

Sensitive High-Resolution Ion Microprobe

A spectrometer designed to measure the energy, energy spread, and mass-to-charge ratio of a particle beam, can be simulated by solving the equations of motion for ions in an electric and magnetic field. Such a device can be most easily understood by looking at the ideal design, where the electric and magnetic fields are at their theoretically optimum values, which are easily derived.

Model Definition

Using some basic mathematics, the magnitude and direction of the electric and magnetic fields (or to be precise, the magnetic flux density) can be computed to ensure 100 % transmission for an ion of a given initial energy and charge to mass ratio.

The geometry of a basic Sensitive High-Resolution Ion Microprobe (SHRIMP) is shown below. The basic operating principle involves isolating particles of a specified energy and mass-to-charge ratio by subjecting the beam to a radial electric field followed by a uniform magnetic field.

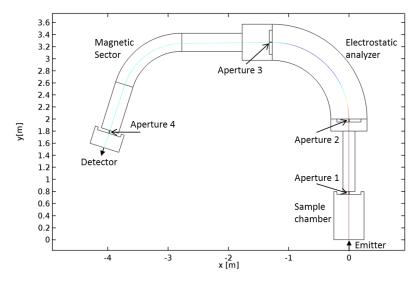


Figure 1: Basic SHRIMP geometry. Particles enter through the emitter, and are subjected first to an electric field directed radially inward, and then to a uniform out-of-plane magnetic flux density.

FORCE BALANCE

The toroidal electrostatic analyzer filters particles according to their kinetic energy. For a particle to propagate through the analyzer along a circular arc of radius r (SI unit: m), the centrifugal force acting on the particle must balance the electric force, that is:

$$\frac{mv^2}{r} = qE_r \tag{1}$$

where

• m (SI unit: kg) is the particle mass,

• v (SI unit: m/s) is the particle velocity magnitude,

• q (SI unit: C) is the absolute value of the particle charge, and

• E_r (SI unit: V/m) is the radial component of the electric field.

Using the classical definition of kinetic energy, $\varepsilon = mv^2/2$, the radial component of the electric field should be:

$$E_r = \frac{2\varepsilon}{qr} \tag{2}$$

This can be conveniently entered into COMSOL using an expression.

The magnetic sector filters particles according to their mass-to-charge ratio. For particles to propagate through a toroidal region along a circular arc of radius r while subjected to a uniform magnetic flux density \mathbf{B} (SI unit: T), the centrifugal force must once again balance the magnetic force:

$$\frac{mv^2}{r} = q(\mathbf{v} \times \mathbf{B}) \tag{3}$$

where \mathbf{v} (SI unit: m/s) is the particle velocity. Since the force should only be produced in the xy-plane, the magnetic flux density should only have a z-component:

$$B_z = -\frac{mv}{qr} \tag{4}$$

For a sulfur hexafluoride ion with an initial energy of 50 eV, electrostatic analyzer with mean radius 1.272 m, and magnetic sector of mean radius 1 m, this results in an electric field magnitude of 78.616 V/m and a magnetic flux density magnitude of 0.012346 T.

The goal of the model is to compute the nominal trajectory of the particle beam and the fraction of ions that reach various points along the beam path (transmission probability).

RELEASE MECHANISM

A realistic velocity distribution of the ions entering the modeling domain is necessary. The Particle Beam feature provides may different ways to characterize the initial beam position and velocity. A common way of characterizing the beam is to use Twiss parameters and emittance, which give a measure of the transverse velocity distribution of the particles. It is also possible to specify the phase space ellipse dimensions directly, as indicated in Figure 2.

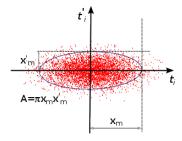


Figure 2: Beam specification using phase space ellipse dimensions.

In this case, the maximum transverse displacement is equal to the size of the inlet aperture and the maximum transverse velocity is 0.001 times the velocity norm, corresponding to a beam which diverges very slowly. Despite this, a significant fraction of the beam current will be lost as the beam travels through 4 additional apertures en route to the detector.

Results and Discussion

The trajectories of the particle beam are indicated in Figure 3 below. The beam starts at (0,0,0) and travels along the y direction. Part of the beam is lost at the first aperture. After traveling 2 m in the y direction, the beam encounters the radial electrostatic force, whose magnitude is selected to ensure maximum transmittance. If there were ions present with a different charge number or initial energy, they would not reach the third aperture, at the other end of the electrostatic separator.

At the boundaries where the electric and magnetic forces change discontinuously, a **Wall** node with a Pass through condition is used. This improves the accuracy of the calculation of the particle trajectories during time steps in which they enter or leave one of these regions.





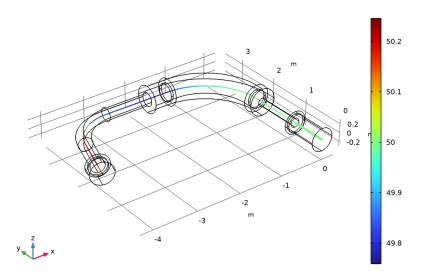


Figure 3: Plot of the particle trajectories through the system.

Once the ions cross the third aperture, they travel in the negative x direction until they enter the domain containing the magnetic filter. The uniform out-of-plane magnetic flux density causes the beam to follow a circular arc in this region. The magnetic flux density is chosen so that only the sulfur hexafluoride ions are transmitted through the forth aperture toward the detector. Any ions with a different initial energy or charge to mass ratio would be separated during this stage.

The nominal trajectory of the beam is shown in Figure 4. This is the average position of the beam, where the averaging only occurs for particles which reach the detector. Each Particle Counter feature in the model creates variables to filter particles based on the domain or boundary they occupy, allowing convenient visualization of the nominal trajectory of a beam which connects a source and a detector.

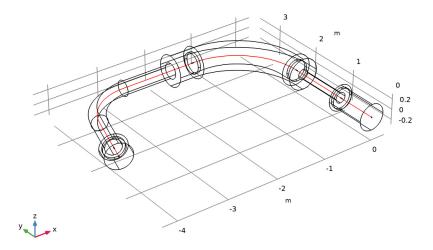


Figure 4: Plot of the nominal trajectory of the particles transmitted from the inlet to the detector.

The transmission probability of the beam in this example is about 0.3.

Reference

1. https://en.wikipedia.org/wiki/Sensitive_high-resolution_ion_microprobe

Application Library path: Particle_Tracing_Module/ Charged_Particle_Tracing/sensitive_high_resolution_ion_microprobe

Modeling Instructions

From the File menu, choose New.

NEW

In the New window, click Model Wizard.

MODEL WIZARD

- I In the Model Wizard window, click **3D**.
- 2 In the Select Physics tree, select AC/DC>Particle Tracing>Charged Particle Tracing (cpt).
- 3 Click Add.
- 4 Click 🗪 Study.
- 5 In the Select Study tree, select General Studies>Time Dependent.
- 6 Click M Done.

GEOMETRY I

- I In the Geometry toolbar, click Insert Sequence and choose Insert Sequence.
- 2 Browse to the model's Application Libraries folder and double-click the file sensitive_high_resolution_ion_microprobe_geom_sequence.mph.
- 3 In the Insert Sequence dialog box, click OK.
- 4 In the Geometry toolbar, click **Build All**.

Load the model's variables, which define the electric and magnetic fields.

DEFINITIONS

Variables 1

- I In the Model Builder window, under Component I (compl) right-click Definitions and choose Variables.
- 2 In the Settings window for Variables, locate the Variables section.
- 3 Click Load from File.
- **4** Browse to the model's Application Libraries folder and double-click the file sensitive_high_resolution_ion_microprobe_variables.txt.

GLOBAL DEFINITIONS

Load the model's physics parameters.

Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- 3 Click Load from File.
- 4 Browse to the model's Application Libraries folder and double-click the file sensitive high resolution ion microprobe phys parameters.txt.

Define selections.

DEFINITIONS

Electrostatic Analyzer

- I In the **Definitions** toolbar, click **\(\frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Electrostatic Analyzer in the Label text field.
- **3** Select Domain 6 only.

Magnetic Sector

- I In the **Definitions** toolbar, click **\(\frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Magnetic Sector in the Label text field.
- **3** Select Domain 3 only.

Sample Chamber

- I In the **Definitions** toolbar, click **\(\frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Sample Chamber in the Label text field.
- **3** Select Domain 8 only.

Detector

- I In the **Definitions** toolbar, click **\(\frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Detector in the Label text field.
- **3** Select Domain 1 only.

Filters

- I In the **Definitions** toolbar, click **\(\frac{1}{2} \) Explicit**.
- 2 In the Settings window for Explicit, type Filters in the Label text field.
- 3 Locate the Input Entities section. From the Geometric entity level list, choose Boundary.
- **4** Select Boundaries 5–8, 14–20, 39–47, 51, 52, 63–69, 72, 75–80, 83–86, and 91–94 only.

Abertures

- I In the **Definitions** toolbar, click **\(\) Explicit**.
- 2 In the Settings window for Explicit, type Apertures in the Label text field.
- 3 Locate the Input Entities section. From the Geometric entity level list, choose Boundary.
- 4 Select Boundaries 23, 28, 52, and 80 only.
- 5 Click the Wireframe Rendering button in the Graphics toolbar.

Specify the particle mass and charge. Then define the forces that will act on the particles.

CHARGED PARTICLE TRACING (CPT)

- I In the Model Builder window, under Component I (compl) click Charged Particle Tracing (cpt).
- 2 In the Settings window for Charged Particle Tracing, locate the Particle Release and Propagation section.
- 3 From the Particle release specification list, choose Specify current.
- 4 From the Formulation list, choose Newtonian, first order.
- 5 Locate the Additional Variables section. Select the Store particle status data check box.

Particle Properties 1

- In the Model Builder window, under Component I (compl)>Charged Particle Tracing (cpt) click Particle Properties I.
- 2 In the Settings window for Particle Properties, locate the Particle Mass section.
- **3** In the $m_{\rm p}$ text field, type Mr*mp_const.
- 4 Locate the Charge Number section. In the Z text field, type 1.

Electric Force 1

- I In the Physics toolbar, click **Domains** and choose **Electric Force**.
- 2 In the Settings window for Electric Force, locate the Domain Selection section.
- 3 From the Selection list, choose Electrostatic Analyzer.
- **4** Locate the **Electric Force** section. Specify the \mathbf{E} vector as

Ex	x
Еу	у
Ez	7

Magnetic Force 1

- I In the Physics toolbar, click **Domains** and choose Magnetic Force.
- 2 In the Settings window for Magnetic Force, locate the Domain Selection section.
- 3 From the Selection list, choose Magnetic Sector.
- **4** Locate the Magnetic Force section. Specify the $\bf B$ vector as



Ву	у
Bz	z

Particle Beam 1

- I In the Physics toolbar, click **Boundaries** and choose Particle Beam.
- **2** Select Boundary 74 only.
- 3 In the Settings window for Particle Beam, locate the Initial Position section.
- **4** In the *N* text field, type 5000.
- 5 Locate the Initial Transverse Velocity section. From the Transverse velocity distribution specification list, choose Specify phase space ellipse dimensions.
- 6 In the $x_{\rm m}$ text field, type 1 [cm].
- 7 In the $x_{\rm m}'$ text field, type 0.001.
- **8** Locate the **Initial Longitudinal Velocity** section. In the E text field, type Ei0.

Add Particle Counter features at the detector as well as at the lens apertures. The particle counters will be used to visualize the nominal trajectory of the beam ions that reach the detector.

Particle Counter 1

- I In the Physics toolbar, click **Boundaries** and choose Particle Counter.
- 2 Select Boundary 11 only.
- 3 In the Settings window for Particle Counter, locate the Particle Counter section.
- 4 From the Release feature list, choose Particle Beam 1.

Particle Counter 2

- I In the Physics toolbar, click **Boundaries** and choose Particle Counter.
- 2 Select Boundary 65 only.
- 3 In the Settings window for Particle Counter, locate the Particle Counter section.
- 4 From the Release feature list, choose Particle Beam 1.

Particle Counter 3

- I In the Physics toolbar, click **Boundaries** and choose Particle Counter.
- 2 Select Boundary 68 only.
- 3 In the Settings window for Particle Counter, locate the Particle Counter section.
- 4 From the Release feature list, choose Particle Beam 1.

Particle Counter 4

- I In the Physics toolbar, click **Boundaries** and choose **Particle Counter**.
- 2 Select Boundary 51 only.
- 3 In the Settings window for Particle Counter, locate the Particle Counter section.
- 4 From the Release feature list, choose Particle Beam 1.

Particle Counter 5

- I In the Physics toolbar, click **Boundaries** and choose **Particle Counter**.
- 2 Select Boundary 8 only.
- 3 In the Settings window for Particle Counter, locate the Particle Counter section.
- 4 From the Release feature list, choose Particle Beam 1.

Wall 2

- I In the Physics toolbar, click **Boundaries** and choose Wall.
- 2 In the Settings window for Wall, locate the Boundary Selection section.
- 3 From the Selection list, choose Apertures.
- 4 Locate the Wall Condition section. From the Wall condition list, choose Pass through. Specifying a Pass through condition at boundaries where the force changes discontinuously will increase the accuracy of the solution.

MESH I

- I In the Model Builder window, under Component I (compl) click Mesh I.
- 2 In the Settings window for Mesh, locate the Physics-Controlled Mesh section.
- 3 From the Element size list, choose Finer.

Free Triangular 1

- I In the Mesh toolbar, click A Boundary and choose Free Triangular.
- 2 Select Boundaries 3, 11, 61, and 74 only.

Size 1

- I Right-click Free Triangular I and choose Size.
- 2 In the Settings window for Size, locate the Element Size section.
- 3 From the Predefined list, choose Extra fine.
- 4 Click Build Selected.

Free Triangular 2

- I In the Model Builder window, under Component I (compl)>Mesh I right-click Free Triangular I and choose Duplicate.
- 2 In the Settings window for Free Triangular, locate the Boundary Selection section.
- **3** From the **Selection** list, choose **Filters**.

Size 1

- I In the Model Builder window, expand the Free Triangular 2 node, then click Size I.
- 2 In the Settings window for Size, locate the Element Size section.
- 3 From the Predefined list, choose Extremely fine.
- 4 Click Build Selected.
- 5 Click the Go to Default View button in the Graphics toolbar.

Free Tetrahedral I

- I In the Mesh toolbar, click A Free Tetrahedral.
- 2 In the Settings window for Free Tetrahedral, click **Build All**.

Because Newtonian, first order was selected from the Formulation list, the default solver uses explicit time stepping. This can significantly improve simulation time in some classes of nonstiff problems.

STUDY I

Step 1: Time Dependent

- I In the Model Builder window, under Study I click Step I: Time Dependent.
- 2 In the Settings window for Time Dependent, locate the Study Settings section.
- **3** From the **Time unit** list, choose **ms**.
- 4 In the Output times text field, type range (0,0.01,1).
- 5 In the Home toolbar, click **Compute**.

RESULTS

Particle Trajectories 1

- I In the Model Builder window, expand the Particle Trajectories (cpt) node, then click Particle Trajectories 1.
- 2 In the Settings window for Particle Trajectories, locate the Coloring and Style section.
- **3** Find the **Line style** subsection. From the **Type** list, choose **Line**.
- **4** Find the **Point style** subsection. From the **Type** list, choose **None**.

5 In the Particle Trajectories (cpt) toolbar, click Plot.

Color Expression 1

- I In the Model Builder window, expand the Particle Trajectories I node, then click Color Expression 1.
- 2 In the Settings window for Color Expression, click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component I (compl)> Charged Particle Tracing>Velocity and energy>cpt.Ep - Particle kinetic energy - J.
- 3 Locate the Expression section. From the Unit list, choose eV.
- 4 In the Particle Trajectories (cpt) toolbar, click Plot.
- 5 Click the **Zoom Extents** button in the **Graphics** toolbar. The resulting image should look like Figure 3.

The nominal trajectory of the fraction of the beam which reaches the detector can be visualized by modifying the default **Point Trajectories** plot.

Point Trajectories I

- I In the Model Builder window, expand the Average Beam Position (cpt) node, then click Point Trajectories 1.
- 2 In the Settings window for Point Trajectories, click Replace Expression in the upper-right corner of the Trajectory Data section. From the menu, choose Component I (compl)> Charged Particle Tracing>Particle Counter I>cpt.pcntl.qavtx,...,cpt.pcntl.qavtz -Average position of transmitted particles, Particle Beam I to Particle Counter I.

Color Expression I

- I In the Model Builder window, expand the Point Trajectories I node.
- 2 Right-click Color Expression I and choose Disable.

Average Beam Position (cpt)

Click the **Zoom Extents** button in the **Graphics** toolbar. The resulting image should look like Figure 4.

Finally, compute the transmission probability of the particles reaching the detector.

Global Evaluation 1

- I In the Results toolbar, click (8.5) Global Evaluation.
- 2 In the Settings window for Global Evaluation, locate the Data section.
- **3** From the Time selection list, choose Last.

- 4 Click Replace Expression in the upper-right corner of the Expressions section. From the menu, choose Component I (compl)>Charged Particle Tracing>Particle Counter I> cpt.pcntl.alpha - Transmission probability - I.
- 5 Click **= Evaluate**.

Appendix A — Geometry Instructions

ADD COMPONENT

In the **Home** toolbar, click **Add Component** and choose **3D**.

GLOBAL DEFINITIONS

Load the model's parameters.

Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- 3 Click Load from File.
- **4** Browse to the model's Application Libraries folder and double-click the file sensitive high resolution ion microprobe parameters.txt.

Create a parameterized geometry part for the four lenses used in the model.

LENS

- I In the Model Builder window, right-click Global Definitions and choose Geometry Parts> 3D Part.
- 2 In the Settings window for Part, type Lens in the Label text field.
- **3** Locate the **Input Parameters** section. In the table, enter the following settings:

Name	Default expression	Value	Description
rinner	0.5[cm]	0.005 m	Inner radius
router	0.2[m]	0.2 m	Outer radius
hlens	0.05[m]	0.05 m	Lens thickness

Cylinder I (cyll)

- I In the Geometry toolbar, click (Cylinder.
- 2 In the Settings window for Cylinder, locate the Size and Shape section.

- 3 In the Radius text field, type router.
- 4 In the **Height** text field, type hlens.
- 5 Locate the Axis section. From the Axis type list, choose y-axis.

Cylinder 2 (cyl2)

- I In the Geometry toolbar, click Cylinder.
- 2 In the Settings window for Cylinder, locate the Size and Shape section.
- 3 In the Radius text field, type rinner.
- 4 In the Height text field, type hlens.
- 5 Locate the Axis section. From the Axis type list, choose y-axis.

Difference I (dif1)

- I In the Geometry toolbar, click Booleans and Partitions and choose Difference.
- 2 Select the object cyll only.
- 3 In the Settings window for Difference, locate the Difference section.
- 4 Click to select the Activate Selection toggle button for Objects to subtract.
- **5** Select the object **cyl2** only.

Work Plane I (wbl)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object dif1, select Boundary 3 only.
- 5 In the Geometry toolbar, click **Build All**.

GEOMETRY I

Cylinder I (cyl1)

- I In the Geometry toolbar, click (Cylinder.
- 2 In the Settings window for Cylinder, locate the Size and Shape section.
- 3 In the Radius text field, type rsample.
- 4 In the **Height** text field, type hsample.
- 5 Locate the Axis section. From the Axis type list, choose y-axis.

Work Plane I (wbl)

I In the Geometry toolbar, click Work Plane.

- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- **4** On the object **cyll**, select Boundary 3 only.

Work Plane I (wbl)>Plane Geometry

In the Model Builder window, click Plane Geometry.

Work Plane I (wbl)>Circle I (cl)

- I In the Work Plane toolbar, click (Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type rin.

Cylinder 2 (cyl2)

- I In the Model Builder window, right-click Geometry I and choose Cylinder.
- 2 In the Settings window for Cylinder, locate the Size and Shape section.
- 3 In the Radius text field, type rentrance.
- 4 In the **Height** text field, type hentrance.
- **5** Locate the **Position** section. In the **y** text field, type hsample.
- 6 Locate the Axis section. From the Axis type list, choose y-axis.

Cylinder 3 (cyl3)

- I In the Geometry toolbar, click Cylinder.
- 2 In the Settings window for Cylinder, locate the Size and Shape section.
- 3 In the Radius text field, type r1 analyzer.
- 4 In the Height text field, type h analyzer pre.
- **5** Locate the **Position** section. In the **y** text field, type hsample+hentrance.
- 6 Locate the Axis section. From the Axis type list, choose y-axis.

Work Plane 2 (wb2)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object cyl3, select Boundary 4 only.
- 5 Click A Go to Plane Geometry.

Work Plane 2 (wp2)>Circle 1 (c1)

I In the Work Plane toolbar, click • Circle.

- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type r1 analyzer.

Revolve I (rev I)

- I Right-click Geometry I and choose Revolve.
- 2 In the Settings window for Revolve, locate the Revolution Angles section.
- 3 Click the Angles button.
- 4 In the End angle text field, type ang_analyzer.
- 5 Locate the Revolution Axis section. From the Axis type list, choose 3D.
- 6 Find the Point on the revolution axis subsection. In the x text field, type -r0 analyzer.
- 7 In the y text field, type hsample+hentrance+h analyzer pre.
- 8 Find the Direction of revolution axis subsection. In the y text field, type 0.
- 9 In the z text field, type 1.

Work Plane 3 (wb3)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object rev1, select Boundary 1 only.
- 5 Click A Go to Plane Geometry.

Work Plane 3 (wp3)>Circle 1 (c1)

- I In the Work Plane toolbar, click (Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type r1 analyzer.

Extrude | (ext|)

- I Right-click Geometry I and choose Extrude.
- 2 In the Settings window for Extrude, locate the Distances section.
- 3 In the table, enter the following settings:

Distances (m)

h analyzer post

Work Plane 4 (wb4)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.

- 3 From the Plane type list, choose Face parallel.
- 4 On the object ext1, select Boundary 1 only.
- 5 Click A Go to Plane Geometry.

Work Plane 4 (wb4)>Circle 1 (c1)

- I In the Work Plane toolbar, click Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type rexit.

Extrude 2 (ext2)

- I Right-click Geometry I and choose Extrude.
- 2 In the Settings window for Extrude, locate the Distances section.
- **3** In the table, enter the following settings:

Distances (m) hexit

Work Plane 5 (wb5)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object ext2, select Boundary 1 only.
- 5 Click A Go to Plane Geometry.

Work Plane 5 (wp5)>Circle 1 (c1)

- I In the Work Plane toolbar, click (Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type rexit.

Revolve 2 (rev2)

- I Right-click Geometry I and choose Revolve.
- 2 In the Settings window for Revolve, locate the Revolution Angles section.
- 3 Click the Angles button.
- 4 In the End angle text field, type ang magnet.
- 5 Locate the Revolution Axis section. From the Axis type list, choose 3D.
- 6 Find the Point on the revolution axis subsection. In the x text field, type -ro_analyzerh_analyzer_post-hexit.

- 7 In the y text field, type hsample+hentrance+h analyzer pre+r0 analyzerr magnet.
- 8 Find the Direction of revolution axis subsection. In the y text field, type 0.
- 9 In the z text field, type 1.

Work Plane 6 (wp6)

- I In the Geometry toolbar, click Swork Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object rev2, select Boundary 1 only.
- 5 Click A Go to Plane Geometry.

Work Plane 6 (wb6)>Circle 1 (c1)

- I In the Work Plane toolbar, click (Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type rexit.

Extrude 3 (ext3)

- I Right-click Geometry I and choose Extrude.
- 2 In the Settings window for Extrude, locate the Distances section.
- **3** In the table, enter the following settings:

Distances (m) hout

Work Plane 7 (wp7)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object ext3, select Boundary 1 only.
- 5 Click A Go to Plane Geometry.

Work Plane 7 (wp7)>Circle 1 (c1)

- I In the Work Plane toolbar, click Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type rdetector.

Extrude 4 (ext4)

- I Right-click Geometry I and choose Extrude.
- 2 In the Settings window for Extrude, locate the Distances section.
- **3** In the table, enter the following settings:

Distances (m) hdetector

Work Plane 8 (wb8)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object ext4, select Boundary 3 only.
- 5 Click A Go to Plane Geometry.

Work Plane 8 (wp8)>Circle 1 (c1)

- I In the Work Plane toolbar, click Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type rtarget.

Add additional work planes for lens placement.

Work Plane 9 (wp9)

- I Right-click Geometry I and choose Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- **4** On the object **cyll**, select Boundary 4 only.

Work Plane 10 (wp10)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 From the Plane type list, choose Face parallel.
- 4 On the object rev1, select Boundary 1 only.
- 5 In the Offset in normal direction text field, type hoffset.

Work Plane II (wbl1)

- I In the Geometry toolbar, click Work Plane.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.

- 3 From the Plane type list, choose Face parallel.
- 4 On the object ext4, select Boundary 4 only.
- 5 In the Offset in normal direction text field, type hoffset.
- 6 Select the Reverse normal direction check box.

Lens I (bil)

- I In the Geometry toolbar, click A Part Instance and choose Lens.
- 2 In the Settings window for Part Instance, locate the Position and Orientation of Output section.
- 3 Find the Coordinate system in part subsection. From the Work plane in part list, choose Work Plane I (wpl).
- 4 Find the Coordinate system to match subsection. From the Work plane list, choose Work Plane 9 (wp9).
- 5 Locate the Selection Settings section. Select the Keep noncontributing selections check box.

Lens 2 (pi2)

- I In the Geometry toolbar, click A Part Instance and choose Lens.
- 2 In the Settings window for Part Instance, locate the Position and Orientation of Output section.
- 3 Find the Coordinate system in part subsection. From the Work plane in part list, choose Work Plane I (wpl).
- 4 Find the Coordinate system to match subsection. From the Work plane list, choose Work Plane 2 (wp2).
- 5 Locate the Selection Settings section. Select the Keep noncontributing selections check box.

Lens 3 (bi3)

- I In the Geometry toolbar, click Part Instance and choose Lens.
- 2 In the Settings window for Part Instance, locate the Position and Orientation of Output
- 3 Find the Coordinate system in part subsection. From the Work plane in part list, choose Work Plane I (wpl).
- 4 Find the Coordinate system to match subsection. From the Work plane list, choose Work Plane 10 (wp10).

5 Locate the Selection Settings section. Select the Keep noncontributing selections check box.

Lens 4 (þi4)

- I In the Geometry toolbar, click Part Instance and choose Lens.
- 2 In the Settings window for Part Instance, locate the Position and Orientation of Output section.
- 3 Find the Coordinate system in part subsection. From the Work plane in part list, choose Work Plane I (wpl).
- 4 Find the Coordinate system to match subsection. From the Work plane list, choose Work Plane II (wpII).
- 5 Locate the Selection Settings section. Select the Keep noncontributing selections check box.

Difference I (dif1)

- I In the Geometry toolbar, click Booleans and Partitions and choose Difference.
- 2 Select the objects cyll, cyl2, cyl3, ext1, ext2, ext3, ext4, rev1, and rev2 only.
- 3 In the Settings window for Difference, locate the Difference section.
- 4 Click to select the Activate Selection toggle button for Objects to subtract.
- 5 Select the objects pi1, pi2, pi3, and pi4 only.
- 6 Click **Build All Objects**.
- 7 Click the **Zoom Extents** button in the **Graphics** toolbar.