

Q: Is $\mathcal{R}(A)$ a subspace?

$$A \in \mathbb{R}^{n \times n}$$

$$\mathcal{R}(A) = \{ y \in \mathbb{R}^n : \exists x \in \mathbb{R}^n, Ax = y \}$$

$$\mathcal{R}(A) \subseteq \mathbb{R}^n$$

$$\begin{array}{l} y_1, y_2 \in \mathcal{R}(A) \\ \downarrow \text{need to see} \\ y_1 + y_2 \in \mathcal{R}(A) \end{array}$$

$$\begin{array}{l} Ax_1 = y_1 \\ Ax_2 = y_2 \end{array}$$

+

✓

$$\begin{array}{l} y \in \mathcal{R}(A) \\ \alpha \in \mathbb{R} \downarrow \alpha y \in \mathcal{R}(A) \end{array}$$

$$\begin{array}{l} \alpha y \in \mathcal{R}(A) \\ 0 \in \mathcal{R}(A) \end{array}$$

$$Ax_1 + Ax_2 = y_1 + y_2$$

$$A(x_1 + x_2) = y_1 + y_2$$

Hence

$$y_1 + y_2 \in \mathcal{R}(A)$$

$$\begin{aligned} & \checkmark \\ & \swarrow Ax = ay \\ & A(ax) = ay \\ & \underline{ay \in \mathcal{R}(A)} \end{aligned}$$

$N(A)$ is vector space

$$N(A) = \{x \in \mathbb{R}^n \mid Ax = \underset{\substack{\uparrow \\ 0_m}}{0}\}$$

$$x_1, x_2 \in N(A)$$

$$Ax_1 = 0$$

$$Ax_2 = 0$$

$$A(x_1 + x_2) = 0$$

$$\swarrow Ax = 0$$

$$A(\tau x) = 0$$

$$\tau x \in N(A)$$

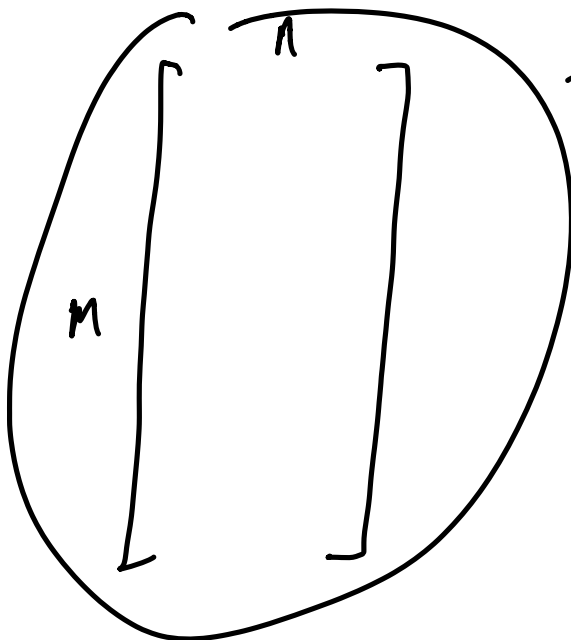
$$x_1 + x_2 \in N(A)$$

$$0 \in N(A)$$

$$A \in \mathbb{R}^{m \times n}$$

[V, W, S] Gram Matrix

$$G = A^T A \neq AA^T$$



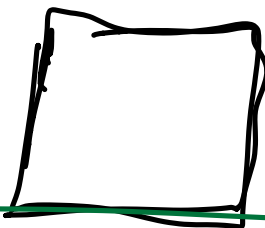
$$G^T = (A^T A)^T$$

$$= (A^T A^T)^T$$

$$= G$$

G is symmetric

$$G \in \mathbb{R}^{n \times n}$$



$\in \mathbb{R}^{m \times n}$

Claim

$\in \mathbb{R}^{n \times n}$

$$N(A) = N(A^T A)$$

\swarrow \searrow \swarrow \searrow
 \mathbb{R}^n \mathbb{R}^m

$Ax = \underline{0}_m$
 \uparrow

$A^T Ax = \underline{0}_n$
 \uparrow

$$\{0\} = N(A) \quad \rightarrow \quad N(A^T A) = \{0\}$$

Not LI \Rightarrow "At least one redundant vector"

$$\{v_1, \dots, v_k\} \text{ not LI}$$

$$\alpha_1 V_1 + \alpha_2 V_2 + \dots + \alpha_K V_K = 0$$

and NOT all $\alpha_i = 0$

$$\begin{bmatrix} V_1 & V_2 & \dots & V_K \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_K \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}_n$$

$$\exists i \text{ } \alpha_i \neq 0$$

$$\cancel{V_i} = -\left(\frac{\alpha_1}{\alpha_i}\right)V_1 - \left(\frac{\alpha_2}{\alpha_i}\right)V_2 - \dots - \left(\frac{\alpha_{i-1}}{\alpha_i}\right)V_{i-1} - \left(\frac{\alpha_{i+1}}{\alpha_i}\right)V_{i+1} - \dots - \left(\frac{\alpha_K}{\alpha_i}\right)V_K$$

$$\{V_1, \dots, V_K\} \subset I$$

$$\Gamma! \quad \text{!} \quad \text{!} \quad \text{!} \quad \text{!} \quad \text{!}$$

$$\begin{bmatrix} | & V_1 & \dots & V_k & | \\ \hline & & & & \end{bmatrix} \begin{bmatrix} | & \alpha & | \\ \hline & & \end{bmatrix} = \begin{bmatrix} | & 0 & | \\ \hline & & \end{bmatrix}$$

$\alpha = 0$

$$X = \alpha_1 V_1 + \alpha_2 V_2 + \dots + \alpha_k V_k$$

$$X = \alpha_1 V_1 + \dots + \alpha_k V_k$$

$$X = \beta_1 V_1 + \dots + \beta_k V_k$$

$$A \alpha = X$$

$$A \beta = X$$

$n=3$

3-vectors

$$e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$k=2$

$$X = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$$

$$= 2e_1 + 3e_2$$

$$0 = (\alpha_1 - \beta_1) \underline{V_1} + \dots + (\alpha_k - \beta_k) \underline{V_k}$$

$\alpha_1 = \beta_1$

$\alpha_k = \beta_k$

$$\alpha_1 = \beta_1 \quad \alpha_2 = \beta_2 \quad \dots \quad \alpha_k = \beta_k$$

$$Ax = b$$

A is "zero null" space

If there is a solution
then it is unique.

A set of orthonormal vectors is $2I$

v_1, \dots, v_k are ON

$$\alpha_1 v_1 + \dots + \alpha_k v_k = 0$$

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$$\alpha_i = 0 \quad \forall i$$

l mult by V_i^T

$$\underbrace{V_i^T \alpha_1 V_1 + \dots + \underbrace{V_i^T \alpha_c V_c}_{\boxed{\alpha_c V_c^T V_c}} + \dots + \underbrace{V_i^T \alpha_k V_k}_{\boxed{\alpha_k V_k^T V_k}}}_{\alpha_i V_i^T V_i} = 0$$

$\boxed{\alpha_c V_c^T V_c}$
 $\boxed{\alpha_k V_k^T V_k}$

$$0 + 0 + 0 \dots 0 + \alpha_c \boxed{1} + 0 + 0 + 0 \dots = 0$$

$$\underline{\alpha_c = 0}$$