

Intro to Spatial Point Patterns Project

Problem Setup

This assignment is a continuation of the heat-related 911 calls example. The file `Spatial911PtPtrn.RData` contains the following information:

- `calls` - a 1389×7 data frame containing demographic information on 1389 911 calls for heat-related health problems.
- `houston` - a shape-file data from with information on Houston city boundaries. Try:

```
> plot(houston)
```
- `pp.grid` - a 1428×2 data frame of lat-long points that form a grid covering the city of Houston. Try:

```
> plot(houston)  
> points(pp.grid$Longitude, pp.grid$Latitude)
```
- `hrlDas.grid` - a 15625×2 data frame of lat-long points that form a complete grid covering the city of Houston. Try:

```
> plot(houston)  
> points(hrlDas.grid$Longitude, hrlDas.grid$Latitude)
```
- `kp.gp` - a length 15625 logical vector such that `pp.grid[kp.gp,]`.

For this assignment we wish to consider only the spatial locations of the 911 calls. Let s_1, \dots, s_N where $N = 1389$ be the latitude-longitude coordinates of the 911 calls in `calls` and \mathcal{S} denote the set of locations corresponding to `houston`. Furthermore let s_1^*, \dots, s_K^* be the $K = 1428$ spatial locations in `pp.grid`.

For spatial point patterns, we wish to model the intensity surface $\Lambda(s)$ as a smooth function of s . Unlike age from the previous assignment, s indexes a continuous spatial location. Hence, $\Lambda(s)$ is a continuous (rather than discrete) intensity surface. Therefore, to make the modeling easier define we discretize $\Lambda(s)$ as,

$$\Lambda(s) = \delta \sum_{k=1}^K \frac{\lambda_k}{|\mathcal{G}_k|} \mathbb{1}\{s \in \mathcal{G}_k\} \quad (1)$$

where \mathcal{G}_k corresponds to the set of points that are closest to grid point s_k^* and $|\mathcal{G}_k| = \int_{\mathcal{G}_k} ds$ is the “area” of grid box \mathcal{G}_k . Furthermore, we assume that each $\lambda_k \in (0, 1)$ and $\sum_{k=1}^K \lambda_k = 1$. Effectively, (1) discretizes the spatial domain \mathcal{S} into K values $\{\lambda_1, \dots, \lambda_K\}$. The associated likelihood function is

$$L(\Lambda) = \exp\{-\delta\} \delta^N \prod_{i=1}^N \frac{\lambda_{\{k: s_i \in \mathcal{G}_k\}}}{|\mathcal{G}_k|} \quad (2)$$

Interpretation Questions

1. Show that $\int_S \Lambda(\mathbf{s}) d\mathbf{s} = \delta$ and interpret δ in context.
2. Show that $\mathbb{Pr}(\mathbf{s} \in \mathcal{G}_k) = \lambda_k$ and interpret λ_k in context.

Modeling Questions

Note that we could assume $\lambda_1, \dots, \lambda_K \sim \text{Dirichlet}$ as we did in the age of 911 caller analysis to get a conjugate analysis but this would ignore spatial smoothness in the intensity surface Λ . Instead let, $\lambda_k \propto \exp\{\lambda_k^*\}$ where λ_k follows a Gaussian process with constant mean μ and covariance given by the Matérn covariance function. In other words,

$$\boldsymbol{\lambda}^* = \begin{pmatrix} \lambda_1^* \\ \vdots \\ \lambda_K^* \end{pmatrix} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{M}) \quad (3)$$

where \mathbf{M} is a $K \times K$ correlation matrix with ij^{th} element $M_\nu(\|\mathbf{s}_i^* - \mathbf{s}_j^*\| \mid \phi)$ where $M_\nu(d \mid \phi)$ is the Matérn correlation function with smoothness ν and decay ϕ . It follows that λ_k is the normalized version of $\exp\{\lambda_k^*\}$ such that $\lambda_k = \exp\{\lambda_k^*\} / \sum_{j=1}^K \exp\{\lambda_j^*\}$. Therefore, $\{\lambda_k^*\}_k$ are the true parameters that need to be estimated.

1. Fix $\nu = 3.5$ to enforce smoothness and let $\phi_k = 343$.
2. Let the prior for δ be a gamma distribution with shape a_δ and rate b_δ (you choose a_δ and b_δ).
3. Let the prior for σ^2 be inverse-gamma with shape a_σ and rate b_σ (you choose a_σ and b_σ).
4. Write a Metropolis within Gibbs sampler to generate draws of $\boldsymbol{\lambda}^*$, δ and σ^2 . Hint: the complete conditional distributions for μ and σ^2 will be Normal and Inverse-gamma, respectively.