OMNeT++ Installation Guide

Version 5.6.2



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Table of Contents

| 1. General Information | |
|------------------------|----|
| 2. Windows | |
| 3. macOS | |
| 4. Linux | 10 |
| 5. Ubuntu | 17 |
| 6. Fedora 25 | |
| 7. Red Hat | 23 |
| 8. OpenSUSE | 25 |
| 9. Generic Unix | 27 |
| 10. Build Options | 34 |

Chapter 1. General Information

1.1. Introduction

This document describes how to install OMNeT + + on various platforms. One chapter is dedicated to each operating system.

1.2. Supported Platforms

OMNeT++ has been tested and is supported on the following operating systems:

- Windows 7 and 10 / 64-bit
- MacOS 10.12
- Linux distributions covered in this Installation Guide

The Simulation IDE is supported on the following platforms:

- Linux x86; 64-bit
- Windows 7, 10; 64-bit
- MacOS 10.12



Simulations can be run practically on any unix-like environment with a decent and fairly up-to-date C++ compiler, for example gcc 5.x. Certain OMNeT++ features (Qtenv, parallel simulation, XML support, etc.) depend on the availability of external libraries (Tcl/Tk, MPI, LibXML or Expat, etc.)

IDE platforms are restricted because the IDE relies on a native shared library, which we compile for the above platforms and distribute in binary form for convenience.

Chapter 2. Windows

2.1. Supported Windows Versions

OMNeT++ supports 64-bit versions of Windows 7 and 10.

| s on Win- | 32-bit Windows versions |
|-----------|---|
| | dows, we recommend using |
| | 32-bit Windows versions dows, we recommend using |

2.2. Installing OMNeT++

Download the OMNeT++ source code from http://omnetpp.org. Make sure you select the Windows-specific archive, named omnetpp-5.6.2-src-windows.zip.

The package is self-contained: in addition to OMNeT++ files it includes a C++ compiler, a command-line build environment, and all libraries and programs required by OMNeT++.

Copy the OMNeT++ archive to the directory where you want to install it. Choose a directory whose full path **does not contain any space**; for example, do not put OMNeT++ under *Program Files*.

Extract the zip file. To do so, right-click the zip file in Windows Explorer, and select *Extract All* from the menu. You can also use external programs like Winzip or 7zip.

When you look into the new omnetpp-5.6.2 directory, should see directories named doc, images, include, tools, etc., and files named mingwenv.cmd, configure, Makefile, and others.

2.3. Configuring and Building OMNeT++

Start mingwenv.cmd in the omnetpp-5.6.2 directory by double-clicking it in Windows Explorer. It will bring up a console with the MSYS *bash* shell, where the path is already set to include the omnetpp-5.6.2/bin directory. On the first start of the shell, you may need to wait for the extraction of the tools directory.



If you want to start simulations from outside the shell as well (for example from Explorer), you need to add OMNeT++'s bin directory and also the bin directories in the tools folder to the path; instructions are provided later.

First, check the contents of the configure.user file to make sure it contains the settings you need. In most cases you don't need to change anything.

notepad configure.user

Then enter the following commands:

```
$ ./configure
$ make
```

The build process will create both debug and release binaries.

2.4. Verifying the Installation

You should now test all samples and check they run correctly. As an example, the *aloha* example is started by entering the following commands:

```
$ cd samples/aloha
$ ./aloha
```

By default, the samples will run using the graphical Qtenv environment. You should see GUI windows and dialogs.

2.5. Starting the IDE

OMNeT++ comes with an Eclipse-based Simulation IDE. You should be able to start the IDE by typing:

\$ omnetpp

We recommend that you start the IDE from the command-line. Yo can also create a shortcut for starting the IDE. To do so, locate the omnetpp.exe program in the omnetpp-5.6.2/ide directory in Windows Explorer, right-click it, and choose Send To > Desktop (create shortcut) from the menu. On Windows 7, you can right-click the taskbar icon while the IDE is running, and select Pin this program to taskbar from the context menu.

2.6. Environment Variables

If you want to start OMNeT++ simulations outside the shell as well (for example from Exlorer), you need to add OMNeT++'s bin, tools/win64/usr/bin and tools/ win64/mingw64/bin directories to the path.

First, open the Environment Variables dialog.

Click the Start button, then start typing environment variables into the search box. Choose *Edit environment variables for your account* when it appears in the list. The dialog comes up.

In the dialog, select path or PATH in the list, click *Edit*. Append ";<omnetpp-dir> \bin" and the other needed directories to the value (without quotes), where <omnetpp-dir> is the name of the OMNeT++ root directory (for example C:\omnetpp-5.6.2). Hit Enter to accept.

You need to log-out and then log-in for the changes to take effect.

2.7. Reconfiguring the Libraries

If you need to recompile the OMNeT++ components with different flags (e.g. different optimization), then change the top-level OMNeT++ directory, edit configure.user accordingly, then type:

```
$ ./configure
$ make clean
$ make
```

If you want to recompile just a single library, then change to the directory of the library (e.g. cd src/sim) and type:

```
$ make clean
$ make
```

By default, libraries are compiled in both debug and release mode. If you want to make release or debug builds only, use:

```
$ make MODE=release
```

or

\$ make MODE=debug

By default, shared libraries will be created. If you want to build static libraries, set SHARED_LIBS=no in configure.user and re-configure your project.

The built libraries and programs are immediately copied to the lib/ and bin/ subdirs.

2.8. Portability Issues

OMNeT++ has been tested with both the gcc and the clang compiler from the MinGW-w64 package.



MinGW/Clang 3.8 generates incorrect code when you use multiple inheritance in your code. Because of this, we do not recommend using MinGW/clang at the moment. Later versions of clang my fix this issue.

Microsoft Visual C++/ClangC2 is not supported in the Academic Edition.

2.9. Additional Packages

Note that Doxygen and GraphViz are already included in the OMNeT++ package, and do not need to be downloaded.

2.9.1. MPI

MPI is only needed if you would like to run parallel simulations.

There are several MPI implementations for Windows, and OMNeT++ does not mandate any specific one. We recommend DeinoMPI, which can be downloaded from http:// mpi.deino.net.

After installing DeinoMPI, adjust the MPI_DIR setting in OMNeT++'s configure.user, and reconfigure and recompile OMNeT++:

```
$ ./configure
$ make cleanall
$ make
```

In general, if you would like to run parallel simulations, we recommend that you use Linux, macOS, or another unix-like platform.

2.9.2. Akaroa

Akaroa 2.7.9, which is the latest version at the time of writing, does not support Windows. You may try to port it using the porting guide from the Akaroa distribution.

Chapter 3. macOS

3.1. Supported Releases

This chapter provides additional information for installing OMNeT++ on macOS.

The following releases are covered:

• macOS 10.12

3.2. Installing the Prerequisite Packages

- Install the Java Runtime from http://support.apple.com/kb/DL1572 , because masOS does not provide it by default. Additionally you must install the latest version of Java Runtime Environment from http://java.com (version 8 or later.)
- Install the command line developer tools for masOS from http://developer.apple.com/downloads/index.action?=Command%20Line%20Tools (you will need a free Apple Developer Account for the download.)

Installing additional packages will enable more functionality in OMNeT++; see the *Additional packages* section at the end of this chapter.

3.3. Additional Steps Required on macOS to Use GDB as the Debugger.

The Command Line Tools package on macOS no longer contains gcc and gdb; instead it contains the Clang compiler and lldb. (The gcc and g++ commands actually run clang.) OMNeT++ will use Clang automatically. However, the OMNeT++ IDE can only use gdb as the underlying debugger, but not lldb.

To be able to debug from the IDE, you have to install gdb from Homebrew. Alternatively, you can use XCode for debugging.

To do the former, first install the Homebrew package manager at http://brew.sh. Follow the instrunctions on the website.

Then you can install gdb:

\$ brew install gdb

macOS 10.10 and later requires that you sign the gdb executable with a self-signed certificate (or with your own certificate, if you have one.)

Start the *Keychain Access* application. Choose *Keychain Access* > *Certificate Assistant* > *Create a Certificate...* from the menu.

Choose a name (e.g. gdb-cert), set *Identity Type* to *Self Signed Root*, set *Certificate Type* to *Code Signing* and select the *Let me override defaults*. Click several times on *Continue* until you get to the *Specify a Location For The Certificate* screen, then set *Keychain* to *System*.

If you can't store the certificate in the *System* keychain, create it in the *Login* keychain, then export it. You can then import it into the *System* keychain.

Finally, using the context menu for the certificate, select *Get Info*, open the *Trust* item, and set *Code Signing* to *Always Trust*.

You must quit the *Keychain Access* application in order to use the certificate and restart the system.

Now sign the executable:

\$ sudo codesign -s gdb-cert /usr/local/bin/gdb

3.4. Downloading and Unpacking OMNeT++

Download OMNeT++ from http://omnetpp.org. Make sure you select to download the generic archive, omnetpp-5.6.2-src-macosx.tgz.

Copy the archive to the directory where you want to install it. This is usually your home directory, /Users/<you>. Open a terminal, and extract the archive using the following command:

\$ tar zxvf omnetpp-5.6.2-src-macosx.tgz

A subdirectory called omnetpp-5.6.2 will be created, containing the simulator files.

Alternatively, you can also unpack the archive using Finder.

The Terminal can be found in the Applications / Utilities folder.

3.5. Environment Variables

NOTE

OMNeT++ needs its bin/ and tools/macosx/bin directories to be in the path. To add them to PATH temporarily (in the current shell only), change into the OMNeT++ directory and source the setenv script:

```
$ cd omnetpp-5.6.2
$ . setenv
```

To set the environment variables permanently, edit .bashrc in your home directory. Use your favourite text editor to edit .bashrc, for example TextEdit:

```
$ touch ~/.bashrc
$ open -e ~/.bashrc
```

touch is needed because open -e only opens existing files. Alternatively, you can use the terminal-based *pico* editor (pico ~/.bashrc)

Add the following line at the end of the file, then save it:

```
export PATH=$HOME/omnetpp-5.6.2/bin:$HOME/omnetpp-5.6.2/tools/macosx/bin:$PATH export QT_PLUGIN_PATH=$HOME/omnetpp-5.6.2/tools/macosx/plugins
```

You need to close and re-open the terminal for the changes to take effect.

Alternatively, you can put the above line into \sim /.bash_profile, but then you need to log out and log in again for the changes to take effect.



If you use a shell other than the default one, *bash*, consult the man page of that shell to find out which startup file to edit, and how to set and export variables.

3.6. Configuring and Building OMNeT++

Check configure.user to make sure it contains the settings you need. In most cases you don't need to change anything in it.

In the top-level OMNeT++ directory, type:

\$./configure

The configure script detects installed software and configuration of your system. It writes the results into the Makefile.inc file, which will be read by the makefiles during the build process.

Normally, the configure script needs to be running under the graphical environment in order to test for wish, the Tcl/Tk shell. If you are logged in via an ssh session or you want to compile OMNeT++ without Tcl/Tk and/or Qtenv, use the command

```
$ ./configure WITH_TKENV=no WITH_QTENV=no
```

instead of plain ./configure.

If there is an error during configure, the output may give hints about what went wrong. Scroll up to see the messages. (You may need to increase the scrollback buffer size of the terminal and re-run ./configure.) The script also writes a very detailed log of its operation into config.log to help track down errors. Since config.log is very long, it is recommended that you open it in an editor and search for phrases like *error* or the name of the package associated with the problem.

When ./configure has finished, you can compile OMNeT++. Type in the terminal:

\$ make



To take advantage of multiple processor cores, add the -j4 option to the make command line.

The build process will not write anything outside its directory, so no special privileges are needed.

The make command will seemingly compile everything twice. This is because both debug and optimized versions of the libraries are built. If you only want to build one set of the libraries, specify MODE=debug or MODE=release:

```
$ make MODE=release
```

3.7. Verifying the Installation

You can now verify that the sample simulations run correctly. For example, the dyna simulation is started by entering the following commands:

```
$ cd samples/aloha
$ ./aloha
```

By default, the samples will run using the Qtenv environment. You should see nice gui windows and dialogs.

3.8. Starting the IDE

OMNeT++ comes with an Eclipse-based Simulation IDE. On macOS 10.10 (Lion) or later, the Java Runtime must be installed (see prerequisites) before you can use the IDE. Start the IDE by typing:

```
$ omnetpp
```

If you would like to be able to launch the IDE via Applications, the Dock or a desktop shortcut, do the following: open the <code>omnetpp-5.6.2</code> folder in Finder, go into the ide subfolder, create an alias for the omnetpp program there (right-click, *Make Alias*), and drag the new alias into the Applications folder, onto the Dock, or onto the desktop.

Alternatively, run one or both of the commands below:

```
$ make install-menu-item
$ make install-desktop-icon
```

which will do roughly the same.

3.9. Using the IDE

When you try to build a project in the IDE, you may get the following warning message:

Toolchain "..." is not supported on this platform or installation. Please go to the Project menu, and activate a different build configuration. (You may need to switch to the C/C++ perspective first, so that the required menu items appear in the Project menu.)

If you encounter this message, choose Project > Properties > C/C++ Build > ToolChain Editor > Current toolchain > GCC for OMNeT++.

The IDE is documented in detail in the User Guide.

3.10. Reconfiguring the Libraries

If you need to recompile the OMNeT++ components with different flags (e.g. different optimization), then change the top-level OMNeT++ directory, edit configure.user accordingly, then type:

```
$ ./configure
$ make clean
$ make
```

To take advantage of multiple processor cores, add the -j4 option to the make command line.

If you want to recompile just a single library, then change to the directory of the library (e.g. cd src/sim) and type:

```
$ make clean
$ make
```

By default, libraries are compiled in both debug and release mode. If you want to make release or debug builds only, use:

```
$ make MODE=release
```

or

\$ make MODE=debug

By default, shared libraries will be created. If you want to build static libraries, set SHARED_LIBS=no in configure.user and re-configure your project.

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|---|-----|
| N | |
| - | - / |

The built libraries and programs are immediately copied to the <code>lib/</code> and <code>bin/</code> sub-directories.

The Tcl/Tk environment uses the native Aqua version of Tcl/Tk, so you will see native widgets. However, due to problems in the Tk/Aqua port, you may experience minor UI quirks. We recommend using Qtenv whenever it is possible.

3.11. Additional Packages

3.11.1. OpenMPI

MacOS does not come with OpenMPI, so you must install it manually. You can install it from the Homebrew repo (http://brew.sh) by typing brew install open-mpi. In this case, you have to manually set the MPI_CFLAGS and MPI_LIBS variables in configure.user and re-run ./configure.

3.11.2. GraphViz

GraphViz is needed if you want to have diagrams in HTML documentation that you generate from NED files in the IDE (*Generate NED Documentation...* item in the project context menu).

You can install it from the Homebrew project (http://brew.sh) by typing brew install graphviz.

After installation, make sure that the dot program is available from the command line. Open a terminal, and type

\$ dot -V

Note the capital V. The command should normally work out of the box. If you get the "command not found" error, you need to put dot into the path. Find the dot program in the GraphViz installation directory, and soft link it into /usr/local/bin(sudo ln -s <path>/dot /usr/local/bin).

3.11.3. Doxygen

Doxygen is needed if you want to generate documentation for C++ code, as part of the HTML documentation that you generate from NED files in the IDE (*Generate NED Documentation...* item in the project context menu).

You can install it from the Homebrew project (http://brew.sh) by typing homebrew install doxygen.

After installation, ensure that the doxygen program is available from the command line. Open a terminal, and type

\$ doxygen

3.11.4. Akaroa

Akaroa 2.7.9, which is the latest version at the time of writing, does not support macOS. You may try to port it using the porting guide from the Akaroa distribution.

Chapter 4. Linux

4.1. Supported Linux Distributions

This chapter provides instructions for installing OMNeT++ on selected Linux distributions:

- Ubuntu 16.04 LTS
- Fedora Core 25
- Red Hat Enterprise Linux Desktop Workstation 7.x
- OpenSUSE 42

This chapter describes the overall process. Distro-specific information, such as how to install the prerequisite packages, are covered by distro-specific chapters.

If your Linux distribution is not listed above, you still may be able to use some distro-specific instructions in this Guide.Ubuntu derivatives (Ubuntu instructions may apply):• Kubuntu, Xubuntu, Edubuntu, ...• Linux MintSome Debian-based distros (Ubuntu instructions may apply, as Ubuntu itself is based on Debian):• Knoppix and derivatives• MepisSome Fedora-based distros (Fedora instructions may apply):• Simplis

• Eeedora

4.2. Installing the Prerequisite Packages

OMNeT++ requires several packages to be installed on the computer. These packages include the C++ compiler (gcc or clang), the Java runtime, and several other libraries and programs. These packages can be installed from the software repositories of your Linux distribution.

See the chapter specific to your Linux distribution for instructions on installing the packages needed by OMNeT++.

Generally, you will need superuser permissions to install packages.

Not all packages are available from software repositories; some (optional) ones need to be downloaded separately from their web sites, and installed manually. See the section *Additional Packages* later in this chapter.

4.3. Downloading and Unpacking

Download OMNeT++ from http://omnetpp.org. Make sure you select to download the generic archive, omnetpp-5.6.2-src.tgz.

Copy the archive to the directory where you want to install it. This is usually your home directory, /home/<you>. Open a terminal, and extract the archive using the following command:

\$ tar xvfz omnetpp-5.6.2-src.tgz

This will create an omnetpp-5.6.2 subdirectory with the OMNeT++ files in it.

4.4. Environment Variables

OMNeT++ needs its bin/ directory to be in the path. To add bin/ to PATH temporarily (in the current shell only), change into the OMNeT++ directory and source the setenv script:

\$ cd omnetpp-5.6.2
\$. setenv

The script also adds the lib/ subdirectory to LD_LIBRARY_PATH, which may be necessary on systems that don't support the rpath mechanism.

To set the environment variables permanently, edit .bashrc in your home directory. Use your favourite text editor to edit .bashrc, for example gedit:

\$ gedit ~/.bashrc

Add the following line at the end of the file, then save it:

export PATH=\$HOME/omnetpp-5.6.2/bin:\$PATH

You need to close and re-open the terminal for the changes to take effect.

Alternatively, you can put the above line into \sim /.bash_profile, but then you need to log out and log in again for the changes to take effect.

If you use a shell other than *bash*, consult the man page of that shell to find out which startup file to edit, and how to set and export variables.

Note that all Linux distributions covered in this Installation Guide use *bash* unless the user has explicitly selected another shell.

4.5. Configuring and Building OMNeT++

In the top-level OMNeT++ directory, type:

```
$ ./configure
```

The configure script detects installed software and configuration of your system. It writes the results into the Makefile.inc file, which will be read by the makefiles during the build process.

Linux

| ubuntu@ubuntu-desktop: ~/omnest-4.0 |
|--|
| <u>File Edit V</u> iew <u>T</u> erminal Ta <u>b</u> s <u>H</u> elp |
| checking for Akaroa with CFLAGS=" -02 -DNDEBUG=1 -fno-stack-protector -DXMLPAR SER=libxml " LIBS="" no |
| checking for Akaroa with CFLAGS=" -02 -DNDEBUG=1 -fno-stack-protector -DXMLPAR SER=libxml " LIBS="-lakaroa -lfl" no configure: WARNING: Optional package Akaroa not found configure: creating ./config.status |
| <pre>config.status: creating Makefile.inc config.status: creating test/core/runtest patching the ide configuration file. default workspace is: /home/ubuntu/omnest-4 .0/samples</pre> |
| WARNING: The configuration script could not detect the following packages: |
| MPI (optional) Akaroa (optional) |
| Scroll up to see the warning messages (use shift+PgUp key), and see config.log for more details. While you can use OMNEST in the current configuration, please be aware that some functionality may be unavailable or incomplete. |
| Your PATH contains /home/ubuntu/omnest-4.0/bin. Good! |
| TCL_LIBRARY is set. Good! ubuntu@ubuntu-desktop:~/omnest-4.0\$ |

Figure 4.1. Configuring OMNeT++

Normally, the configure script needs to be running under the graphical environment (X11) in order to test for wish, the Tcl/Tk shell. If you are logged in via an *ssh* session, or there is some other reason why X is not running, the easiest way to work around the problem is to tell OMNeT++ to build without Tcl/Tk and Qtenv. To do that, use the command

\$./configure WITH_TKENV=no WITH_QTENV=no

instead of plain ./configure.

If there is an error during configure, the output may give hints about what went wrong. Scroll up to see the messages. (Use Shift+PgUp; you may need to increase the scrollback buffer size of the terminal and re-run ./configure.) The script also writes a very detailed log of its operation into config.log to help track down errors. Since config.log is very long, it is recommended that you open it in an editor and search for phrases like *error* or the name of the package associated with the problem.

When ./configure has finished, you can compile OMNeT++. Type in the terminal:

\$ make

| ubuntu@ubuntu-desktop; ~/omnest-4.0 | × |
|--|---|
| <u>F</u> ile <u>E</u> dit <u>V</u> iew <u>T</u> erminal Ta <u>b</u> s <u>H</u> elp | |
| ++ -c -g -Wall -fno-stack-protector | |
| TBUILDER -IIhtdocs -I/home/ubuntu/omnest-4.0/include -o out/gcc-debug//Htt | p |
| lsg_m.o HttpMsg_m.cc | |
| ++ -c -g -Wall -fno-stack-protector -DXMLPARSER=libxml -DWITH PARSIM -DWITH | |
| TBUILDER -IIhtdocs -I/home/ubuntu/omnest-4.0/include -o out/gcc-debug//Net | P |
| t_m.o NetPkt_m.cc ++ -c -g -Wall -fno-stack-protector -DXMLPARSER=libxml -DWITH PARSIM -DWITH | N |
| TBUILDER -IIhtdocs -I/home/ubuntu/omnest-4.0/include -o out/gcc-debug//Tel | |
| tPkt m.o TelnetPkt m.cc | |
| ++ -Wl,export-dynamic -Wl,-rpath,/home/ubuntu/omnest-4.0/lib:o out/gcc-d | e |
| ug//sockets out/gcc-debug//Cloud.o out/gcc-debug//ExtHttpClient.o out/gcc-deb | |
| //ExtTelnetClient.o out/gcc-debug//HttpClient.o out/gcc-debug//HttpServer.o ou | |
| gcc-debug//QueueBase.o out/gcc-debug//SocketRTScheduler.o out/gcc-debug//Telne | t |
| lient.o out/gcc-debug//TelnetServer.o out/gcc-debug//HttpMsg_m.o out/gcc-debug | |
| NetPkt_m.o out/gcc-debug//TelnetPkt_m.o -Wl,whole-archive -Wl,no-whole-a | |
| hive -L"/home/ubuntu/omnest-4.0/lib/gcc" -L"/home/ubuntu/omnest-4.0/lib" -u _t | |
| nv_liblopptkenvdloppenvird -lopplayoutd -u _cmdenv_lib -loppcmdenvd -loppe | n |
| ird -loppsimd -ldl -lstdc++ | |
| n -s -f out/gcc-debug//sockets . | |
| ake[2]: Leaving directory `/home/ubuntu/omnest-4.0/samples/sockets' ake[1]: Leaving directory `/home/ubuntu/omnest-4.0' | |
| ake[1]. Leaving directory /nome/ubuntu/Omnest-4.0 | |
| ow you can type "omnest" to start the IDE | |
| buntu@ubuntu-desktop:~/omnest-4.0\$ | |

Figure 4.2. Building OMNeT++



To take advantage of multiple processor cores, add the $\verb-j8$ option to the <code>make</code> command line.



The build process will not write anything outside its directory, so no special privileges are needed.

The make command will seemingly compile everything twice. This is because both debug and optimized versions of the libraries are built. If you only want to build one set of the libraries, specify MODE=debug or MODE=release:

```
$ make MODE=release
```

4.6. Verifying the Installation

You can now verify that the sample simulations run correctly. For example, the dyna simulation is started by entering the following commands:

```
$ cd samples/dyna
$ ./dyna
```

By default, the samples will run using the Tcl/Tk environment. You should see nice gui windows and dialogs.

4.7. Starting the IDE

You can launch the OMNeT++ Simulation IDE by typing the following command in the terminal:

\$ omnetpp

| 2 | Simul | ation - OMNEST IDE | | | _ O × |
|---|---|--------------------------------|---------------------|---------------|------------|
| <u>F</u> ile <u>E</u> dit <u>S</u> ource <u>N</u> avigate Se <u>a</u> r | rch <u>P</u> roject <u>B</u> un <u>W</u> indow <u>H</u> | elp | | | |
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| | | | | | |
| O items selected | | | | 2 🖉 | 🔶 🖂 🐲 |

Figure 4.3. The Simulation IDE

If you would like to be able to access the IDE from the application launcher or via a desktop shortcut, run one or both of the commands below:

```
$ make install-menu-item
$ make install-desktop-icon
```

Or add a shortcut that points to the omnetpp program in the ide subdirectory by other means, for example using the Linux desktop's context menu.

4.8. Using the IDE

When you try to build a project in the IDE, you may get the following warning message:

Toolchain "..." is not supported on this platform or installation. Please go to the Project menu, and activate a different build configuration. (You may need to switch to the C/C++ perspective first, so that the required menu items appear in the Project menu.)

If you encounter this message, choose Project > Properties > C/C++ Build > ToolChain Editor > Current toolchain > GCC for OMNeT++.

The IDE is documented in detail in the User Guide.

4.9. Reconfiguring the Libraries

If you need to recompile the OMNeT++ components with different flags (e.g. different optimization), then change the top-level OMNeT++ directory, edit configure.user accordingly, then type:

```
$ ./configure
$ make cleanall
$ make
```

If you want to recompile just a single library, then change to the directory of the library (e.g. cd src/sim) and type:

```
$ make clean
$ make
```

By default, libraries are compiled in both debug and release mode. If you want to make release or debug builds only, use:

```
$ make MODE=release
or
```

\$ make MODE=debug

By default, shared libraries will be created. If you want to build static libraries, set SHARED_LIBS=no in configure.user and re-configure your project.

NOTE

For detailed description of all options please read the Build Options chapter.

4.10. Additional Packages

Note that at this point, MPI, Doxygen and GraphViz have been installed as part of the prerequisites.

4.10.1. Gtenv

OMNeT++5 comes with a new Qt based runtime environment that supports also 3D visualization. The new environment can be disabled by the WITH_QTENV=no variable in the configure.user file and then running ./configure.

4.10.2. Akaroa

Linux distributions do not contain the Akaroa package. It must be downloaded, compiled and installed manually before installing OMNeT++.

```
NOTE
```

As of version 2.7.9, Akaroa only supports Linux and Solaris.

Download Akaroa 2.7.9 from: http://www.cosc.canterbury.ac.nz/research/RG/net_sim/ simulation_group/akaroa/download.chtml

Extract it into a temporary directory:

```
$ tar xfz akaroa-2.7.9.tar.gz
```

Configure, build and install the Akaroa library. By default, it will be installed into the /usr/local/akaroa directory.

```
$ ./configure
$ make
$ sudo make install
```

Go to the OMNeT++ directory, and (re-)run the configure script. Akaroa will be automatically detected if you installed it to the default location.

4.10.3. PCAP

The optional Pcap library allows simulation models to capture and transmit network packets bypassing the operating system's protocol stack. It is not used directly by OM-NeT++, but models may need it to support network emulation.

4.10.4. Nemiver

Nemiver is the default debugger for the OMNeT++ just-in-time debugging facility (see the debugger-attach-on-startup and debugger-attach-on-error configuration

options). Nemiver can be installed via the package manager in most Linux distros. For example, on Ubuntu and other Debian-based distros you can install it by the following command:

\$ sudo apt-get install nemiver

Chapter 5. Ubuntu

5.1. Supported Releases

This chapter provides additional information for installing OMNeT + + on Ubuntu Linux installations. The overall installation procedure is described in the *Linux* chapter.

The following Ubuntu releases are covered:

• Ubuntu 16.04 LTS or 18.04 LTS

They were tested on the following architectures:

• Intel 64-bit

The instructions below assume that you use the default desktop and the bash shell. If you use another desktop environment or shell, you may need to adjust the instructions accordingly.

5.2. Opening a Terminal

Type *terminal* in Dash and click on the Terminal icon.

5.3. Installing the Prerequisite Packages

You can perform the installation using the graphical user interface or from the terminal, whichever you prefer.

5.3.1. Command-Line Installation

Before starting the installation, refresh the database of available packages. Type in the terminal:

\$ sudo apt-get update

To install the required packages, type in the terminal:

```
$ sudo apt-get install build-essential gcc g++ bison flex perl \
    python python3 qt5-default libqt5opengl5-dev tcl-dev tk-dev \
    libxml2-dev zliblg-dev default-jre doxygen graphviz libwebkitgtk-3.0-0
```

To use Qtenv with 3D visualization support, install the development packages for OpenSceneGraph (3.2 or later) and the osgEarth (2.7 or later) packages. (You may need to enable the *Universe* software repository in Software Sources. In case of Ubuntu 16.04 (Xenial), you have to add the ubuntugis/ppa repository manually to your software sources, because Xenial contains only osgEarth 2.5 which is too old.):

```
# for Ubuntu 16.04 add extra GIS repo
$ sudo add-apt-repository ppa:ubuntugis/ppa
$ sudo apt-get update
# install osgearth development package (and OpenSceneGraph, too)
$ sudo apt-get install openscenegraph-plugin-osgearth libosgearth-dev
```

You may opt to use clang and clang++ instead of the gcc and g++ compilers. If you do not need the 3D visualization capabilities, you can disable them in the *configure.user* file.

To enable the optional parallel simulation support you will need to install the MPI packages:

```
$ sudo apt-get install openmpi-bin libopenmpi-dev
```

At the confirmation questions (*Do you want to continue?* [Y/N]), answer Y.

| ubuntu@ubuntu-desktop: ~ | × |
|--|---|
| <u>F</u> ile <u>E</u> dit <u>V</u> iew <u>T</u> erminal Ta <u>b</u> s <u>H</u> elp | |
| <pre>xllproto-input-dev xllproto-kb-dev xtrans-dev Suggested packages: bison-doc blt-demo cpp-doc gcc-4.2-locales debian-keyring g++-multilib g++-4.2-multilib gcc-4.2-doc libstdc++6-4.2-dbg autoconf automake1.9 gcc-doc gcc-multilib libtool manpages-dev gcc-4.2-multilib libgcc1-dbg libgomp1-dbg libmudflap0-4.2-dev libmudflap0-dbg glibc-doc libstdc++6-4.2-doc diff-doc libterm-readline-gnu-perl libterm-readline-perl-perl tclreadline tcl8.4-doc tk8.4-doc</pre> | |
| Recommended packages: perl-doc | |
| The following NEW packages will be installed: bison blt blt-dev build-essential dpkg-dev flex g++ g++-4.2 libc6-dev libice-dev libpthread-stubs0 libpthread-stubs0-dev libsm-dev libstdc++6-4.2-dev libtimedate-perl libx11-dev libxau-dev libxcb-xlib0-dev libxcb1-dev libxdmcp-dev libxml2-dev libxt-dev linux-libc-dev m4 patch tcl8.4 tcl8.4-dev tk8.4 tk8.4-dev x11proto-core-dev x11proto-input-dev x11proto-kb-dev xtrans-dev zlib1g-dev | |
| The following packages will be upgraded: cpp cpp-4.2 gcc gcc-4.2 gcc-4.2-base libc6 libc6-i686 libffi4 libgc1 libgomp1 libperl5.8 libstdc++6 libxml2 perl perl-base perl-modules 16 upgraded, 34 newly installed, 0 to remove and 389 not upgraded. Need to get 18.4MB/35.4MB of archives. After this operation, 62.3MB of additional disk space will be used. Do you want to continue [Y/n]? y | |

Figure 5.1. Command-Line Package Installation

5.3.2. PCAP

The optional Pcap library allows simulation models to capture and transmit network packets bypassing the operating system's protocol stack. It is not used directly by OM-NeT++, but models may need it to support network emulation.

```
$ sudo apt-get install libpcap-dev
```

5.3.3. Graphical Installation

Open the dash and type Synaptic.

Since software installation requires root permissions, Synaptic will ask you to type your password.

Search for the following packages in the list, click the squares before the names, then choose *Mark for installation* or *Mark for upgrade*.

If the *Mark additional required changes*? dialog comes up, choose the *Mark* button.

The packages:

- required: build-essential, gcc, g++, bison, flex, perl, qt5-default, tcl-dev, tk-dev, libxml2-dev, zlib1g-dev, default-jre, doxygen, graphviz, libwebkitgtk-3.0-0
- recommended: libopenscenegraph-dev, openscenegraph-plugin-osgearth, libosgearth-dev, openmpi-bin, libopenmpi-dev

| ୦ Sy | naptic Package Manager | _ O X |
|-------------------------------------|--|--------------------------|
| <u>File Edit Package Setting</u> | s <u>H</u> elp | |
| C (Solution Reload Mark All Upgrade | s Apply Properties Quick s | |
| All | S Package | Installed Version Late ^ |
| Amateur Radio (universe) | moonlight-plugin-mozilla | 1.0. |
| Base System | 🗌 🔮 xulrunner-dev | 1.9. |
| Base System (universe) | mozzemberek | 0.1. |
| Communication | google-gadgets-xul | 0.10 |
| Communication (multivers | prism 📃 | 1.0- |
| Communication (universe) | libxul0d-dbg | 1.8. |
| | xulrunner-1.9.1 | 1.9.1.5+nobinonly- 1.9. |
| Sections | libxul-dev | 1.8. |
| Sections | prism-google-talk | 1.0- |
| S <u>t</u> atus | prism-google-calendar | 1.0- |
| Origin | | <u> </u> |
| <u>C</u> ustom Filters | No package is selected. | |
| Search Results | | |
| 0 packages listed, 1313 install | ed, 0 broken. 0 to install/upgrade, 0 to | o remove |

Figure 5.2. Synaptic Package Manager

Click *Apply*, then in the *Apply the following changes*? window, click *Apply* again. In the *Changes applied* window, click *Close*.

5.3.4. Post-Installation Steps

Fixing Tooltip Colors

The default tooltip background color in Ubuntu is black, which causes certain tooltips in the OMNeT++ IDE to become unreadable (black-on-black). This annoyance can be resolved by changing the tooltip colors in Ubuntu.

| return O; } | | | |
|----------------|---|--|----|
| | s not set, then execute skip the code or end. L | | |
| | t(const uint8_t **pd, ui | .nt16_t word0, struct stack_object *objec | t) |
| | it is not set, then exec ise, skip the code or er const | | |
| const | | | |
| | | | |

Figure 5.3. Black-on-black text in tooltips

Install gnome-color-chooser:

\$ sudo apt-get install gnome-color-chooser

Run it:

```
$ gnome-color-chooser
```

Find the *Tooltips* group on the *Specific* tab, and change the settings to black foreground over pale yellow background. Click Apply.

| File Tools Help | | | | |
|---------------------------------------|-------------|-------------|-------------|-----------|
| Global Colors Bu | ittons Par | nel Deskto | op Specific | Icons 🕨 |
| Window Decoratio Metacity (normal) | | Title/Butto | ns Backg | ground |
| active window | | | | |
| inactive window | v 🗆 | | | |
| Complz | | | | |
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| Color | X-Pado | ding ‡ | Y-Padding | 3 |
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| Links | ted 🗆 🚺 | | visited 🗌 | |
| | | | | |
| | Profile: | None | | : |
| | | Close | Revert | Apply |

Figure 5.4. Fixing the tooltip color issue

Setting Up Debugging

By default, Ubuntu does not allow ptracing of non-child processes by non-root users. That is, if you want to be able to debug simulation processes by attaching to them with a debugger, or similar, you want to be able to use OMNeT++ just-in-time debugging (debugger-attach-on-startup and debugger-attach-on-error configuration options), you need to explicitly enable them.

To temporarily allow ptracing non-child processes, enter the following command:

\$ echo 0 | sudo tee /proc/sys/kernel/yama/ptrace_scope

To permanently allow it, edit /etc/sysctl.d/10-ptrace.conf and change the line:

kernel.yama.ptrace_scope = 1

to read

kernel.yama.ptrace_scope = 0

Note that the default debugger for OMNeT++ just-in-time debugging is *Nemiver*, so it also needs to be installed:

\$ sudo apt-get install nemiver

Chapter 6. Fedora 25

6.1. Supported Releases

This chapter provides additional information for installing OMNeT++ on Fedora installations. The overall installation procedure is described in the *Linux* chapter.

The following Fedora release is covered:

• Fedora 25

It was tested on the following architectures:

• Intel 64-bit

6.2. Opening a Terminal

Open the Search bar, and type Terminal.

6.3. Installing the Prerequisite Packages

You can perform the installation using the graphical user interface or from the terminal, whichever you prefer.

6.3.1. Command-Line Installation

NOTE

To install the required packages, type in the terminal:

```
$ sudo dnf install make gcc gcc-c++ bison flex perl \
    python2 tcl-devel tk-devel qt5-devel libxml2-devel \
    zlib-devel java doxygen graphviz webkitgtk
```

To use 3D visualization support in Qtenv, you should install OpenSceneGraph 3.2 or later and osgEarth 2.7 or later (recommended):

\$ sudo dnf install OpenSceneGraph-devel osgearth-devel

You may opt to use clang and clang++ instead of the gcc and g++ compilers.

To enable the optional parallel simulation support you will need to install the MPI package:

\$ sudo dnf install openmpi-devel

Note that *openmpi* will not be available by default, it needs to be activated in every session with the

```
$ module load mpi/openmpi-x86_64
```

command. When in doubt, use module avail to display the list of available modules. If you need MPI in every session, you may add the module load command to your startup script (.bashrc).

6.3.2. PCAP

The optional Pcap library allows simulation models to capture and transmit network packets bypassing the operating system's protocol stack. It is not used directly by OM-NeT++, but models may need it to support network emulation.

6.3.3. Graphical Installation

The graphical package manager can be launched by opening the Search bar and typing dnf.

Search for the following packages in the list. Select the checkboxes in front of the names, and pick the latest version of each package.

The packages:

• make, bison, gcc, gcc-c++, flex, perl, tcl-devel, tk-devel, qt5-devel, libxml2-devel, zlib-devel, webkitgtk, java, doxygen, graphviz, openmpi-devel, libpcap-devel, OpenSceneGraph-devel, osgearth-devel

Click *Apply*, then follow the instructions.

Chapter 7. Red Hat

7.1. Supported Releases

This chapter provides additional information for installing OMNeT++ on Red Hat Enterprise Linux installations. The overall installation procedure is described in the *Linux* chapter.

The following Red Hat release is covered:

• Red Hat Enterprise Linux Desktop Workstation 7.x

It was tested on the following architectures:

• Intel 64-bit

7.2. Opening a Terminal

Choose *Applications > Accessories > Terminal* from the menu.

7.3. Installing the Prerequisite Packages

You can perform the installation using the graphical user interface or from the terminal, whichever you prefer.



You will need Red Hat Enterprise Linux Desktop Workstation for OMNeT++. The *Desktop Client* version does not contain development tools.

7.3.1. Command-Line Installation

To install the required packages, type in the terminal:

```
$ su -c 'yum install make gcc gcc-c++ bison flex perl \
    tcl-devel tk-devel qt-devel libxml2-devel zlib-devel \
    java doxygen graphviz openmpi-devel libpcap-devel'
```

To use 3D visualization support in Qtenv (recommended), you should install the OpenSceneGraph-devel (3.2 or later) and osgEarth-devel (2.7 or later) packages. These packages are not available from the official RedHat repository so you may need to get them from different sources (e.g. rpmfind.net).

You may opt to use clang and clang++ instead of the gcc and g++ compilers.

To install additional (optional) packages for parallel simulation and packet capture support, type:

\$ su -c 'yum install openmpi-devel libpcap'

Note that *openmpi* will not be available by default, it needs to be activated in every session with the

\$ module load openmpi_<arch>

command, where <arch> is your architecture (usually i386 or $x86_64$). When in doubt, use module avail to display the list of available modules. If you need MPI in every session, you may add the module load command to your startup script (.bashrc).`

7.3.2. PCAP

The optional Pcap library allows simulation models to capture and transmit network packets bypassing the operating system's protocol stack. It is not used directly by OM-NeT++, but models may need it to support network emulation.

7.3.3. Graphical Installation

The graphical installer can be launched by choosing *Applications > Add/Remove Software* from the menu.

Search for the following packages in the list. Select the checkboxes in front of the names, and pick the latest version of each package.

The packages:

• make gcc, gcc-c++, bison, flex, perl, tcl-devel, tk-devel, qt-devel, libxml2-devel, zlibdevel, make, java, doxygen, graphviz, openmpi-devel, libpcap-devel

Click *Apply*, then follow the instructions.

7.4. SELinux

NOTE

You may need to turn off SELinux when running certain simulations. To do so, click on *System > Administration > Security Level > Firewall*, go to the *SELinux* tab, and choose *Disabled*.

You can verify the SELinux status by typing the sestatus command in a terminal.

From OMNeT++ 4.1 on, makefiles that build shared libraries include the chcon -t textrel_shlib_t lib<name>.so command that properly sets the security context for the library. This should prevent the SELinux-related "cannot restore segment prot after reloc: Permission denied" error from occurring, unless you have a shared library which was built using an obsolete or hand-crafted makefile that does not contain the chcon command.

Chapter 8. OpenSUSE

8.1. Supported Releases

This chapter provides additional information for installing OMNeT++ on openSUSE installations. The overall installation procedure is described in the *Linux* chapter.

The following openSUSE release is covered:

• openSUSE 42.2

It was tested on the following architectures:

• Intel 64-bit

8.2. Opening a Terminal

Open the Search bar, and type Terminal.

8.3. Installing the Prerequisite Packages

You can perform the installation using the graphical user interface or from the terminal, whichever you prefer.

8.3.1. Command-Line Installation

To install the required packages, type in the terminal:

```
$ sudo zypper install make gcc gcc-c++ bison flex perl \
    tcl-devel tk-devel libqt5-qtbase-devel libxml2-devel zlib-devel \
    java-1_8_0-openjdk doxygen graphviz libwebkitgtk-3_0-0
```



You may opt to use clang and clang++ instead of the gcc and g++ compilers.

To use 3D visualization support in Qtenv (recommended), you should install the OpenSceneGraph-devel (3.2 or later) and osgEarth-devel (2.7 or later) packages. These packages are not available from the official RedHat repository so you may need to get them from different sources (e.g. rpmfind.net).

To enable the optional parallel simulation support you will need to install the MPI package:

\$ sudo zypper install openmpi-devel

Note that *openmpi* will not be available by default, first you need to log out and log in again, or source your .profile script:

\$. ~/.profile

8.3.2. PCAP

The optional Pcap library allows simulation models to capture and transmit network packets bypassing the operating system's protocol stack. It is not used directly by OM-NeT++, but models may need it to support network emulation.

8.3.3. Graphical Installation

The graphical installer can be launched by opening the Search bar and typing *Software Management*.

| File Package Configuration Dependencies Options Extras Help View Search RPM Groups Installation Summary Installation C++ Search C Package Summary Installed (Available) C++ Search C Cucene-core Clucene is a 0.9.21-67.2 Mame Cucene-core Clucene-core Clucene-sone 4.4.4.2 V package Adoxygen Automated C 1.5.9-3.2 Ø gcc4+c++ The GNU C++ 4.4.1.2 00009030-2.4 Ø gcc4+c++ The GNU C++ 4.4.1.2 00009030-2.4 Ø blcLAC++6 Free Lossless 1.2.1-70.2 Ø blcLAC++6 Free Lossless 1.2.1-70.2 Ø blcLacx6 BloCX/C-C++ 2.1.0.342-129.1 Ø bliblacx6 BloCX/C-C++ 2.1.0.342-129.1 Ø bliblacx6 BloCX/D-C++ 2.1.0.342-129.1 Ø bliblagopp1 C++ Program 4.5.3-2.4.2 Ø bliblagopo1 C++ Program 4.5.3-2.4.2 Ø bliblagopo1 The system GNU C++ Compiler | 🗙 🕢 YaST2 | | 0 | × |
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| | | | | <u> </u> |

Figure 8.1. Yast Software Management

Search for the following packages in the list. Select the checkboxes in front of the names, and pick the latest version of each package.

The packages:

• make, gcc, gcc-c++, bison, flex, perl, tcl-devel, tk-devel, libqt5-qtbase-devel, libxml2devel, zlib-devel, java-1_8_0-openjdk, doxygen, graphviz, libwebkitgtk-3_0-0, openmpi-devel, libpcap-devel

Click *Accept*, then follow the instructions.

Chapter 9. Generic Unix

9.1. Introduction

This chapter provides additional information for installing OMNeT++ on Unix-like operating systems not specifically covered by this Installation Guide. The list includes FreeBSD, Solaris, and Linux distributions not covered in other chapters.



In addition to Windows and macOS, the Simulation IDE will only work on Linux x86 64-bit platforms. Other operating systems (FreeBSD, Solaris, etc.) and architectures may still be used as simulation platforms, without the IDE.

9.2. Dependencies

The following packages are required for OMNeT++ to work:

| build-essential, GNU make, | These packages are needed for compiling OMNeT++ |
|----------------------------------|--|
| gcc, $g++$, bison (2.4+), flex, | and simulation models, and also for certain OM- |
| perl | NeT++ tools to work. C++ compilers other than g+ |
| | +, will also be accepted. |



You may opt to use clang and clang++ instead of the gcc and g++ compilers.

The following packages are strongly recommended, because their absence results in severe feature loss:

| Tcl/Tk 8.5 or later | Required by the Tkenv simulation runtime environ- ment. You need the <i>devel</i> packages that include the C header files as well. It is also possible to compile OM- NeT++ without Tcl/Tk (and Tkenv), by setting then WITH_TKENV=no variable in configure.user. |
|---|--|
| LibXML2 or Expat | Either one of these XML parsers are needed for OM-NeT++ to be able to read XML files. The <i>devel</i> packages (that include the header files) are needed. LibXML2 is the preferred one. |
| OpenJDK, version 8.0 or later | The Java runtime is required to run the Eclipse- based Simulation IDE. Other implementations, for example Kaffe, have been found to have problems running the IDE. You do not need this package if you do not plan to use the Simulation IDE. |
| Qt 5.4 or later | Required by the Qtenv simulation runtime environ- ment. You need the <i>devel</i> packages that include head- er files as well. |
| OpenSceneGraph (3.2+) and osgEarth (2.7+) | These packages will enable 3D visualization in Qtenv. You need the <i>devel</i> packages that include header files as well. |

The following packages are required if you want to take advantage of some advanced OMNeT++ features:

| GraphViz, Doxygen | These packages are used by the NED documentation gener- ation feature of the IDE. When they are missing, documen- tation will have less content. |
|-------------------|--|
| MPI | openmpi or some other MPI implementation is required to support parallel simulation execution. |
| Akaroa | Implements Multiple Replications In Parallel (MRIP). Akaroa can be downloaded from the project's website. |
| Рсар | The optional Pcap library allows simulation models to cap- ture and transmit network packets bypassing the operat- ing system's protocol stack. It is not used directly by OM- NeT++, but models may need it to support network emu- lation. |

The exact names of these packages may differ across distributions.

9.3. Determining Package Names

If you have a distro unrelated to the ones covered in this Installation Guide, you need to figure out what is the established way of installing packages on your system, and what are the names of the packages you need.

9.3.1. Tcl/Tk

Tcl/Tk may be present as separate packages (tcl and tk), or in one package (tcltk). The version number (e.g. 8.5) is usually part of the name in some form (85, 8.5, etc). You will need the development packages, which are usually denoted with the -dev or -devel name suffix.

Troubleshooting:

If your platform does not have suitable Tcl/Tk and/or QT packages, you may still use OMNeT++ to run simulations from the command line. To disable the graphical runtime environment use:

\$./configure WITH_TKENV=no WITH_QTENV=no

This will prevent the build system to link with Tcl/Tk or QT libraries. This is required also if you are installing OMNeT++ from a remote terminal session.

By default, the configure script expects to find the Tcl/Tk libraries in the standard linker path (without any -Ldirectory linker option) and under the standard names (i.e. with the -ltcl8.5 or -ltcl85 linker option). If you have them in different places or under different names, you have to edit configure.user and explicitly set TK_LIBS there (see the Build Options chapter for further details).

If you get the error *no display and DISPLAY environment variable not set*, then you're either not running X (the wish command, and thus ./configure won't work just in the console) or you really need to set the DISPLAY variable (export DISPLAY=:0.0 usually does it).

If you get the error: Tcl_Init failed: Can't find a usable init.tcl...

The TCL_LIBRARY environment variable should point to the directory which contains init.tcl. That is, you probably want to put a line like

```
export TCL_LIBRARY=/usr/lib/tcl8.5
```

into your ~/.bashrc.

9.3.2. The Java Runtime

You need to install the Oracle JRE or OpenJDK. The IDE is not supported on Unix platforms other than Linux, so JRE is not required either. We have tested various other Java runtimes (*gcj*, *kaffe*, etc.), and the IDE does not work well with them.

Java version 1.8 (i.e. JRE 1.8) or later is required.

9.3.3. MPI

OMNeT++ is not sensitive to the particular MPI implementation. You may use Open-MPI, or any other standards-compliant MPI package.

9.4. Downloading and Unpacking

Download OMNeT++ from http://omnetpp.org. Make sure you select to download the generic archive, omnetpp-5.6.2-src.tgz.

Copy the archive to the directory where you want to install it. This is usually your home directory, /home/<you>. Open a terminal, and extract the archive using the following command:

\$ tar xvfz omnetpp-5.6.2-src.tgz

This will create an omnetpp-5.6.2 subdirectory with the OMNeT++ files in it.

9.5. Environment Variables

In general OMNeT+ + requires that its bin directory should be in the PATH. You should add a line something like this to your .bashrc:

```
$ export PATH=$HOME/omnetpp-5.6.2/bin:$PATH
```

You may also have to specify the path where shared libraries are loaded from. Use:

\$ export LD_LIBRARY_PATH=\$LD_LIBRARY_PATH:\$HOME/omnetpp-5.6.2/lib

If configure complains about not finding the Tcl library directory, you may specify it by setting the TCL_LIBRARY environment variable.

NOTE

If you use a shell other than bash, consult the man page of that shell to find out which startup file to edit, and how to set and export variables.

9.6. Configuring and Building OMNeT++

In the top-level OMNeT++ directory, type:

```
$ ./configure
```

The configure script detects installed software and configuration of your system. It writes the results into the Makefile.inc file, which will be read by the makefiles during the build process.

| ubuntu@ubuntu-desktop: ~/omnest-4.0 | |
|---|-------|
| <u>F</u> ile <u>E</u> dit <u>V</u> iew <u>T</u> erminal Ta <u>b</u> s <u>H</u> elp | |
| <pre>checking for Akaroa with CFLAGS=" -02 -DNDEBUG=1 -fno-stack-protector -DX SER=libxml " LIBS="" no</pre> | MLPAR |
| checking for Akaroa with CFLAGS=" -02 -DNDEBUG=1 -fno-stack-protector -DX SER=libxml " LIBS="-lakaroa -lfl" no | MLPAR |
| configure: WARNING: Optional package Akaroa not found | |
| configure: creating ./config.status config.status: creating Makefile.inc | |
| config.status: creating test/core/runtest | |
| patching the ide configuration file. default workspace is: /home/ubuntu/omn .0/samples | est-4 |
| WARNING: The configuration script could not detect the following packages: | |
| MPI (optional) Akaroa (optional) | |
| Scroll up to see the warning messages (use shift+PgUp key), and see config. for more details. While you can use OMNEST in the current | log |
| configuration, please be aware that some functionality may be unavailable or incomplete. | |
| Your PATH contains /home/ubuntu/omnest-4.0/bin. Good! | |
| TCL LIBRARY is set. Good! | |
| ubuntu-desktop:~/omnest-4.0\$ | - |

Figure 9.1. Configuring OMNeT++

Normally, the configure script needs to be running under the graphical environment (X11) in order to test for wish, the Tcl/Tk shell. If you are logged in via an ssh session, or there is some other reason why X is not running, the easiest way to work around the problem is to tell OMNeT++ to build without Tcl/Tk. To do that, use the command

\$./configure WITH_TKENV=no WITH_QTENV=no

instead of plain ./configure.

If there is an error during configure, the output may give hints about what went wrong. Scroll up to see the messages. (Use Shift+PgUp; you may need to increase the scrollback buffer size of the terminal and re-run ./configure.) The script also writes a very detailed log of its operation into config.log to help track down errors. Since config.log is very long, it is recommended that you open it in an editor and search for phrases like *error* or the name of the package associated with the problem.
The configure script tries to build and run small test programs that are using specific libraries or features of the system. You can check the config.log file to see which

libraries or features of the system. You can check the config.log file to see which test program has failed and why. In most cases the problem is that the script cannot figure out the location of a specific library. Specifying the include file or library location in the configure.user file and then re-running the configure script usually solves the problem.

When ./configure has finished, you can compile OMNeT++. Type in the terminal:

\$ make

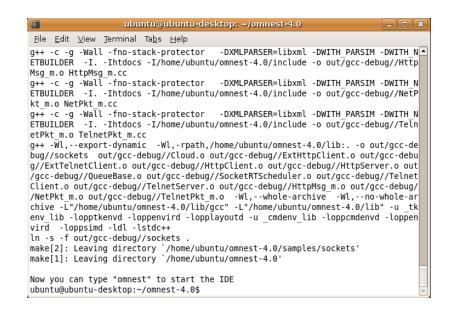


Figure 9.2. Building OMNeT++



To take advantage of multiple processor cores, add the -j8 option (for 8 cores) to the make command line.



The build process will not write anything outside its directory, so no special privileges are needed.

The make command will seemingly compile everything twice. This is because both debug and optimized versions of the libraries are built. If you only want to build one set of the libraries, specify MODE=debug or MODE=release:

```
$ make MODE=release
```

9.7. Verifying the Installation

You can now verify that the sample simulations run correctly. For example, the dyna simulation is started by entering the following commands:

```
$ cd samples/aloha
$ ./aloha
```

By default, the samples will run using the Qtenv environment. You should see nice gui windows and dialogs.

9.8. Starting the IDE

The IDE is supported only on 64-bit versions of Windows, macOS X and Linux.

You can run the IDE by typing the following command in the terminal:

```
$ omnetpp
```

NOTE

| ĵ. | Simulation - OM | INEST IDE | | | 0 |
|--|---|---------------------|-------------------|---------------|------------|
| ile <u>E</u> dit <u>S</u> ource <u>N</u> avigate Se <u>a</u> r | rch <u>P</u> roject <u>B</u> un <u>W</u> indow <u>H</u> elp | | | | |
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| | 0 items | | | | |
| | Description | Resource | Path | Location Type | |
| | | | | | |
| | | 1 | | | |
| 0 items selected | | | | 2 1 | > 🔶 💌 |

Figure 9.3. The Simulation IDE

If you would like to be able to access the IDE from the application launcher or via a desktop shortcut, run one or both of the commands below:

```
$ make install-menu-item
$ make install-desktop-icon
```

9.9. Optional Packages

9.9.1. Akaroa

If you wish to use Akaroa, it must be downloaded, compiled, and installed manually before installing OMNeT++.

As of version 2.7.9, Akaroa only supports Linux and Solaris. NOTE

Download Akaroa 2.7.9 from: http://www.cosc.canterbury.ac.nz/research/RG/net_sim/ simulation_group/akaroa/download.chtml

Extract it into a temporary directory:

```
$ tar xfz akaroa-2.7.9.tar.gz
```

Configure, build and install the Akaroa library. By default, it will be installed into the /usr/local/akaroa directory.

```
$ ./configure
$ make
$ sudo make install
```

Go to the OMNeT++ directory, and (re-)run the configure script. Akaroa will be automatically detected if you installed it to the default location.

9.9.2. PCAP

The optional Pcap library allows simulation models to capture and transmit network packets bypassing the operating system's protocol stack. It is not used directly by OM-

NeT++, but OMNeT++ detects the necessary compiler and linker options for models in case they need it.

Chapter 10. Build Options

10.1. Configure.user Options

The configure.user file contains several options that can be used to fine-tune the simulation libraries.

You always need to re-run the configure script in the installation root after changing the configure.user file.

\$./configure

After this step, you have to remove all previous libraries and recompile OMNeT++:

| \$ make cleanall \$ make | |
|--|---|
| Options: | |
| PREFER_CLANG=no | If both gcc and clang are installed on your system, setting this variable to no will force the configure script to use gcc as $C++$ compiler. |
| <componentname>_CFLAGS, <componentname>_LIBS</componentname></componentname> | The configure.user file contains variables for defining the compile and link options needed by var- ious external libraries. By default, the configure command detects these automatically, but you may override the auto detection by specifying the values by hand. (e.g. <comp>_CFLAGS=-I/path/to/comp/in- cludedir and <comp>_LIBS=-L/path/to/comp/ libdir -lnameoflib.)</comp></comp> |
| WITH_PARSIM=no | Use this variable to explicitly disable parallel simula- tion support in OMNeT++. |
| WITH_NETBUILDER=no | This option allows you to leave out the NED language parser and the network builder. (This is needed only if you are building your network with $C++$ API calls and you do not use the built-in NED language parser at all.) |
| WITH_TKENV=no | This will prevent the build system to link with Tcl/ Tk libraries. Use this option if your platform does not have a suitable Tcl/Tk package or you will run the sim- ulation only in command line mode. (i.e. You want to run OMNeT++ in a remote terminal session.) |
| WITH_QTENV=no | This will prevent the build system to link with the Qt libraries. Use this option if your platform does not have a suitable Qt package or you will run the simulation only in command line mode. (i.e. You want to run $OMNeT++$ in a remote terminal session.) |
| WITH_OSG=no | This will prevent the build system to use OpenScreen- Graph which is used for 3D visualization in Qtenv. |

This will prevent the build system to use osgEarth WITH_OSGEARTH=no which is used for 2D/3D mapping and visualization in Qtenv. Use Tkenv as the default graphical runtime instead PREFER_QTENV=no of Qtenv. Tcl/Tk is a script language and the source of the EMBED_TCL_CODE=no graphical runtime environment is stored as .tcl files in the src/tkenv directory. By default, these files are not used directly, but are embedded as string literals in the executable file. Setting EMBED_TCL_CODE=yes allows you to move the OMNeT++ installation without caring about the location of the .tcl files. If you want to make changes to the Tcl code, you better switch off the embedding with the EMBED_T-CL CODE=no option. This way you can make changes to the .tcl files and see the changes immediately without recompiling the OMNeT++ libraries. To change the compiler command line options the CFLAGS_[RELEASE/DEBUG] build process is using, you should specify them in the CFLAGS_RELEASE and CFLAGS_DEBUG variables. By default, the flags required for debugging or optimization are detected automatically by the configure script. If you set them manually, you should spec-

By default, the hags required for debugging or optimization are detected automatically by the configure script. If you set them manually, you should specify all options you need. It is recommended to check what options are detected automatically (check the Makefile.inc after running configure and look for the CFLAGS_[RELEASE/DEBUG] variables.) and add/modify those options manually in the configure.user file.

LDFLAGS Linker command line options can be explicitly set using this variable. It is recommended to check what options are detected automatically (check the Makefile.inc after running configure and look for the LDFLAGS variable.) and add/modify those options manually in the configure.user file.

SHARED_LIBSThis variable controls whether the OMNeT++ build
process will create static or dynamic libraries.
By default, the OMNeT++ runtime is built as
a set of shared libraries. If you want to build
a single executable from your simulation, speci-
fy SHARED_LIBS=no in configure.user to cre-
ate static OMNeT++ libraries and then reconfig-
ure (./configure) and recompile OMNeT++ (make
cleanall; make). Once the OMNeT++ static li-
braries are correctly built, your own project have to
be rebuilt, too. You will get a single, statically linked
executable, which requires only the NED and INI files
to run.



It is important to completely delete the OMNeT++ libraries (make cleanall) and then rebuild them, otherwise it cannot be guaranteed that the created simulations are linked against the correct libraries.

The USE_DOUBLE_SIMTIME and WITHOUT_CPACKET options are no longer supported. They were introduced in OMNeT++ 4.0 to help porting model code from OMNeT++ 3.x, and having fulfilled their role, they were removed in OMNeT++ 5.0. If you still have old model code to port, use OMNeT++ 4.x.

10.2. Moving the Installation

When you build OMNeT++ on your machine, several directory names are compiled into the binaries. This makes it easier to set up OMNeT++ in the first place, but if you rename the installation directory or move it to another location in the file system, the built-in paths become invalid and the correct paths have to be supplied via environment variables.

The following environment variables are affected (in addition to PATH, which also needs to be adjusted):

| OMNETPP_IMAGE_PATH | This variable contains the list of directories where Tkenv looks for icons. Set it to point to the images/ subdirectory of your OMNeT++ installation. |
|--------------------|--|
| OMNETPP_TKENV_DIR | This variable points to the directory that contains the Tcl script parts of Tkenv, which is by default the src/tkenv/ subdirectory of your OMNeT++ installation. Normally you don't need to set this variable, because the Tkenv shared library contains all Tcl code compiled in as string literals. However, if you compile OMNeT++ with the EM-BED_TCL_CODE=no setting and then you move the installation, then you need to set OMNETPP_TKENV_DIR, otherwise Tkenv won't start. |
| LD_LIBRARY_PATH | This variable contains the list of additional directo- ries where shared libraries are looked for. Initially, LD_LIBRARY_PATH is not needed because shared libraries are located via the <i>rpath</i> mechanism. When you move the installation, you need to add the lib/ subdirectory of your OMNeT++ installation to LD_LIBRARY_PATH. |



On macOS, DYLD_LIBRARY_PATH is used instead of LD_LIBRARY_PATH. On Windows, the PATH variable must contain the directory where shared libraries (DLLs) are present.

10.3. Using Different Compilers

By default, the configure script detects the following compilers automatically in the path:

- Intel compiler (icc, icpc)
- GNU C/C++ (gcc, g++)
- Clang (clang, clang++)
- Clang/C2 (from Microsoft Visual Studio)
- Sun Studio (cc, cxx)
- IBM compiler (xlc, xlC)

If you want to use compilers other than the above ones, you should specify the compiler name in the CC and CXX variables, and re-run the configuration script.



Different compilers may have different command line options. If you use a compiler other than the default gcc, you may have to revise the CFLAGS_[RELEASE/DEBUG] and LDFLAGS variables.