

Process Control Final Project

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INTRODUCTION

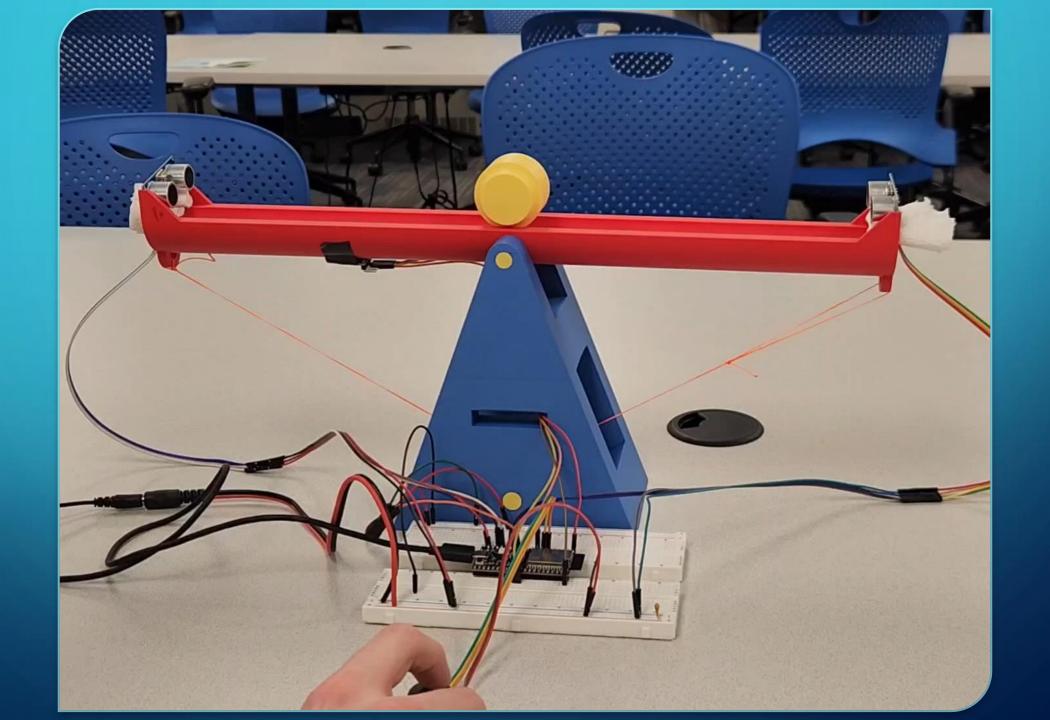
Hardware

- 3D printed components
- ESP32 Microcontroller

Software

- Micropython
- Cascade-type PID control

DEMONSTRATION



MOVING FORWARD

Limitations

Slow max angular velocity

led to messy data

Curved surface of ball

Pros

- Economical learning opportunity
- Engaging design

