# Robust inference and model selection using bagged posteriors

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Joint work with Jonathan Huggins

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Slides: http://jwmi.github.io/talks/uw2022.pdf Preprint 1: https://arxiv.org/abs/1912.07104 Preprint 2: https://arxiv.org/abs/2007.14845

## Outline

- Motivation
- 2 Background
- Methodology (Bagged posteriors)
- 4 Theory
- 6 Applications
  - Variable selection
  - Phylogenetic tree inference
  - Phylogenetic tree interence
  - Hierarchical mixed effects logistic regression

## Outline

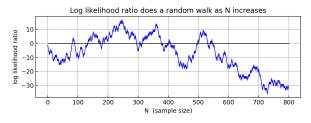
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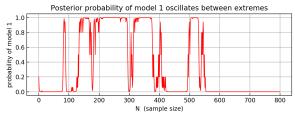
#### Motivation

- Standard Bayesian inference is known to be sensitive to model misspecification.
- This leads to unreliable uncertainty quantification and poor predictive performance.
- Several methods exist for robust Bayesian inference under misspecification.
- However, finding generally applicable and computationally feasible methods is a difficult challenge.

## Toy Bernoulli example

- Suppose  $X_1, \ldots, X_N \sim \text{Bernoulli}(p)$  i.i.d.
- Consider the (yes, contrived!) situation in which we only consider two models: (1) p=0.2 and (2) p=0.8, but the true value is p=0.501.

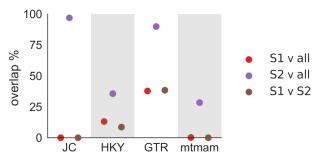




# Example: Phylogenetic tree inference for whale species

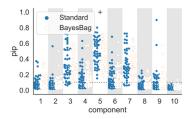
- This is not just a contrived issue it frequently occurs in practice in phylogenetic inference.
  - ▶ Alfaro et al. (2003), Douady et al. (2003), Wilcox et al. (2002).
- Bayesian phylogenetic inference is very widely used, however, it often yields self-contradictory results due to misspecification.

Overlap between posteriors from two subsets of a whale genetics data set

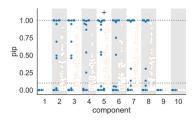


## Example: Variable selection in linear regression

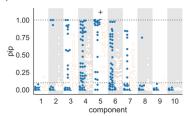
- Similarly, variable selection is unstable when there is misspecification.
- ullet Posterior inclusion probabilities (pips) often flip-flop as N grows.



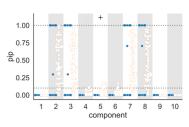
(a) 
$$N = 5 \times 10^1$$



(c) 
$$N = 5 \times 10^3$$



(b) 
$$N = 5 \times 10^2$$



(d) 
$$N = 5 \times 10^4$$

## Outline

- Background

- - Variable selection
  - Phylogenetic tree inference

  - Hierarchical mixed effects logistic regression

## Background

- $P_0$  = true distribution of the observed data.
- $\{P_{\theta}: \theta \in \Theta\}$  is the assumed model.
- Suppose  $P_0$  is not in the assumed model.
- The pseudo-true parameter  $\theta^*$  is the nearest point to  $P_0$  in terms of Kullback–Leibler divergence.
- ullet In this talk, we take the usual perspective that  $heta^*$  is of interest.
- ullet The posterior concentrates at  $heta^*$  (under regularity conditions), but . . .
  - It is typically miscalibrated: credible sets do not have correct coverage.
    - ★ Kleijn & van der Vaart (2012)
    - ★ Can recalibrate using sandwich covariance (Müller, 2013, and others)
  - Slow concentration can occur, causing poor prediction performance.
    - ★ Grünwald & van Ommen (2014)
    - \* Can fix this using a power posterior  $\propto p(x|\theta)^{\zeta}p(\theta)$  for certain  $\zeta\in(0,1)$

# Background

Many methods have been proposed for improving robustness to model misspecification.

- Fitting/prediction, focus on pseudo-true parameter  $\theta^*$ .
  - Robust adjusted likelihood (Royall & Tsou, 2003)
  - ► SafeBayes (Grünwald & van Ommen, 2014)
  - Modular posteriors (Jacob et al., 2017)
  - Sandwich covariance adjustment (Müller, 2013)
  - ► Holmes & Walker (2017)
    - ...and many others.
- Inference/understanding, focus on ideal parameter  $\theta_I$ .
  - Coarsened posterior (M. & Dunson, 2019)
  - Nonparametric perturbation models (M., forthcoming)

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# Bagged posterior (BayesBag)

- Basic idea: Use bagging on the posterior, that is, average the posterior over many bootstrapped datasets.
- More precisely:
  - Original data set:  $x = (x_1, \dots, x_N)$ .
  - ▶ Bootstrapped copy of original data set:  $x^* = (x_1^*, \dots, x_M^*)$ .
  - ▶ Posterior obtained by treating  $x^*$  as the original data set:

$$\pi(\theta \mid x^*) \propto \pi_0(\theta) \prod_{m=1}^M p_{\theta}(x_m^*).$$

▶ The *bagged posterior* is defined by averaging these posteriors:

$$\pi^*(\theta \mid x) := \frac{1}{N^M} \sum_{x^*} \pi(\theta \mid x^*),$$

where the sum is over all  ${\cal N}^M$  possible bootstrap datasets of M samples drawn with replacement from the original dataset.

# Bagged posterior (BayesBag): Practical considerations

• In practice, we approximate  $\pi^*(\theta \mid x)$  by generating B bootstrap datasets  $x^*_{(1)},\dots,x^*_{(B)}$  and forming the simple Monte Carlo approximation

$$\pi^*(\theta \mid x) \approx \frac{1}{B} \sum_{b=1}^{B} \pi(\theta \mid x_{(b)}^*).$$

- Any posterior computation technique for the standard posterior can be used to compute each term  $\pi(\theta \mid x_{(b)}^*)$ .
  - ▶ For example, a closed-form solution, MCMC, or quadrature.
- How to choose the number of bootstrap datasets *B*?
  - As a default,  $B \approx 50$  to 100 often suffices.
  - Formally, the Monte Carlo error can easily be estimated, since the bootstrap datasets  $x_{(b)}^*$  are i.i.d. given the original dataset.

# Bagged posterior (BayesBag): Practical considerations

- How to choose the bootstrap dataset size M?
  - ▶ The choice of *M* is connected to calibration of uncertainty.
  - ightharpoonup As M/N increases, the bagged posterior becomes more concentrated.
- Recommended choice of M for model selection:
  - ▶ Our theory suggests choosing M = o(N) or M = cN with  $c \in (0,1]$ .
  - As a default,  $M=N^{0.95}$  works well in theory and practice.
  - lacktriangle When M/N is large, the bagged posterior behaves like the standard posterior.
- ullet Recommended choice of M for parameter inference:
  - $\blacktriangleright$  As a default, M=N is a conservative choice that is robust to misspecification.
  - If the model is correct, then M=2N coincides with the standard posterior, asymptotically.

# Previous work on bagged posteriors (BayesBag)

- Suggested by Waddell et al. (2002) and Douady et al. (2003).
  - Limited empirical study of BayesBag on phylogenetic inference.
- Independently proposed by Bühlmann (2014).
  - Limited empirical/theoretical study on a simple univariate Gaussian location model.
  - ► Coined the name "BayesBag", which we adopt here.
- Surprisingly, there seems to have been little empirical or theoretical investigation of bagged posteriors.
- Bagging the posterior is very different than Bayesian Bagging (Clyde & Lee, 2001) and the Bayesian Bootstrap (Rubin, 1981), which are Bayesian ways of doing bagging and bootstrap, respectively.

# Principled justification via Jeffrey conditionalization

- Jeffrey conditionalization (Diaconis & Zabell, 1982; Jeffrey, 1968):
  - Assume we have a model p(x,y) for some variables x and y.
  - ▶ Suppose we are informed that  $p_0(x)$  is the true distribution of x.
  - ▶ Then, Jeffrey says to quantify uncertainty in y using

$$q(y) := \int p(y|x)p_0(x)dx.$$

- Now, to connect this to the bagged posterior:
  - ▶ Take  $x = x_{1:N}$  and  $y = \theta$ .
  - If we are informed that the true distribution is  $p_0^{(N)}(x_{1:N})$ , then

$$q(\theta) := \int p(\theta \mid x_{1:N}) p_0^{(N)}(x_{1:N}) dx_{1:N}.$$

▶ Plugging in the empirical distribution  $\frac{1}{N}\sum_{i=1}^{N}\delta_{x_i}$  for  $p_0$ , we obtain

$$q(\theta) \approx \frac{1}{N^N} \sum_{x_{1:N}^*} p(\theta \mid x_{1:N}^*),$$

which is precisely the bagged posterior with M=N.

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#### Overview of theoretical results

- We consider the setting of i.i.d. data  $X_1, \ldots, X_N \sim P_0$ .
- **Model selection.** We show that if two models provide a nearly equally good fit to the data distribution  $P_0$ , then:
  - the standard posterior oscillates randomly, strongly favoring one model or the other at random.
  - the bagged posterior stabilizes the probabilities probabilities of the two models, improving reproducibility.
- Parameter inference. We derive the mean and covariance of the bagged posterior, and prove a Bernstein-von Mises result characterizing the asymptotic normal distribution.

- Asymptotically, we know the posterior concentrates on the model that is nearest in Kullback–Leibler (KL) divergence to the true distribution.
- To study the non-asymptotic regime via an asymptotic analysis, we consider sequences of models  $\mathfrak{m}_{1,N}$  and  $\mathfrak{m}_{2,N}$ .
- Letting  $\Lambda_N = \log \frac{p(X_{1:N}|\mathfrak{m}_{1,N})}{p(X_{1:N}|\mathfrak{m}_{2,N})}$  (the log-likelihood ratio), suppose:
  - lacktriangledain  $\mathfrak{m}_{1,N}$  and  $\mathfrak{m}_{2,N}$  are asymptotically comparable in the sense that

$$\lim_{N\to\infty} \mathrm{E}_{P_0}(\Lambda_N/\sqrt{N}) = \mu_\infty \in \mathbb{R},$$

- 2  $\operatorname{Var}_{P_0}(\Lambda_N/\sqrt{N}) = \sigma_\infty^2 \in (0,\infty)$  for all N, and
- 3  $M/N \to c \in [0, \infty)$  as  $N \to \infty$ , where  $M = M(N) \to \infty$ .
- The effect size  $\mu_{\infty}/\sigma_{\infty}$  is the evidence in favor of model 1.

• Then as  $N \to \infty$ , the standard posterior probability of model 1 concentrates at 0 and 1, that is, it converges to a Bernoulli r.v.:

$$\pi(\mathfrak{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} \text{Bernoulli}(\Phi(\mu_{\infty}/\sigma_{\infty})).$$

The bagged posterior probability of model 1 converges to a r.v.:

$$\pi^*(\mathfrak{m}_{1,N}\mid X_{1:N})\xrightarrow{D}\Phi(c^{1/2}Z)$$
 where  $Z\sim\mathcal{N}(\mu_\infty/\sigma_\infty,1).$ 

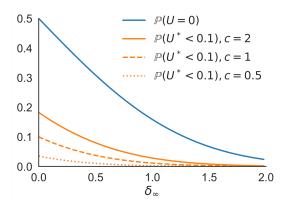
• In particular, if  $\mu_{\infty}=0$  and c>0, then

$$\pi(\mathfrak{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} \operatorname{Bernoulli}(1/2)$$
  
 $\pi^*(\mathfrak{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} \operatorname{Uniform}(0,1).$ 

• Meanwhile, if c=0 then

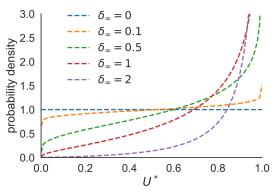
$$\pi^*(\mathfrak{m}_{1,N} \mid X_{1:N}) \xrightarrow{D} 1/2.$$

The standard posterior overwhelmingly favors the wrong model with non-negligible probability. The bagged posterior does much better.



- ullet Standard posterior probability of model 1 converges to U.
- ullet Bagged posterior probability of model 1 converges to  $U^*$ .
- $\delta_{\infty} := \mu_{\infty}/\sigma_{\infty} = \text{mean effect size in favor of model } 1.$

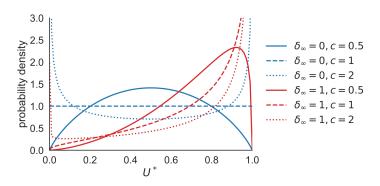
The bagged posterior converges to a continuous r.v.  $U^*$  on [0,1], avoiding misleading extreme probabilities close to 0 or 1. (Shown: c=1.)



$$U^* = \Phi(c^{1/2}Z)$$
 where  $Z \sim \mathcal{N}(\mu_{\infty}/\sigma_{\infty}, 1)$ 

•  $\delta_{\infty} := \mu_{\infty}/\sigma_{\infty} = \text{mean effect size in favor of model } 1.$ 

Choosing M smaller makes the bagged posterior tend to be more uniform over the set of plausible models.



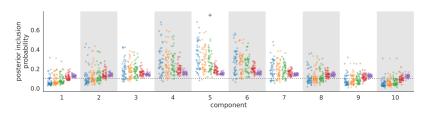
- $c = \lim_{N \to \infty} M/N$ , where M = M(N).
  - ▶ For instance,  $c \in \{0.5, 1, 2\}$  when  $M \in \{0.5N, N, 2N\}$ , respectively.
- $\delta_{\infty} := \mu_{\infty}/\sigma_{\infty} =$  mean effect size in favor of model 1.

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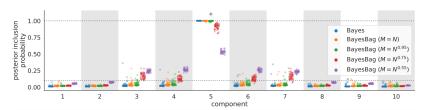
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- We consider a standard Bayesian variable selection model for linear regression.
- Specifically, under the prior, each variable is included with probability  $q_0$ , independently, and we integrate out Normal and InverseGamma priors on the coefficients and variance, respectively.
- First, we simulate datasets from (1) the assumed model and (2) a model with nonlinearly transformed covariates.
- In both scenarios, the true coefficient vector is sparse.
- We consider using  $M=N^{\alpha}$  for  $\alpha \in \{1,0.95,0.75,0.55\}$  to compute the bagged posterior.

When the model is correct, the bagged posterior with  $M=N^{\alpha}$  is similar to the standard posterior when  $\alpha=1$  and more stable as  $\alpha$  decreases.

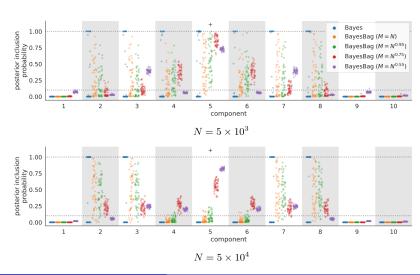


1-sparse-linear,  $N = 5 \times 10^1$ 

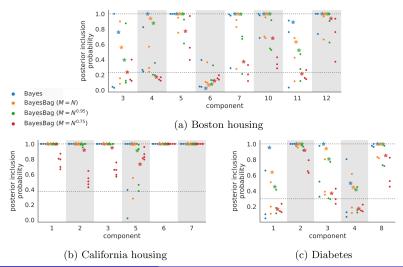


1-sparse-linear,  $N = 5 \times 10^3$ 

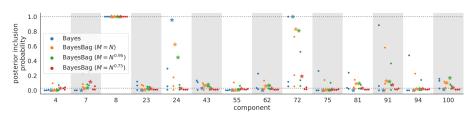
When the model is incorrect, the bagged posterior avoids the self-contradictory results produced by the standard posterior.



On real datasets, the bagged posterior yields greater reproducibility across subsets of the data.



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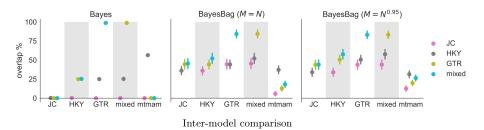


(d) Residential building

## Application: Phylogenetic tree inference

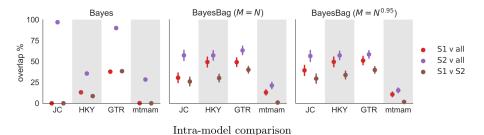
- We use a standard Bayesian package for phylogenetic inference (MrBayes 3.2, Ronquist et al., 2012).
- We used the whale dataset from Yang (2008), consisting of mitochondrial DNA from 13 whale species.
- To compute the posterior on trees, MrBayes was run using five different models for the evolutionary process (JC, HKY, GTR, mixed, and mtmam).
- For the bagged posterior, we used  $M \in \{N, N^{0.95}\}$  and B = 100.
- To assess reproducibility, we computed the overlap of 99% highest posterior density regions for selected pairs of posteriors.

# Application: Phylogenetic tree inference



- First, we consider the posterior overlap for each pair of evolutionary models.
- The standard posteriors sometimes have extremely low overlap, suggesting poor reproducibility.
- Meanwhile, the bagged posteriors exhibit more reasonable overlaps for each pair.

# Application: Phylogenetic tree inference



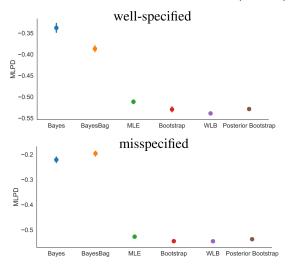
- Then, we split the genetic data into two parts, and compute the overlap for (1) the posteriors of the two splits, and (2) the posteriors for each split and the full data.
- Again, the standard posterior exhibits poor reproducibility, while the bagged posterior is more self-consistent.

# Application: Hierarchical mixed effects logistic regression

- Finally, we consider a mixed effects model from Browne and Draper (2006), applied to prenatal care data from Guatemalan communities.
- We compare the predictive performance of the standard posterior, the bagged posterior, and four methods based on maximum likelihood estimation (with the random effects integrated out):
  - the standard MLE.
  - the bootstrapped MLE,
  - ▶ the weighted likelihood bootstrap (Newton and Raftery, 1994), and
  - ▶ the posterior bootstrap (Lyddon, Walker and Holmes, 2018).

# Application: Hierarchical mixed effects logistic regression

The bagged posterior performs favorably compared to the other methods in terms of mean log predictive density (MLPD).



#### Conclusion

- Bagging the posterior is an easy-to-use and widely applicable method that improves upon standard Bayesian inference by making it more stable, accurate, and reproducible.
- Directions for future work or improvements:
  - Extensions to non-i.i.d. settings such as time-series and spatial data.
  - Improved computation of bagged posteriors.
  - Finite-sample theory for bagged posteriors.
  - Improved model assessment/criticism techniques and theory.

# Robust inference and model selection using bagged posteriors

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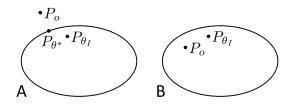
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# Perspective 2: Model is an idealization of a true process

- Model is interpretable, but not exactly right of course.
- Ideal parameter  $\theta_I$  is of interest.
- Data is from  $P_0$ , which we think of as a perturbation of  $P_{\theta_I}$ .
- The objective is to understand not to fit.
- This perspective is common in science & medicine.



- Now, consider the bagged posterior on a parameter  $\theta \in \mathbb{R}^D$ .
- Given dataset  $x = x_{1:N}$ , let  $X^*$  be a random bootstrap dataset.
- Let  $\mu(x)$  and  $\Sigma(x)$  denote the mean and covariance matrix of the standard posterior  $p(\theta|x)$ .
- By the law of total expectation, the mean of the bagged posterior is

$$E(\mu(X^*) \mid x) = \frac{1}{N^M} \sum_{x^*} \mu(x^*).$$

By the law of total variance, the covariance of the bagged posterior is

$$E(\Sigma(X^*) \mid x) + Cov(\mu(X^*) \mid x).$$

- Thus, the covariance of the bagged posterior decomposes as the sum of two terms:
  - $\bullet \ \mathrm{E}(\Sigma(X^*) \mid x)$ 
    - ★ ≈ mean of the posterior covariance matrix under its sampling distribution.
    - Bayesian model-based uncertainty averaged with respect to frequentist sampling variability.
  - - $\star$   $\approx$  covariance of the posterior mean under its sampling distribution.
    - Frequentist sampling-based uncertainty of the Bayesian model-based point estimate.

- Suppose  $X_1,\ldots,X_N\sim P_0$  i.i.d., and let  $\theta_0$  minimize the KL divergence from  $P_0$ .
- For the standard posterior, by Bernstein-von Mises we know that

$$N^{1/2}(\theta - \hat{\theta}_N)|X_{1:N} \xrightarrow{D} \mathcal{N}(0, J_{\theta_0}^{-1})$$

where  $\theta \sim p(\theta|X_{1:N})$ ,  $\hat{\theta}_N$  is the MLE, and  $J_{\theta_0} = -\mathrm{E}(\nabla^2 \log p_{\theta}(X_i))$ .

Meanwhile, we also know that the MLE is asymptotically normal:

$$N^{1/2}(\hat{\theta}_N - \theta_0)|X_{1:N} \xrightarrow{D} \mathcal{N}(0, J_{\theta_0}^{-1}I_{\theta_0}J_{\theta_0}^{-1}).$$

where  $I_{\theta_0} = \operatorname{Cov}(\nabla \log p_{\theta}(X_i))$ .

 Hence, asymptotically, the standard posterior is correctly calibrated if these two covariance matrices coincide.

 We prove a Bernstein-von Mises theorem for the bagged posterior, showing that the asymptotic covariance is

$$(J_{\theta_0}^{-1}+J_{\theta_0}^{-1}I_{\theta_0}J_{\theta_0}^{-1})/c$$

where  $c=\lim_{N\to\infty}M/N$ , and the asymptotic mean is the same as for the standard posterior.

- This is the asymptotic form of the total covariance decomposition.
- When the model is correct, c=2 recovers the standard posterior, asymptotically, since then  $J_{\theta_0}^{-1}=J_{\theta_0}^{-1}I_{\theta_0}J_{\theta_0}^{-1}$ .
- In general, c=1 is a safe choice, since it is guaranteed to prevent overconfident credible regions, asymptotically.

## Application: Linear regression

- To illustrate in the parameter inference setting, we consider a standard Bayesian linear regression model.
- As before, we use Normal and InverseGamma priors on the coefficients and variance.
- We simulate data from three scenarios:
  - the assumed model ("default"),
  - 2 the coefficient vector has only one nonzero entry ("1-sparse"), and
  - the covariates are nonlinearly transformed ("nonlinear").
- ullet For the bagged posterior, we selected M using an approach based on our asymptotic theory (see Huggins and M., 2019 for details).

# Application: Linear regression

The bagged posterior usually recovers the KL-optimal parameter better in terms of relative squared error (RSE) and log posterior density (LPD).

