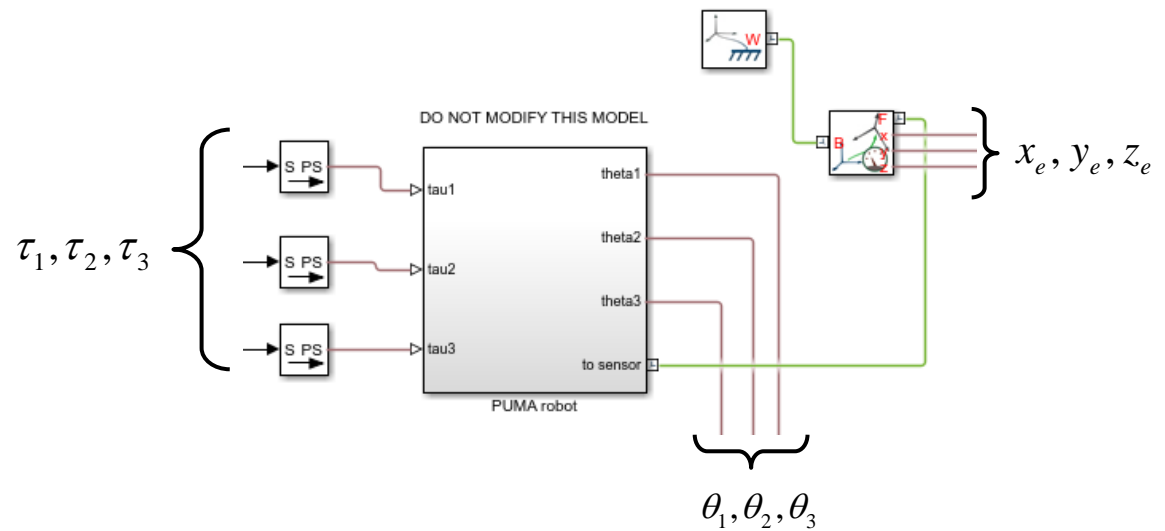
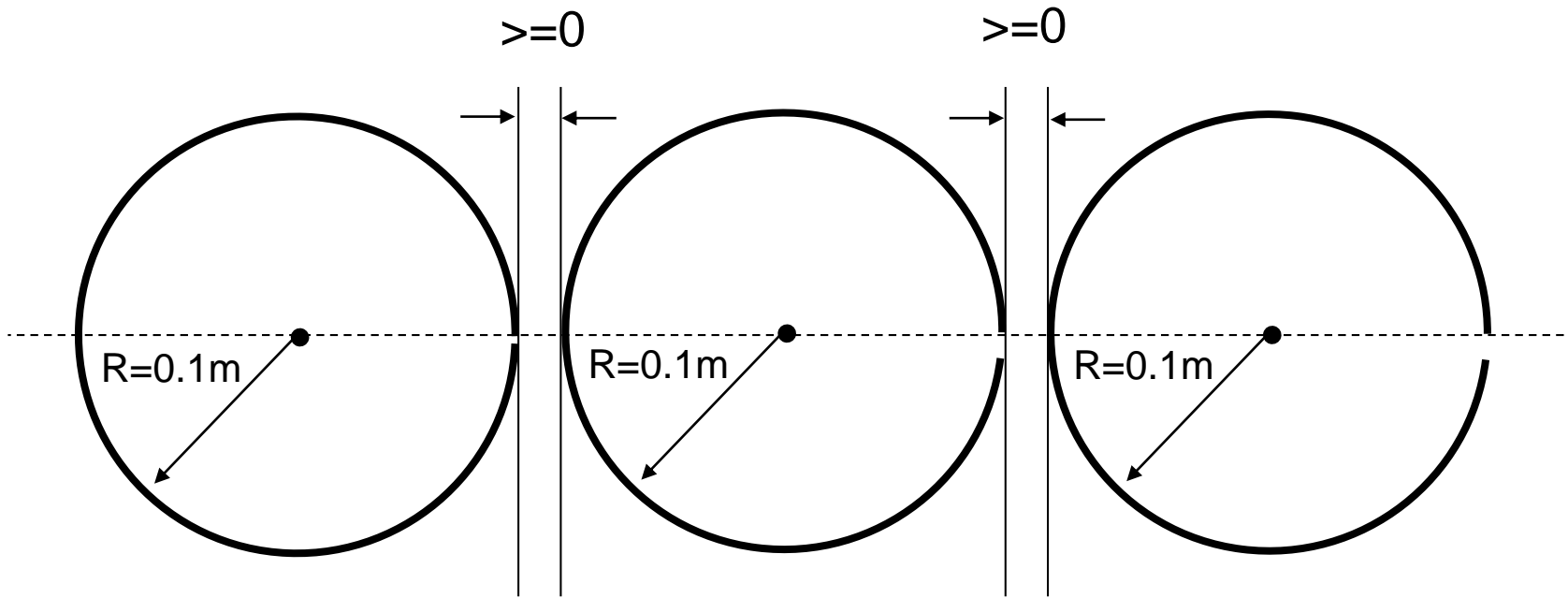


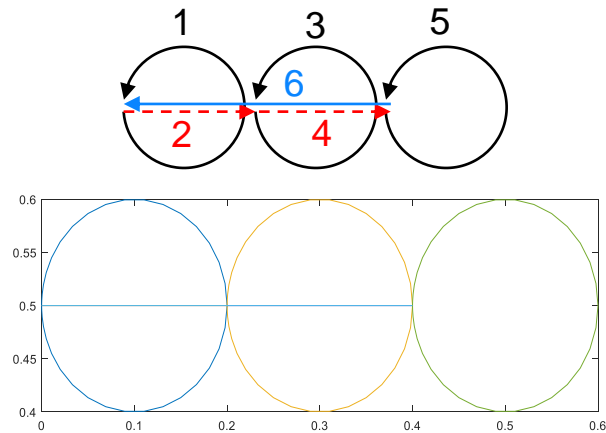
Implement your controller here



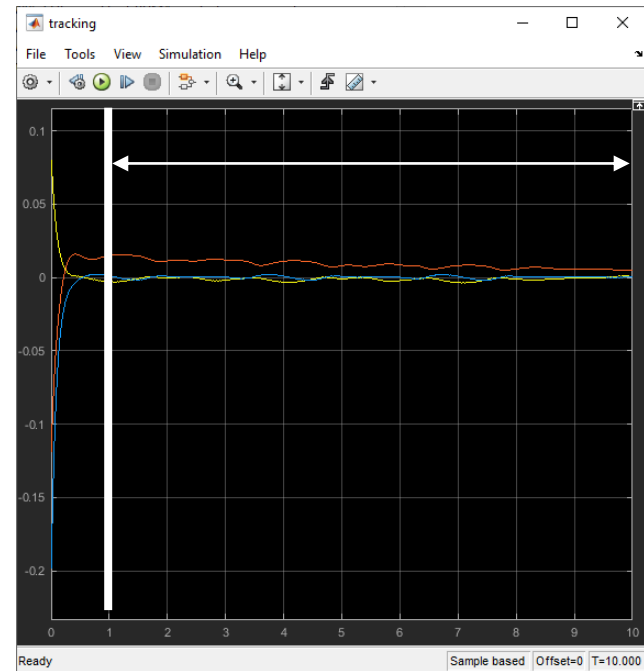


Draw three circles with a radius of 0.1m that are aligned on a line. There should be zero or greater distances between them. Trajectory from one cycle to next needs to be planned, too.

Reference

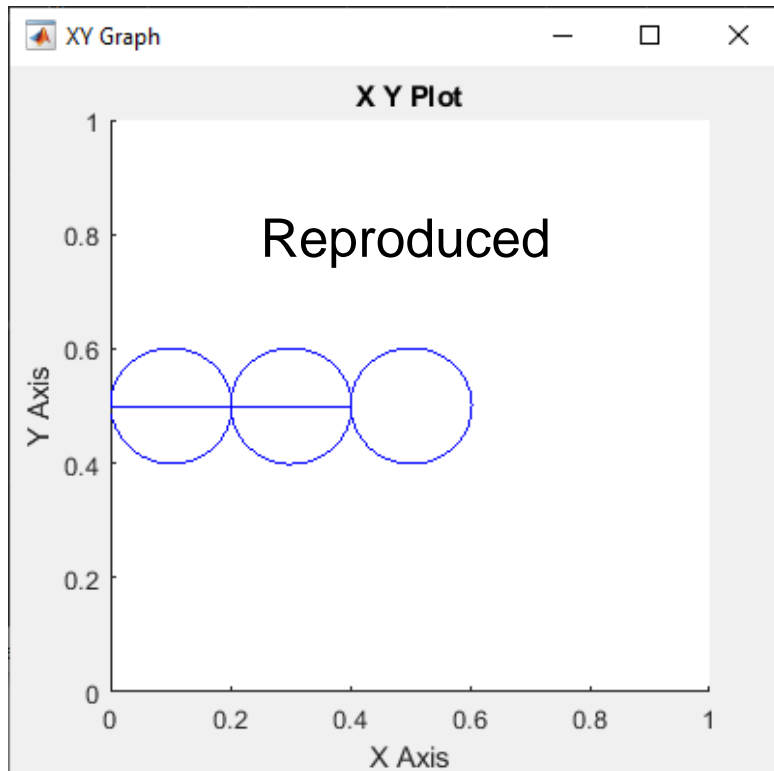
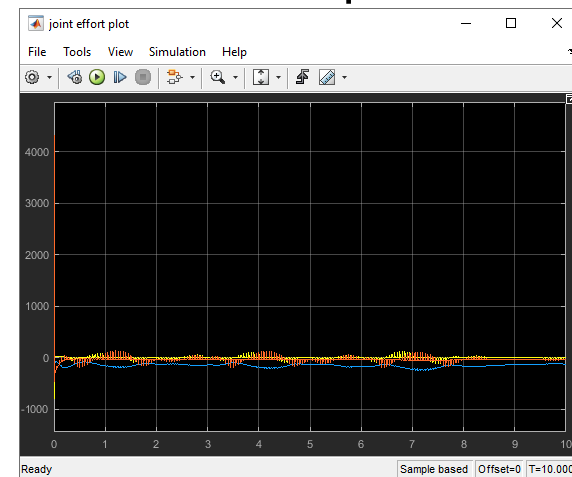


Tracking error



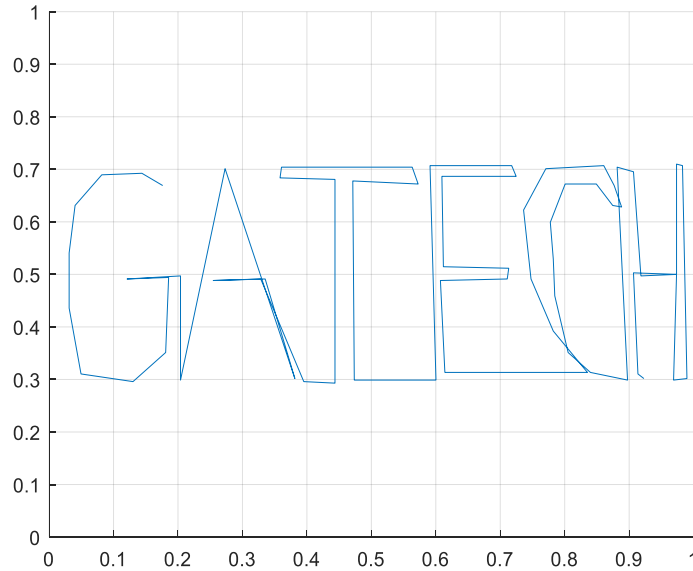
Peak error between $t=1 \sim 10$ is $< 3\text{cm}$.
RMSE is XXX cm

Joint torques

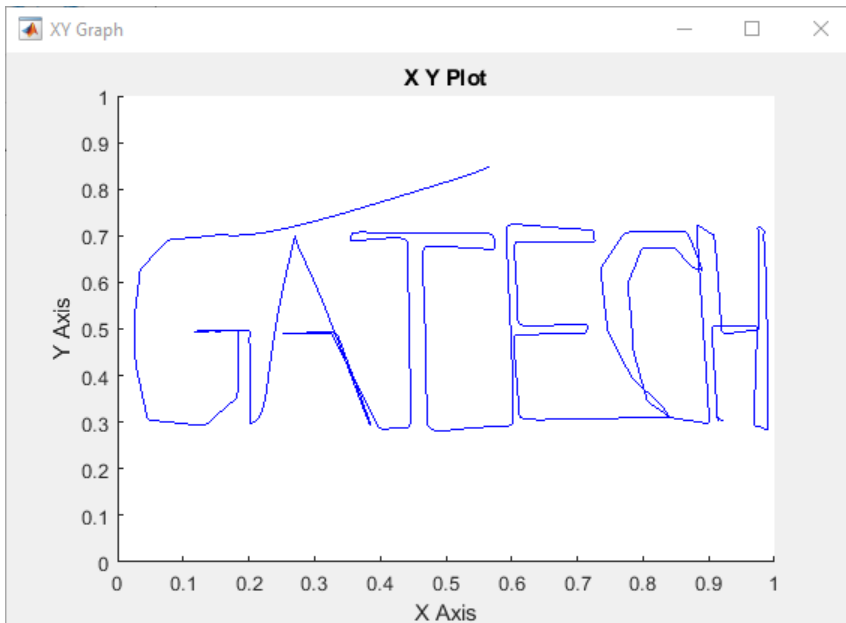


This particular sample does NOT satisfy the requirements.

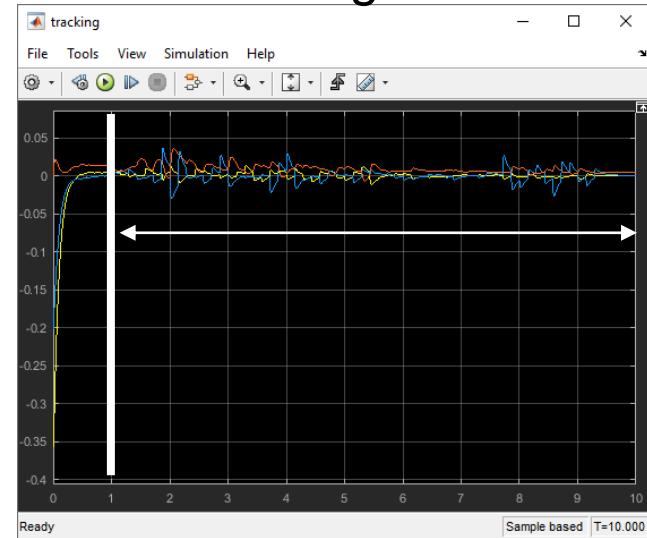
Reference



Reproduced



Tracking error



Peak error between $t=1 \sim 10$ is **4.4 cm**.
RMSE between $t=1 \sim 10$ is **1.42 cm**.

Joint torques

