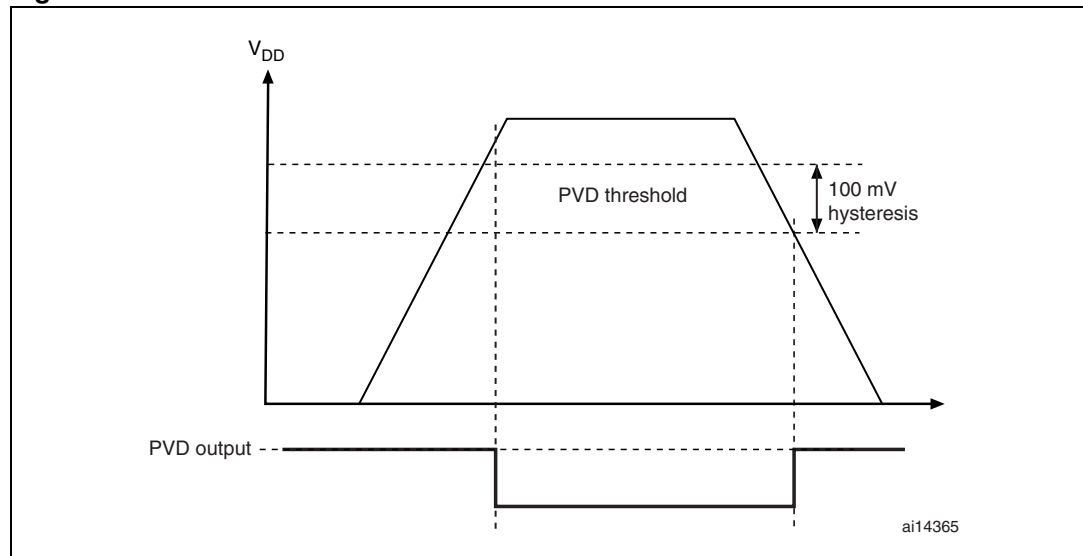
### 1.3.2 Programmable voltage detector (PVD)

You can use the PVD to monitor the  $V_{DD}$  power supply by comparing it to a threshold selected by the PLS[2:0] bits in the Power control register (PWR\_CR).

The PVD is enabled by setting the PVDE bit.

A PVDO flag is available, in the Power control/status register (PWR\_CSR), to indicate whether  $V_{DD}$  is higher or lower than the PVD threshold. This event is internally connected to EXTI Line16 and can generate an interrupt if enabled through the EXTI registers. The PVD output interrupt can be generated when  $V_{DD}$  drops below the PVD threshold and/or when  $V_{DD}$  rises above the PVD threshold depending on the EXTI Line16 rising/falling edge configuration. As an example the service routine can perform emergency shutdown tasks.

**Figure 4. PVD thresholds**



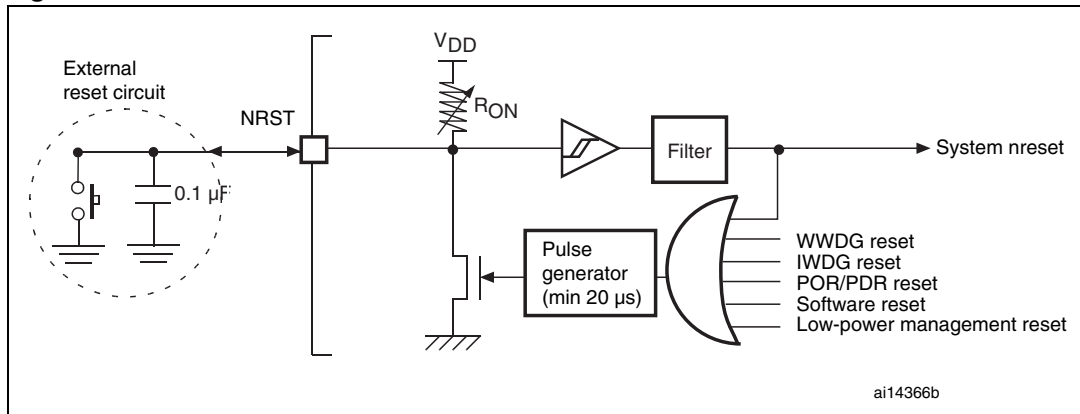
### 1.3.3 System reset

A system reset sets all registers to their reset values except for the reset flags in the clock controller CSR register and the registers in the Backup domain (see [Figure 1](#)).

A system reset is generated when one of the following events occurs:

1. A low level on the NRST pin (external reset)
2. window watchdog end-of-count condition (WWDG reset)
3. Independent watchdog end-of-count condition (IWDG reset)
4. A software reset (SW reset)
5. Low-power management reset

The reset source can be identified by checking the reset flags in the Control/Status register, RCC\_CSR.

**Figure 5. Reset circuit**

## 2 Clocks

Three different clock sources can be used to drive the system clock (SYSCLK):

- HSI oscillator clock (high-speed internal clock signal)
- HSE oscillator clock (high-speed external clock signal)
- PLL clock

The devices have two secondary clock sources:

- 40 kHz low-speed internal RC (LSI RC) that drives the independent watchdog and, optionally, the RTC used for Auto-wakeup from the Stop/Standby modes.
- 32.768 kHz low-speed external crystal (LSE crystal) that optionally drives the real-time clock (RTCCLK)

Each clock source can be switched on or off independently when it is not used, to optimize the power consumption.

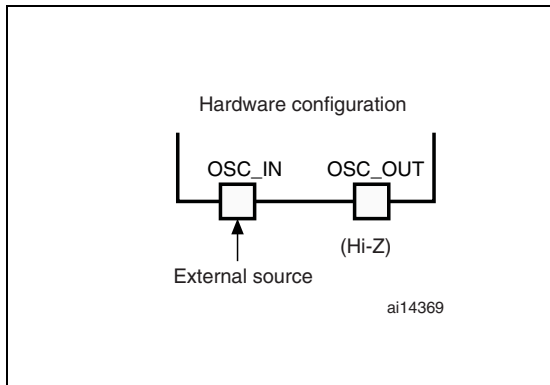
Refer to the STM32F10xxx reference manual RM0008 for a description of the clock tree.

### 2.1 HSE OSC clock

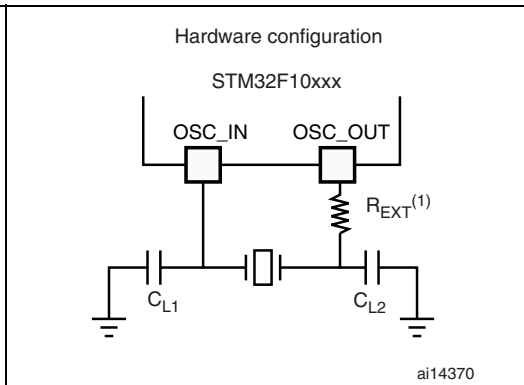
The high-speed external clock signal (HSE) can be generated from two possible clock sources:

- HSE external crystal/ceramic resonator (see [Figure 7](#))
- HSE user external clock (see [Figure 6](#))

**Figure 6. External clock**



**Figure 7. Crystal/ceramic resonators**



1. The value of  $R_{EXT}$  depends on the crystal characteristics. Typical value is in the range of 5 to 6  $R_S$  (resonator series resistance).
2. Load capacitance  $C_L$  has the following formula:  $C_L = C_{L1} \times C_{L2} / (C_{L1} + C_{L2}) + C_{stray}$  where:  $C_{stray}$  is the pin capacitance and board or trace PCB-related capacitance. Typically, it is between 2 pF and 7 pF. Please refer to [Section 5: Recommendations on page 19](#) to minimize its value.

#### 2.1.1 External source (HSE bypass)

In this mode, an external clock source must be provided. It can have a frequency of up to 25 MHz for high, medium and low-density devices, and up to 50 MHz for connectivity line devices. The external clock signal (square, sine or triangle) with a duty cycle of about 50%,

has to drive the OSC\_IN pin while the OSC\_OUT pin must be left in the high impedance state (see [Figure 7](#) and [Figure 6](#)).

### 2.1.2 External crystal/ceramic resonator (HSE crystal)

The external oscillator frequency ranges from 4 to 16 MHz on high, medium and low-density devices, and from 3 to 25 MHz on connectivity line devices.

The external oscillator has the advantage of producing a very accurate rate on the main clock. The associated hardware configuration is shown in [Figure 7](#).

The resonator and the load capacitors have to be connected as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. The load capacitance values must be adjusted according to the selected oscillator.

For  $C_{L1}$  and  $C_{L2}$  it is recommended to use high-quality ceramic capacitors in the 5 pF-to-25 pF range (typ.), designed for high-frequency applications and selected to meet the requirements of the crystal or resonator.  $C_{L1}$  and  $C_{L2}$  are usually the same value. The crystal manufacturer typically specifies a load capacitance that is the series combination of  $C_{L1}$  and  $C_{L2}$ . The PCB and MCU pin capacitances must be included when sizing  $C_{L1}$  and  $C_{L2}$  (10 pF can be used as a rough estimate of the combined pin and board capacitance).

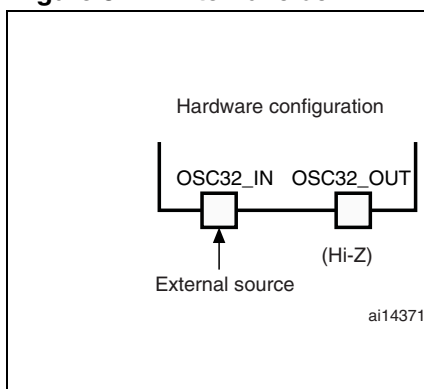
Refer to the electrical characteristics sections in the high, medium, low-density, and connectivity line STM32F10xxx datasheets for more details.

## 2.2 LSE OSC clock

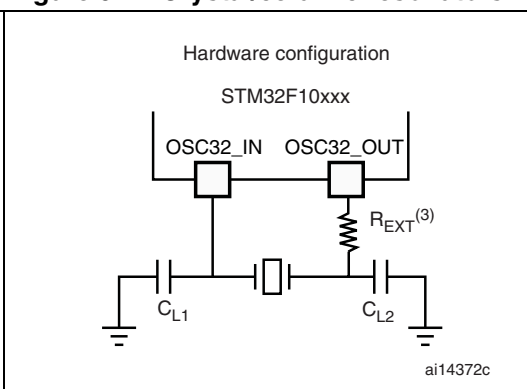
The low-speed external clock signal (LSE) can be generated from two possible clock sources:

- LSE external crystal/ceramic resonator (see [Figure 9](#))
- LSE user external clock (see [Figure 8](#))

**Figure 8. External clock<sup>(1)(2)</sup>**



**Figure 9. Crystal/ceramic resonators<sup>(2)</sup>**



1. To avoid exceeding the maximum value of  $C_{L1}$  and  $C_{L2}$  (15 pF) it is strongly recommended to use a resonator with a load capacitance  $C_L \leq 7$  pF. Never use a resonator with a load capacitance of 12.5 pF.
2. OSC32\_IN and OSC\_OUT pins can be used also as GPIO, but it is recommended not to use them as both RTC and GPIO pins in the same application.
3. The value of  $R_{EXT}$  depends on the crystal characteristics. A  $0 \Omega$  resistor would work but would not be optimal. Typical value is in the range of 5 to 6  $R_S$  (resonator series resistance). To fine tune  $R_S$  value refer to AN2867 - Oscillator design guide for ST microcontrollers.

### 2.2.1 External source (LSE bypass)

In this mode, an external clock source must be provided. It must have a frequency of 32.768 kHz. The external clock signal (square, sine or triangle) with a duty cycle of about 50% has to drive the OSC32\_IN pin while the OSC32\_OUT pin must be left high impedance (see [Figure 9](#) and [Figure 8](#)).

### 2.2.2 External crystal/ceramic resonator (LSE crystal)

The LSE crystal is a 32.768 kHz low-speed external crystal or ceramic resonator. It has the advantage of providing a low-power, but highly accurate clock source to the real-time clock peripheral (RTC) for clock/calendar or other timing functions.

The resonator and the load capacitors have to be connected as close as possible to the oscillator pins in order to minimize output distortion and start-up stabilization time. The load capacitance values must be adjusted according to the selected oscillator.

## 2.3 Clock security system (CSS)

The clock security system can be activated by software. In this case, the clock detector is enabled after the HSE oscillator startup delay, and disabled when this oscillator is stopped.

- If a failure is detected on the HSE oscillator clock, the oscillator is automatically disabled. A clock failure event is sent to the break input of the TIM1 advanced control timer and an interrupt is generated to inform the software about the failure (clock security system interrupt CSSI), allowing the MCU to perform rescue operations. The CSSI is linked to the Cortex™-M3 NMI (non-maskable interrupt) exception vector.
- If the HSE oscillator is used directly or indirectly as the system clock (indirectly means that it is used as the PLL input clock, and the PLL clock is used as the system clock), a detected failure causes a switch of the system clock to the HSI oscillator and the disabling of the external HSE oscillator. If the HSE oscillator clock (divided or not) is the clock entry of the PLL used as system clock when the failure occurs, the PLL is disabled too.

For details, see the STM32F10xxx reference manual available from the STMicroelectronics website [www.st.com](http://www.st.com).

## 3 Boot configuration

### 3.1 Boot mode selection

In the STM32F10xxx, three different boot modes can be selected by means of the BOOT[1:0] pins as shown in [Table 1](#).

**Table 1. Boot modes**

BOOT mode selection pins		Boot mode	Aliasing
BOOT1	BOOT0		
x	0	Main Flash memory	Main Flash memory is selected as boot space
0	1	System memory	System memory is selected as boot space
1	1	Embedded SRAM	Embedded SRAM is selected as boot space

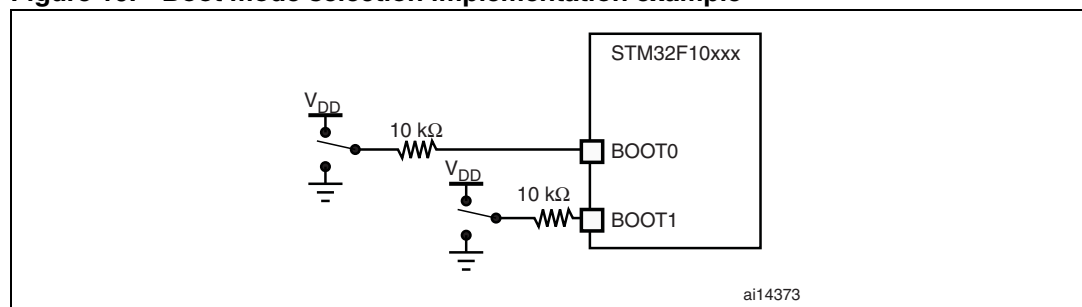
The values on the BOOT pins are latched on the 4<sup>th</sup> rising edge of SYSCCLK after a reset. It is up to the user to set the BOOT1 and BOOT0 pins after reset to select the required boot mode.

The BOOT pins are also resampled when exiting the Standby mode. Consequently, they must be kept in the required Boot mode configuration in the Standby mode. After this startup delay has elapsed, the CPU fetches the top-of-stack value from address 0x0000 0000, and starts code execution from the boot memory starting from 0x0000 0004.

### 3.2 Boot pin connection

[Figure 10](#) shows the external connection required to select the boot memory of the STM32F10xxx.

**Figure 10. Boot mode selection implementation example**



1. Resistor values are given only as a typical example.

### 3.3 Embedded Boot Loader mode

The Embedded Boot Loader mode is used to reprogram the Flash memory using one of the available serial interfaces:

- In low-, medium- and high-density devices the bootloader is activated through the USART1 interface. For further details please refer to AN2606.
- In connectivity line devices the bootloader can be activated through one of the following interfaces: USART1, USART2 (remapped), CAN2 (remapped) or USB OTG FS in Device mode (DFU: device firmware upgrade).  
The USART peripheral operates with the internal 8 MHz oscillator (HSI). The CAN and USB OTG FS, however, can only function if an external 8 MHz, 14.7456 MHz or 25 MHz clock (HSE) is present. For further details, please refer to AN2662.

This embedded boot loader is located in the System memory and is programmed by ST during production.

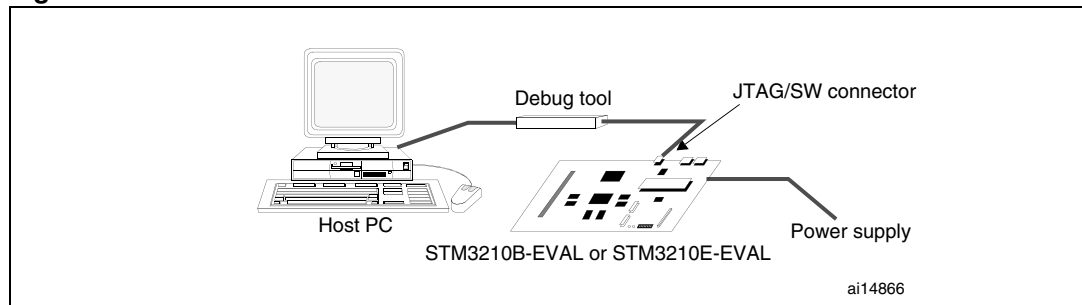
## 4 Debug management

### 4.1 Introduction

The Host/Target interface is the hardware equipment that connects the host to the application board. This interface is made of three components: a hardware debug tool, a JTAG or SW connector and a cable connecting the host to the debug tool.

[Figure 11](#) shows the connection of the host to the evaluation board (STM3210B-EVAL, STM3210C-EVAL, STM3210E-EVAL, or board).

**Figure 11. Host-to-board connection**



### 4.2 SWJ debug port (serial wire and JTAG)

The STM32F10xxx core integrates the serial wire / JTAG debug port (SWJ-DP). It is an ARM® standard CoreSight™ debug port that combines a JTAG-DP (5-pin) interface and a SW-DP (2-pin) interface.

- The JTAG debug port (JTAG-DP) provides a 5-pin standard JTAG interface to the AHP-AP port
- The serial wire debug port (SW-DP) provides a 2-pin (clock + data) interface to the AHP-AP port

In the SWJ-DP, the two JTAG pins of the SW-DP are multiplexed with some of the five JTAG pins of the JTAG-DP.

### 4.3 Pinout and debug port pins

The STM32F10xxx MCU is offered in various packages with different numbers of available pins. As a result, some functionality related to the pin availability may differ from one package to another.

#### 4.3.1 SWJ debug port pins

Five pins are used as outputs for the SWJ-DP as *alternate functions* of general-purpose I/Os (GPIOs). These pins, shown in [Table 2](#), are available on all packages.



**Table 2. Debug port pin assignment**

SWJ-DP pin name	JTAG debug port		SW debug port		Pin assignment
	Type	Description	Type	Debug assignment	
JTMS/SWDIO	I	JTAG test mode selection	I/O	Serial wire data input/output	PA13
JTCK/SWCLK	I	JTAG test clock	I	Serial wire clock	PA14
JTDI	I	JTAG test data input	-	-	PA15
JTDO/TRACESWO	O	JTAG test data output	-	TRACESWO if async trace is enabled	PB3
JNTRST	I	JTAG test nReset	-	-	PB4

### 4.3.2 Flexible SWJ-DP pin assignment

After reset (SYSRESETn or PORESETn), all five pins used for the SWJ-DP are assigned as dedicated pins immediately usable by the debugger host (note that the trace outputs are not assigned except if explicitly programmed by the debugger host).

However, the STM32F10xxx MCU implements a register to disable some part or all of the SWJ-DP port, and so releases the associated pins for general-purpose I/Os usage. This register is mapped on an APB bridge connected to the Cortex™-M3 system bus. This register is programmed by the user software program and not by the debugger host.

**Table 3. SWJ I/O pin availability**

Available Debug ports	SWJ I/O pin assigned				
	PA13 / JTMS / SWDIO	PA14 / JTCK / SWCLK	PA15 / JTDI	PB3 / JTDO	PB4 / JNTRST
Full SWJ (JTAG-DP + SW-DP) - reset state	X	X	X	X	X
Full SWJ (JTAG-DP + SW-DP) but without JNTRST	X	X	X	X	
JTAG-DP disabled and SW-DP enabled	X	X			
JTAG-DP disabled and SW-DP disabled	Released				

*Table 3* shows the different possibilities to release some pins.

For more details, see the STM32F10xxx reference manual, available from the STMicroelectronics website [www.st.com](http://www.st.com).

### 4.3.3 Internal pull-up and pull-down resistors on JTAG pins

The JTAG input pins must *not* be floating since they are directly connected to flip-flops to control the debug mode features. Special care must be taken with the SWCLK/TCK pin that is directly connected to the clock of some of these flip-flops.

To avoid any uncontrolled I/O levels, the STM32F10xxx embeds internal pull-up and pull-down resistors on JTAG input pins:

- JNTRST: Internal pull-up
- JTDI: Internal pull-up
- JTMS/SWDIO: Internal pull-up
- TCK/SWCLK: Internal pull-down

Once a JTAG I/O is released by the user software, the GPIO controller takes control again. The reset states of the GPIO control registers put the I/Os in the equivalent state:

- JNTRST: Input pull-up
- JTDI: Input pull-up
- JTMS/SWDIO: Input pull-up
- JTCK/SWCLK: Input pull-down
- JTDO: Input floating

The software can then use these I/Os as standard GPIOs.

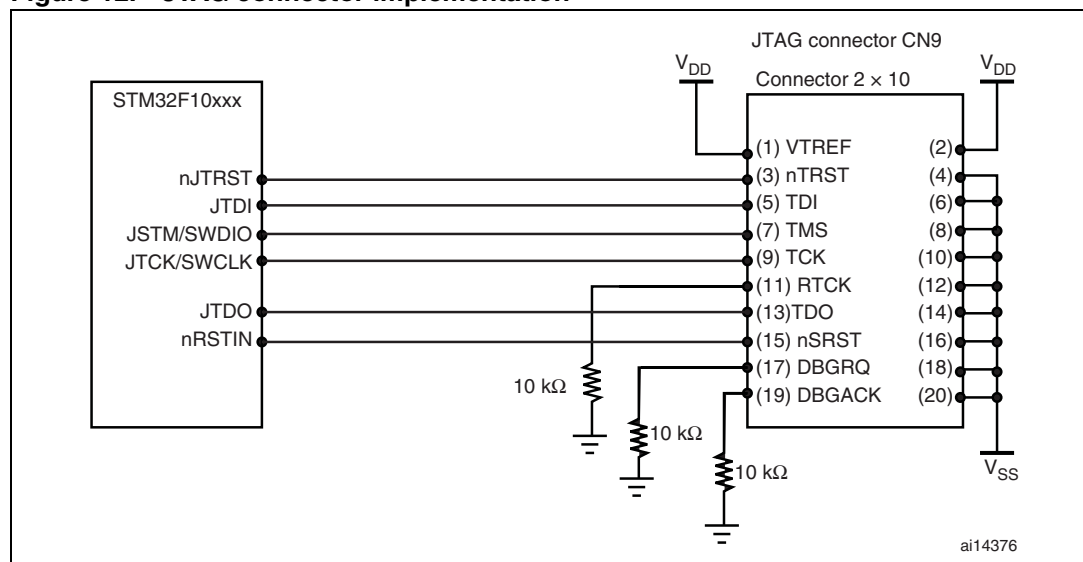
*Note: The JTAG IEEE standard recommends to add pull-up resistors on TDI, TMS and nTRST but there is no special recommendation for TCK. However, for the STM32F10xxx, an integrated pull-down resistor is used for JTCK.*

*Having embedded pull-up and pull-down resistors removes the need to add external resistors.*

#### 4.3.4 SWJ debug port connection with standard JTAG connector

Figure 12 shows the connection between the STM32F10xxx and a standard JTAG connector.

**Figure 12. JTAG connector implementation**



## 5 Recommendations

### 5.1 Printed circuit board

For technical reasons, it is best to use a multilayer printed circuit board (PCB) with a separate layer dedicated to ground ( $V_{SS}$ ) and another dedicated to the  $V_{DD}$  supply. This provides good decoupling and a good shielding effect. For many applications, economical reasons prohibit the use of this type of board. In this case, the major requirement is to ensure a good structure for ground and for the power supply.

### 5.2 Component position

A preliminary layout of the PCB must separate the different circuits according to their EMI contribution in order to reduce cross-coupling on the PCB, that is noisy, high-current circuits, low-voltage circuits, and digital components.

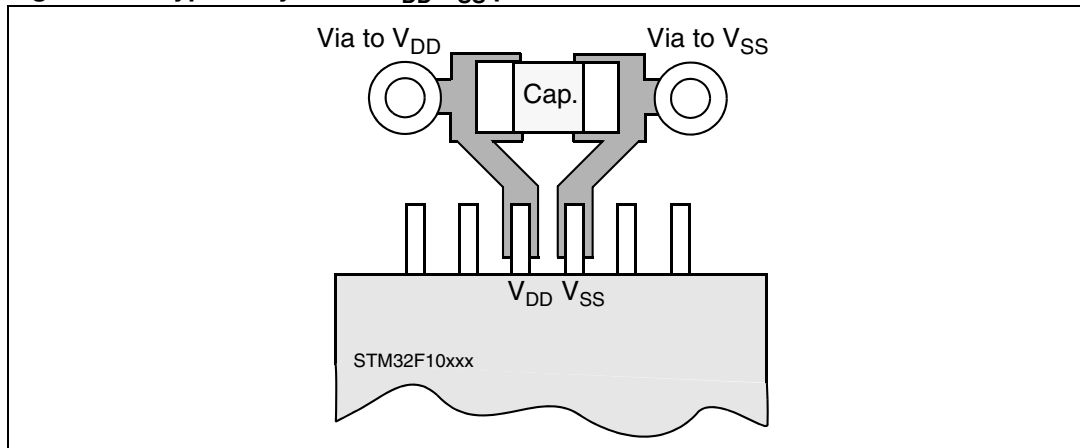
### 5.3 Ground and power supply ( $V_{SS}$ , $V_{DD}$ )

Every block (noisy, low-level sensitive, digital, etc.) should be grounded individually and all ground returns should be to a single point. Loops must be avoided or have a minimum area. The power supply should be implemented close to the ground line to minimize the area of the supply loop. This is due to the fact that the supply loop acts as an antenna, and is therefore the main transmitter and receiver of EMI. All component-free PCB areas must be filled with additional grounding to create a kind of shielding (especially when using single-layer PCBs).

### 5.4 Decoupling

All pins need to be properly connected to the power supplies. These connections, including pads, tracks and vias should have as low an impedance as possible. This is typically achieved with thick track widths and, preferably, the use of dedicated power supply planes in multilayer PCBs.

In addition, each power supply pair should be decoupled with filtering ceramic capacitors  $C$  (100 nF) and a chemical capacitor  $C$  of about 10  $\mu$ F connected in parallel on the STM32F10xxx device. These capacitors need to be placed as close as possible to, or below, the appropriate pins on the underside of the PCB. Typical values are 10 nF to 100 nF, but exact values depend on the application needs. [Figure 13](#) shows the typical layout of such a  $V_{DD}/V_{SS}$  pair.

**Figure 13. Typical layout for  $V_{DD}/V_{SS}$  pair**

## 5.5 Other signals

When designing an application, the EMC performance can be improved by closely studying:

- sigNals for which a temporary disturbance affects the running process permanently (the case of interrupts and handshaking strobe signals, and not the case for LED commands).  
For these signals, a surrounding ground trace, shorter lengths and the absence of noisy and sensitive traces nearby (crosstalk effect) improve EMC performance.  
For digital signals, the best possible electrical margin must be reached for the two logical states and slow Schmitt triggers are recommended to eliminate parasitic states.
- Noisy signals (clock, etc.)
- Sensitive signals (high impedance, etc.)

## 5.6 Unused I/Os and features

All microcontrollers are designed for a variety of applications and often a particular application does not use 100% of the MCU resources.

To increase EMC performance, unused clocks, counters or I/Os, should not be left free, e.g. I/Os should be set to "0" or "1" (pull-up or pull-down to the unused I/O pins.) and unused features should be "frozen" or disabled.

## 6 Reference design

### 6.1 Description

The reference design shown in [Figure 14](#), is based on the STM32F103ZE(T6), a highly integrated microcontroller running at 72 MHz, that combines the new Cortex™-M3 32-bit RISC CPU core with 512 Kbytes of embedded Flash memory and up to 64 Kbytes of high-speed SRAM.

This reference design can be tailored to any other STM32F10xxx device with different package, using the pins correspondence given in [Table 6: Reference connection for all packages](#).

#### 6.1.1 Clock

Two clock sources are used for the microcontroller:

- LSE: X1– 32.768 kHz crystal for the embedded RTC
- HSE: X2– 8 MHz crystal for the STM32F10xxx microcontroller

Refer to [Section 2: Clocks on page 11](#).

#### 6.1.2 Reset

The reset signal in [Figure 14](#) is active low. The reset sources include:

- Reset button (B1)
- Debugging tools via the connector CN1

Refer to [Section 1.3: Reset & power supply supervisor on page 8](#).

#### 6.1.3 Boot mode

The boot option is configured by setting switches SW2 (Boot 0) and SW1 (Boot 1). Refer to [Section 3: Boot configuration on page 14](#).

*Note:* In low-power mode (more specially in Standby mode) the boot mode is mandatory to be able to connect to tools (the device should boot from the SRAM).

#### 6.1.4 SWJ interface

The reference design shows the connection between the STM32F10xxx and a standard JTAG connector. Refer to [Section 4: Debug management on page 16](#).

*Note:* It is recommended to connect the reset pins so as to be able to reset the application from the tools.

#### 6.1.5 Power supply

Refer to [Section 1: Power supplies on page 6](#).

## 6.2 Component references

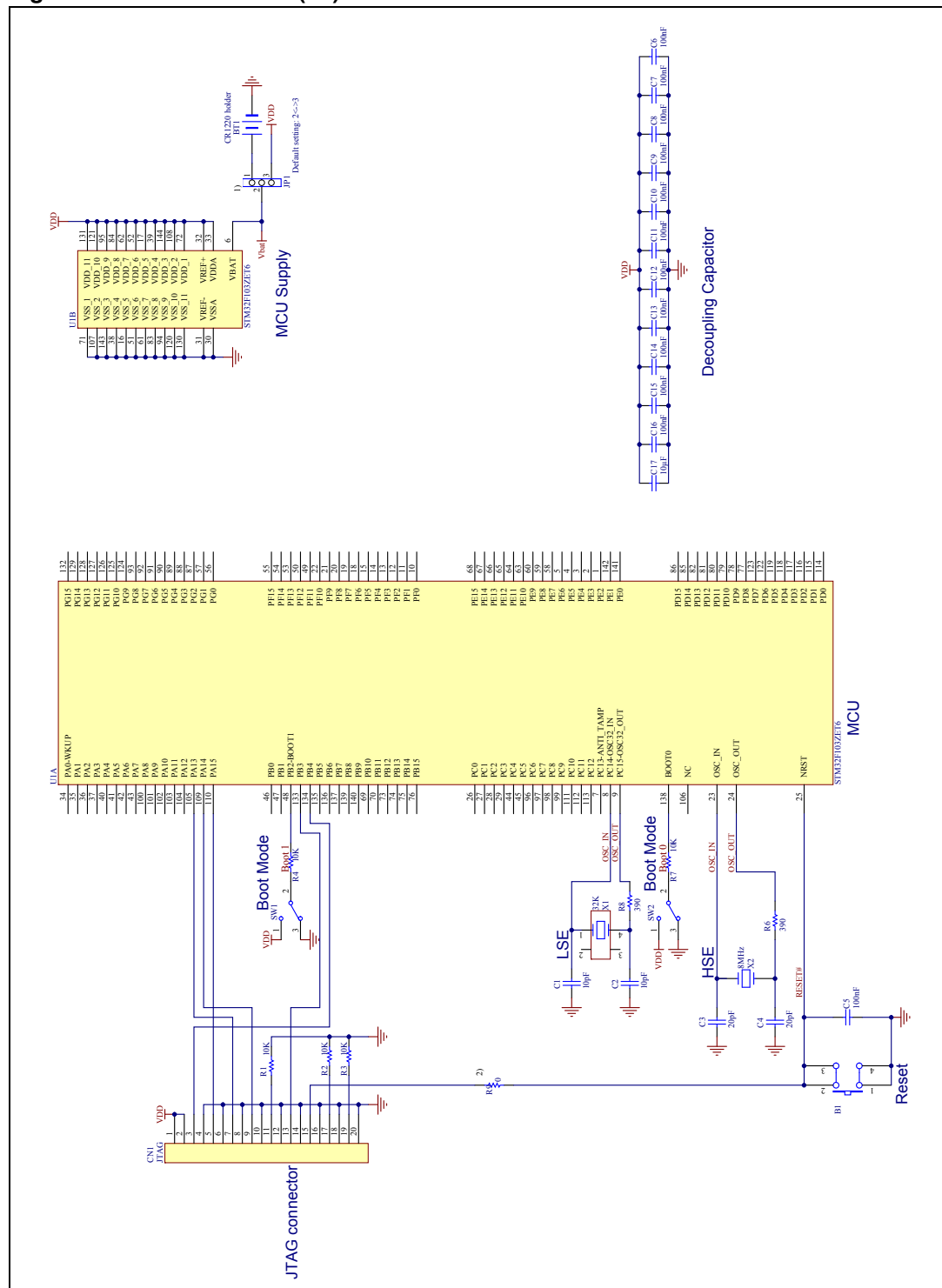
**Table 4. Mandatory components**

Id	Components name	Reference	Quantity	Comments
1	Microcontroller	STM32F103ZE(T6)	1	144-pin package
2	Capacitors	100 nF	11	Ceramic capacitors (decoupling capacitors)
3	Capacitor	10 $\mu$ F	1	Ceramic capacitor (decoupling capacitor)

**Table 5. Optional components**

Id	Components name	Reference	Quantity	Comments
1	Resistor	10 k $\Omega$	5	pull-up and pull-down for JTAG and Boot mode.
2	Resistor	390 $\Omega$	1	Used for HSE: the value depends on the crystal characteristics. This resistor value is given only as a typical example.
3	Resistor	0 $\Omega$	1	Used for LSE: the value depends on the crystal characteristics. This resistor value is given only as a typical example.
4	Capacitor	100 nF	1	Ceramic capacitor
5	Capacitor	10 pF	2	Used for LSE: the value depends on the crystal characteristics.
6	Capacitor	20 pF	2	Used for HSE: the value depends on the crystal characteristics.
7	Quartz	8 MHz	1	Used for HSE
8	Quartz	32 kHz	1	Used for LSE
9	JTAG connector	HE10	1	
10	Battery	3V3	1	If no external battery is used in the application, it is recommended to connect V <sub>BAT</sub> externally to V <sub>DD</sub>
11	Switch	3V3	2	Used to select the right boot mode
12	Push-button	B1	1	

**Figure 14. STM32F103ZE(T6) microcontroller reference schematic**



1. If no external battery is used in the application, it is recommended to connect  $V_{BAT}$  externally to  $V_{DD}$ .
2. To be able to reset the device from the tools this resistor has to be kept.

**Table 6. Reference connection for all packages**

Pin name	Pin numbers for LQFP packages				Pin numbers for BGA packages		Pin numbers for VFQFPN package
	144 pins	100 pins	64 pins	48 pins	144 pins	100 pins	36 pins
OSC_IN	23	12	5	5	D1	C1	2
OSC_OUT	24	13	6	6	E1	D1	3
PC15-OSC32_OUT	9	9	4	4	C1	B1	-
PC14-OSC32_IN	8	8	3	3	B1	A1	-
BOOT0	138	94	60	44	D5	D5	35
PB2-BOOT1	48	37	28	20	J5	G5	17
NRST	25	14	7	7	F1	E1	4
PA13	105	72	46	34	A12	A10	25
PA14	109	76	49	37	A11	A9	28
PA15	110	77	50	38	A10	A8	29
PB4	134	90	56	40	A6	A6	31
PB3	133	89	55	39	A7	A7	30
V <sub>SS_1</sub>	71	49	31	23	H7	E7	18
V <sub>SS_2</sub>	107	74	47	35	G9	E6	26
V <sub>SS_3</sub>	143	99	63	47	E5	E5	36
V <sub>SS_4</sub>	38	27	18	-	G4	E4	-
V <sub>SS_5</sub>	16	10	-	-	D2	C2	-
V <sub>SS_6</sub>	51	-	-	-	H5	-	-
V <sub>SS_7</sub>	61	-	-	-	H6	-	-
V <sub>SS_8</sub>	83	-	-	-	G8	-	-
V <sub>SS_9</sub>	94	-	-	-	G10	-	-
V <sub>SS_10</sub>	120	-	-	-	E7	-	-
V <sub>SS_11</sub>	130	-	-	-	E6		-
V <sub>DD_1</sub>	72	50	32	24	G7	F7	19
V <sub>DD_2</sub>	108	75	48	36	F9		27
V <sub>DD_3</sub>	144	100	64	48	F5	F5	1
V <sub>DD_4</sub>	39	28	19	-	F4	F4	-
V <sub>DD_5</sub>	17	11	-	-	D3	D2	-
V <sub>DD_6</sub>	52	-	-	-	G5	-	-
V <sub>DD_7</sub>	62	-	-	-	G6	-	-
V <sub>DD_8</sub>	84	-	-	-	F8	-	-



**Table 6. Reference connection for all packages (continued)**

Pin name	Pin numbers for LQFP packages				Pin numbers for BGA packages		Pin numbers for VFQFPN package
	144 pins	100 pins	64 pins	48 pins	144 pins	100 pins	36 pins
V <sub>DD_9</sub>	95	-	-	-	F10	-	-
V <sub>DD_10</sub>	121	-	-	-	F7	-	-
V <sub>DD_11</sub>	131	-	-	-	F6	-	-
V <sub>REF+</sub>	32	21	-	-	L1	J1	-
V <sub>REF-</sub>	31	20	-	-	K1	H1	-
V <sub>SSA</sub>	30	19	12	8	J1	G1	-
V <sub>DDA</sub>	33	22	13	9	M1	K1	-
V <sub>BAT</sub>	6	6	1	1	C2	B2	-

## 7 Revision history

**Table 7. Document revision history**

Date	Revision	Changes
12-Jul-2007	1	Initial release.
23-May-2008	2	Application note also applicable to High-density devices. <i>Figure 1: Power supply overview</i> , <i>Figure 2: Power supply scheme</i> and <i>Figure 6: Clock overview</i> updated. Low-speed internal RC frequency modified in <i>Section 2: Clocks on page 11</i> . $V_{REF+}$ voltage range modified. <i>Table 6: Reference connection for all packages on page 24</i> added. Small text changes.
23-Jun-2009	3	Connectivity line STM32F10xxx and <i>Section : Glossary</i> added. <i>Section 1.2: Power supply schemes</i> and <i>Figure 2: Power supply scheme</i> updated. <i>Figure 5: Reset circuit</i> updated. Figure 6 Clock overview removed in <i>Section 2: Clocks</i> . <i>Note 1</i> added <i>Note 3</i> updated below <i>Figure 8: External clock</i> . <i>Section 2.1.1: External source (HSE bypass)</i> and <i>Section 2.1.2: External crystal/ceramic resonator (HSE crystal)</i> updated. Section 2.3 Clock-out capability section removed. <i>Section 3.1: Boot mode selection</i> and <i>Section 3.3: Embedded Boot Loader mode</i> updated. When no external battery is used, it is recommended to externally connect the $V_{BAT}$ pin to $V_{DD}$ . PA14 updated in <i>Table 7: Document revision history</i> . Small text changes. STM3210C-EVAL evaluation board added in <i>Section 4</i> .

**Please Read Carefully:**

Information in this document is provided solely in connection with ST products. STMicroelectronics NV and its subsidiaries ("ST") reserve the right to make changes, corrections, modifications or improvements, to this document, and the products and services described herein at any time, without notice.

All ST products are sold pursuant to ST's terms and conditions of sale.

Purchasers are solely responsible for the choice, selection and use of the ST products and services described herein, and ST assumes no liability whatsoever relating to the choice, selection or use of the ST products and services described herein.

No license, express or implied, by estoppel or otherwise, to any intellectual property rights is granted under this document. If any part of this document refers to any third party products or services it shall not be deemed a license grant by ST for the use of such third party products or services, or any intellectual property contained therein or considered as a warranty covering the use in any manner whatsoever of such third party products or services or any intellectual property contained therein.

**UNLESS OTHERWISE SET FORTH IN ST'S TERMS AND CONDITIONS OF SALE ST DISCLAIMS ANY EXPRESS OR IMPLIED WARRANTY WITH RESPECT TO THE USE AND/OR SALE OF ST PRODUCTS INCLUDING WITHOUT LIMITATION IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE (AND THEIR EQUIVALENTS UNDER THE LAWS OF ANY JURISDICTION), OR INFRINGEMENT OF ANY PATENT, COPYRIGHT OR OTHER INTELLECTUAL PROPERTY RIGHT.**

**UNLESS EXPRESSLY APPROVED IN WRITING BY AN AUTHORIZED ST REPRESENTATIVE, ST PRODUCTS ARE NOT RECOMMENDED, AUTHORIZED OR WARRANTED FOR USE IN MILITARY, AIR CRAFT, SPACE, LIFE SAVING, OR LIFE SUSTAINING APPLICATIONS, NOR IN PRODUCTS OR SYSTEMS WHERE FAILURE OR MALFUNCTION MAY RESULT IN PERSONAL INJURY, DEATH, OR SEVERE PROPERTY OR ENVIRONMENTAL DAMAGE. ST PRODUCTS WHICH ARE NOT SPECIFIED AS "AUTOMOTIVE GRADE" MAY ONLY BE USED IN AUTOMOTIVE APPLICATIONS AT USER'S OWN RISK.**

Resale of ST products with provisions different from the statements and/or technical features set forth in this document shall immediately void any warranty granted by ST for the ST product or service described herein and shall not create or extend in any manner whatsoever, any liability of ST.

ST and the ST logo are trademarks or registered trademarks of ST in various countries.

Information in this document supersedes and replaces all information previously supplied.

The ST logo is a registered trademark of STMicroelectronics. All other names are the property of their respective owners.

© 2009 STMicroelectronics - All rights reserved

STMicroelectronics group of companies

Australia - Belgium - Brazil - Canada - China - Czech Republic - Finland - France - Germany - Hong Kong - India - Israel - Italy - Japan - Malaysia - Malta - Morocco - Philippines - Singapore - Spain - Sweden - Switzerland - United Kingdom - United States of America

[www.st.com](http://www.st.com)

