

# Process Control Using a PID Controller

# Introduction

In the chemical process industry it is often important to control a specific process. PID control (proportional-integral-derivative control) is one way to achieve that, but it can be difficult to optimize the parameters in the PID algorithm. This example illustrates how you can implement a PID control algorithm to simulate a process control system and to find the optimal PID parameters.

This application is a generic example but could resemble the environment in a combustion chamber where the concentration at the ignition point is crucial. Two gas streams with different oxygen concentrations are mixed in the combustion chamber. The concentration is measured at the ignition point before complete mixing of the streams is reached. The control algorithm alters the inlet velocity of the gas with the lower oxygen content to achieve the desired total concentration at the ignition point. Since an increased flow of that gas will decrease the concentration, the PID coefficients will have a negative sign for this PID controller.

# Model Definition

The model geometry appears in Figure 1. At the upper inlet, a gas stream with high oxygen content enters the reactor at a velocity of 10 mm/s, while a gas with a lower oxygen level enters from the left. The oxygen concentration is measured at a measurement point, and the inlet velocity of the less concentrated stream is altered by the PID control algorithm to achieve the desired concentration at that point.

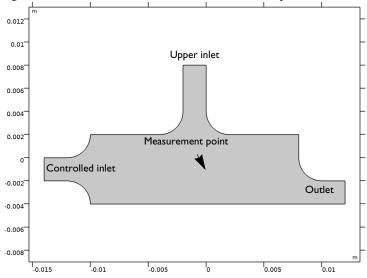


Figure 1: Model geometry.

The model uses the Laminar Flow interface to describe the fluid flow and the Transport of Diluted Species interface for the mass balance. The corresponding equations read (assuming incompressible flow and absence of reactions)

$$\rho \frac{\partial \mathbf{u}}{\partial t} - \nabla \cdot [\eta (\nabla \mathbf{u} + (\nabla \mathbf{u})^T)] + \rho \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p = \mathbf{0}$$

$$\nabla \cdot \mathbf{u} = 0$$

$$\frac{\partial c}{\partial t} + \nabla \cdot (-D\nabla c) = -\mathbf{u} \cdot \nabla c$$

To formulate the boundary conditions for the mass-transport equation, begin by assuming that you know the two inlet concentrations. In addition, assume that the reactant transport at the outlet is mainly driven by convection; that is, neglect diffusion in the main direction

of the convective flow. A no-flux boundary condition describes all walls. The boundary conditions for the mass balance are:

TABLE I: MASS-BALANCE BOUNDARY CONDITIONS.

BOUNDARY	CONSTRAINT
Upper inlet	$c = c_{ m in,top}$
Controlled inlet	$c = c_{ m in,inlet}$
Outlet	$\mathbf{n} \cdot (-D\nabla c) = 0$
Walls	$\mathbf{N} \cdot \mathbf{n} = 0$

Here c is the concentration;  $c_{\mathrm{in,top}}$  and  $c_{\mathrm{in,inlet}}$  are the inlet concentrations (SI unit: mol/  $\mathrm{m}^3$ ) for the upper and controlled inlets, respectively; D is the applied diffusivity (SI unit:  $m^2/s$ ); and **N** is the molar flux (SI unit: mol/( $m^2 \cdot s$ )).

The model uses the following boundary conditions for the fluid flow:

TABLE 2: FLUID-FLOW BOUNDARY CONDITIONS.

BOUNDARY	CONSTRAINT
Upper inlet	$\mathbf{u} = (0, -v_{\text{in,top}})$
Controlled inlet	$\mathbf{u} = (u_{\text{in}}, 0)$
Outlet	$p_0 = 0$
Inlet sections	$\mathbf{n} \cdot \mathbf{u} = 0$
Walls	$\mathbf{u} = 0$

Here  $\mathbf{u}$  is the velocity vector (SI unit: m/s),  $v_{\text{in,top}}$  is the inlet velocity at the top inlet, and  $u_{\rm in}$  is the PID-controlled velocity. At the outlet, set the pressure to 0. No Slip boundary conditions describe all walls except the inlet sections where slip conditions apply, allowing for a smooth transition to a laminar velocity profile.

The PID control algorithm used to calculate  $u_{in}$  is the following, which is the standard PID control algorithm available in the PID Controller add-in:

$$u_{\rm in}(t) = k_{\rm P}(c_{\rm set} - c(t)) + k_{\rm I} \int_{0}^{t} (c_{\rm set} - c(\tau)) d\tau - k_{\rm D} \frac{\partial}{\partial t} c(t)$$
 (1)

with the following parameters:

TABLE 3: PID CONTROLLER PARAMETERS.

PARAMETER	VALUE
$c_{ m set}$	0.5 mol/m <sup>3</sup>
$k_{ m P}$	-0.5 m <sup>4</sup> /(mol·s)
$k_{ m I}$	$-1 \text{ m}^4/(\text{mol}\cdot\text{s}^2)$
$k_{ m D}$	-10 <sup>-3</sup> m <sup>4</sup> /mol

As mentioned, the negative values of the coefficients reflect the fact that  $c_{\rm set}$  is lower than the concentration at the upper inlet,  $c_{
m in,top}$ , and that the purpose of the gas stream at the controlled inlet thus is to reduce the concentration. In practice, the derivative constant,  $k_{\rm D}$ , is set to 0 in most cases as this parameter can be difficult to determine. Moreover, the derivative term may increase the fluctuations in the system because it amplifies noise in the measurement c. The PID Controller add-in includes the option to filter the derivative part, which reduced the influence of high-frequency noise and therefore makes the derivative part more useful.

# Results and Discussion

The two plots in Figure 2 show the oxygen concentration and the velocity streamlines in the chamber after 0.05 s and 2 s, respectively. The figures show that the measured concentration depends strongly on the flow field. At startup, when the inlet velocity of the stream entering from the left is very low, the sensor is entirely exposed to the highly concentrated stream, and as the left inlet velocity increases the opposite relation occurs.

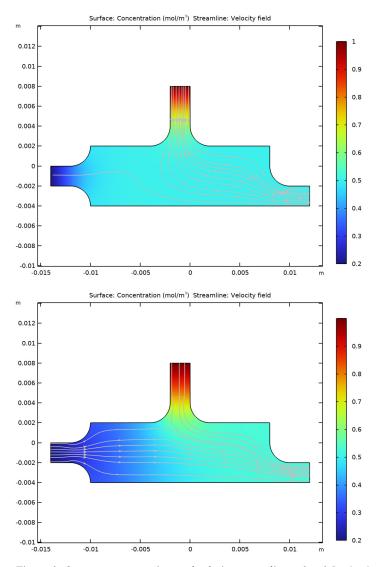


Figure 2: Oxygen concentration and velocity streamlines after 0.1 s (top) and 1.5 s (bottom).

Figure 3 shows the inlet velocity and concentration in the measurement point as a function of time for two different values for the  $k_{\rm P}$  parameter. The green line represents the results for a  $k_{\rm P}$  value of 0.5 m<sup>4</sup>/(mol·s) while the blue line corresponds to  $k_{\rm P}$  equal to 0.1 m<sup>4</sup>/

(mol·s). The results evaluated for the smaller  $k_{\rm P}$  value oscillate more before stabilizing. Thus, it is clear that for this case the higher  $k_{\rm P}$  value yields a more stable process control.

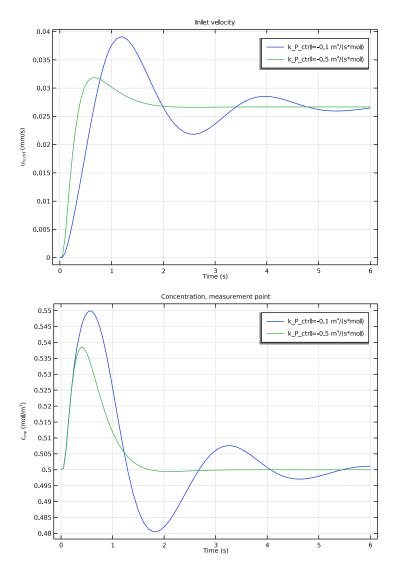


Figure 3: PID-controlled inlet velocity (top) and concentration in the measurement point (bottom) as a function of time for  $k_{\rm P}=0.5~m^4/({\rm mol\cdot s})$  (green) and  $k_{\rm P}=0.1~m^4/({\rm mol\cdot s})$  (blue).

# Application Library path: COMSOL Multiphysics/Multiphysics/pid control

# Modeling Instructions

From the File menu, choose New.

#### NEW

In the New window, click Model Wizard.

#### MODEL WIZARD

- I In the Model Wizard window, click **2** 2D.
- 2 In the Select Physics tree, select Fluid Flow>Single-Phase Flow>Laminar Flow (spf).
- 3 Click Add.
- 4 In the Select Physics tree, select Chemical Species Transport> Transport of Diluted Species (tds).
- 5 Click Add.
- 6 Click Study.
- 7 In the Select Study tree, select General Studies>Time Dependent.
- 8 Click **Done**.

#### **GLOBAL DEFINITIONS**

#### Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.

**3** In the table, enter the following settings:

Name	Expression	Value	Description
v_in_top	0.01[m/s]	0.01 m/s	Velocity, upper inlet
c_in_top	1[mol/m^3]	I mol/m³	Concentration, upper inlet
c_in_inlet	0.2[mol/m^3]	0.2 mol/m³	Concentration, controlled inlet
c00	0.5[mol/m^3]	0.5 mol/m³	Initial concentration, chamber interior
D	1e-4[m^2/s]	IE-4 m <sup>2</sup> /s	Diffusivity
c_set	0.5[mol/m^3]	0.5 mol/m³	Setpoint concentration
k_P_ctrl	-0.5[m^4/(mol*s)]	-0.5 m <sup>4</sup> /(s·mol)	Proportional parameter
k_I_ctrl	-1[m^4/(mol*s^2)]	-1 m <sup>4</sup> /(s <sup>2</sup> ·mol)	Integral parameter
k_D_ctrl	-1e-3[m^4/mol]	-0.001 m <sup>4</sup> /mol	Derivative parameter

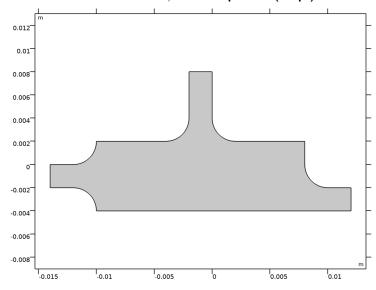
As mentioned in the Model Definition section, the PID parameters are negative because the setpoint concentration is lower than that at the upper inlet.

# GEOMETRY I

Create the geometry. To simplify this step, insert a prepared geometry sequence.

- I In the Geometry toolbar, click Insert Sequence and choose Insert Sequence.
- 2 Browse to the model's Application Libraries folder and double-click the file pid\_control\_geom\_sequence.mph.
- 3 In the Geometry toolbar, click **Build All**.
- 4 Click the **Zoom Extents** button in the **Graphics** toolbar.





#### DEFINITIONS

Next, add a probe to sample the concentration and its time derivative at the point x = 0, y = -0.002.

#### Domain Point Probe I

- I In the Definitions toolbar, click Probes and choose Domain Point Probe.
- 2 In the Settings window for Domain Point Probe, locate the Point Selection section.
- 3 In row Coordinates, set y to -0.002.

# Point Probe Expression I (ppb1)

- I In the Model Builder window, expand the Domain Point Probe I node, then click Point Probe Expression I (ppbI).
- 2 In the Settings window for Point Probe Expression, type c\_mp in the Variable name text field.
- **3** Click **Replace Expression** in the upper-right corner of the **Expression** section. From the menu, choose Component I (compl)>Transport of Diluted Species>Species c>c -Concentration - mol/m3.

# Point Probe Expression 2 (ppb2)

I In the Model Builder window, right-click Domain Point Probe I and choose Point Probe Expression.

- 2 In the Settings window for Point Probe Expression, type ct\_mp in the Variable name text field
- 3 Locate the Expression section. In the Expression text field, type ct.
  Proceed to import the PID Controller add-in and set up the control algorithm.
- 4 In the Home toolbar, click Windows and choose Add-in Libraries.

#### ADD-IN LIBRARIES

- I In the Add-in Libraries window, in the tree, select the check box for the node COMSOL Multiphysics>pid\_controller (if it is not already selected).
- 2 Click Done to load the add-in and close the Add-in Libraries window.

#### DEVELOPER

In the Developer toolbar, click 🍰 Add-ins and choose PID Controller>PID Controller.

#### **GLOBAL DEFINITIONS**

PID Controller I

- I In the Model Builder window, under Global Definitions click PID Controller I.
- 2 In the Settings window for PID Controller, locate the Controller Parameters section.
- **3** Enter the following settings:

Parameter	Value
Proportional gain	k_P_ctrl
Integral gain	k_I_ctrl
Derivative gain	k_D_ctrl
Reference value	c_set

Keep the default values for the remaining parameters.

4 Click Create.

#### MATERIALS

For the physics setup, you need to specify the density,  $\rho$ , and the dynamic viscosity,  $\mu$ , of the fluid. For this purpose, define a material.

#### Fluid

- I In the Model Builder window, under Component I (compl) right-click Materials and choose Blank Material.
- 2 In the Settings window for Material, type Fluid in the Label text field.

- **3** Select Domain 1 only.
- **4** Locate the **Material Contents** section. In the table, enter the following settings:

Property	Variable	Value	Unit	Property group
Density	rho	1.2[kg/m^3]	kg/m³	Basic
Dynamic viscosity	mu	3e-5[Pa*s]	Pa·s	Basic

You are now ready to set up the physics of the model.

# LAMINAR FLOW (SPF)

#### Inlet I

- I In the Model Builder window, under Component I (compl) right-click Laminar Flow (spf) and choose Inlet.
- 2 Select Boundary 1 only.
- 3 In the Settings window for Inlet, locate the Velocity section.
- 4 In the  $U_0$  text field, type comp2.u in ctr1. This is the inlet velocity defined by the PID controller.

#### Inlet 2

- I In the Physics toolbar, click Boundaries and choose Inlet.
- **2** Select Boundary 7 only.
- 3 In the Settings window for Inlet, locate the Velocity section.
- **4** In the  $U_0$  text field, type v\_in\_top.

#### Outlet 1

- I In the Physics toolbar, click Boundaries and choose Outlet.
- 2 Select Boundary 13 only.

# Wall 2

- I In the Physics toolbar, click Boundaries and choose Wall.
- 2 Select Boundaries 2, 3, 6, and 8 only.
- 3 In the Settings window for Wall, locate the Boundary Condition section.
- 4 From the Wall condition list, choose Slip.

#### TRANSPORT OF DILUTED SPECIES (TDS)

# Transport Properties 1

- In the Model Builder window, under Component I (compl)>
   Transport of Diluted Species (tds) click Transport Properties I.
- 2 In the Settings window for Transport Properties, locate the Convection section.
- 3 From the u list, choose Velocity field (spf).
- **4** Locate the **Diffusion** section. In the  $D_{\rm c}$  text field, type D.

#### Initial Values 1

- I In the Model Builder window, click Initial Values I.
- 2 In the Settings window for Initial Values, locate the Initial Values section.
- **3** In the c text field, type c00.

### Inflow I

- I In the Physics toolbar, click Boundaries and choose Inflow.
- 2 Select Boundary 1 only.
- 3 In the Settings window for Inflow, locate the Concentration section.
- **4** In the  $c_{0,c}$  text field, type c\_in\_inlet.

#### Inflow 2

- I In the Physics toolbar, click Boundaries and choose Inflow.
- **2** Select Boundary 7 only.
- 3 In the Settings window for Inflow, locate the Concentration section.
- **4** In the  $c_{0,c}$  text field, type c\_in\_top.

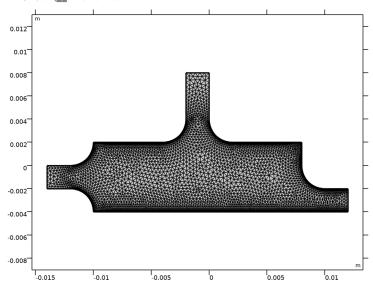
#### Outflow I

- I In the Physics toolbar, click Boundaries and choose Outflow.
- 2 Select Boundary 13 only.

#### MESH I

- I In the Model Builder window, under Component I (compl) click Mesh I.
- 2 In the Settings window for Mesh, locate the Physics-Controlled Mesh section.
- **3** From the **Element size** list, choose **Finer**.





# STUDY I

Use a parametric sweep to solve for two different values of the proportional parameter,  $k\_P$ .

# Parametric Sweep

- I In the Study toolbar, click Parametric Sweep.
- 2 In the Settings window for Parametric Sweep, locate the Study Settings section.
- 3 Click + Add.
- 4 In the table, enter the following settings:

Parameter name	Parameter value list
k_P_ctrl (Proportional parameter)	-0.1 -0.5

# Step 1: Time Dependent

- I In the Model Builder window, click Step I: Time Dependent.
- 2 In the Settings window for Time Dependent, locate the Study Settings section.
- 3 In the Output times text field, type range (0,0.05,1) range (1.1,0.1,6).

# Solution I (soll)

I In the Study toolbar, click Show Default Solver.

- 2 In the Model Builder window, expand the Solution I (soll) node, then click Time-Dependent Solver I.
- 3 In the Settings window for Time-Dependent Solver, click to expand the Time Stepping section.
- 4 From the Method list, choose Generalized alpha.
- 5 From the Steps taken by solver list, choose Intermediate.
  This forces the solver to take at least one step in each of the time intervals you specified.
- **6** Click to expand the **Advanced** section. In the **Study** toolbar, click **Compute**.

#### RESULTS

# Concentration (tds)

The default **Concentration** plot group contains a surface plot that shows the concentration at the end of the simulated time span, as well as a streamline plot of the velocity. Study the solution at t = 0.05 s and t = 2 s.

First, however, adjust the streamline positioning so that the streamline density reflects the velocity magnitude.

#### Streamline 1

- I In the Model Builder window, expand the Concentration (tds) node, then click Streamline I.
- 2 In the Settings window for Streamline, click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component 1 (comp1)>Laminar Flow> Velocity and pressure>u,v Velocity field.
- **3** Locate the **Streamline Positioning** section. From the **Positioning** list, choose **Magnitude controlled**.
- 4 In the Minimum distance text field, type 0.005.
- 5 In the Maximum distance text field, type 0.1.
- 6 In the Concentration (tds) toolbar, click Plot.

#### Concentration (tds)

- I In the Model Builder window, click Concentration (tds).
- 2 In the Settings window for 2D Plot Group, locate the Data section.
- 3 From the Time (s) list, choose 0.05.
- 4 In the Concentration (tds) toolbar, click Plot.
- 5 Click the **Zoom Extents** button in the **Graphics** toolbar.

- 6 From the Time (s) list, choose 3.
- 7 In the Concentration (tds) toolbar, click **Plot**.

Compare the resulting plots with those in Figure 2.

Inlet Velocity

Plot the PID-controlled inlet velocity (Figure 3).

- I In the Model Builder window, under Results click ID Plot Group 5.
- 2 In the Settings window for ID Plot Group, type Inlet Velocity in the Label text field.
- 3 Click to expand the **Title** section. From the **Title type** list, choose **Manual**.
- 4 In the Title text area, type Inlet velocity.
- 5 Locate the Plot Settings section.
- 6 Select the y-axis label check box. In the associated text field, type u<sub>in,ctrl</ sub> (mm/s).

Global I

- I In the Model Builder window, expand the Inlet Velocity node, then click Global I.
- 2 In the Settings window for Global, click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Component 2 (comp2)>Definitions> Variables>comp2.u\_in\_ctrl - Control variable - m/s.
- 3 Locate the x-Axis Data section. From the Axis source data list, choose Time.
- 4 Click to expand the Legends section. Find the Include subsection. Clear the Description check box.
- 5 In the Inlet Velocity toolbar, click Plot.

Proceed to plot the concentration at the measurement point as a function of time (Figure 3).

Inlet Velocity

In the Model Builder window, right-click Inlet Velocity and choose Duplicate.

Concentration, Measurement Point

- I In the Model Builder window, under Results click Inlet Velocity I.
- 2 In the Settings window for ID Plot Group, type Concentration, Measurement Point in the Label text field.
- 3 Locate the Title section. In the Title text area, type Concentration, measurement point.

4 Locate the **Plot Settings** section. In the **y-axis label** text field, type c<sub>mp</sub> (mo1/m<sup>3</sup>).

# Global I

- I In the Model Builder window, expand the Concentration, Measurement Point node, then click Global I.
- 2 In the Settings window for Global, click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Component I (compl)>Definitions> c\_mp Domain Point Probe I, c mol/m³.
- 3 Locate the x-Axis Data section. From the Axis source data list, choose Time.
- **4** In the **Concentration, Measurement Point** toolbar, click **Plot**. The resulting plot should look like that in the lower panel of Figure 3.