



# Structured Disentangled Representations

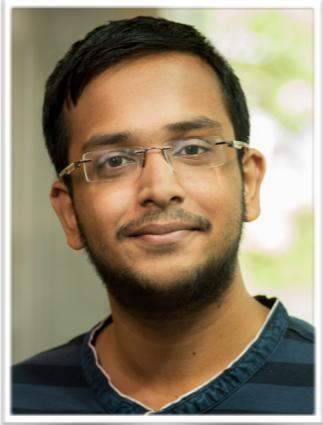
**Jan-Willem van de Meent**



Babak Esmaeli



Hao Wu



Sarthak Jain

*Northeastern University*



Alican Bozkurt



Siddharth N.

*Oxford*



Brooks Paige

*Alan Turing  
Institute*

# Learning Representations

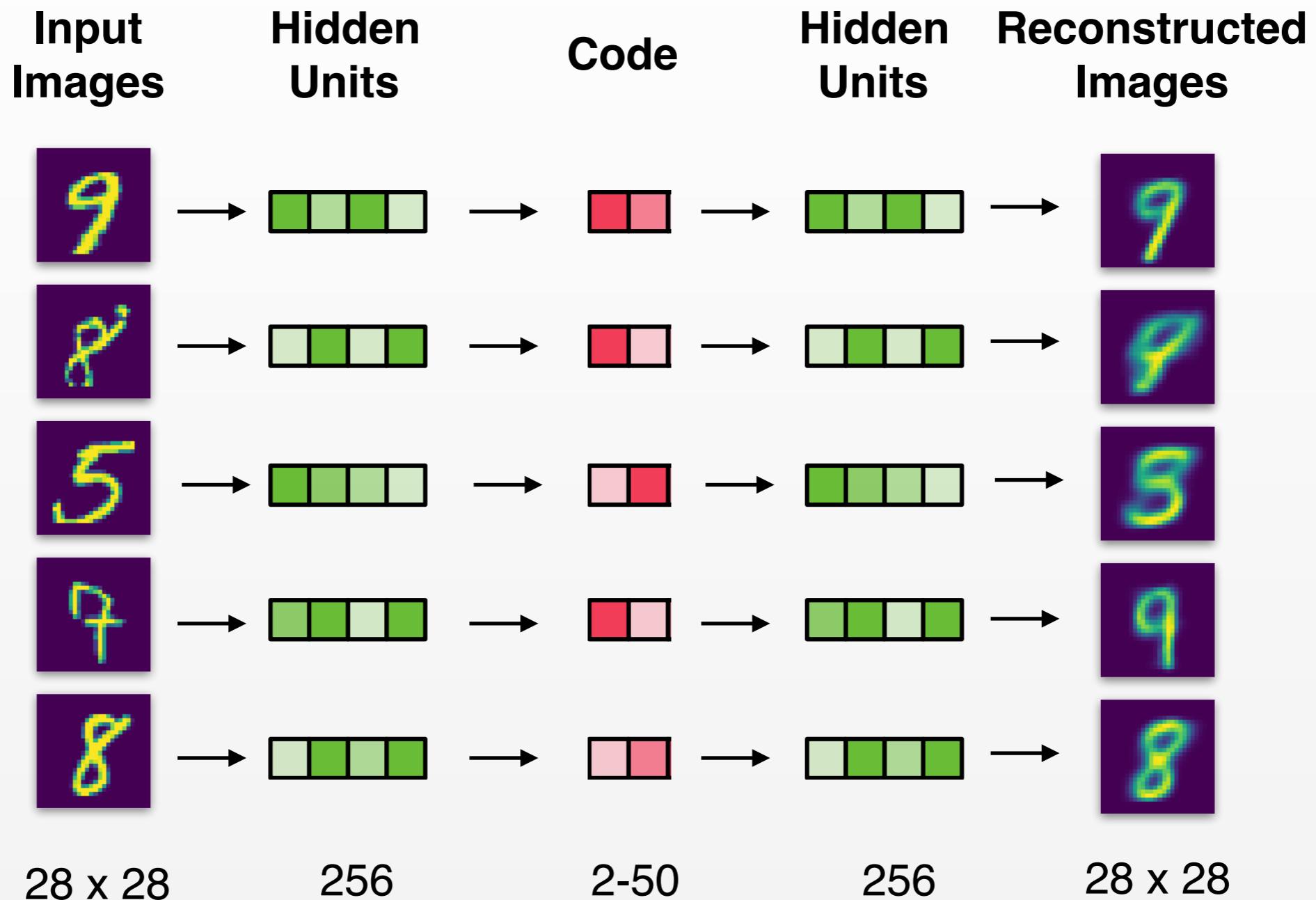
Everyone's Favorite Example: MNIST



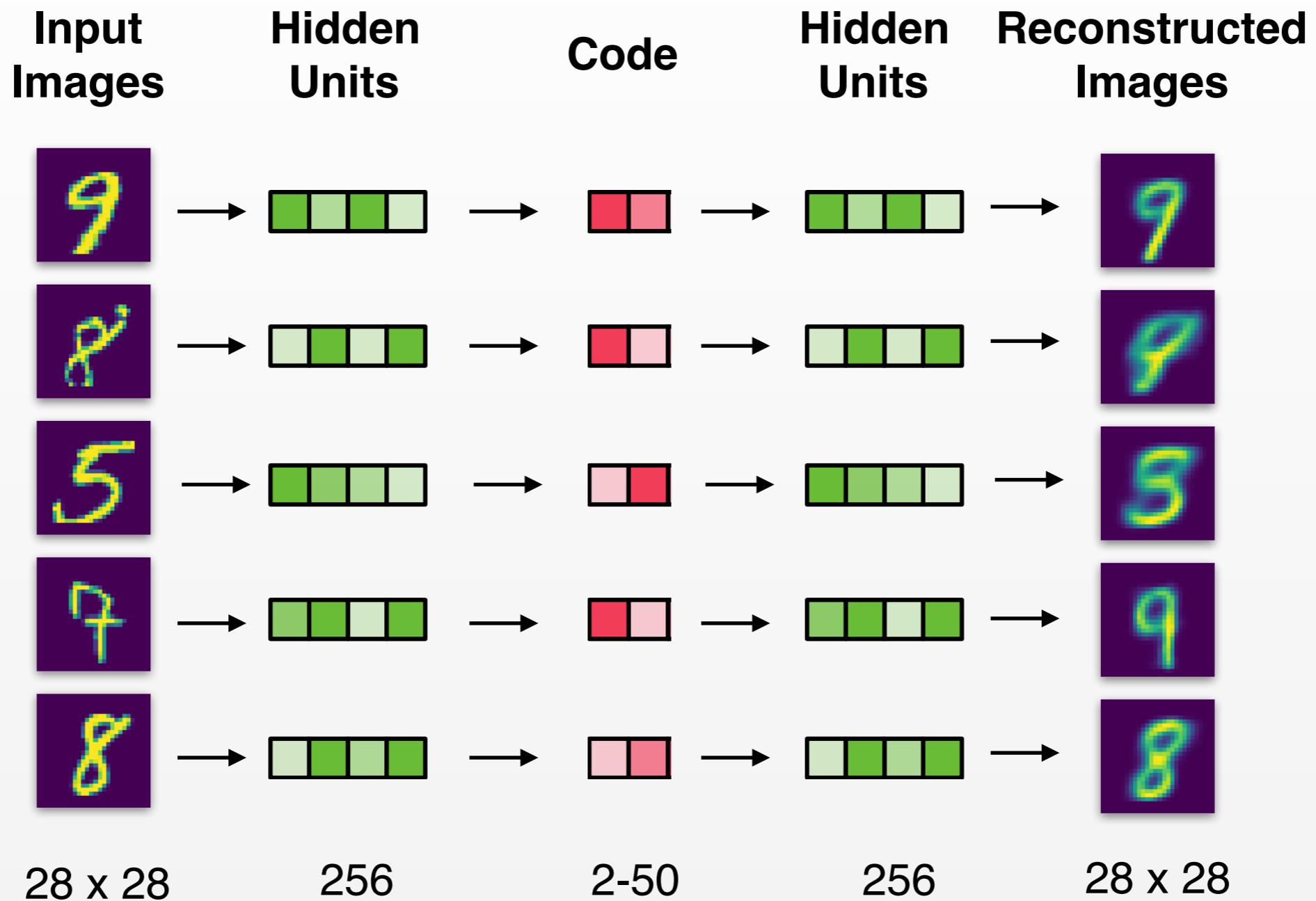
Goal: Learn features that capture *similarities* and *dissimilarities*

Requirement: Objective that defines notion of *utility* (*task-dependent*)

# Autoencoders

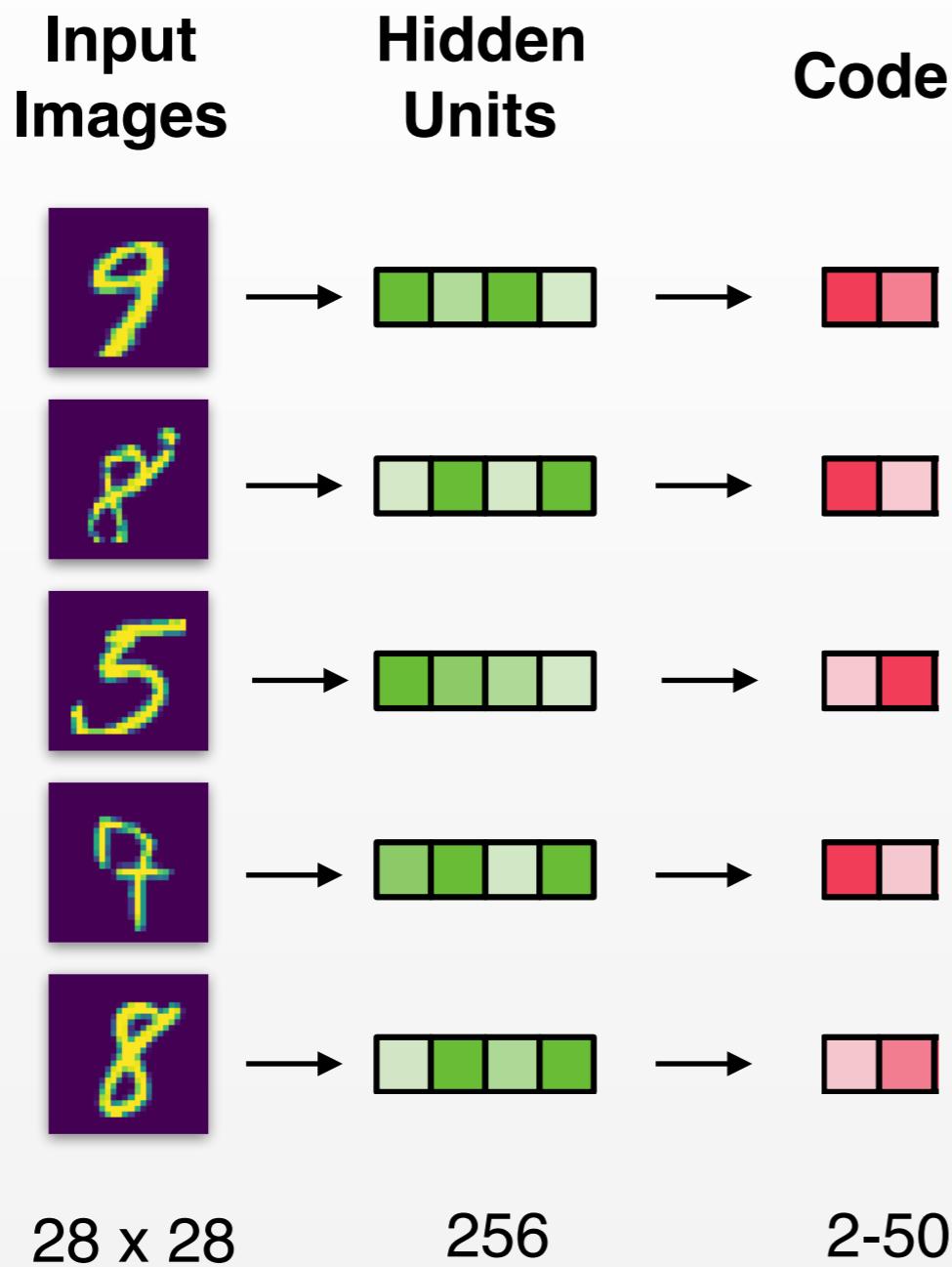


# Autoencoders



**Notion of Utility:** Ability to reconstruction of pixels from code  
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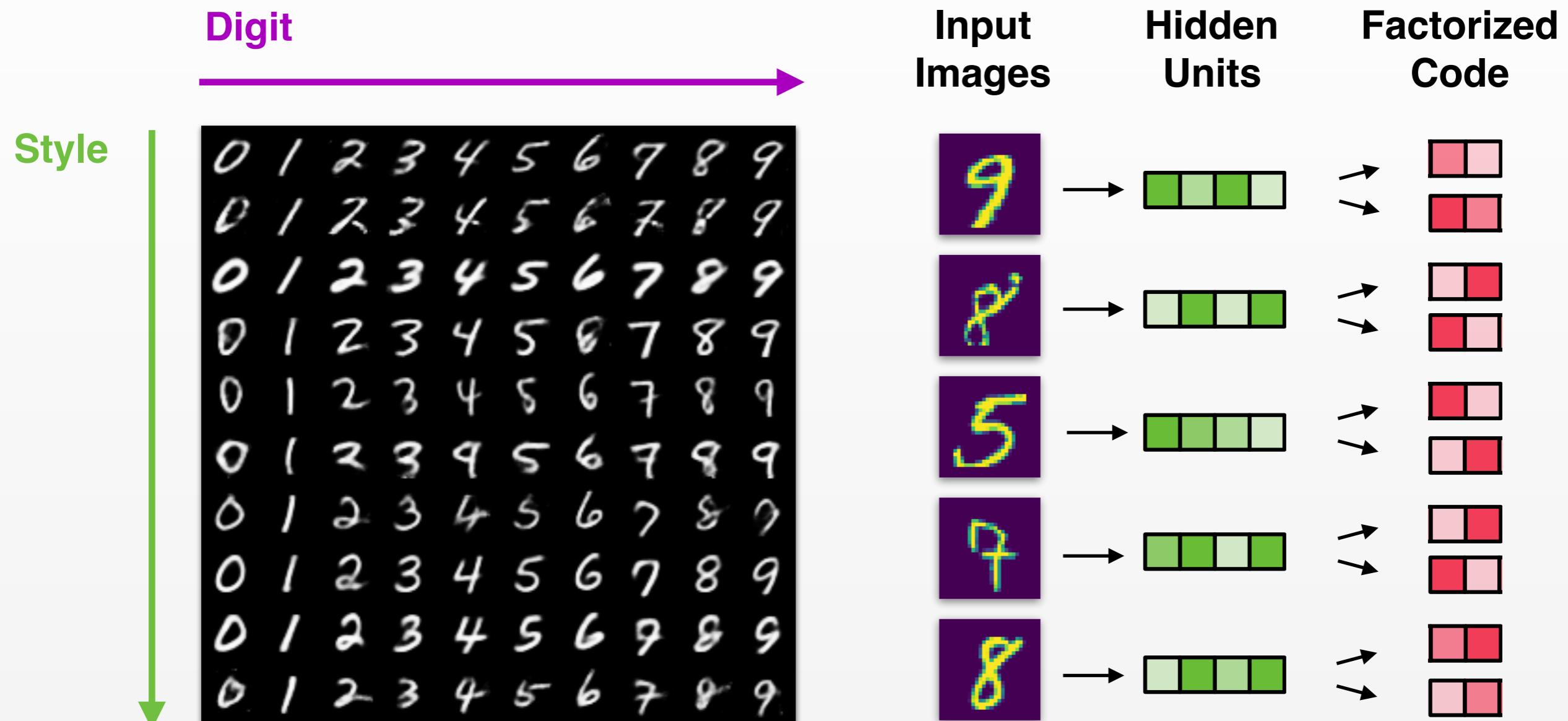


**Entangled Representation:** Individual dimensions in code encode some unknown combination of features in the data.

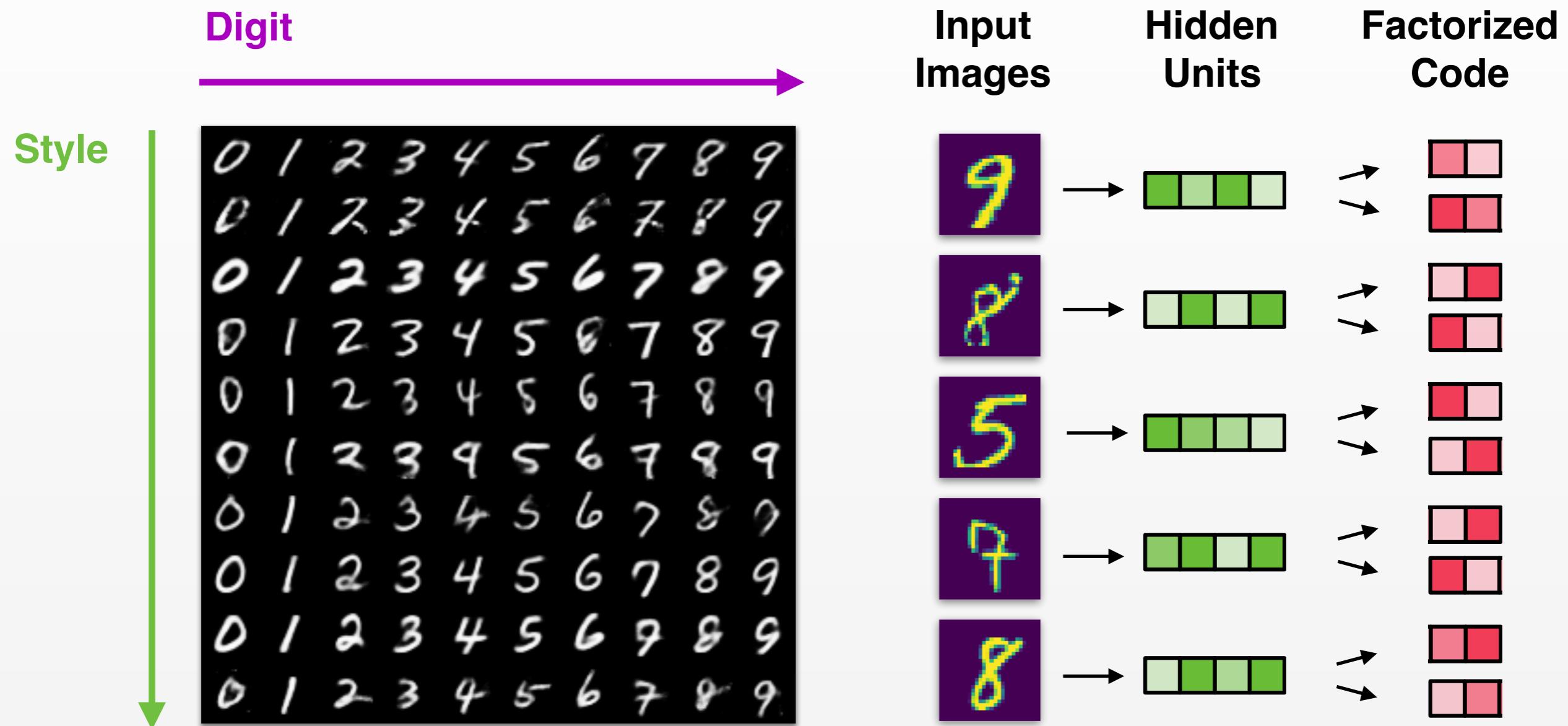
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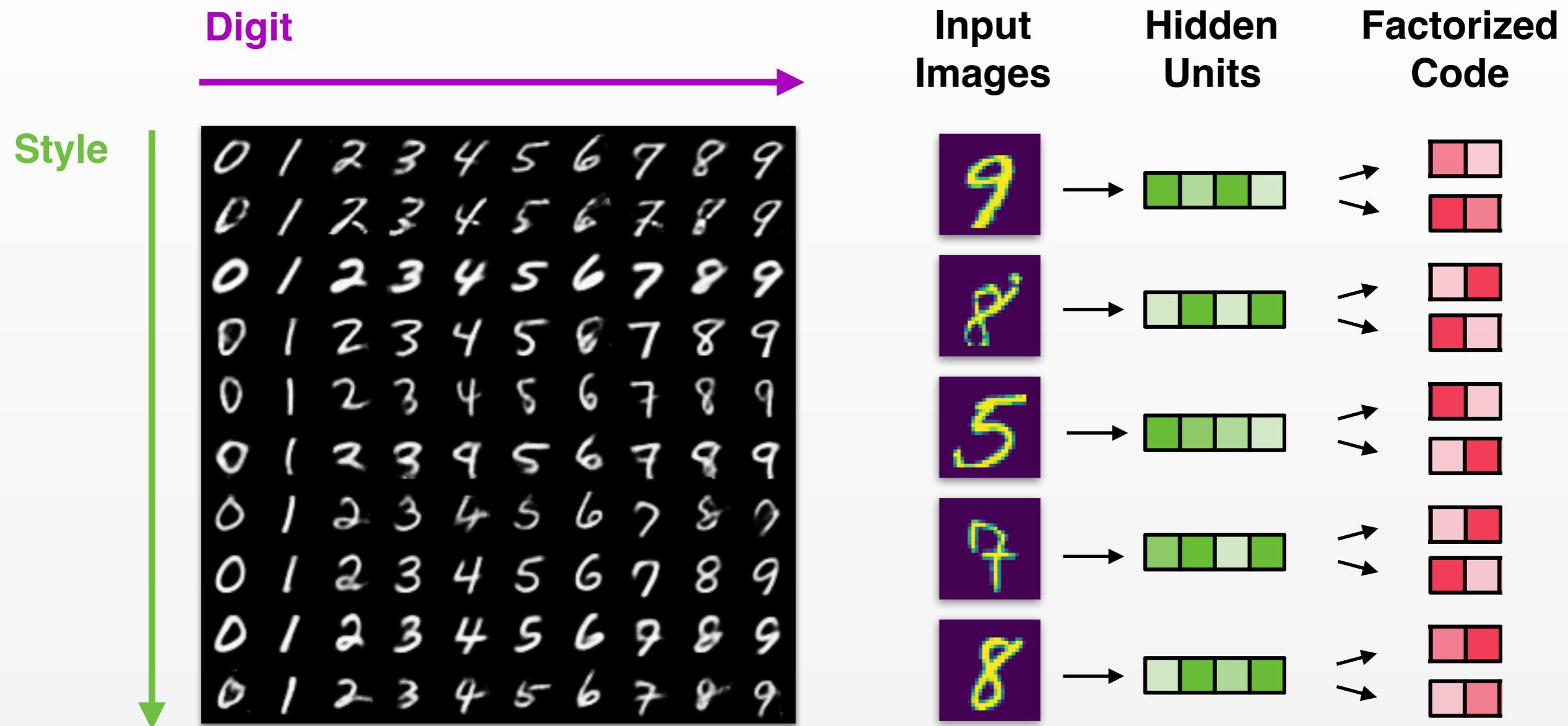


# Disentangled Representations



Goal: Learn features that correspond to *distinct* factors of variation

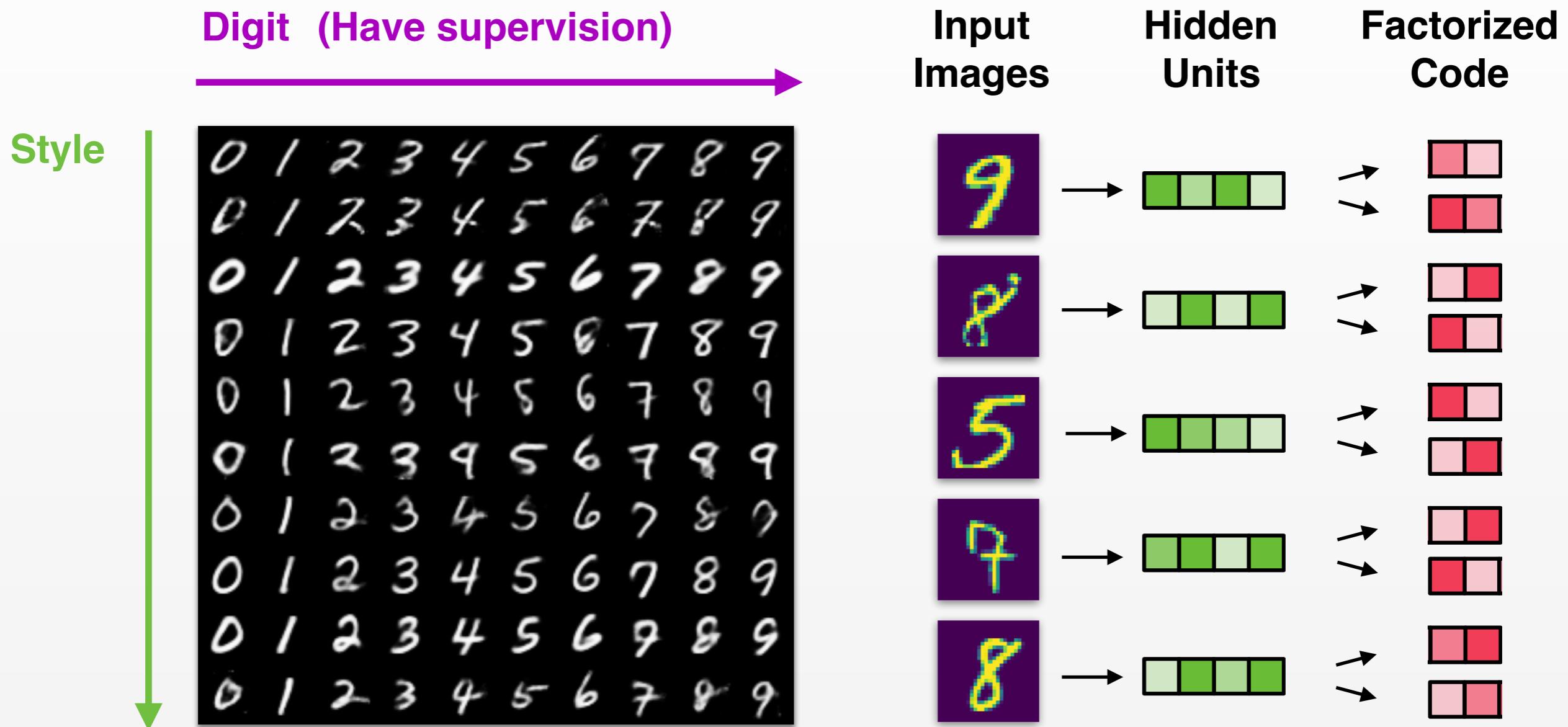
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One Notion of Utility: Statistical independence

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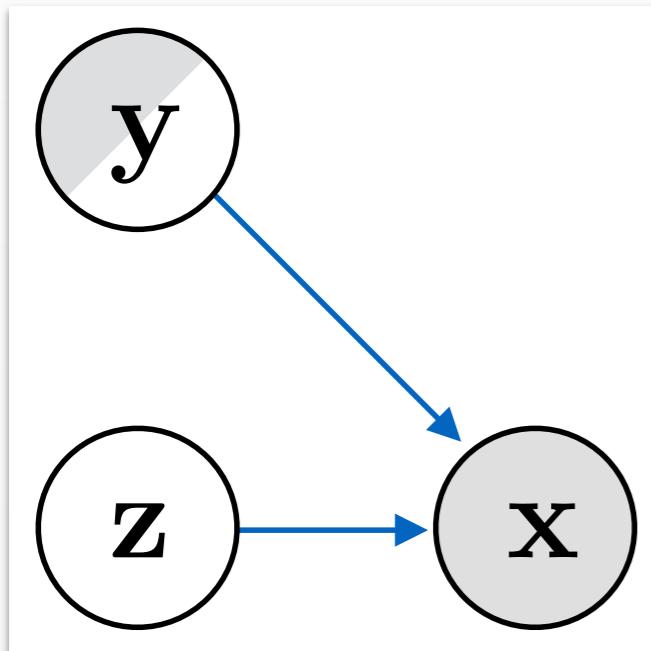
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One Notion of Utility: Statistical independence

# Semi-supervised Learning

Generative Model (Decoder)

$$p_{\theta}(x | y, z)$$

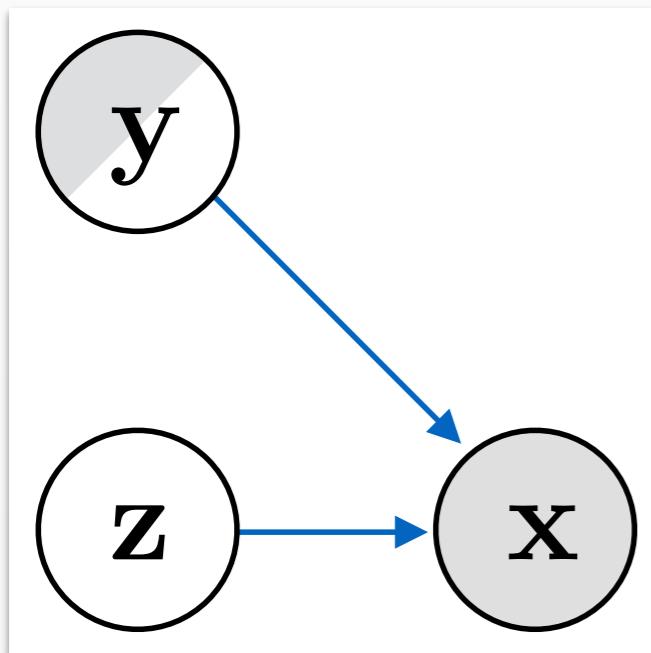


Assume independence  
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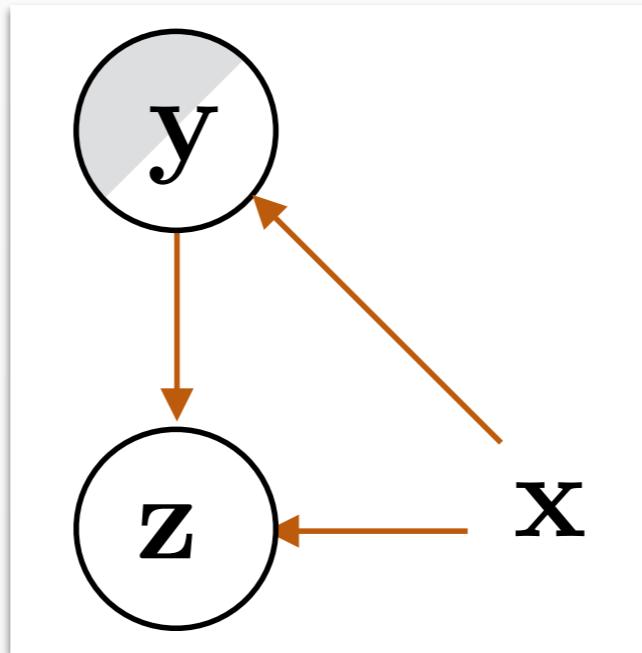
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Inference Model (Encoder)

$$q_{\phi}(y, z|x)$$



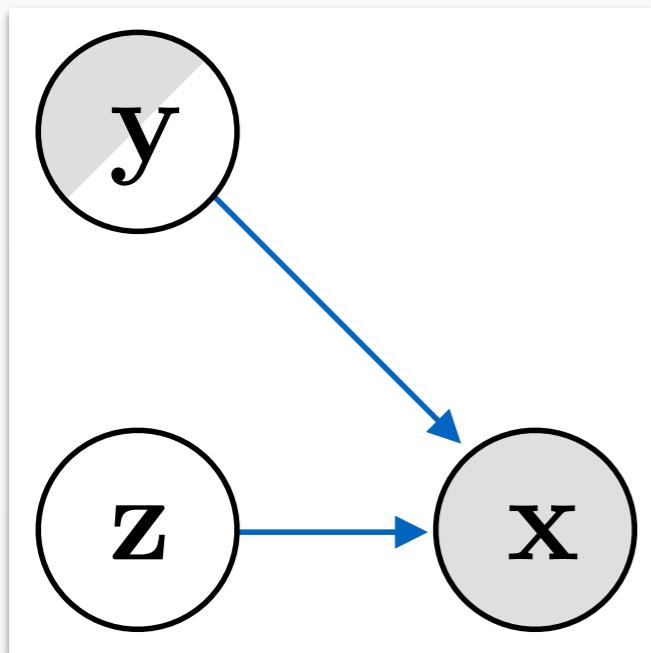
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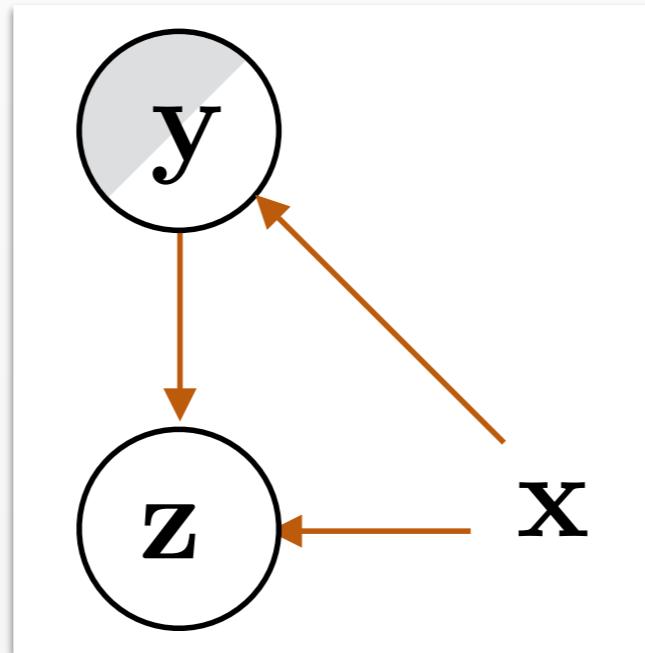
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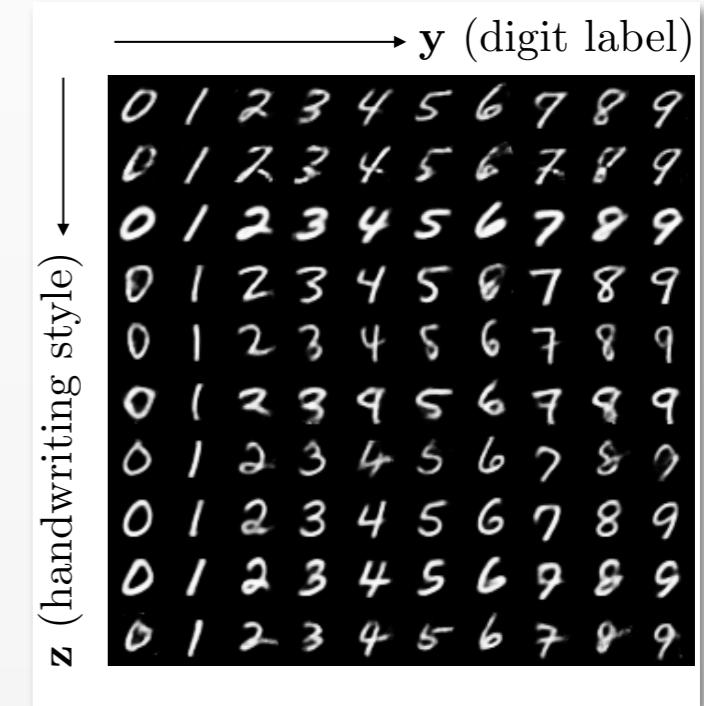


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Disentangled Representation



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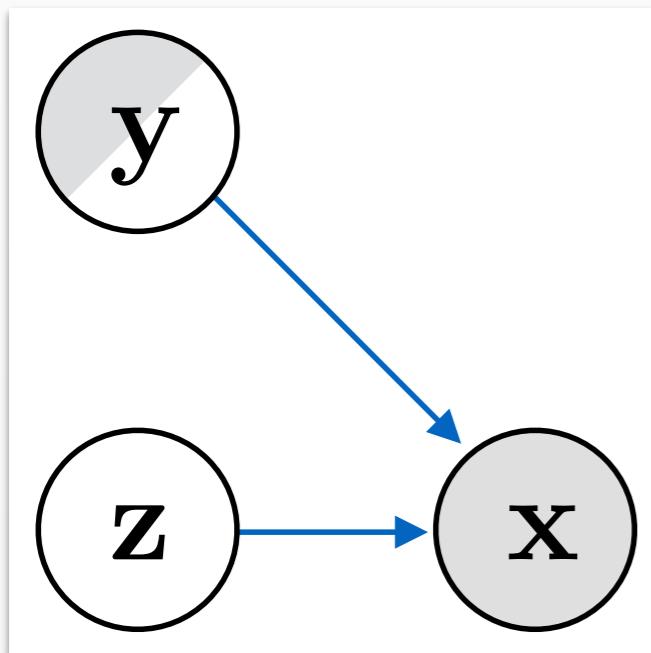
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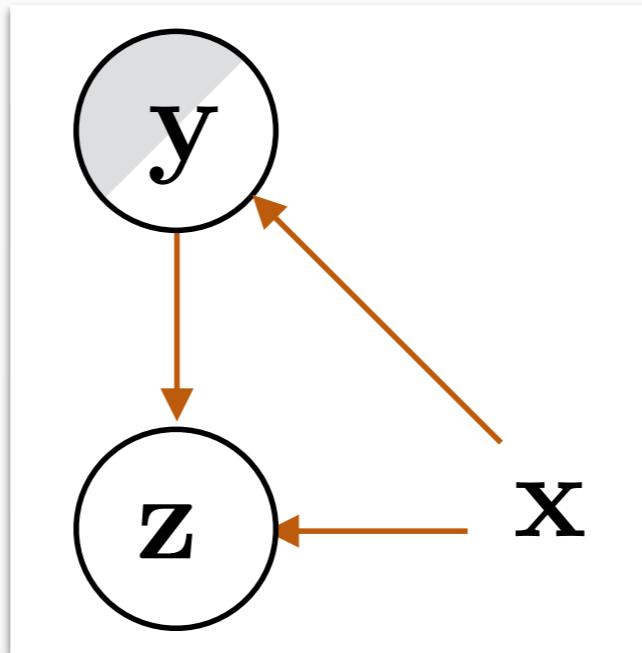
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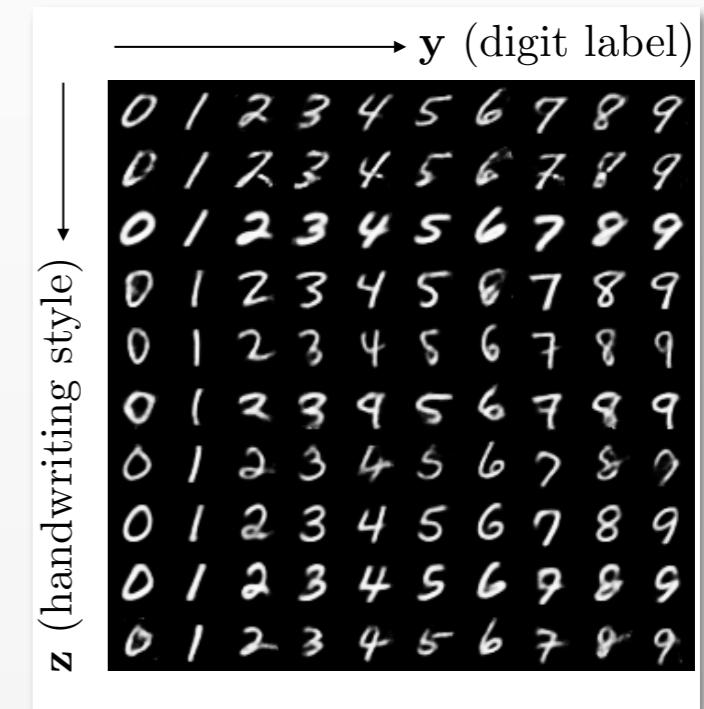


Inference Model (Encoder)

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Disentangled Representation



Assume independence between digit  $y$  and style  $z$

Infer  $y$  from pixels  $x$ , and  $z$  from  $y$  and  $x$

Separate interpretable  $y$  from “nuisance” variables  $z$

**Hypothesis:** Assuming a statistical independence under the prior induces disentangled representations.

# Deep Probabilistic Programs

## Inference Model (Encoder)

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class Encoder(torch.nn.Module):
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        q = probtorch.Trace()
        h = self.h(x)
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<https://github.com/probtorch/probtorch>

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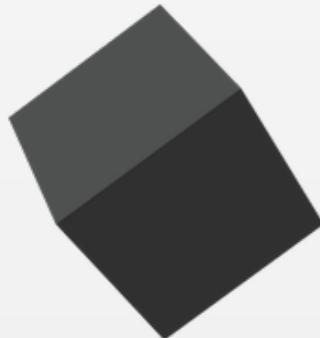
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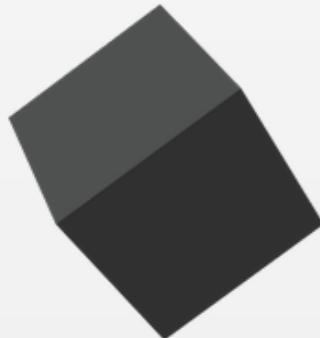
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    def __init__(self, x_sz, h_sz, y_sz, z_sz):
        # initializes layers: h, x_mean, ...
        ...

    def forward(self, x, q):
        p = probtorch.Trace()
        y = p.concrete(self.y_log_weights, 0.66,
                        value=q['y'], name='y')
        z = p.normal(0.0, 1.0,
                     value=q['z'], name='z')
        h = self.h(torch.cat([y, z], -1))
        x = p.loss(self.bce,
                   self.x_mean(h), x,
                   name='x')
        return p
```

Edward



Probabilistic Torch

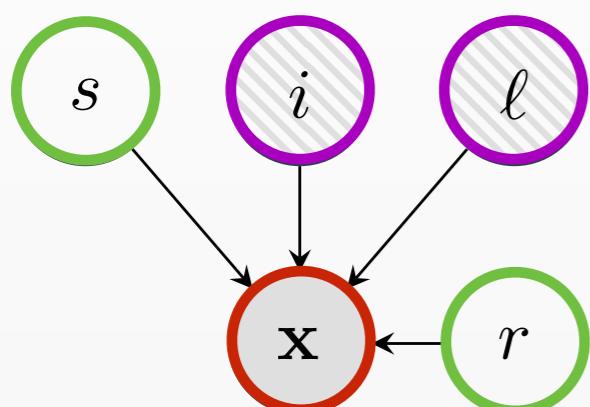


Pyro

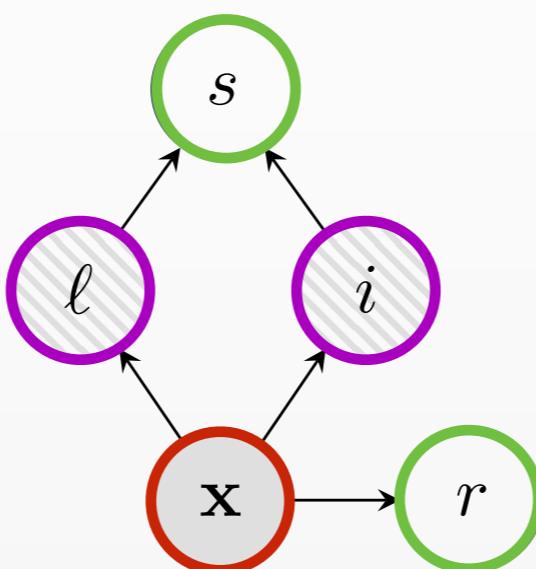


# Example: Yale B Faces

**Generative Model**



**Inference Model**



**Semi-supervised:**  
**Identity ( $i$ ), Lighting ( $\ell$ )**

**Unsupervised:**  
**Shading ( $s$ ), Reflectance ( $r$ )**

**Data:**  
**Pixels ( $x$ )**

Original



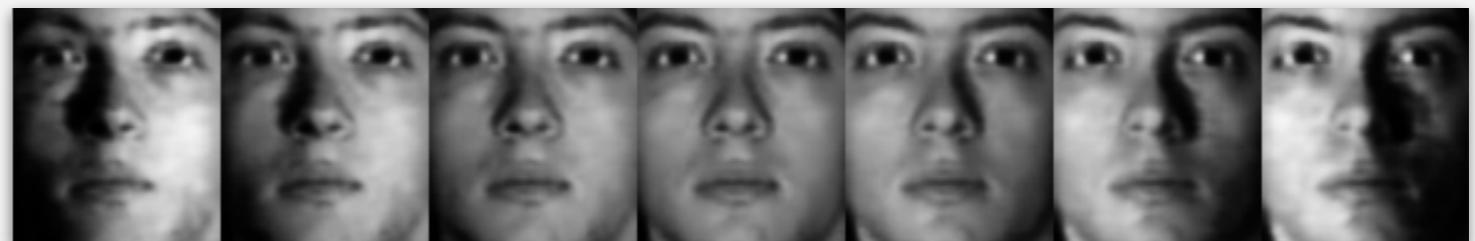
Reconstruction



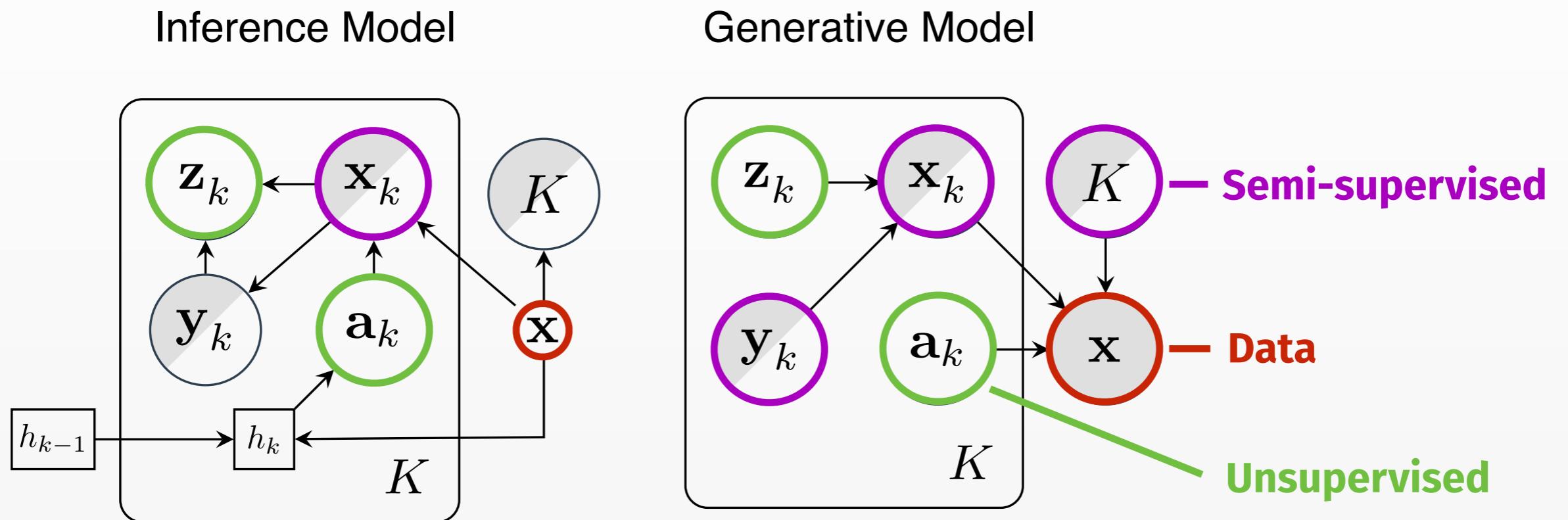
Same Lighting, Different Identity



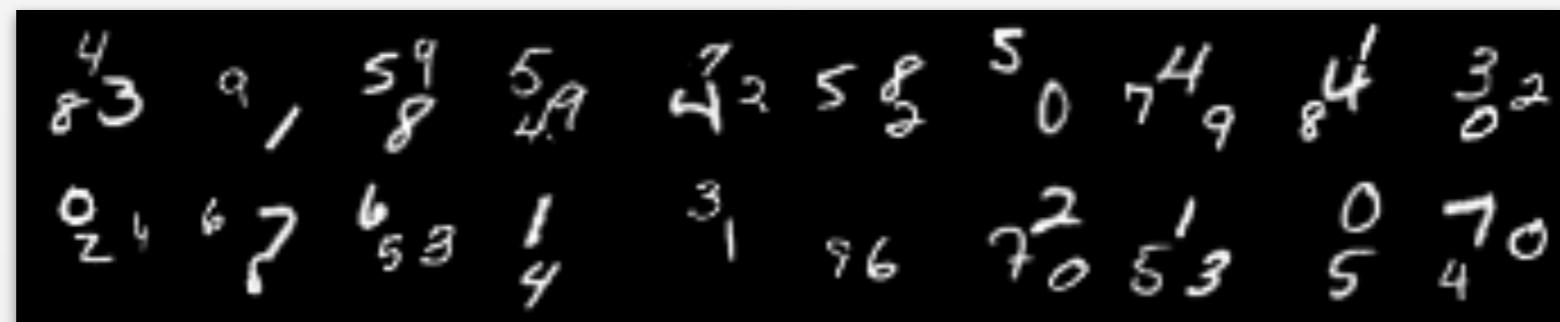
Same Identity, Different Lighting



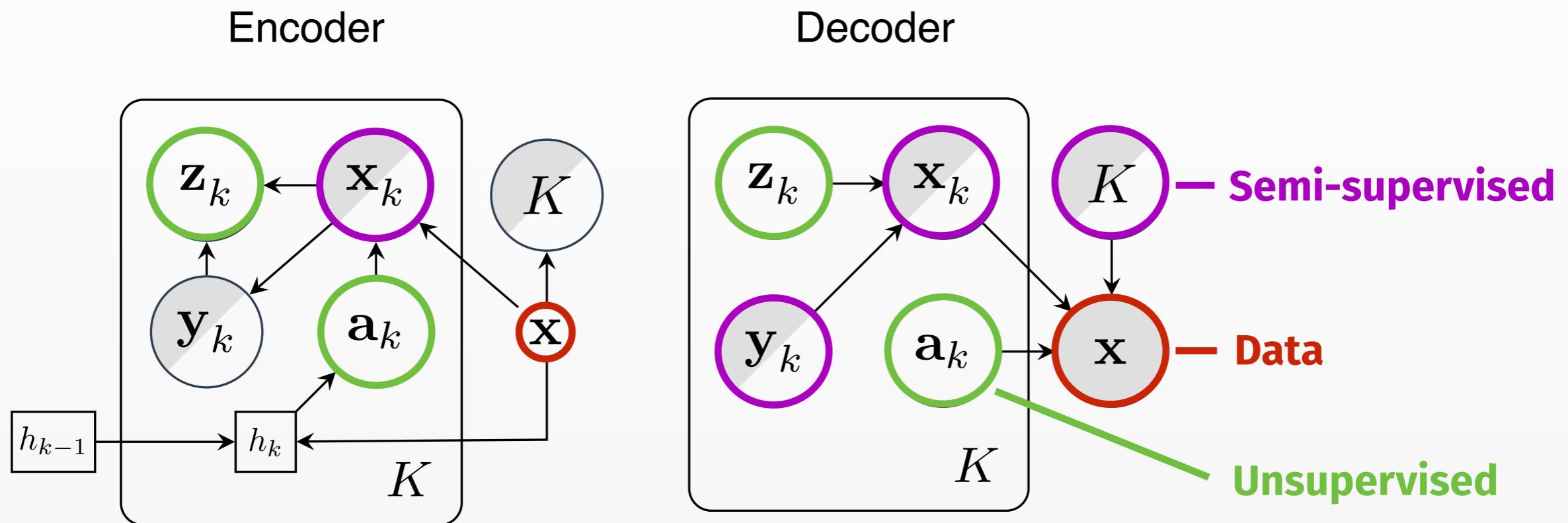
# Example: Multiple MNIST Digits



Multiple MNIST digits



# Example: Multiple MNIST Digits

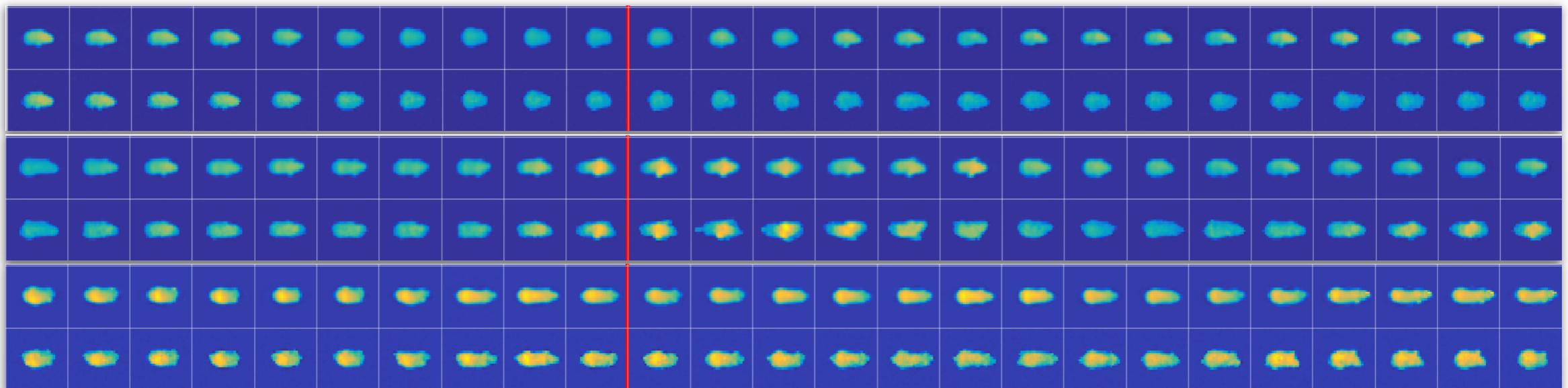


**Accuracy**

$\frac{M}{M+N}$	Count Error (%)	
	w/o MNIST	w/ MNIST
0.1	85.45 ( $\pm 5.77$ )	76.33 ( $\pm 8.91$ )
0.5	93.27 ( $\pm 2.15$ )	80.27 ( $\pm 5.45$ )
1.0	99.81 ( $\pm 1.81$ )	84.79 ( $\pm 5.11$ )

# Deep Probabilistic Models

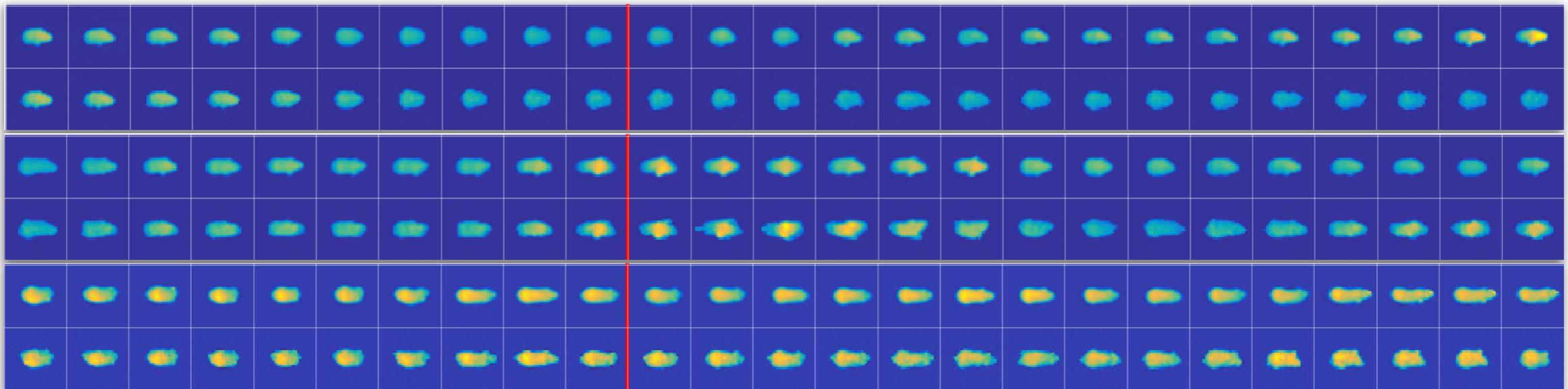
Example: Modeling Laboratory Mice with Deep State Space Models



[Johnson, Duvenaud, Wiltschko, Adams, Datta, NIPS 2016]

# Deep Probabilistic Models

Example: Modeling Laboratory Mice with Deep State Space Models



[Johnson, Duvenaud, Wiltschko, Adams, Datta, NIPS 2016]

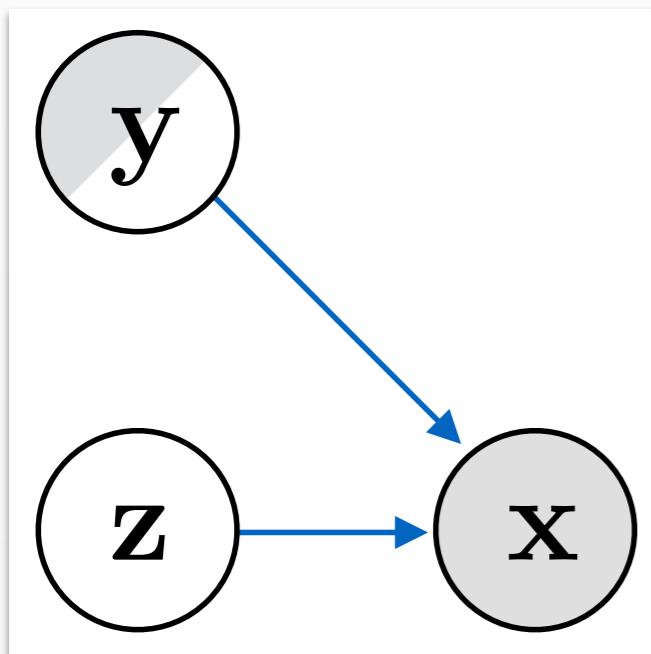
## Data Science ❤️ Probabilistic Modeling + Deep Learning?

- Structured priors model problem domain
- Bayesian inference for uncertainty estimates
- Neural likelihood models for data such as text and images
- Neural inference models predict values for latent variables

# Today: Unsupervised Learning

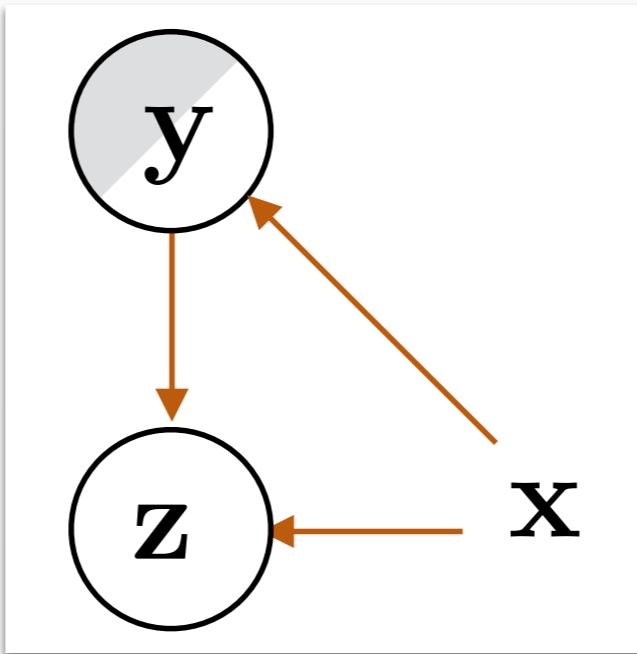
Generative Model (Decoder)

$$p_{\theta}(x | y, z)$$

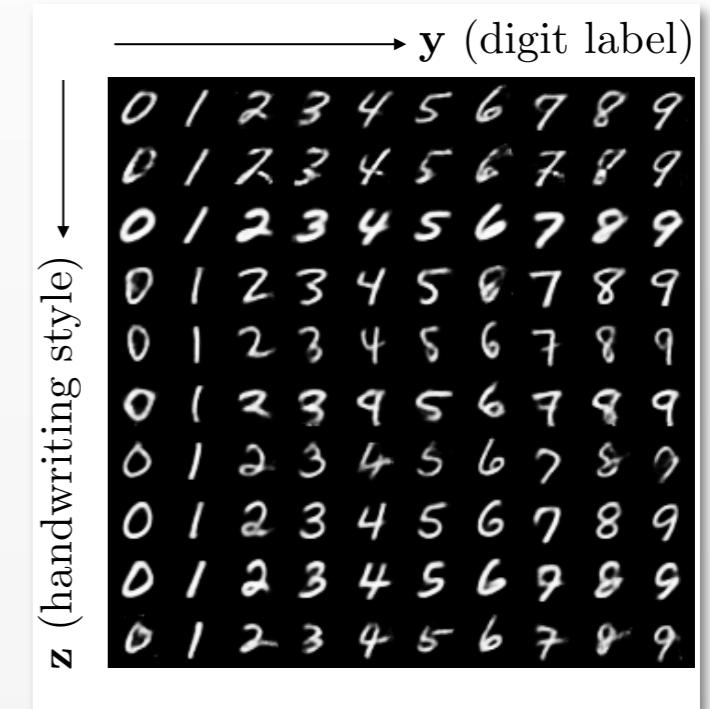


Inference Model (Encoder)

$$q_{\phi}(y, z|x)$$



Disentangled Representation



Assume independence between digit **y** and style **z**

Infer **y** from pixels **x**, and **z** from **y** and **x**

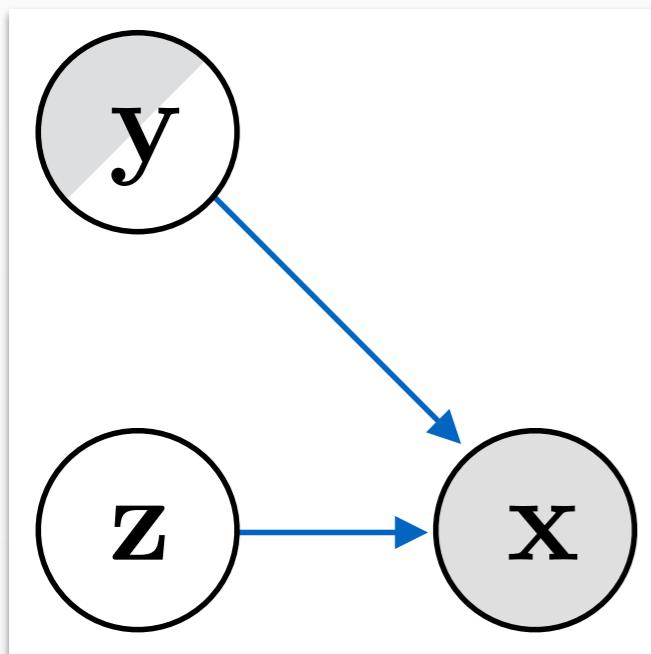
Separate interpretable **y** from “nuisance” variables **z**

**Hypothesis:** Assuming a statistical independence under the prior induces disentangled representations.

# Today: Unsupervised Learning

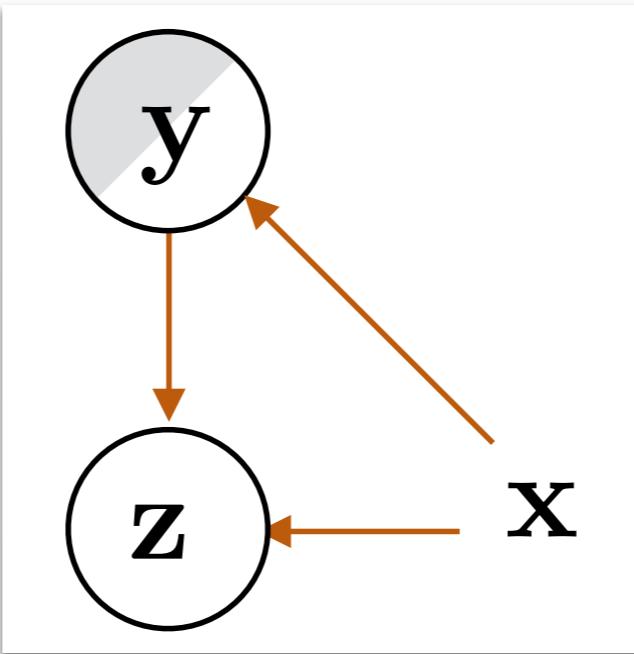
Generative Model (Decoder)

$$p_{\theta}(x | y, z)$$

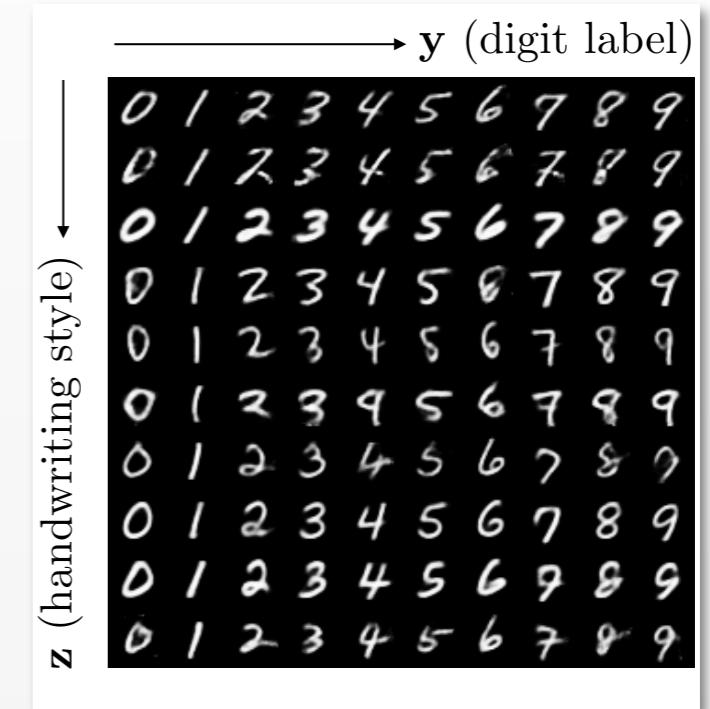


Inference Model (Encoder)

$$q_{\phi}(y, z|x)$$



Disentangled Representation



Assume independence between digit **y** and style **z**

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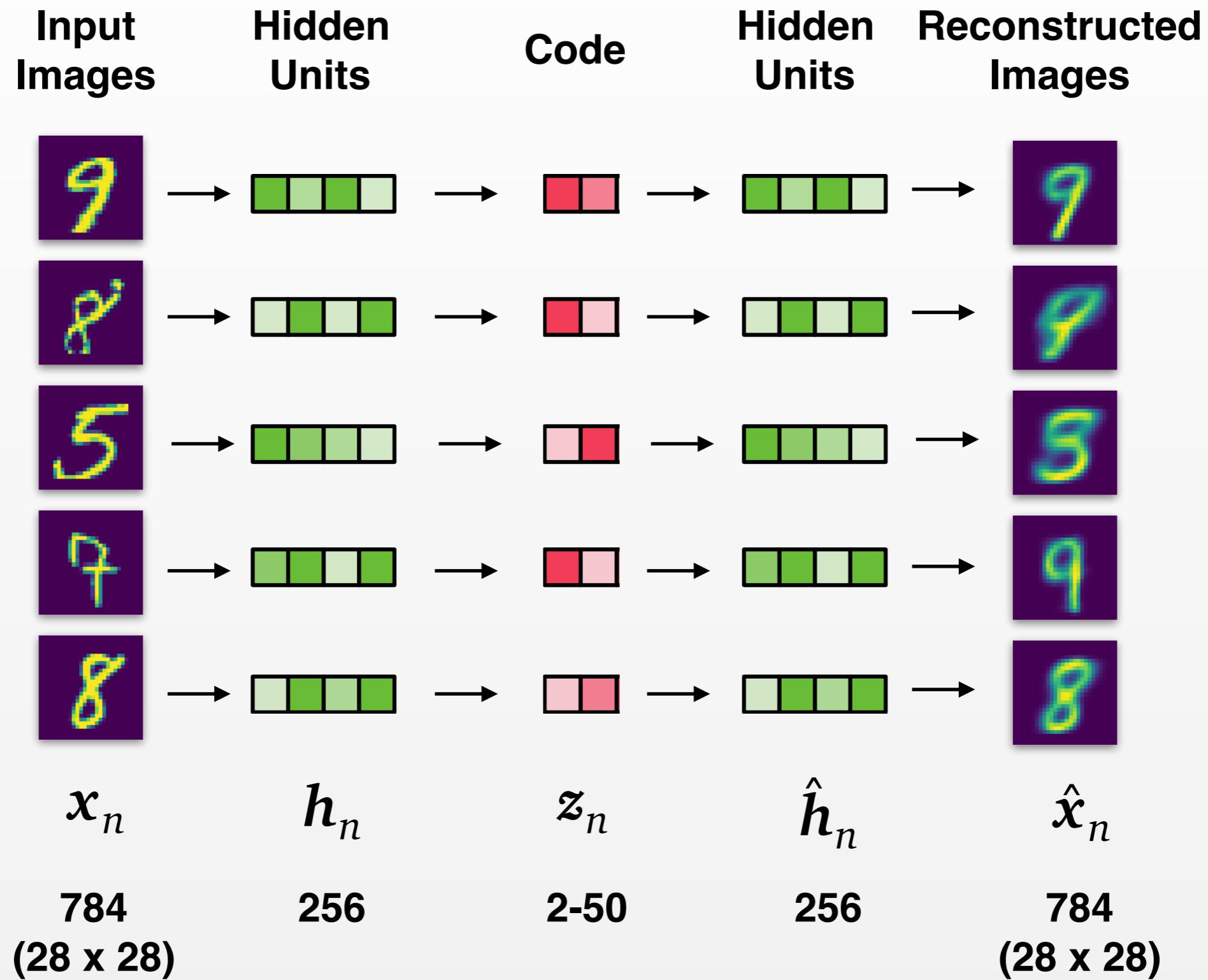
Separate interpretable **y** from “nuisance” variables **z**

**Problem:** Unsupervised learning (with same model) does *not* disentangle digit from style

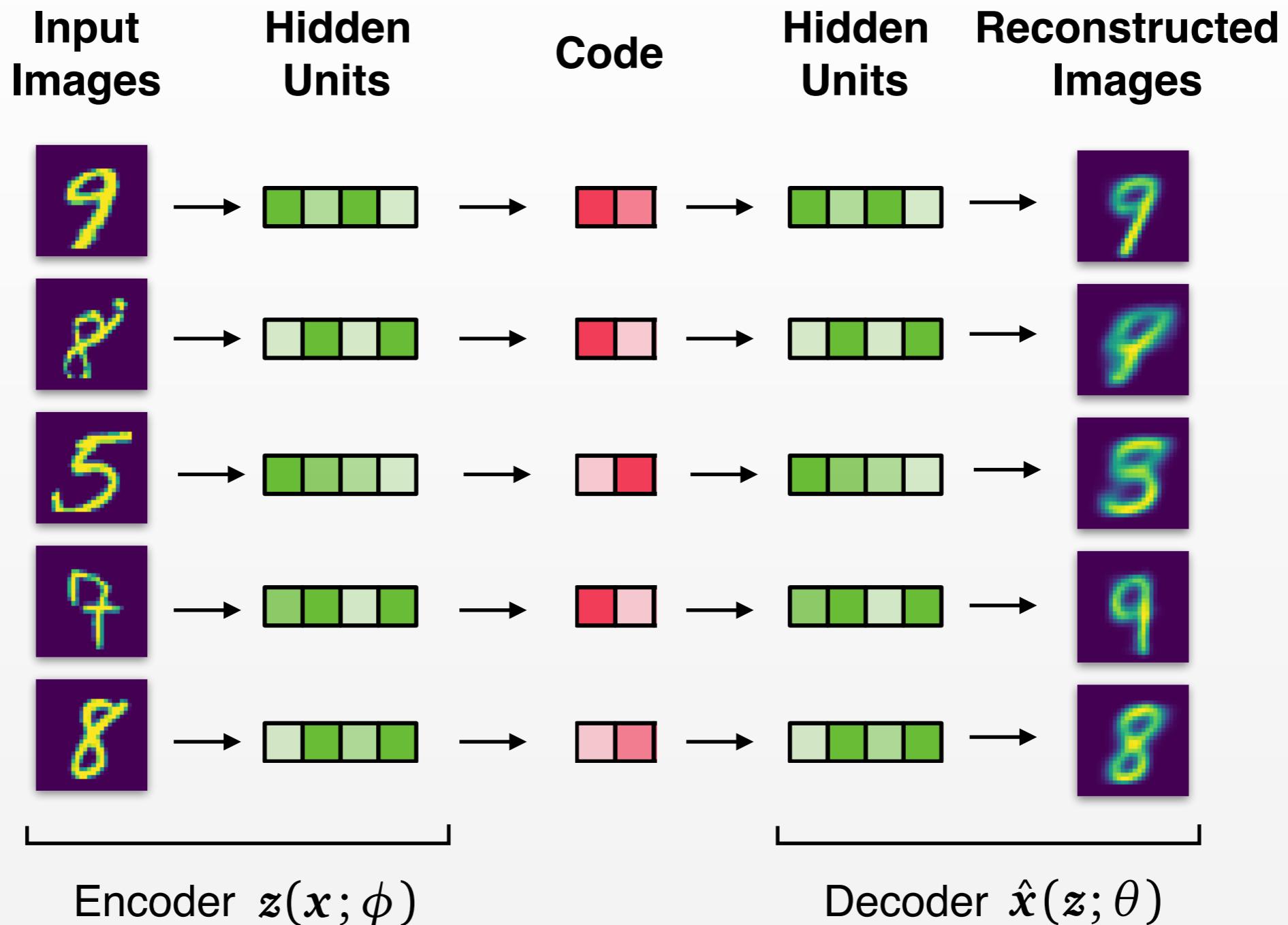
# Variational Autoencoders

(a.k.a. Deep Latent-Variable Models)

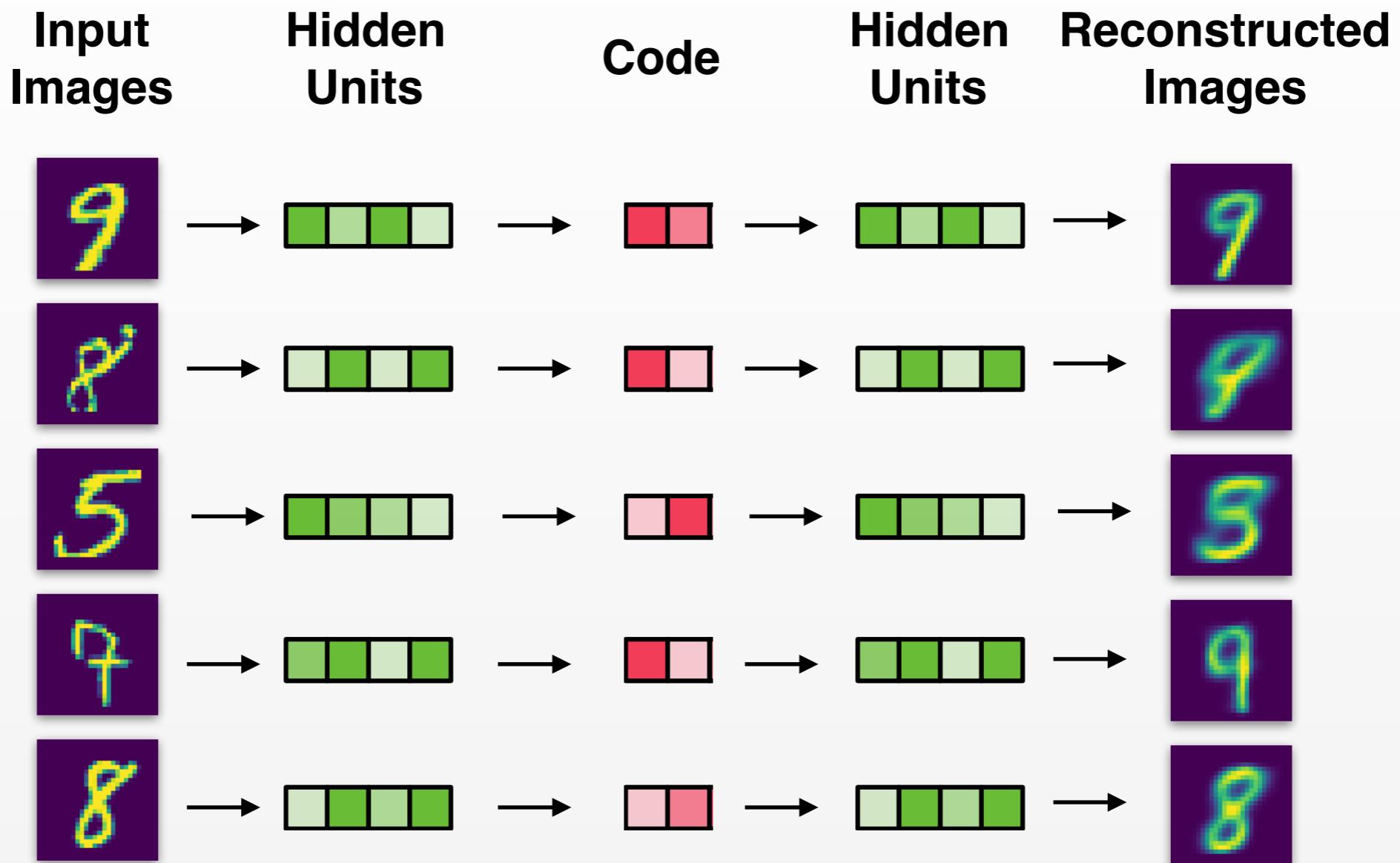
# Autoencoders



# Autoencoders



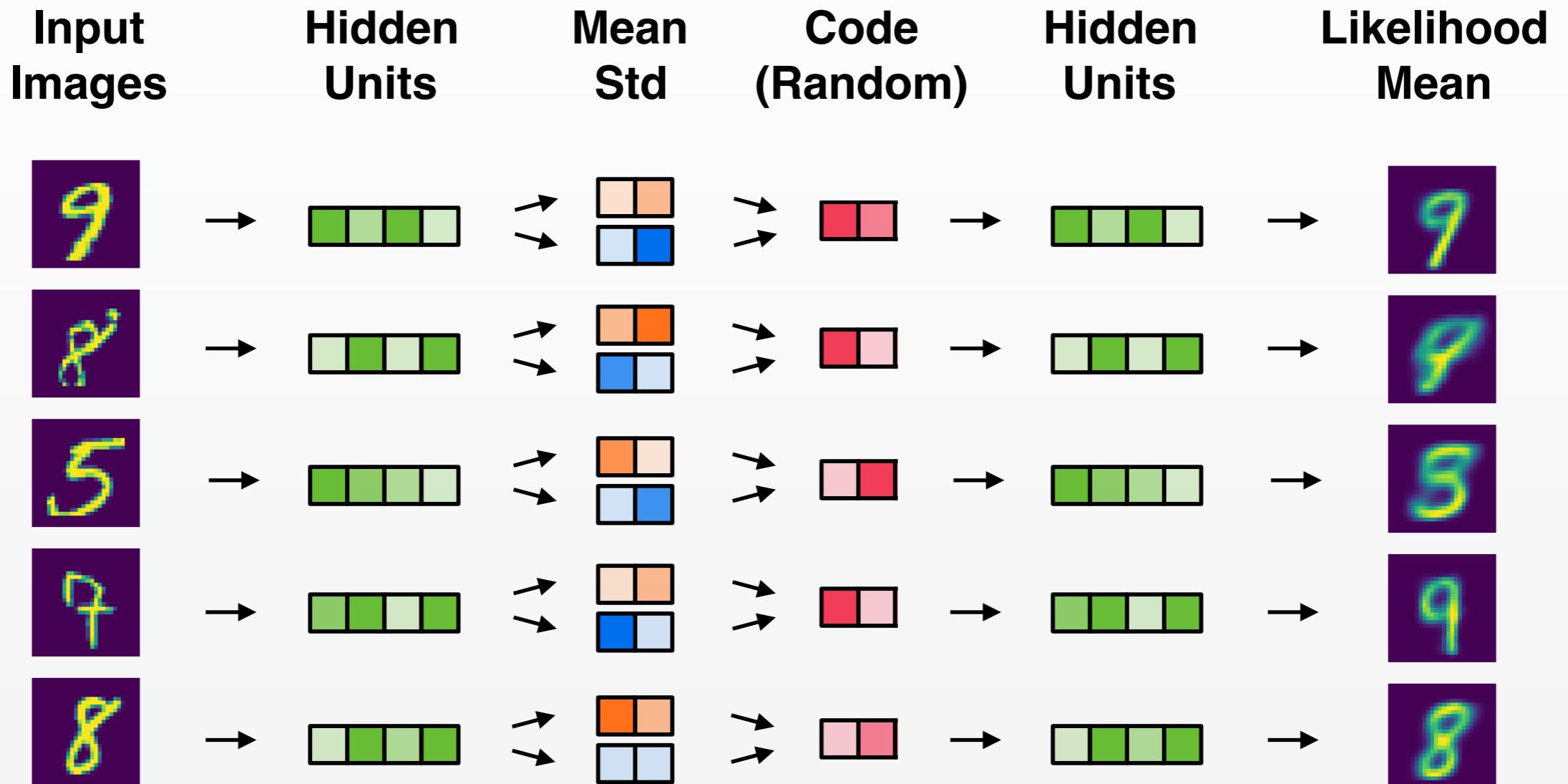
# Autoencoders



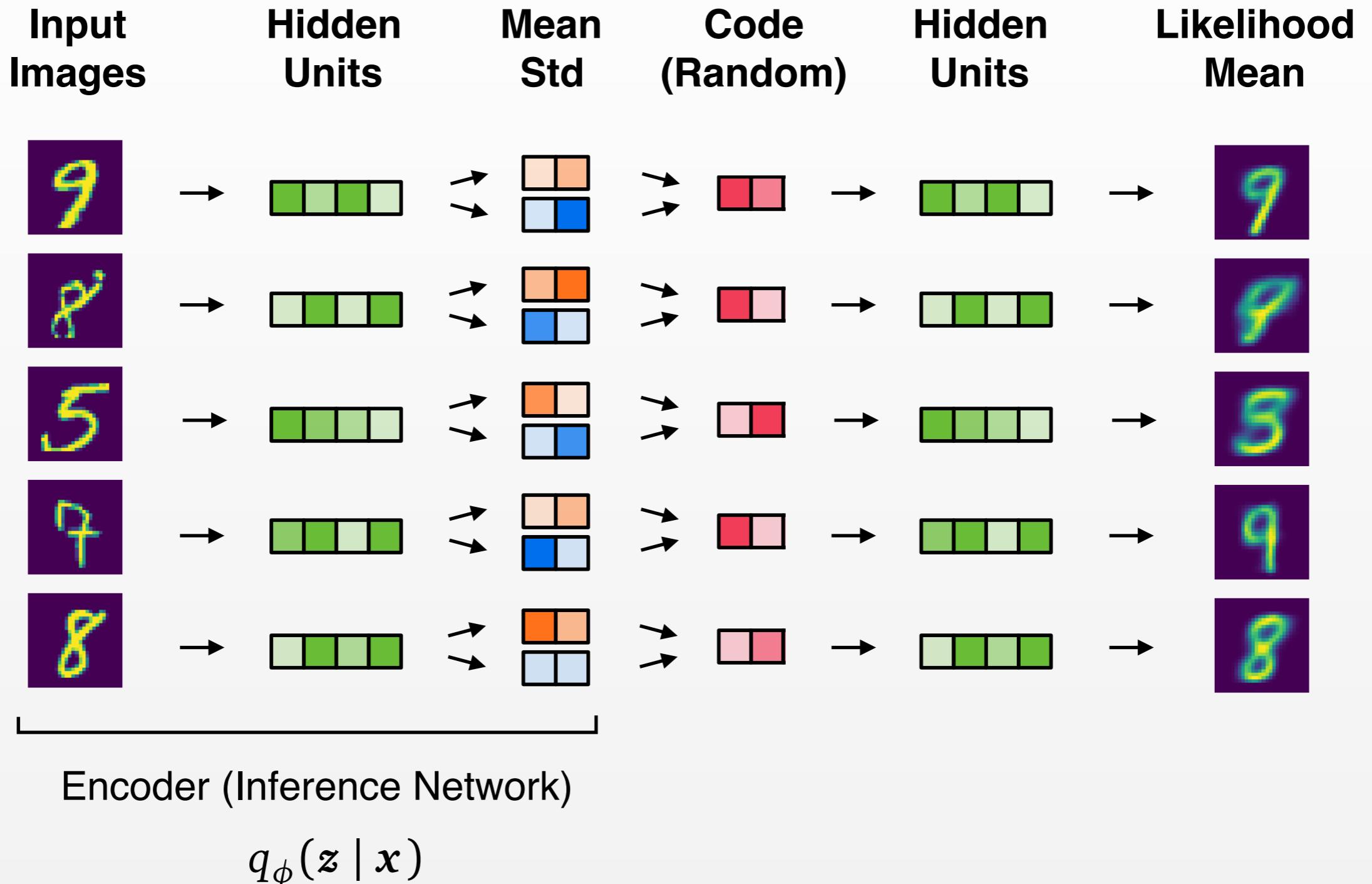
Objective: Maximize Reconstruction Quality

$$\max_{\phi, \theta} \frac{1}{N} \sum_{n=1}^N \sum_{p=1}^P x_{n,p} \log \hat{x}_{n,p}(z(x_n; \phi); \theta)$$

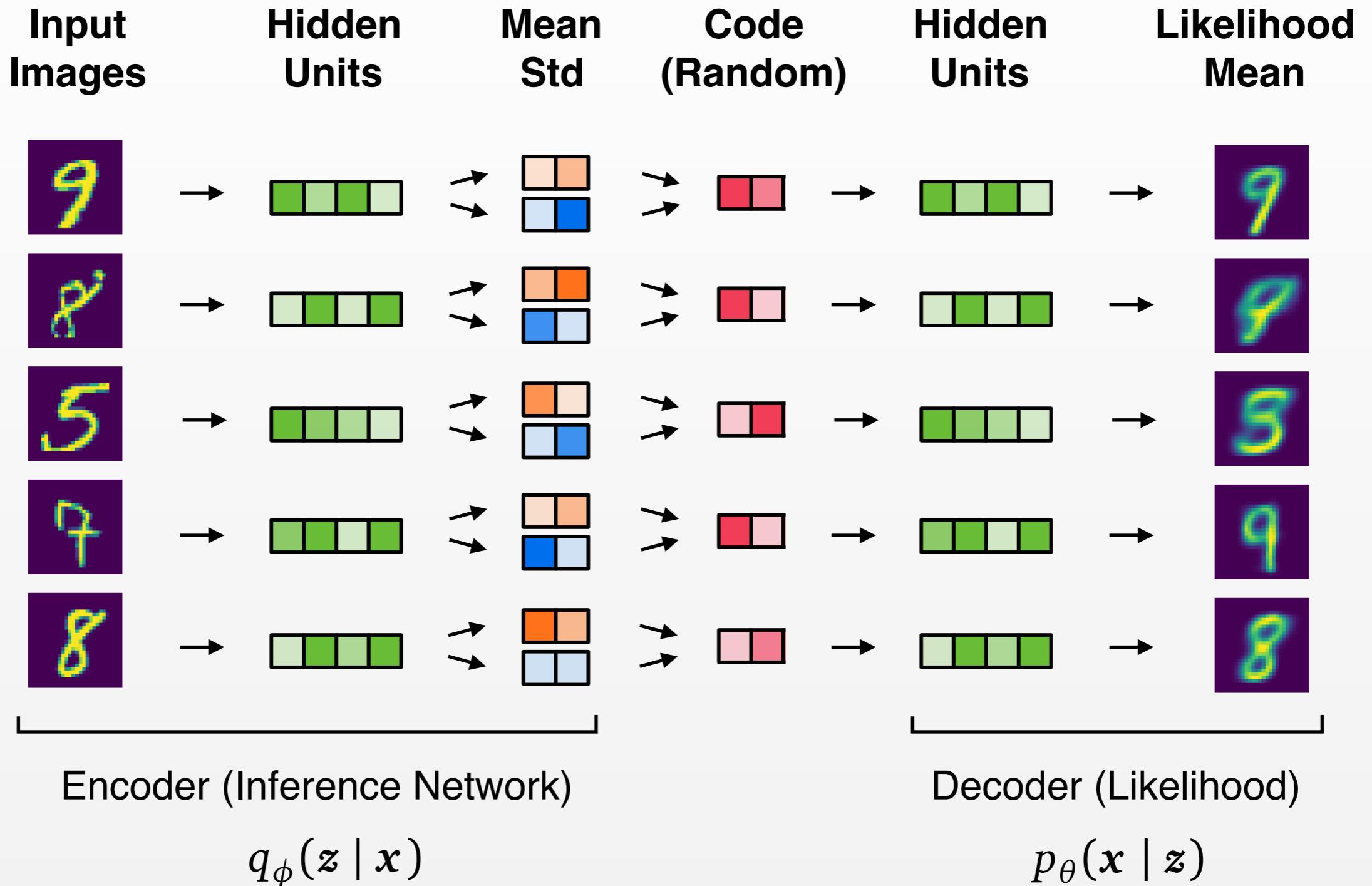
# Variational Autoencoders



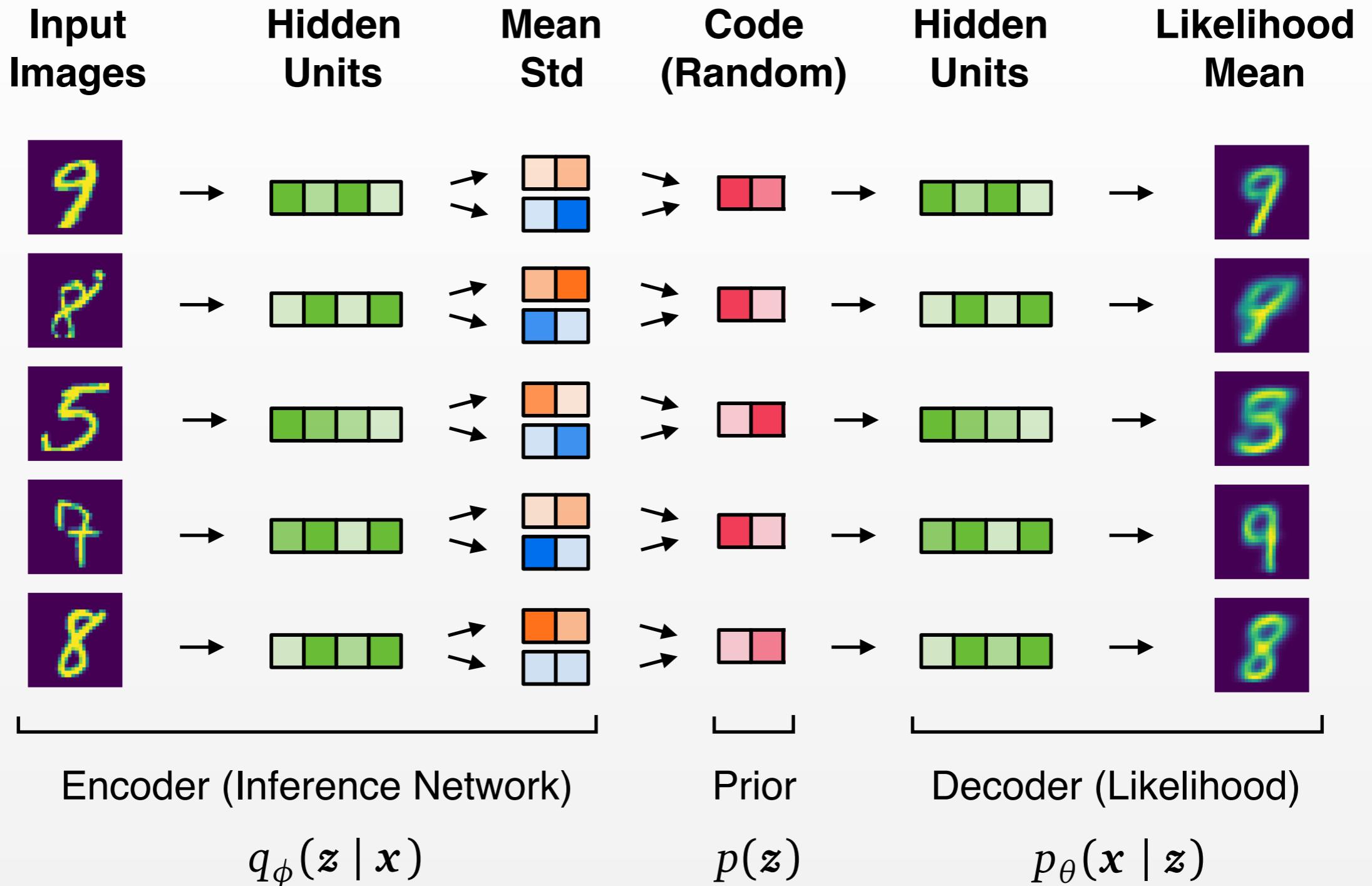
# Variational Autoencoders



# Variational Autoencoders



# Variational Autoencoders



# Variational Inference

Objective: Maximize Evidence Lower Bound

$$\mathcal{L}(\theta, \phi) := \mathbb{E}_{p^{\text{data}}(x)} \left[ \log p_\theta(x) - \text{KL}(q_\phi(z | x) || p_\theta(z | x)) \right]$$

# Variational Inference

Objective: Maximize Evidence Lower Bound

$$\begin{aligned}\mathcal{L}(\theta, \phi) &:= \mathbb{E}_{p^{\text{data}}(x)} \left[ \log p_{\theta}(x) - \text{KL}(q_{\phi}(z|x) \parallel p_{\theta}(z|x)) \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log \frac{p_{\theta}(x)p_{\theta}(z|x)}{q_{\phi}(z|x)} \right] \right]\end{aligned}$$

# Variational Inference

Objective: Maximize Evidence Lower Bound

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# Variational Inference

Objective: Maximize Evidence Lower Bound

$$\mathcal{L}(\theta, \phi) := \mathbb{E}_{p^{\text{data}}(x)} \left[ \log p_\theta(x) - \text{KL}(q_\phi(z|x) \parallel p_\theta(z|x)) \right]$$

$$= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_\phi(z|x)} \left[ \log \frac{p_\theta(x)p_\theta(z|x)}{q_\phi(z|x)} \right] \right]$$

$$= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_\phi(z|x)} \left[ \log \frac{p_\theta(x,z)}{q_\phi(z|x)} \right] \right] \quad (\text{computable})$$

$$= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_\phi(z|x)} \left[ \log p_\theta(x|z) + \log \frac{p(z)}{q_\phi(z|x)} \right] \right]$$

# Variational Inference

Objective: Maximize Evidence Lower Bound

$$\begin{aligned}\mathcal{L}(\theta, \phi) &:= \mathbb{E}_{p^{\text{data}}(x)} \left[ \log p_{\theta}(x) - \text{KL}(q_{\phi}(z|x) \parallel p_{\theta}(z|x)) \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log \frac{p_{\theta}(x)p_{\theta}(z|x)}{q_{\phi}(z|x)} \right] \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log \frac{p_{\theta}(x, z)}{q_{\phi}(z|x)} \right] \right] \quad (\text{computable}) \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log p_{\theta}(x|z) + \log \frac{p(z)}{q_{\phi}(z|x)} \right] \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} [\log p_{\theta}(x|z)] - \text{KL}(q_{\phi}(z|x) \parallel p(z)) \right]\end{aligned}$$

# Variational Inference

Objective: Maximize Evidence Lower Bound

$$\begin{aligned}\mathcal{L}(\theta, \phi) &:= \mathbb{E}_{p^{\text{data}}(x)} \left[ \log p_{\theta}(x) - \text{KL}(q_{\phi}(z|x) \parallel p_{\theta}(z|x)) \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log \frac{p_{\theta}(x)p_{\theta}(z|x)}{q_{\phi}(z|x)} \right] \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log \frac{p_{\theta}(x, z)}{q_{\phi}(z|x)} \right] \right] \quad (\text{computable}) \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log p_{\theta}(x|z) + \log \frac{p(z)}{q_{\phi}(z|x)} \right] \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \underbrace{\mathbb{E}_{q_{\phi}(z|x)} [\log p_{\theta}(x|z)]}_{\text{Reconstruction Error}} - \text{KL}(q_{\phi}(z|x) \parallel p(z)) \right]\end{aligned}$$

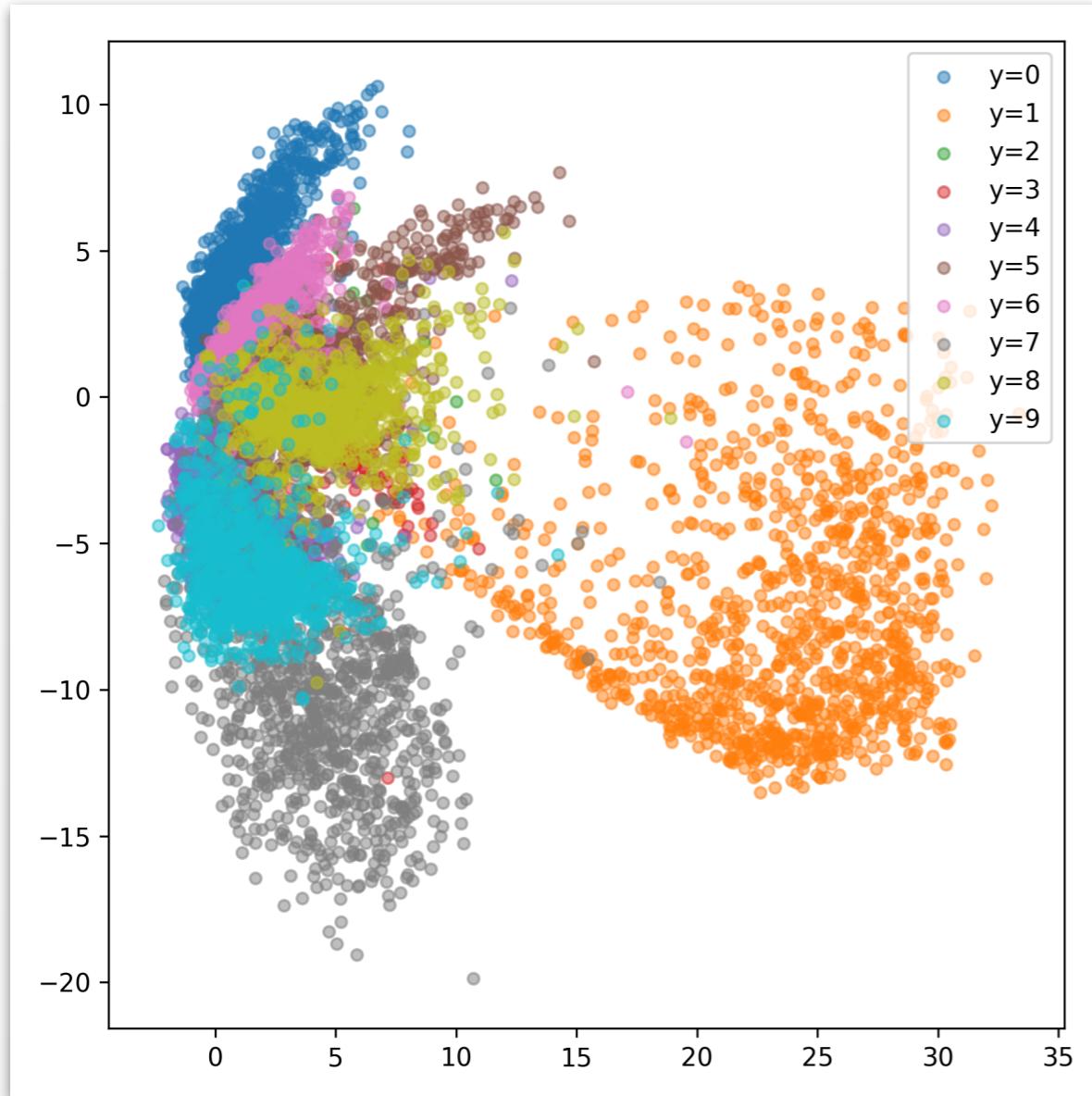
# Variational Inference

Objective: Maximize Evidence Lower Bound

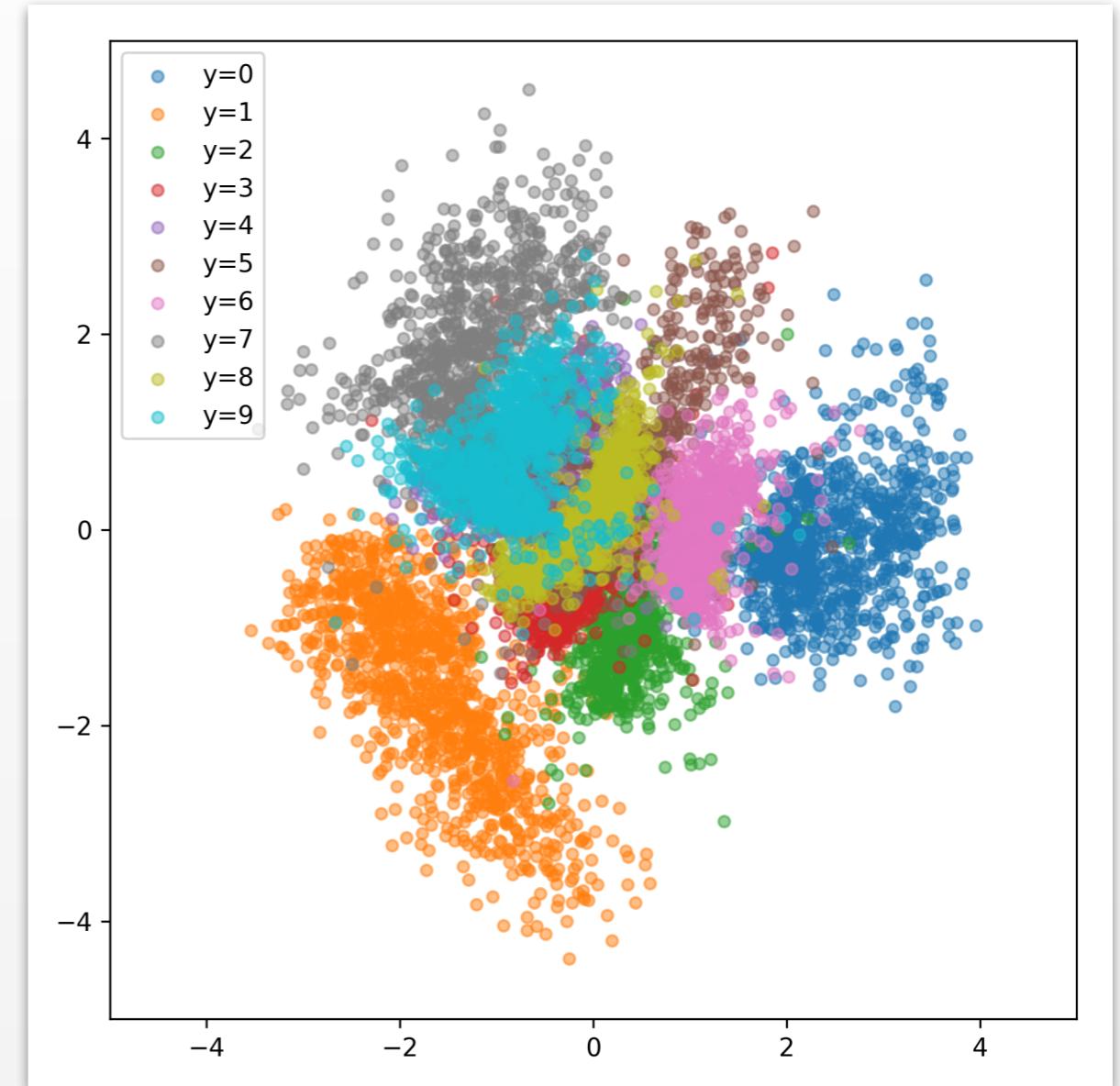
$$\begin{aligned}\mathcal{L}(\theta, \phi) &:= \mathbb{E}_{p^{\text{data}}(x)} \left[ \log p_{\theta}(x) - \text{KL}(q_{\phi}(z|x) \parallel p_{\theta}(z|x)) \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log \frac{p_{\theta}(x)p_{\theta}(z|x)}{q_{\phi}(z|x)} \right] \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log \frac{p_{\theta}(x, z)}{q_{\phi}(z|x)} \right] \right] \quad (\text{computable}) \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \mathbb{E}_{q_{\phi}(z|x)} \left[ \log p_{\theta}(x|z) + \log \frac{p(z)}{q_{\phi}(z|x)} \right] \right] \\ &= \mathbb{E}_{p^{\text{data}}(x)} \left[ \underbrace{\mathbb{E}_{q_{\phi}(z|x)} [\log p_{\theta}(x|z)]}_{\text{Reconstruction Error}} - \underbrace{\text{KL}(q_{\phi}(z|x) \parallel p(z))}_{\text{KL Regularization}} \right]\end{aligned}$$

# Regular vs Variational Autoencoders

Autoencoder (2-dim)



VAE (2-dim)



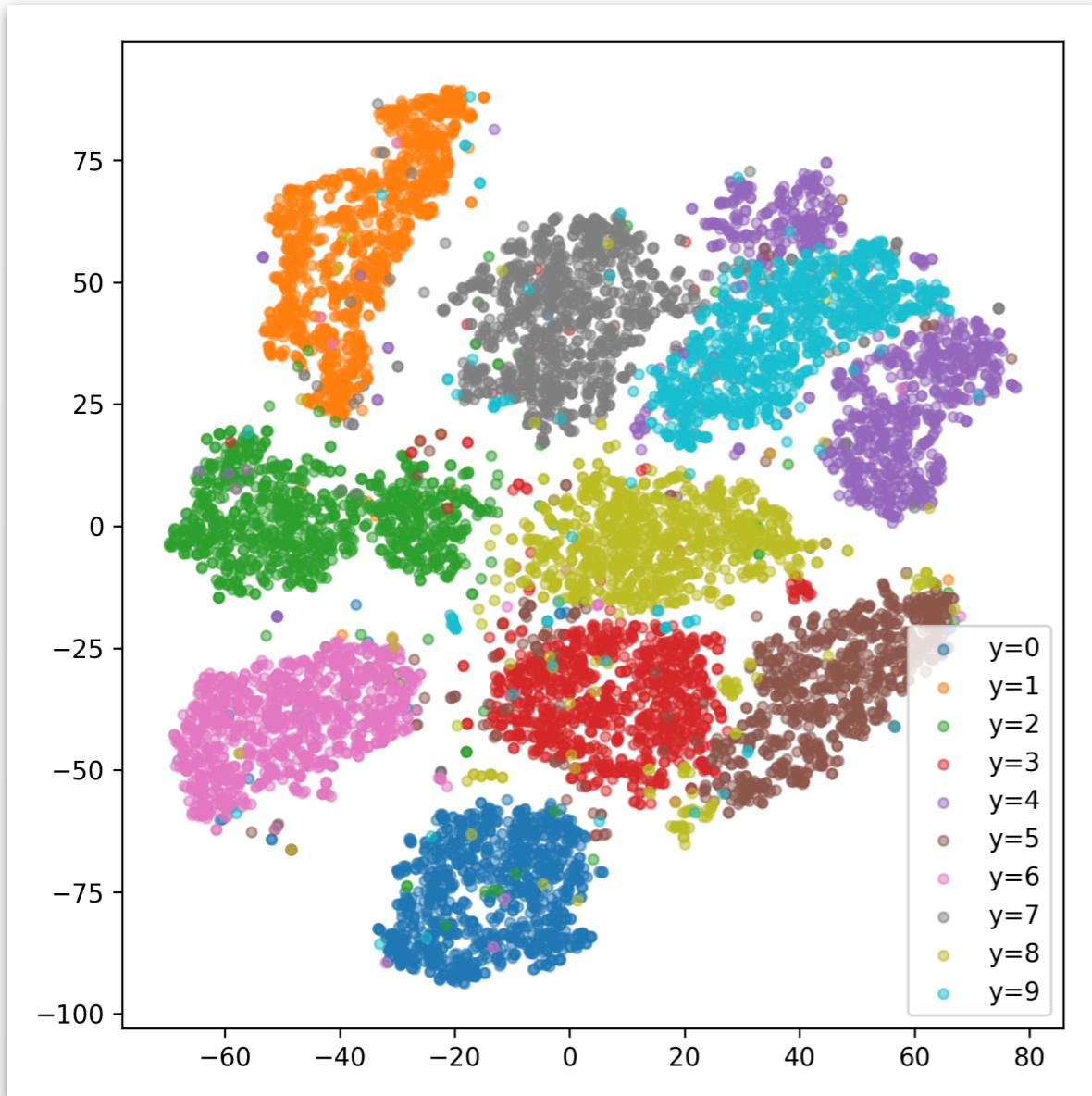
Arbitrary scale (no “typical” values)

Well-defined scale ( $-4 < z < 4$ )

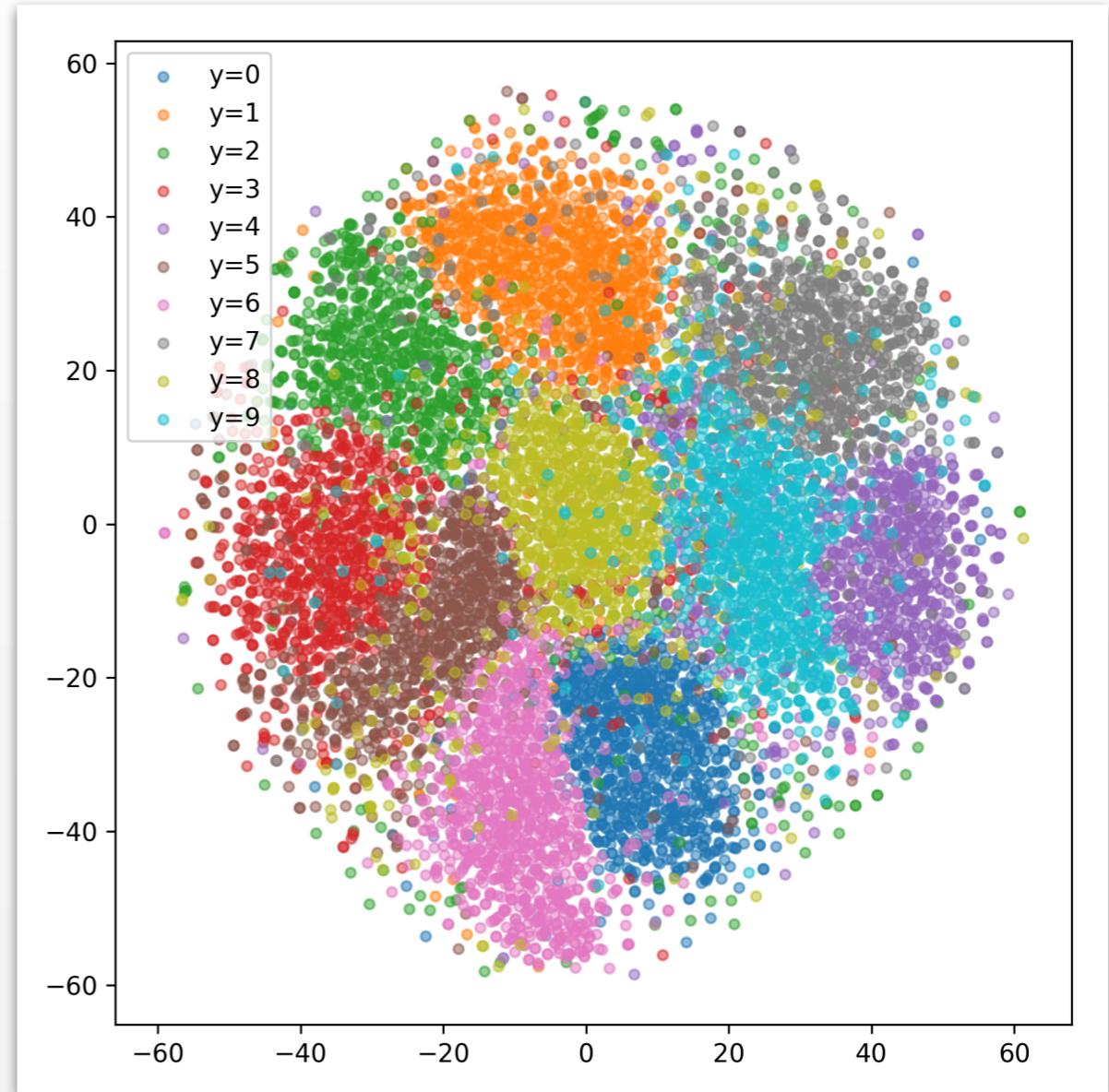
**KL regularization constrains values of latent codes**

# Regular vs Variational Autoencoders

Autoencoder (50-dim TSNE)

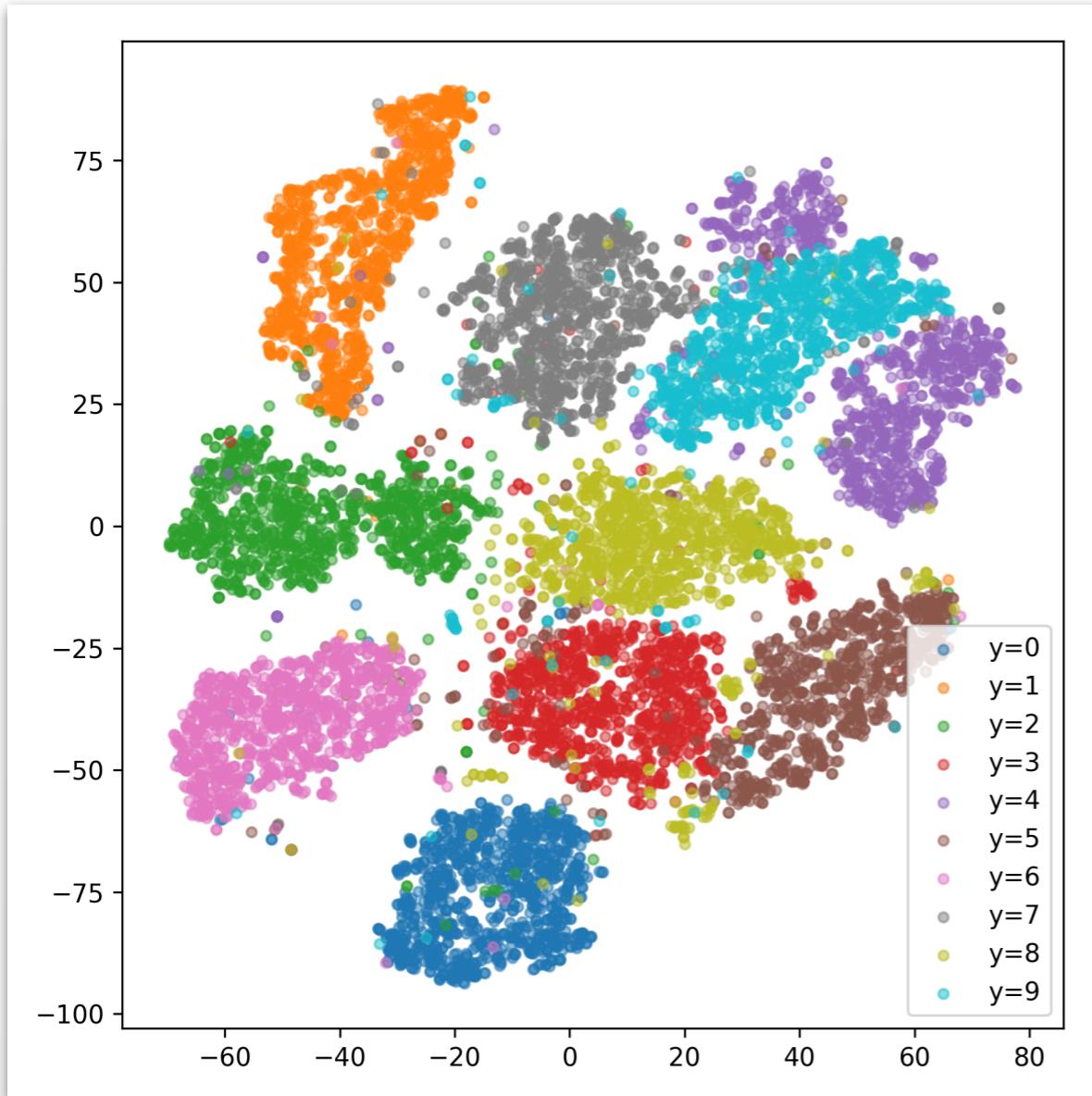


VAE (50-dim TSNE)

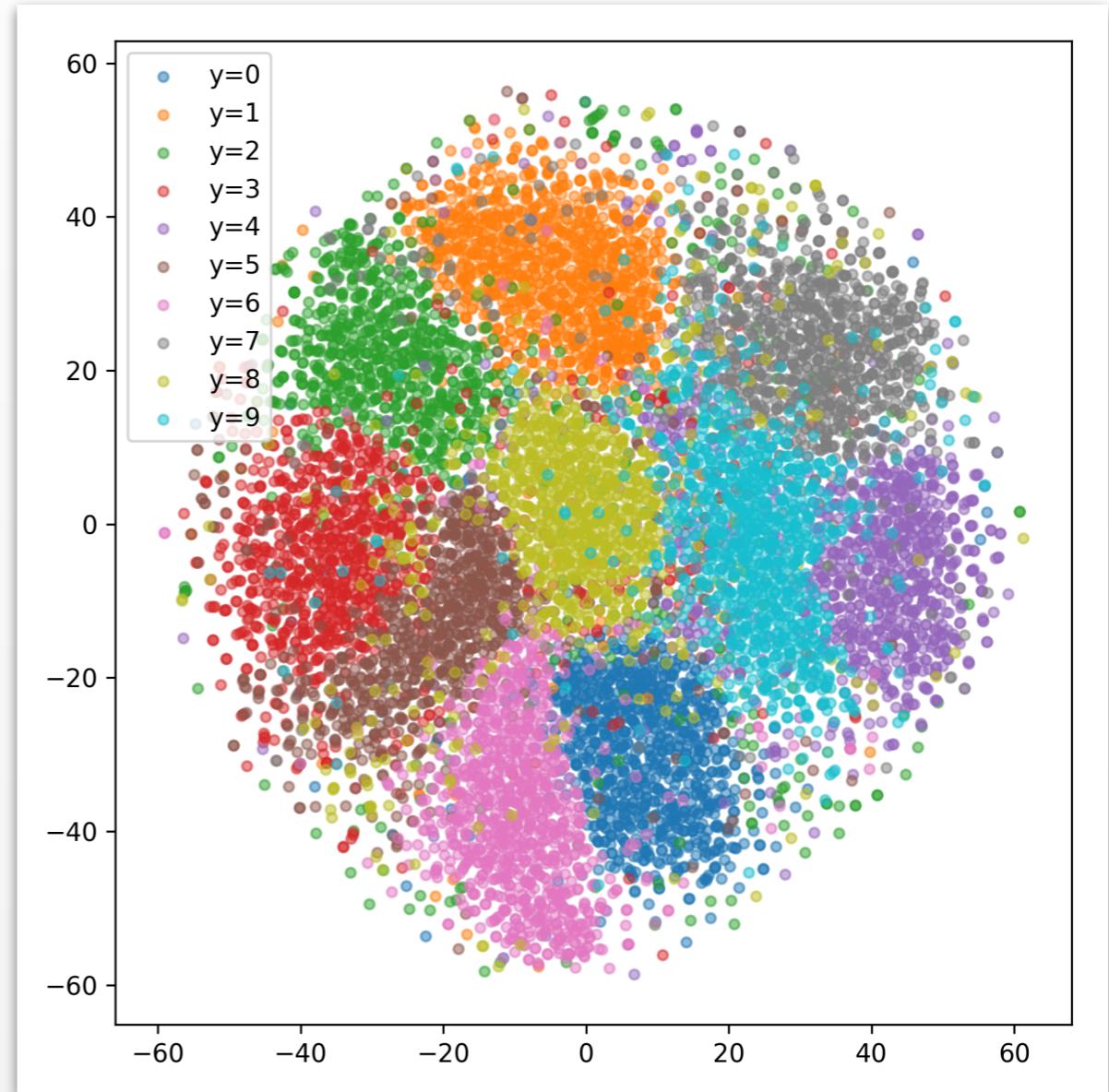


# Regular vs Variational Autoencoders

Autoencoder (50-dim TSNE)



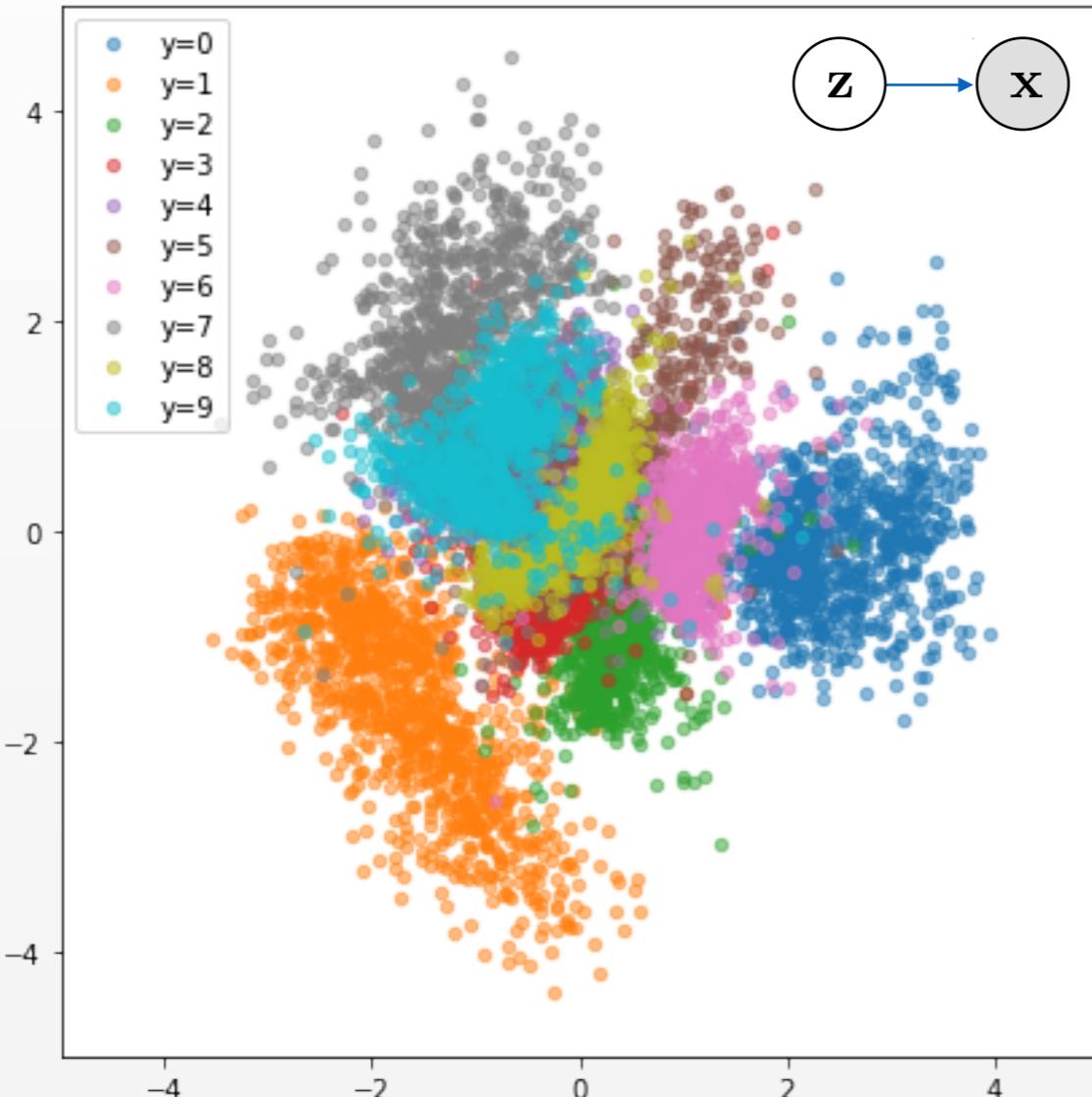
VAE (50-dim TSNE)



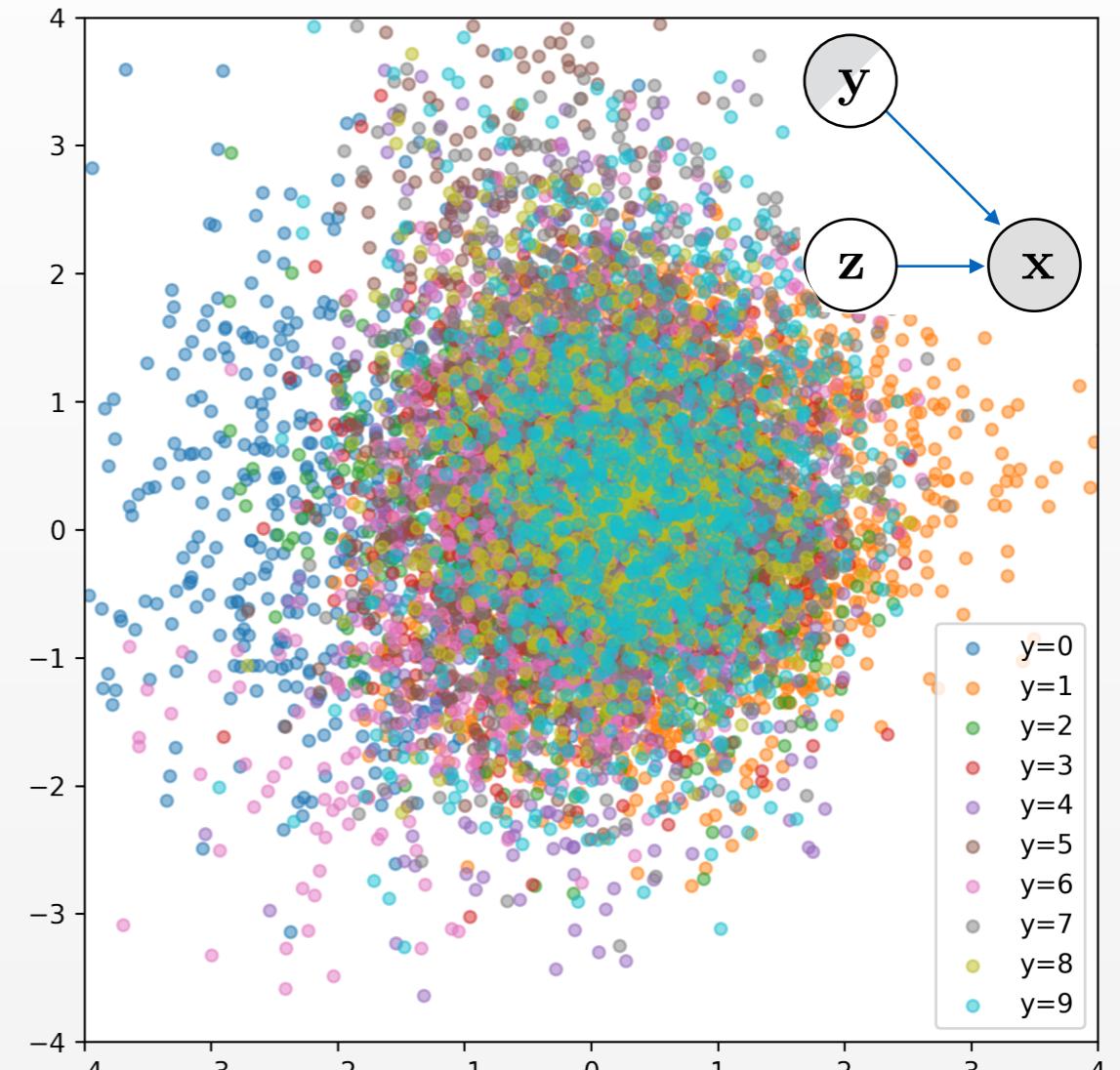
Representations are still entangled

# Unsupervised vs Semi-Supervised

**Unsupervised, Entangled**

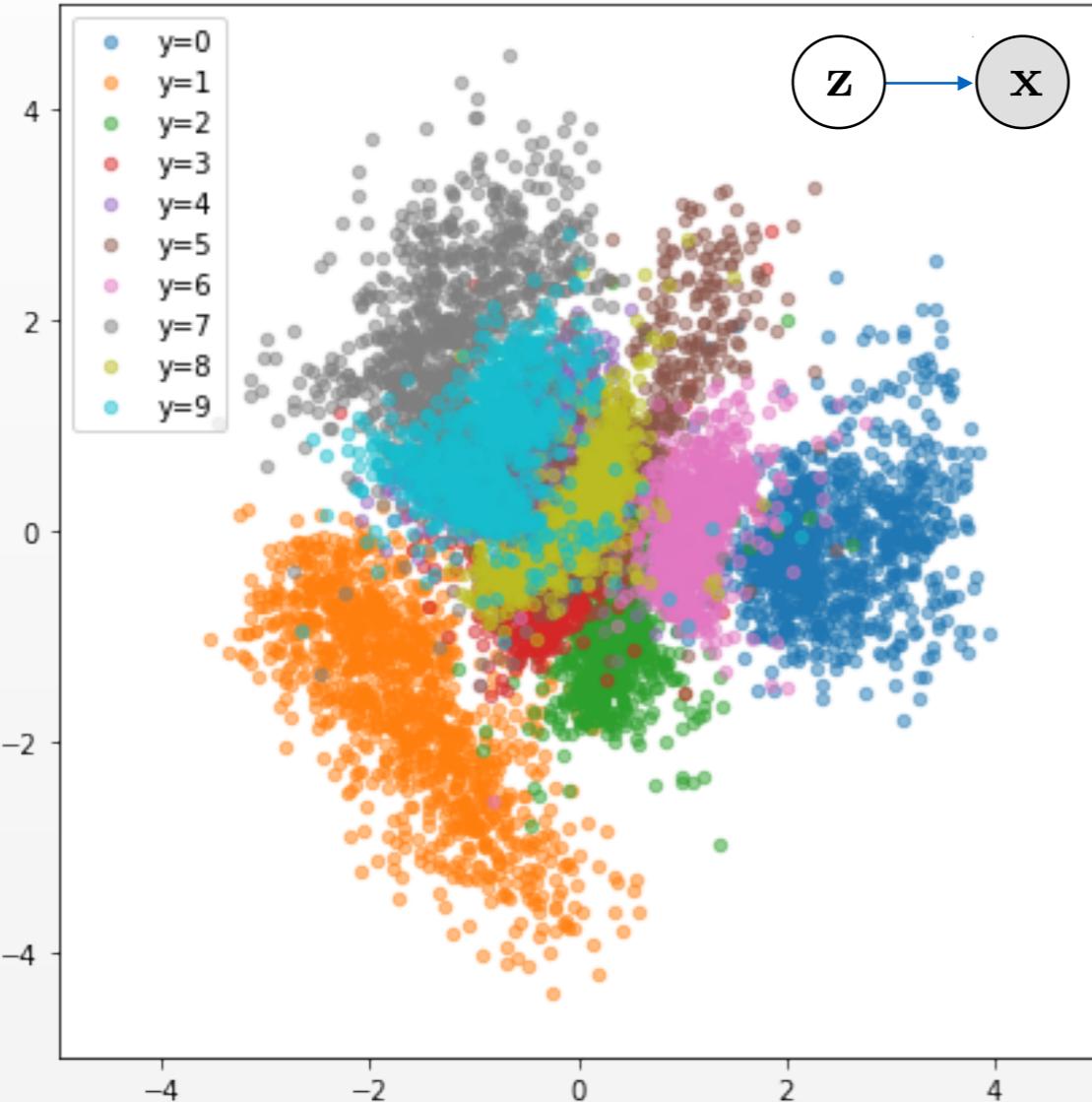


**Semi-supervised, Disentangled**

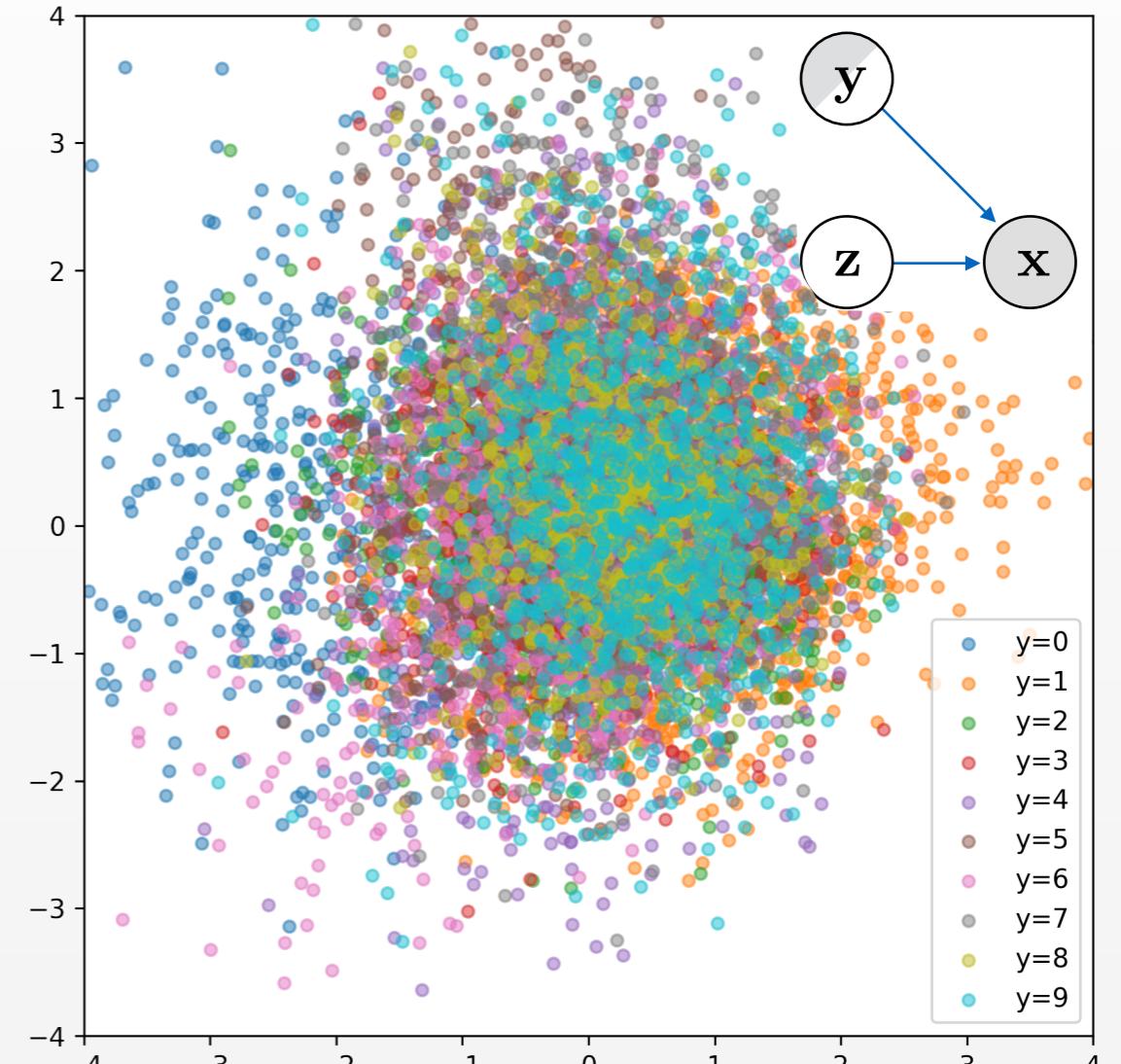


# Unsupervised vs Semi-Supervised

**Unsupervised, Entangled**



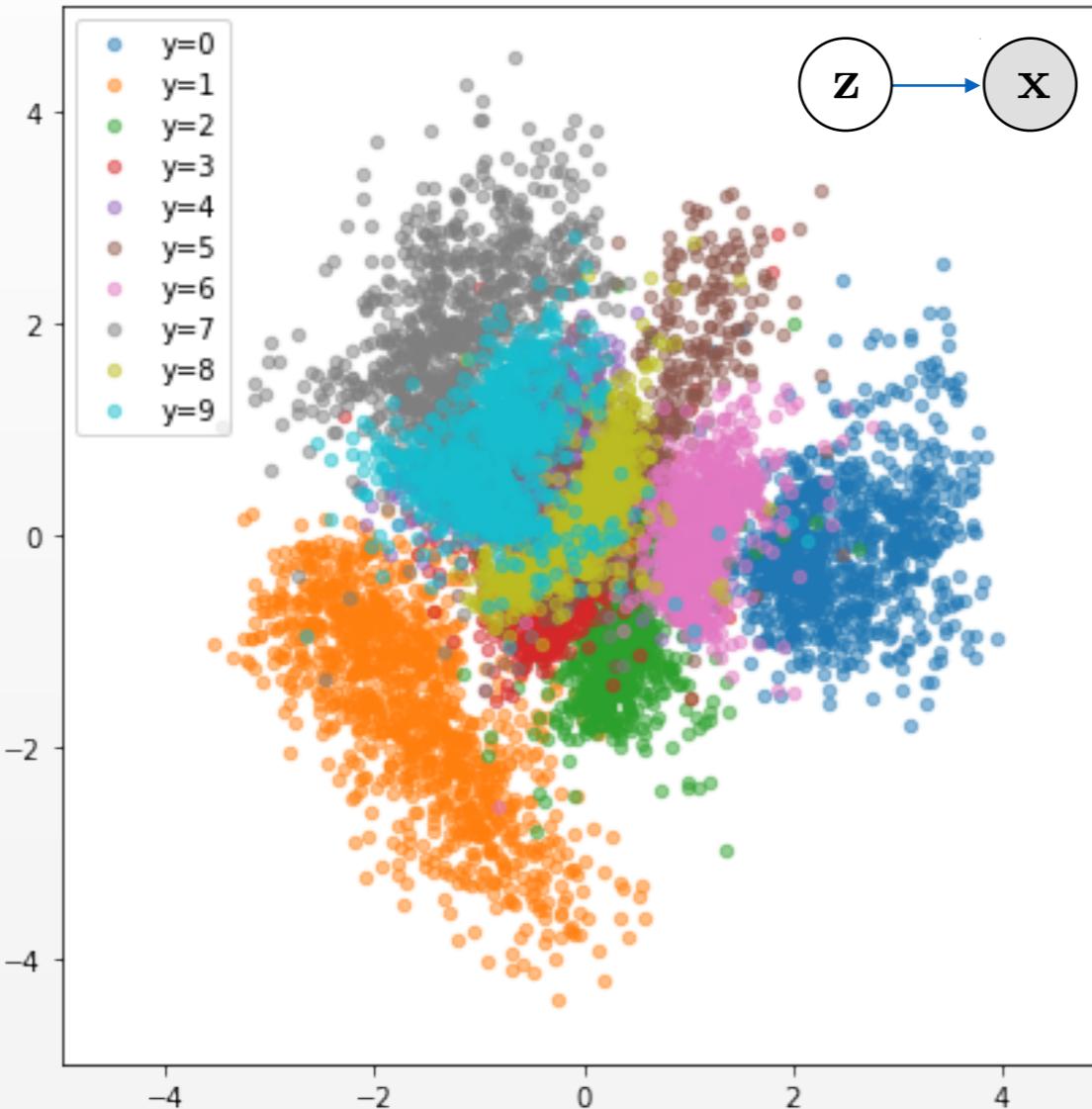
**Semi-supervised, Disentangled**



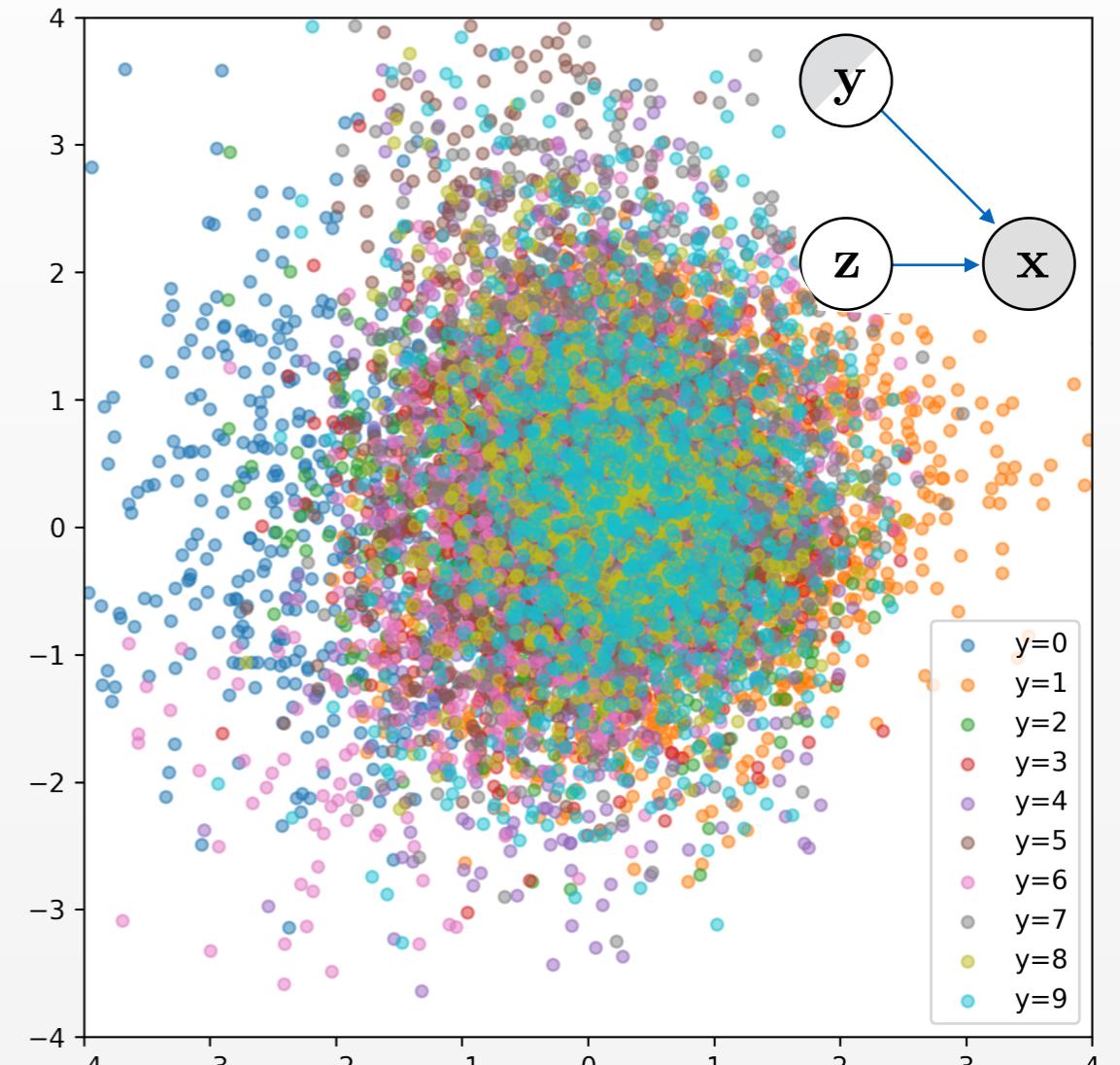
Latent code  $z$  represents  
both style and digit

# Unsupervised vs Semi-Supervised

**Unsupervised, Entangled**



**Semi-supervised, Disentangled**

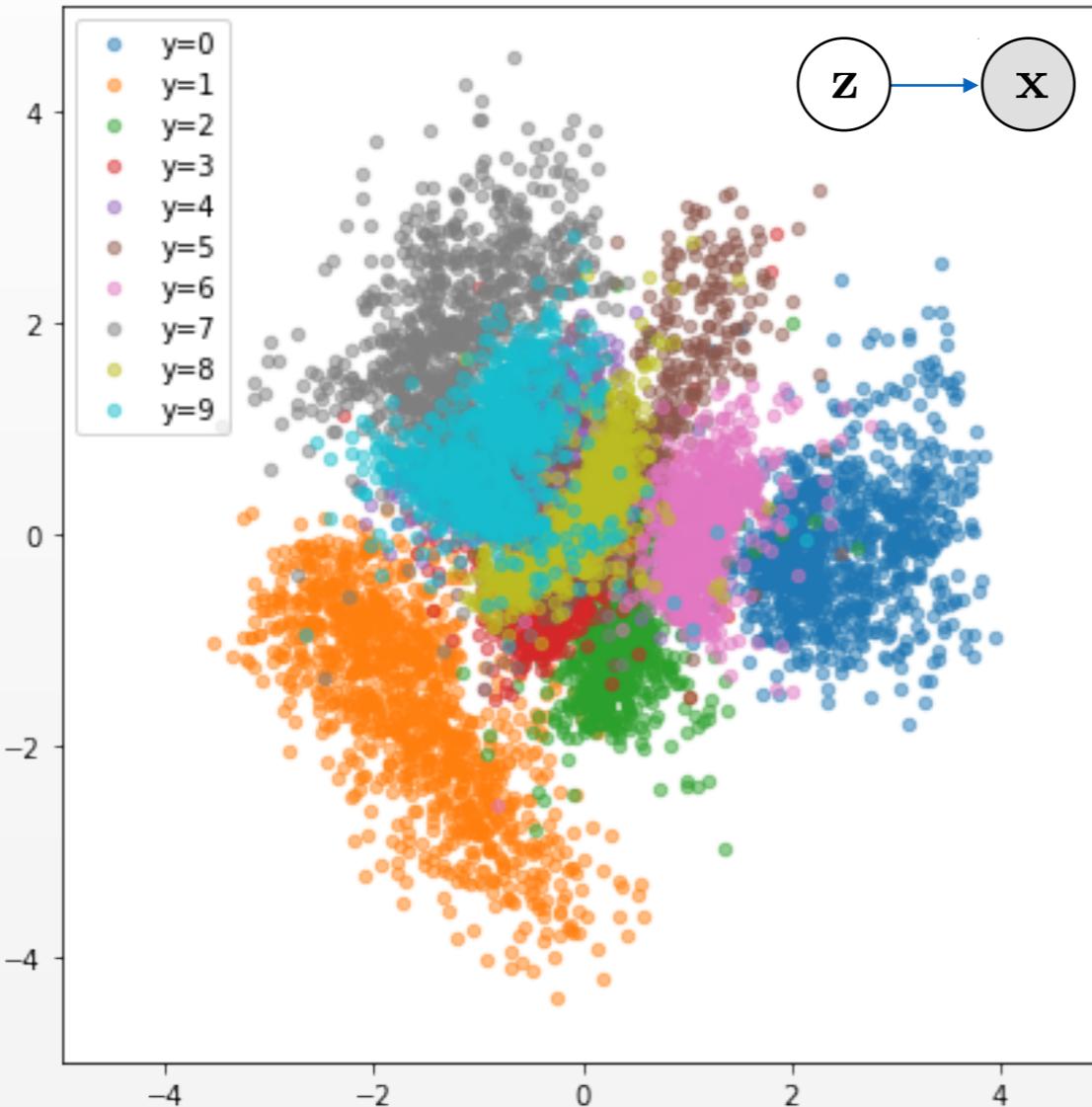


Latent code  $z$  represents  
both style and digit

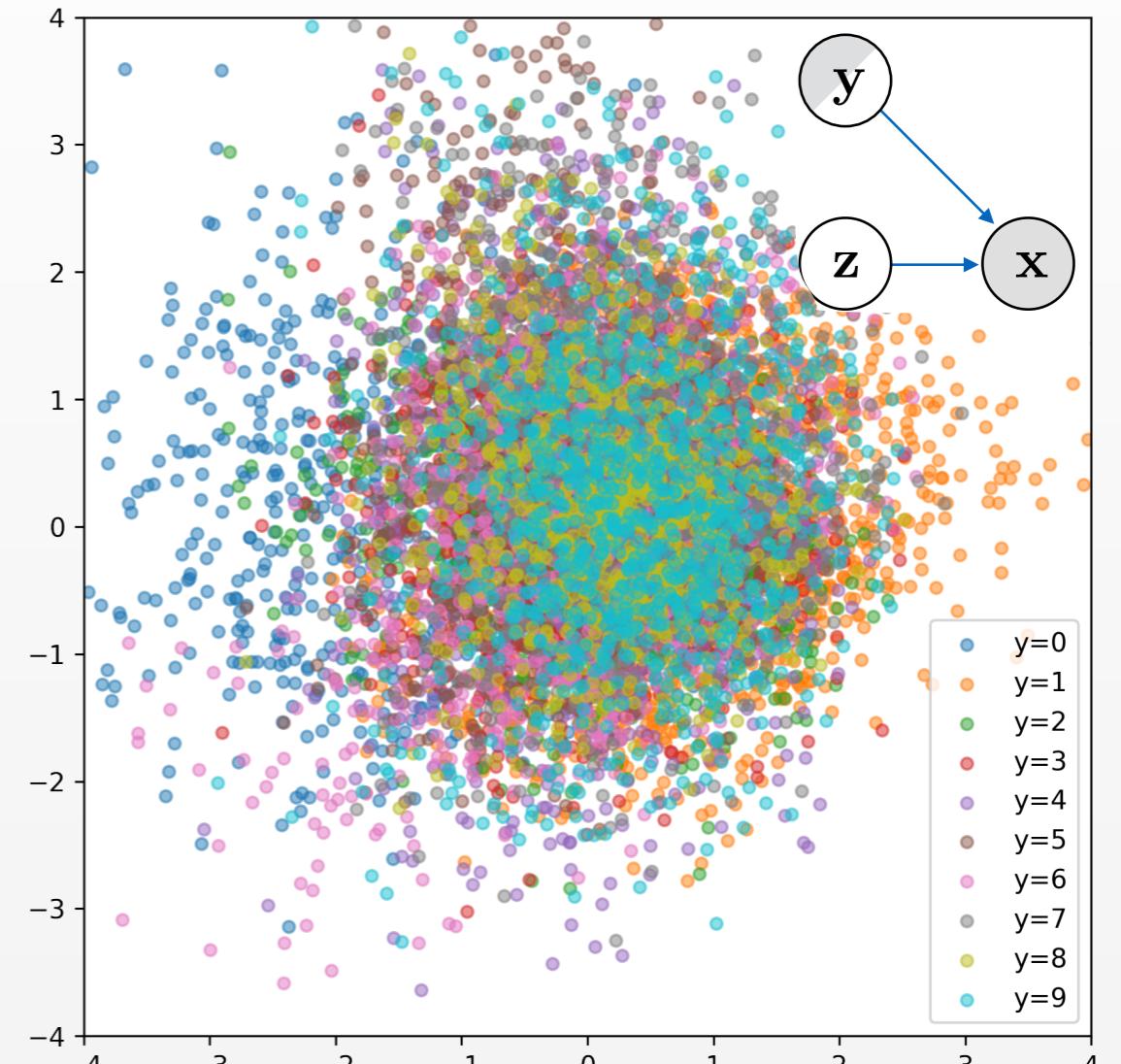
Style variable  $z$  is conditionally  
independent from digit  $y$  (\*)

# Unsupervised vs Semi-Supervised

**Unsupervised, Entangled**



**Semi-supervised, Disentangled**

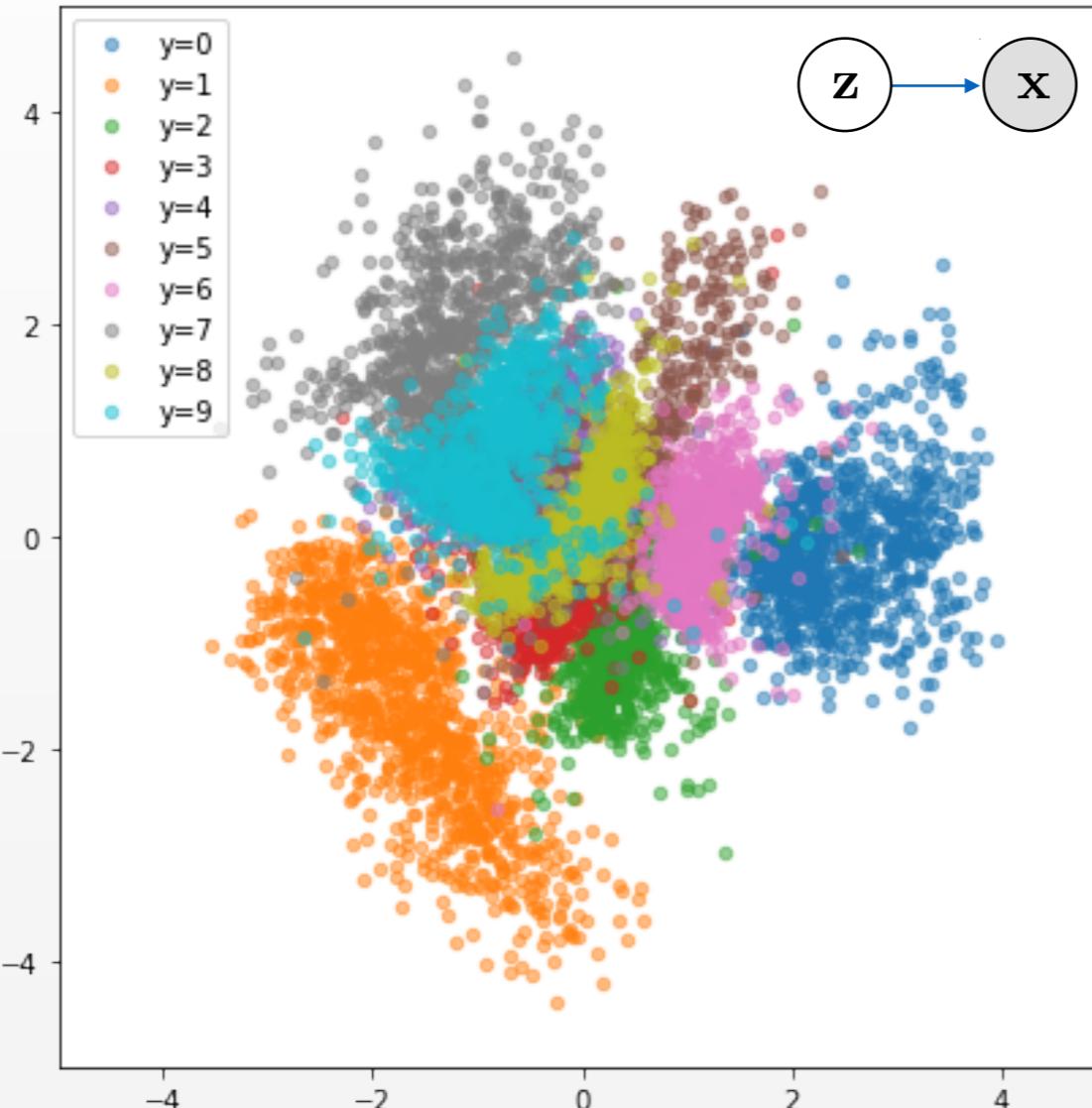


Latent code  $z$  represents  
both style and digit

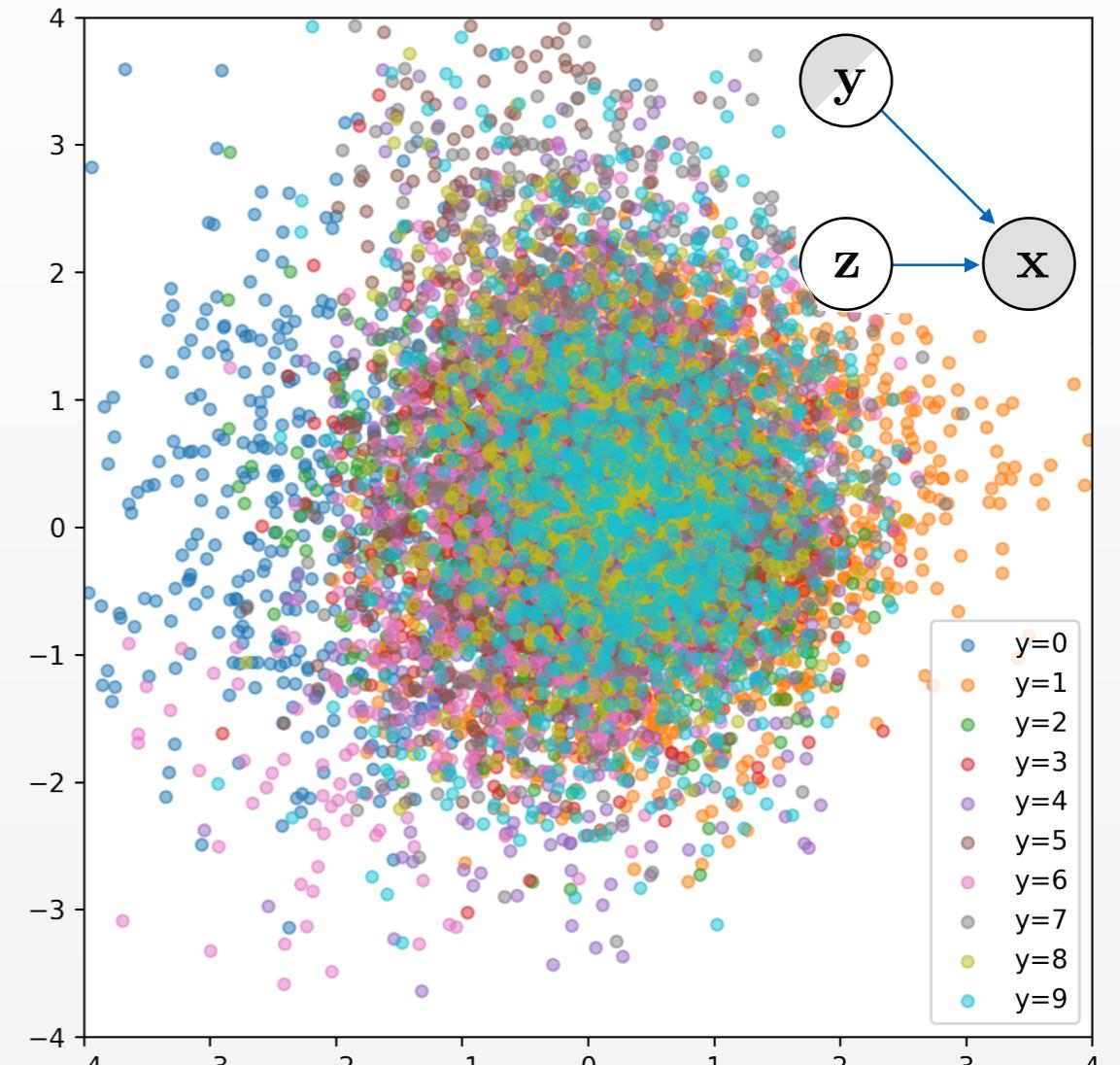
Style variable  $z$  is conditionally  
independent from digit  $y$  (\*)  
(\*but not without supervision)

# Unsupervised vs Semi-Supervised

**Unsupervised, Entangled**



**Semi-supervised, Disentangled**



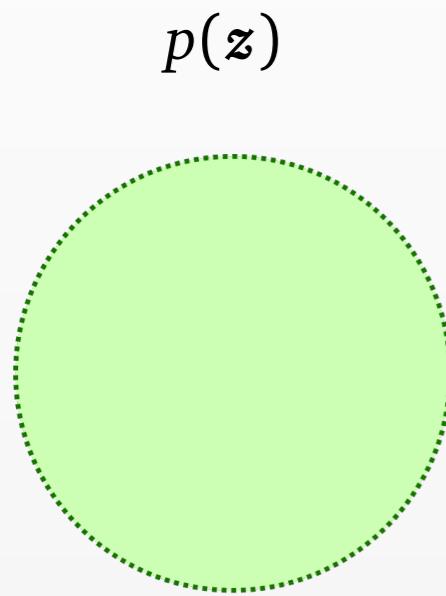
In both models, prior on  $z$  assumes uncorrelated dimensions

$$p(z) = \prod_d p(z_d)$$

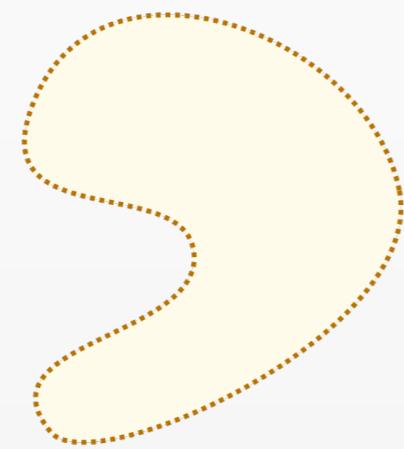
# Learning Statistically Independent Factors

# Deep Latent-Variable Models

## Generative Model

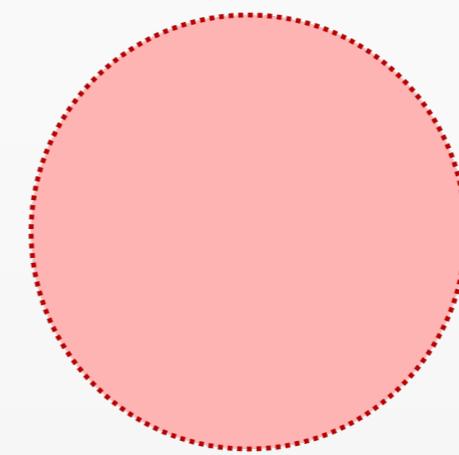


$$p_{\theta}(\mathbf{x})$$

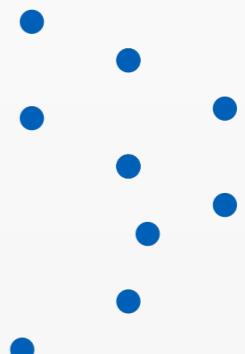


## Inference Model

$$q_{\phi}(\mathbf{z})$$



$$q(\mathbf{x})$$



Prior  
(*known*)

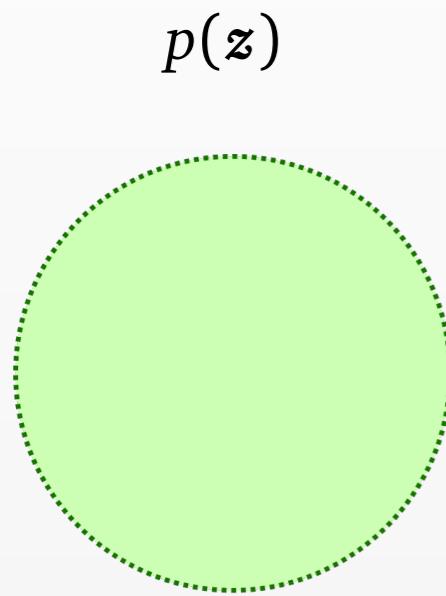
Data Distribution  
(*learned*)

Inference Marginal  
(*learned*)

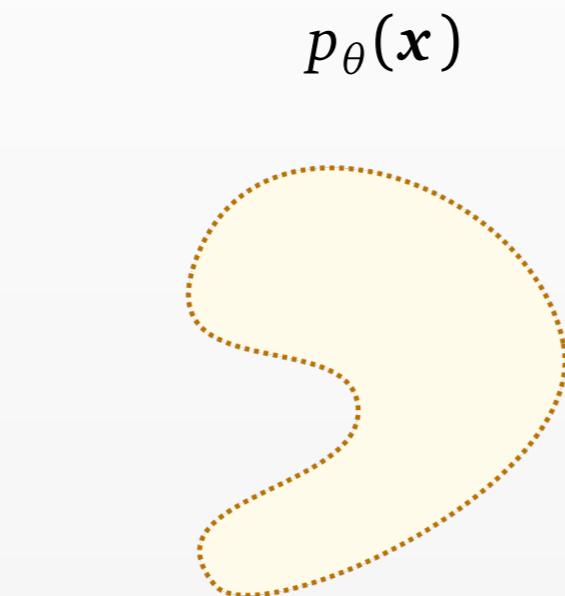
Empirical Distribution  
(*known*)

# Deep Latent-Variable Models

## Generative Model



Prior  
*(known)*

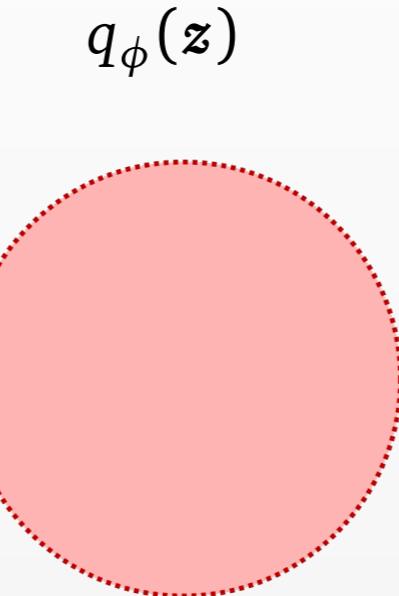


Data Distribution  
*(learned)*

$$\mathbf{x}_n \sim p^{\text{data}}(\mathbf{x})$$

Data Sampled from  
Unknown Distribution

## Inference Model



Inference Marginal  
*(learned)*



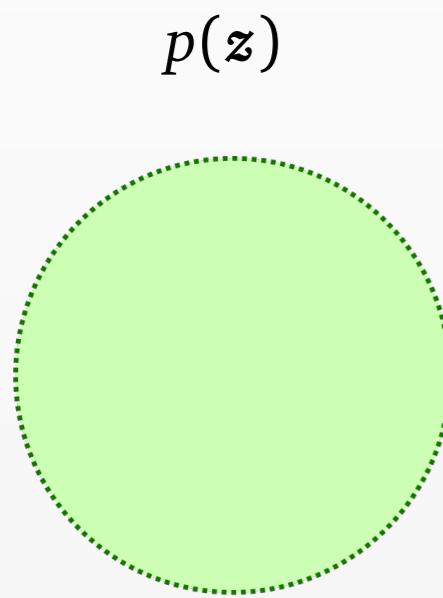
Empirical Distribution  
*(known)*

$$q(\mathbf{x}) := \frac{1}{N} \sum_{n=1}^N \delta_{\mathbf{x}_n}(\mathbf{x})$$

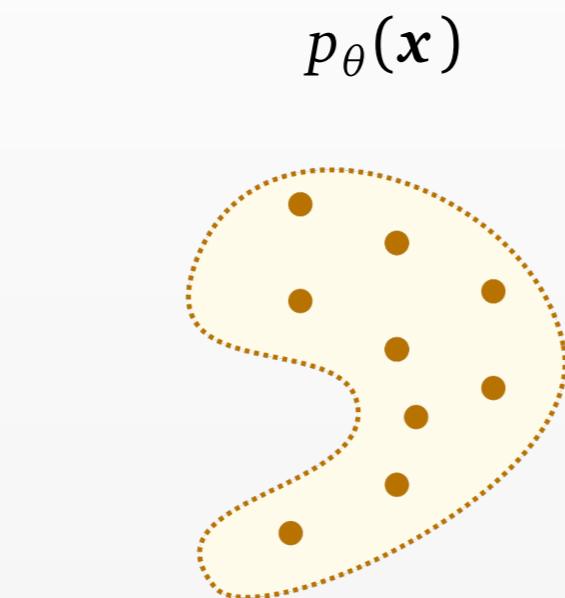
Approximation of  
Data Distribution

# Deep Latent-Variable Models

## Generative Model



Prior  
*(known)*

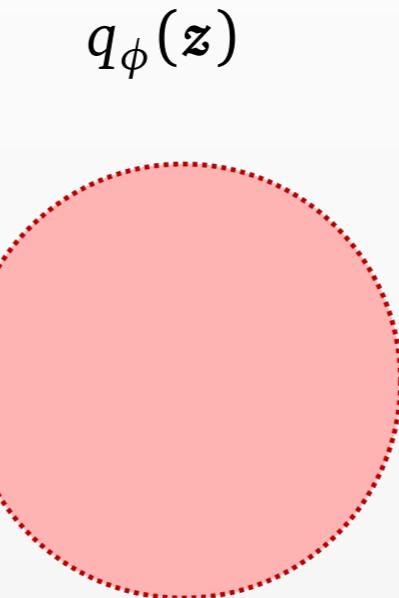


Data Distribution  
*(learned)*

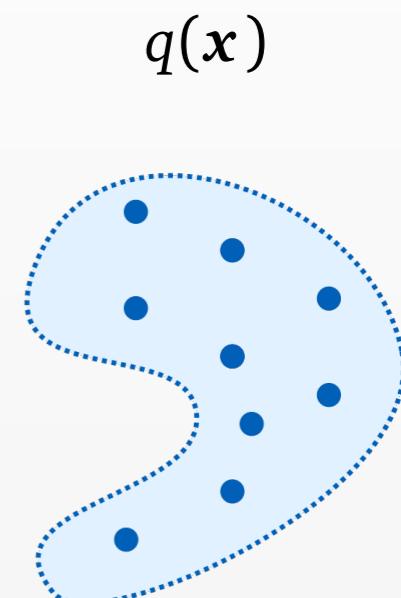
$$\mathbf{x}_n \sim p^{\text{data}}(\mathbf{x})$$

Data Sampled from  
Unknown Distribution

## Inference Model



Inference Marginal  
*(learned)*



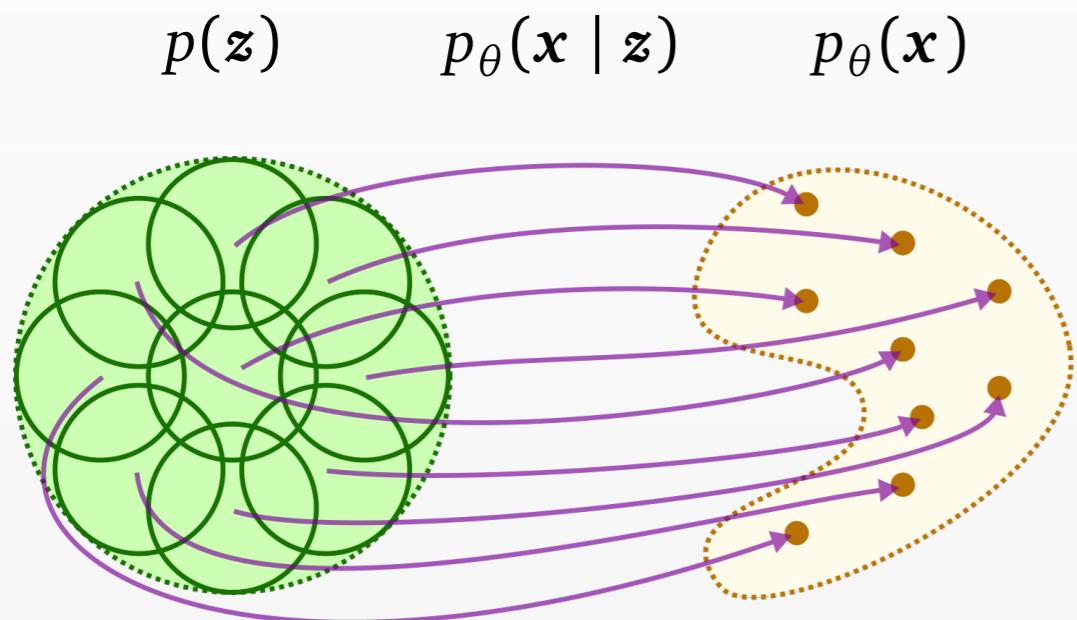
Empirical Distribution  
*(known)*

$$q(\mathbf{x}) := \frac{1}{N} \sum_{n=1}^N \delta_{\mathbf{x}_n}(\mathbf{x})$$

Approximation of  
Data Distribution

# Deep Latent-Variable Models

## Generative Model



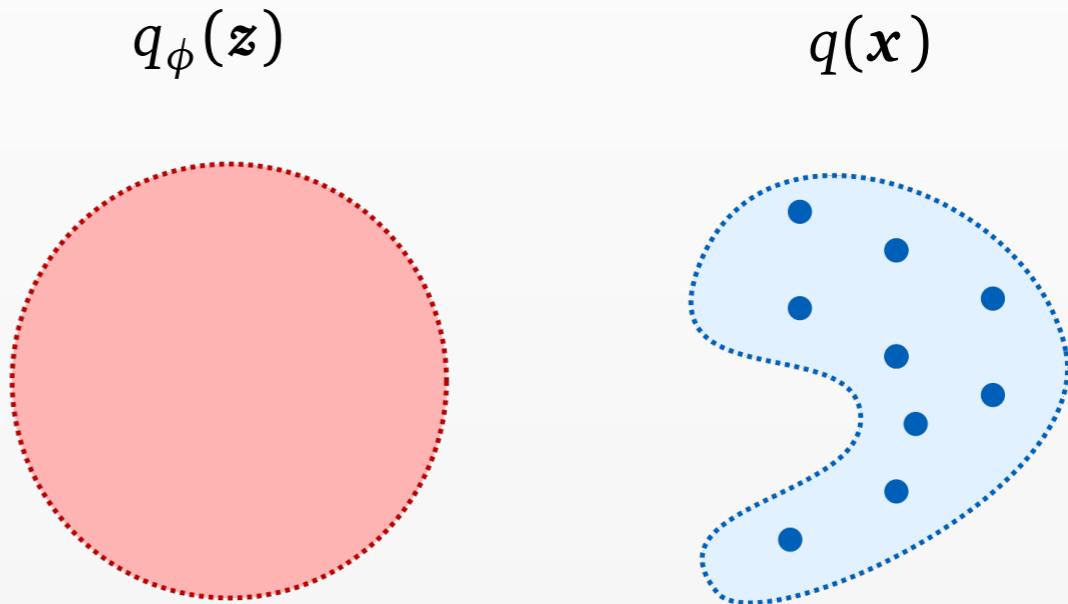
Prior  
(known)

Data Distribution  
(learned)

$$\mathbf{x}_n \sim p^{\text{data}}(\mathbf{x})$$

Data Sampled from  
Unknown Distribution

## Inference Model



Inference Marginal  
(learned)

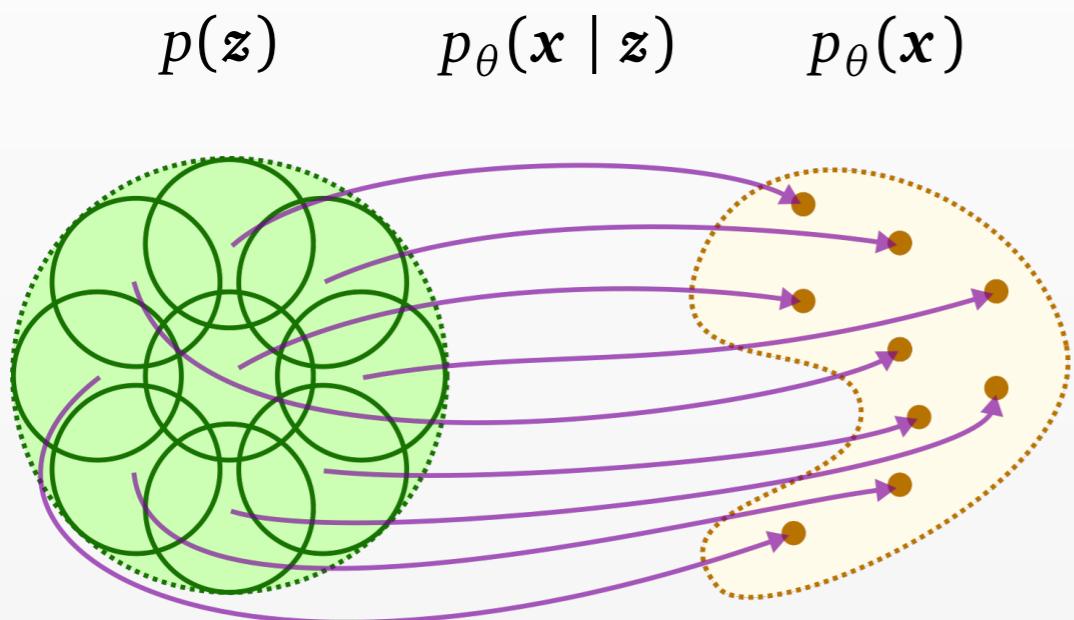
Empirical Distribution  
(known)

$$q(\mathbf{x}) := \frac{1}{N} \sum_{n=1}^N \delta_{\mathbf{x}_n}(\mathbf{x})$$

Approximation of  
Data Distribution

# Deep Latent-Variable Models

## Generative Model



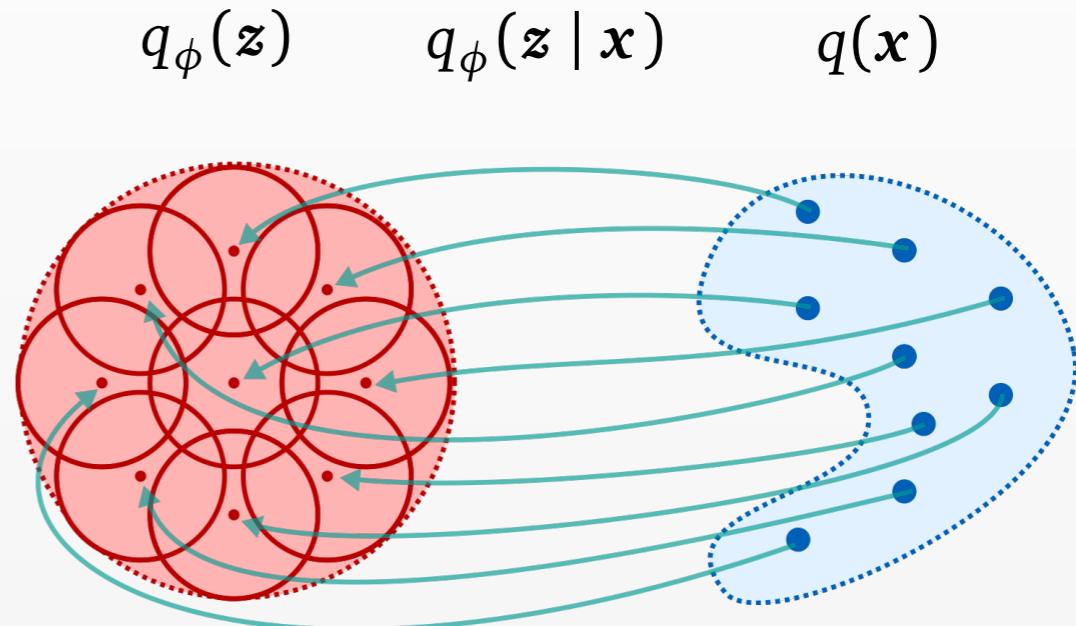
Prior  
*(known)*

Data Distribution  
*(learned)*

$$\mathbf{x}_n \sim p^{\text{data}}(\mathbf{x})$$

Data Sampled from  
Unknown Distribution

## Inference Model



Inference Marginal  
*(learned)*

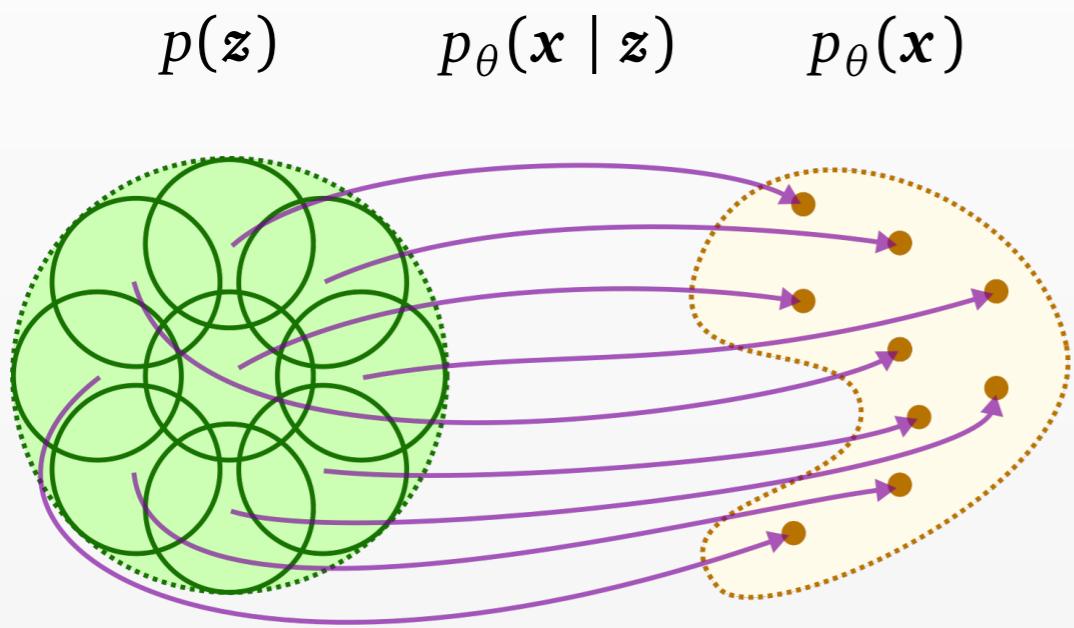
Empirical Distribution  
*(known)*

$$q(\mathbf{x}) := \frac{1}{N} \sum_{n=1}^N \delta_{\mathbf{x}_n}(\mathbf{x})$$

Approximation of  
Data Distribution

# Deep Latent-Variable Models

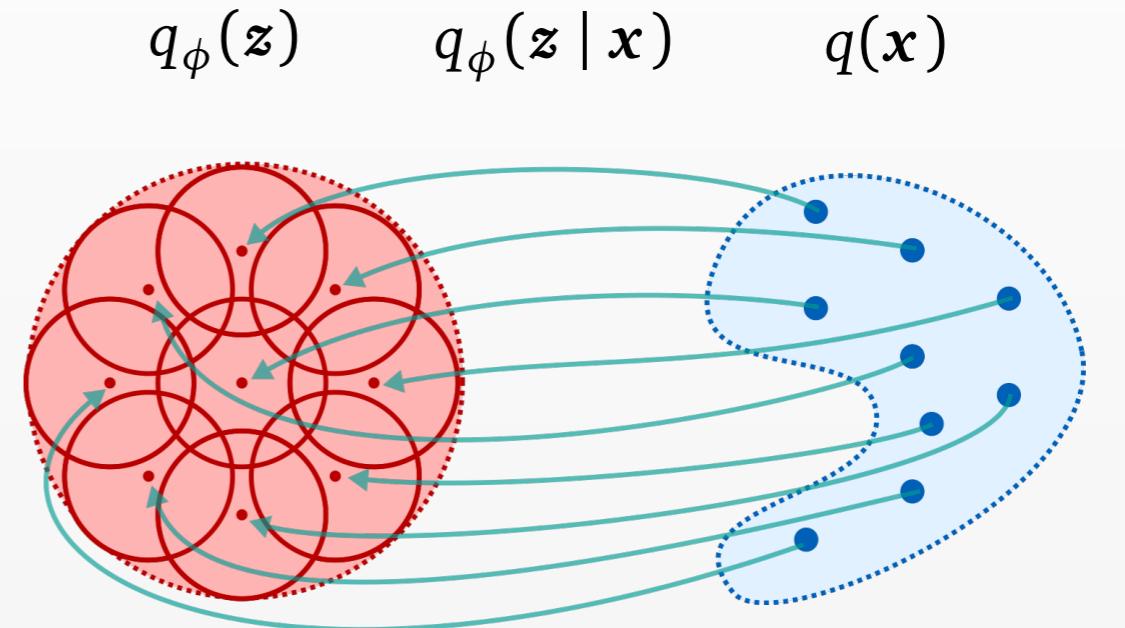
## Generative Model



Prior  
(known)

Data Distribution  
(learned)

## Inference Model

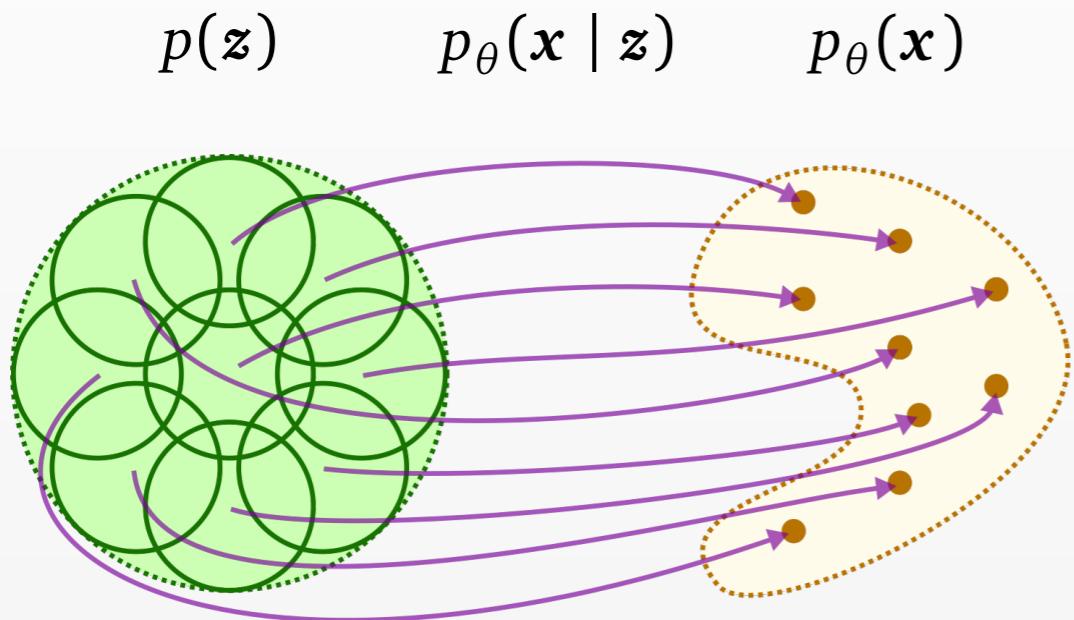


Inference Marginal  
(learned)

Empirical Distribution  
(known)

# Deep Latent-Variable Models

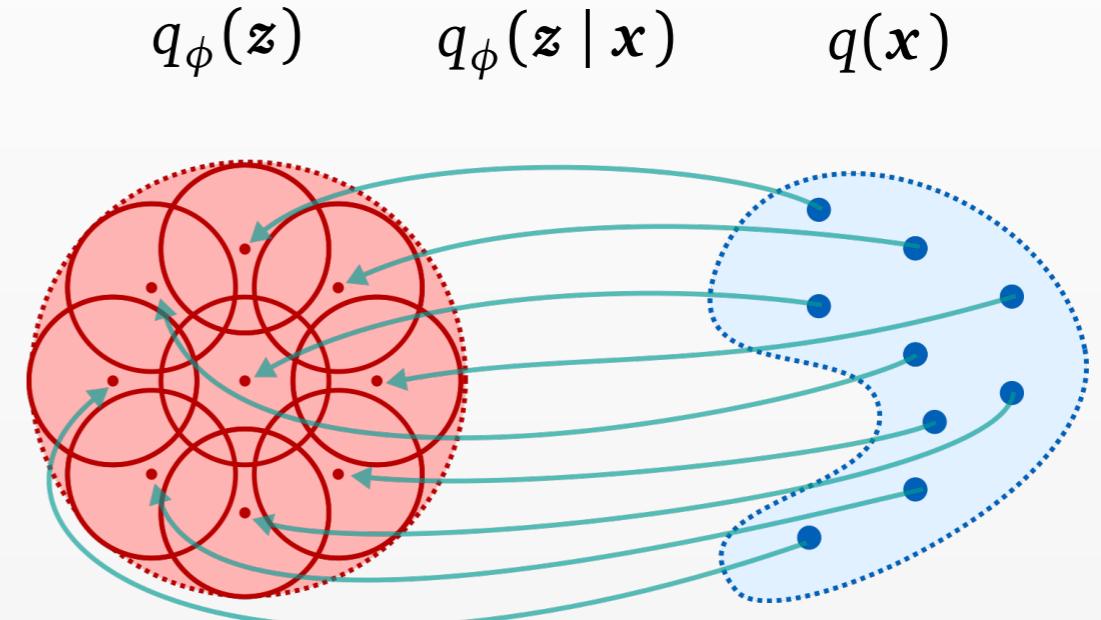
## Generative Model



Prior  
(known)

Data Distribution  
(learned)

## Inference Model



Inference Marginal  
(learned)

Empirical Distribution  
(known)

Constraints: Models are Equivalent when

$$p_\theta(x) = q(x)$$

$$q_\phi(z) = p(z)$$

$$p_\theta(z | x) = p_\phi(z | x) \quad \forall x$$

# Implicit Tradeoffs in the Variational Objective

Classical View: Maximize Evidence Lower Bound

$$\mathcal{L}(\theta, \phi) = \mathbb{E}_{q(x)} \left[ \underbrace{\mathbb{E}_{q_\phi(z|x)} [\log p_\theta(x | z)]}_{\text{Reconstruction Error}} - \underbrace{\text{KL}(q_\phi(z | x) || p(z))}_{\text{KL Regularization}} \right]$$

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Alternate View: KL Divergence Between Two Models

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Alternate View: KL Divergence Between Two Models

$$\mathcal{L}(\theta, \phi) = \mathbb{E}_{q_\phi(x,z)} \left[ \log \frac{p_\theta(x, z)}{q_\phi(z | x)} \right]$$

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# Implicit Tradeoffs in the Variational Objective

$$\mathcal{L}(\theta, \phi) := -\text{KL}\left(q_{\phi}(z, x) \parallel p_{\theta}(x, z)\right) = \mathbb{E}_{q_{\phi}(z, x)} \left[ \log \frac{p_{\theta}(x, z)}{q_{\phi}(z, x)} \right]$$

[Hoffman, Johnson, NIPS AABI Workshop 2016], [Chen, Li, Grosse, Duvenaud, Arxiv 2018]

[Esmaeli, Wu, Jain, Bozkurt, Siddharth, Paige, Brooks, Dy, van de Meent, Arxiv 2018]

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[Hoffman, Johnson, NIPS AABI Workshop 2016], [Chen, Li, Grosse, Duvenaud, Arxiv 2018]  
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[Hoffman, Johnson, NIPS AABI Workshop 2016], [Chen, Li, Grosse, Duvenaud, Arxiv 2018]

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[Hoffman, Johnson, NIPS AABI Workshop 2016], [Chen, Li, Grosse, Duvenaud, Arxiv 2018]

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# Implicit Tradeoffs in the Variational Objective

$$\begin{aligned}
\mathcal{L}(\theta, \phi) &:= -\text{KL}\left(q_{\phi}(z, x) \parallel p_{\theta}(x, z)\right) = \mathbb{E}_{q_{\phi}(z, x)} \left[ \log \frac{p_{\theta}(x, z)}{q_{\phi}(z, x)} \right] \\
&= \mathbb{E}_{q_{\phi}(z, x)} \left[ \log \frac{p_{\theta}(x, z)}{p_{\theta}(x)p(z)} + \log \frac{q_{\phi}(z)q(x)}{q_{\phi}(z, x)} + \log \frac{p_{\theta}(x)}{q(x)} + \log \frac{p(z)}{q_{\phi}(z)} \right] \\
&= \mathbb{E}_{q_{\phi}(z, x)} \left[ \underbrace{\log \frac{p_{\theta}(z | x)}{p(z)}}_{\textcircled{1}} - \underbrace{\log \frac{q_{\phi}(z | x)}{q_{\phi}(z)}}_{\textcircled{2}} \right] - \underbrace{\text{KL}(q(x) \parallel p_{\theta}(x))}_{\textcircled{3}} - \underbrace{\text{KL}(q_{\phi}(z) \parallel p(z))}_{\textcircled{4}} \\
p_{\theta}(z | x) &= p_{\phi}(z | x) \quad \forall x \quad p_{\theta}(x) = q(x) \quad q_{\phi}(z) = p(z)
\end{aligned}$$

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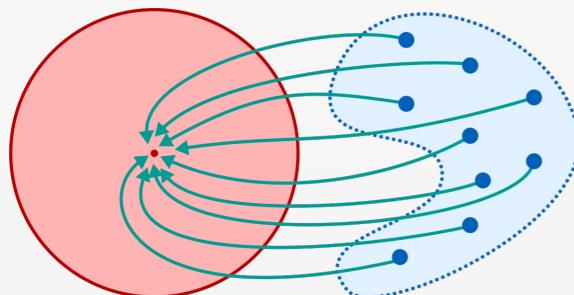
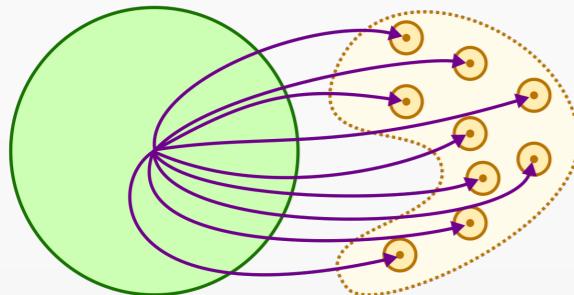
[Esmaeli, Wu, Jain, Bozkurt, Siddharth, Paige, Brooks, Dy, van de Meent, Arxiv 2018]

# Relaxing Constraints in the Objective

$$\mathcal{L}(\theta, \phi) = \mathbb{E}_{q_\phi(z|x)} \left[ \underbrace{\log \frac{p_\theta(z|x)}{p(z)}}_{\textcircled{1}} - \underbrace{\log \frac{q_\phi(z|x)}{q_\phi(z)}}_{\textcircled{2}} \right] - \underbrace{\text{KL}(q(x) \| p_\theta(x))}_{\textcircled{3}} - \underbrace{\text{KL}(q_\phi(z) \| p(z))}_{\textcircled{4}}$$

# Relaxing Constraints in the Objective

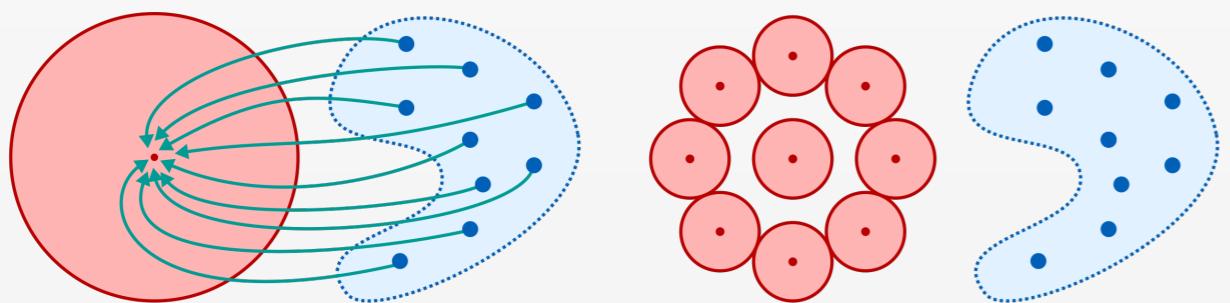
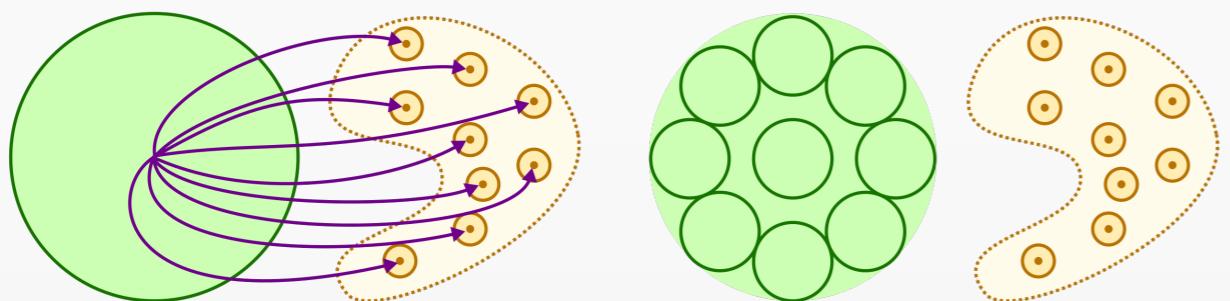
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② + ③ + ④

# Relaxing Constraints in the Objective

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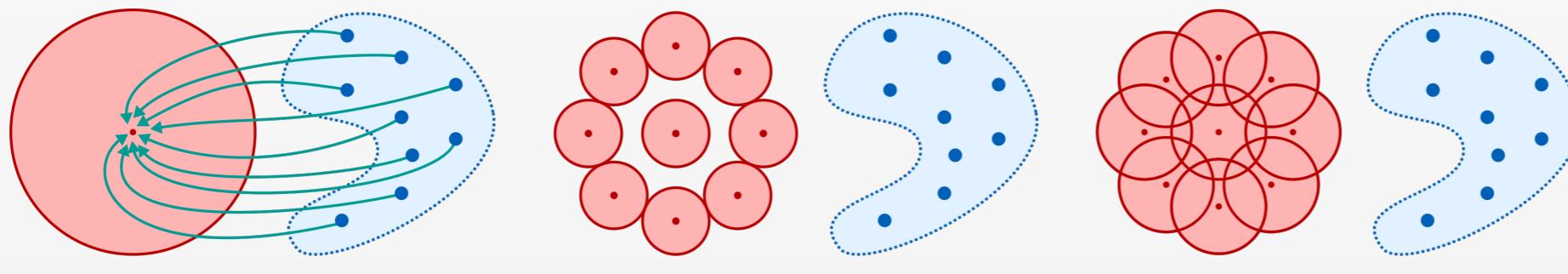
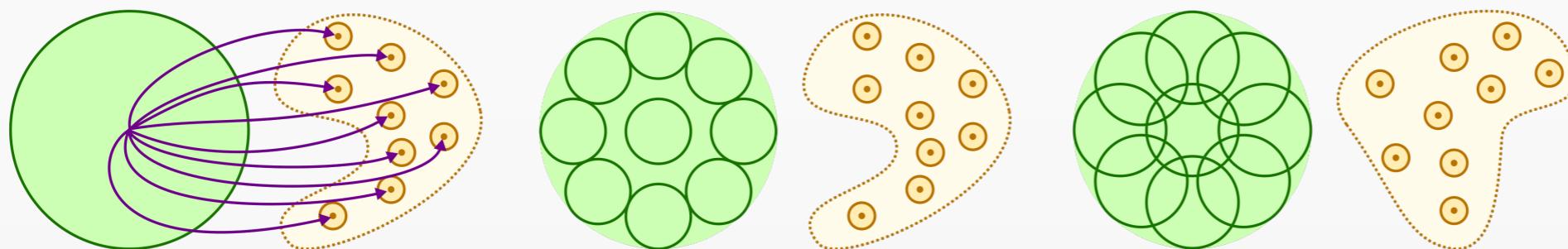


$\textcircled{2} + \textcircled{3} + \textcircled{4}$

$\textcircled{1} + \textcircled{3} + \textcircled{4}$

# Relaxing Constraints in the Objective

$$\mathcal{L}(\theta, \phi) = \mathbb{E}_{q_\phi(z|x)} \left[ \underbrace{\log \frac{p_\theta(z|x)}{p(z)}}_{\textcircled{1}} - \underbrace{\log \frac{q_\phi(z|x)}{q_\phi(z)}}_{\textcircled{2}} \right] - \underbrace{\text{KL}(q(x) \| p_\theta(x))}_{\textcircled{3}} - \underbrace{\text{KL}(q_\phi(z) \| p(z))}_{\textcircled{4}}$$



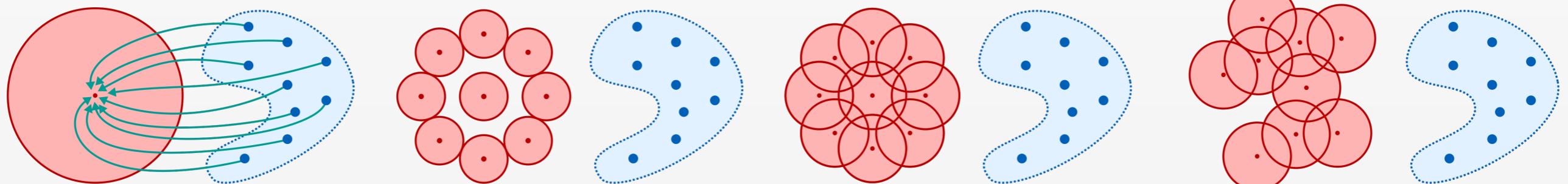
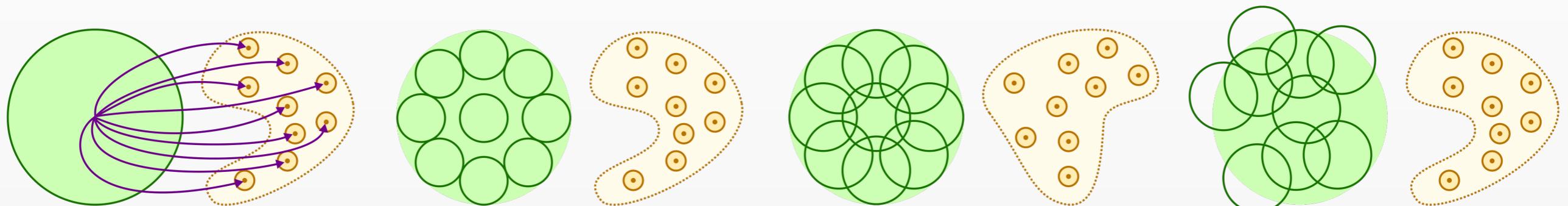
$\textcircled{2} + \textcircled{3} + \textcircled{4}$

$\textcircled{1} + \textcircled{3} + \textcircled{4}$

$\textcircled{1} + \textcircled{2} + \textcircled{4}$

# Relaxing Constraints in the Objective

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$\textcircled{2} + \textcircled{3} + \textcircled{4}$

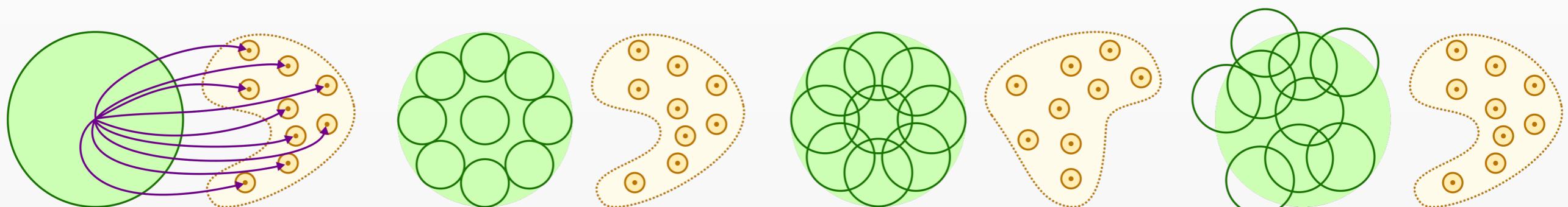
$\textcircled{1} + \textcircled{3} + \textcircled{4}$

$\textcircled{1} + \textcircled{2} + \textcircled{4}$

$\textcircled{1} + \textcircled{2} + \textcircled{3}$

# Relaxing Constraints in the Objective

$$\mathcal{L}(\theta, \phi) = \mathbb{E}_{q_\phi(z|x)} \left[ \underbrace{\log \frac{p_\theta(z|x)}{p(z)}}_{\textcircled{1}} - \underbrace{\log \frac{q_\phi(z|x)}{q_\phi(z)}}_{\textcircled{2}} \right] - \underbrace{\text{KL}(q(x) \| p_\theta(x))}_{\textcircled{3}} - \underbrace{\text{KL}(q_\phi(z) \| p(z))}_{\textcircled{4}}$$



② + ③ + ④

① + ③ + ④

① + ② + ④

① + ② + ③

Idea: Relax ①, ②, and ③ in favor of ④

# Hierarchical Decomposition

$$-\text{KL}(q_\phi(\mathbf{z}) \parallel p(\mathbf{z})) = -\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} + \log \frac{\prod_d q_\phi(\mathbf{z}_d)}{\prod_d p(\mathbf{z}_d)} + \log \frac{\prod_d p(\mathbf{z}_d)}{p(\mathbf{z})} \right]$$

# Hierarchical Decomposition

$$\begin{aligned} -\text{KL}(q_\phi(\mathbf{z}) \parallel p(\mathbf{z})) &= -\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} + \log \frac{\prod_d q_\phi(\mathbf{z}_d)}{\prod_d p(\mathbf{z}_d)} + \log \frac{\prod_d p(\mathbf{z}_d)}{p(\mathbf{z})} \right] \\ &= \underbrace{\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{p(\mathbf{z})}{\prod_d p(\mathbf{z}_d)} - \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} \right]}_{\textcircled{A}} - \underbrace{\sum_d \text{KL}(q_\phi(\mathbf{z}_d) \parallel p(\mathbf{z}_d))}_{\textcircled{B}}. \end{aligned}$$

# Hierarchical Decomposition

$$\begin{aligned} -\text{KL}(q_\phi(\mathbf{z}) \parallel p(\mathbf{z})) &= -\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} + \log \frac{\prod_d q_\phi(\mathbf{z}_d)}{\prod_d p(\mathbf{z}_d)} + \log \frac{\prod_d p(\mathbf{z}_d)}{p(\mathbf{z})} \right] \\ &= \underbrace{\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{p(\mathbf{z})}{\prod_d p(\mathbf{z}_d)} - \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} \right]}_{\textcircled{A}} - \underbrace{\sum_d \text{KL}(q_\phi(\mathbf{z}_d) \parallel p(\mathbf{z}_d))}_{\textcircled{B}}. \end{aligned}$$

Marginals should  
be identical

# Hierarchical Decomposition

$$\begin{aligned} -\text{KL}(q_\phi(\mathbf{z}) \parallel p(\mathbf{z})) &= -\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} + \log \frac{\prod_d q_\phi(\mathbf{z}_d)}{\prod_d p(\mathbf{z}_d)} + \log \frac{\prod_d p(\mathbf{z}_d)}{p(\mathbf{z})} \right] \\ &= \underbrace{\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{p(\mathbf{z})}{\prod_d p(\mathbf{z}_d)} - \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} \right]}_{\textcircled{A}} - \underbrace{\sum_d \text{KL}(q_\phi(\mathbf{z}_d) \parallel p(\mathbf{z}_d))}_{\textcircled{B}}. \end{aligned}$$

Correlations between variables  
should be identical      Marginals should  
be identical

# Hierarchical Decomposition

$$\begin{aligned} -\text{KL}(q_\phi(\mathbf{z}) \parallel p(\mathbf{z})) &= -\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} + \log \frac{\prod_d q_\phi(\mathbf{z}_d)}{\prod_d p(\mathbf{z}_d)} + \log \frac{\prod_d p(\mathbf{z}_d)}{p(\mathbf{z})} \right] \\ &= \underbrace{\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{p(\mathbf{z})}{\prod_d p(\mathbf{z}_d)} - \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} \right]}_{\textcircled{A}} - \underbrace{\sum_d \text{KL}(q_\phi(\mathbf{z}_d) \parallel p(\mathbf{z}_d))}_{\textcircled{B}}. \end{aligned}$$

Correlations between variables  
should be identical      Marginals should  
be identical

Disentanglement:  $p(\mathbf{z}) = \prod_d p(\mathbf{z}_d)$     $q_\phi(\mathbf{z}) = \prod_d q_\phi(\mathbf{z}_d)$

# Hierarchical Decomposition

$$\begin{aligned}
 -\text{KL}(q_\phi(\mathbf{z}) \parallel p(\mathbf{z})) &= -\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} + \log \frac{\prod_d q_\phi(\mathbf{z}_d)}{\prod_d p(\mathbf{z}_d)} + \log \frac{\prod_d p(\mathbf{z}_d)}{p(\mathbf{z})} \right] \\
 &= \underbrace{\mathbb{E}_{q_\phi(\mathbf{z})} \left[ \log \frac{p(\mathbf{z})}{\prod_d p(\mathbf{z}_d)} - \log \frac{q_\phi(\mathbf{z})}{\prod_d q_\phi(\mathbf{z}_d)} \right]}_{\textcircled{A}} - \underbrace{\sum_d \text{KL}(q_\phi(\mathbf{z}_d) \parallel p(\mathbf{z}_d))}_{\textcircled{B}}. \\
 &\quad \text{Correlations between variables} \quad \text{Marginals should} \\
 &\quad \text{should be identical} \quad \text{be identical}
 \end{aligned}$$

**Disentanglement:**  $p(\mathbf{z}) = \prod_d p(\mathbf{z}_d)$   $q_\phi(\mathbf{z}) = \prod_d q_\phi(\mathbf{z}_d)$

$$\textcircled{B} = \mathbb{E}_{q_\phi(\mathbf{z}_d)} \underbrace{\left[ \log \frac{p(\mathbf{z}_d)}{\prod_e p(\mathbf{z}_{d,e})} - \log \frac{q_\phi(\mathbf{z}_d)}{\prod_e q_\phi(\mathbf{z}_{d,e})} \right]}_{\textcircled{i}} - \underbrace{\sum_e \text{KL}(q_\phi(\mathbf{z}_{d,e}) \parallel p(\mathbf{z}_{d,e}))}_{\textcircled{ii}}$$

(Can continue decomposition for any number of levels)

# Generalizations of VAE objectives

Hierarchically Factorized Variational Autoencoders

$$\mathcal{L}(\theta, \phi) = \textcircled{1} + \textcircled{3} + \textcircled{ii} + \alpha \textcircled{2} + \beta \textcircled{A} + \gamma \textcircled{i}$$

# Generalizations of VAE objectives

## Hierarchically Factorized Variational Autoencoders

$$\mathcal{L}(\theta, \phi) = \textcircled{1} + \textcircled{3} + \textcircled{ii} + \alpha \textcircled{2} + \beta \textcircled{A} + \gamma \textcircled{i}$$

Paper	Objective
Kingma and Welling [2013], Rezende et al. [2014]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{4}$
Higgins et al. [2016]	$\textcircled{1} + \textcircled{3} + \beta (\textcircled{2} + \textcircled{4})$
Kumar et al. [2017]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \lambda \textcircled{4}$
Zhao et al. [2017]	$\textcircled{1} + \textcircled{3} + \lambda \textcircled{4}$
Gao et al. [2018]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{4} - \lambda \textcircled{2}^a$
Achille and Soatto [2018]	$\textcircled{1} + \textcircled{3} + \beta \textcircled{2} + \gamma \textcircled{A}^*$
Kim and Mnih [2018], Chen et al. [2018]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{B} + \beta \textcircled{A}^*$
HFVAE (this paper)	$\textcircled{1} + \textcircled{3} + \textcircled{ii} + \alpha \textcircled{2} + \beta \textcircled{A} + \gamma \textcircled{i}$

# Generalizations of VAE objectives

## Hierarchically Factorized Variational Autoencoders

$$\mathcal{L}(\theta, \phi) = \textcircled{1} + \textcircled{3} + \textcircled{ii} + \alpha \textcircled{2} + \beta \textcircled{A} + \gamma \textcircled{i}$$

Paper	Objective
Kingma and Welling [2013], Rezende et al. [2014]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{4}$
Higgins et al. [2016]	$\textcircled{1} + \textcircled{3} + \beta (\textcircled{2} + \textcircled{4})$
Kumar et al. [2017]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \lambda \textcircled{4}$
Zhao et al. [2017]	$\textcircled{1} + \textcircled{3} + \lambda \textcircled{4}$
Gao et al. [2018]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{4} - \lambda \textcircled{2}^a$
Achille and Soatto [2018]	$\textcircled{1} + \textcircled{3} + \beta \textcircled{2} + \gamma \textcircled{A}^*$
Kim and Mnih [2018], Chen et al. [2018]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{B} + \beta \textcircled{A}^*$
HFVAE (this paper)	$\textcircled{1} + \textcircled{3} + \textcircled{ii} + \alpha \textcircled{2} + \beta \textcircled{A} + \gamma \textcircled{i}$

# Generalizations of VAE objectives

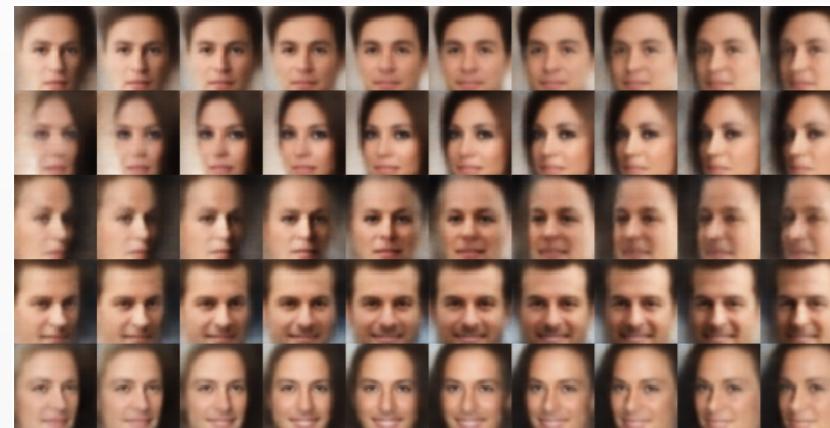
## Hierarchically Factorized Variational Autoencoders

$$\mathcal{L}(\theta, \phi) = \textcircled{1} + \textcircled{3} + \textcircled{ii} + \alpha \textcircled{2} + \beta \textcircled{A} + \gamma \textcircled{i}$$

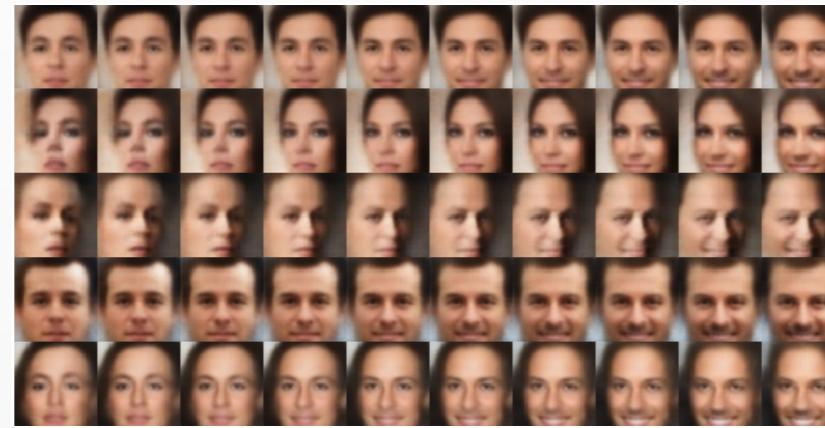
Paper	Objective
Kingma and Welling [2013], Rezende et al. [2014]	$\textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{4}$
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Zhao et al. [2017]	$\textcircled{1} + \textcircled{3} + \lambda \textcircled{4}$
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HFVAE (this paper)	$\textcircled{1} + \textcircled{3} + \textcircled{ii} + \alpha \textcircled{2} + \beta \textcircled{A} + \gamma \textcircled{i}$

# Results: CelebA

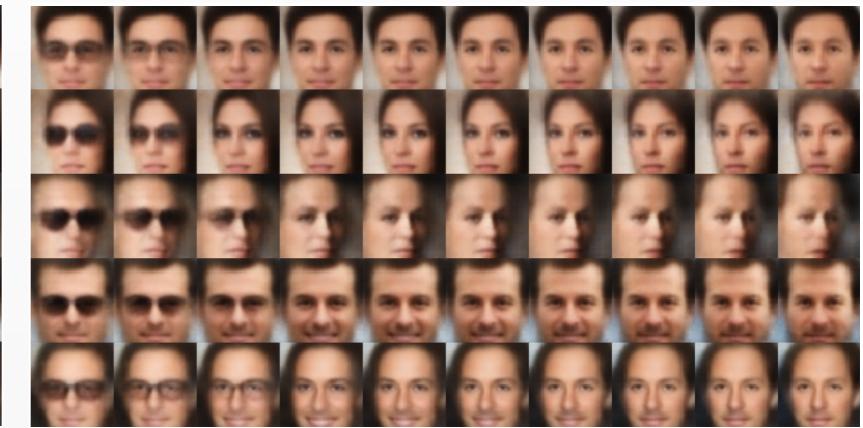
Orientation



Smiling

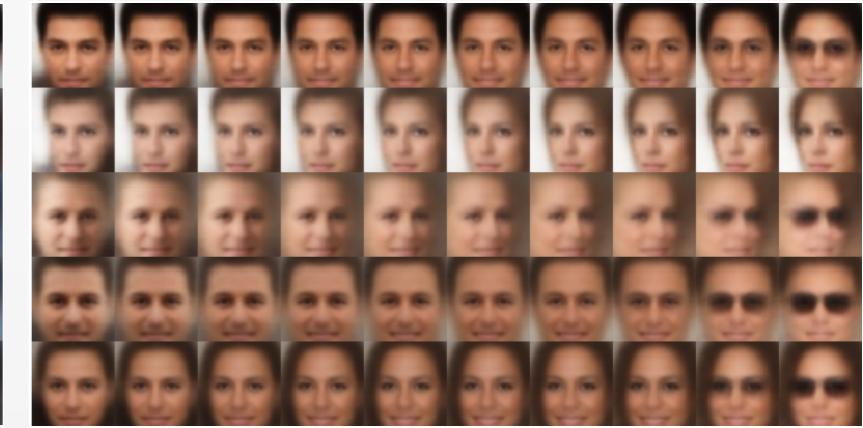
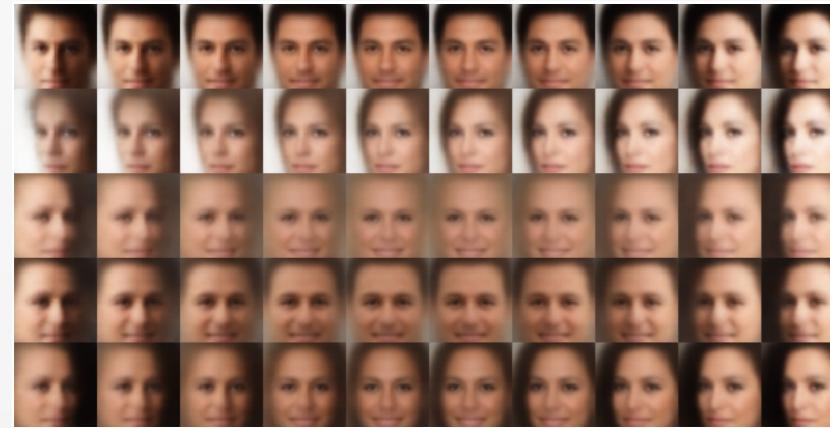


Sunglasses



HFVAE

$\beta$ -VAE



HFVAE and  $\beta$ -VAE are qualitatively similar

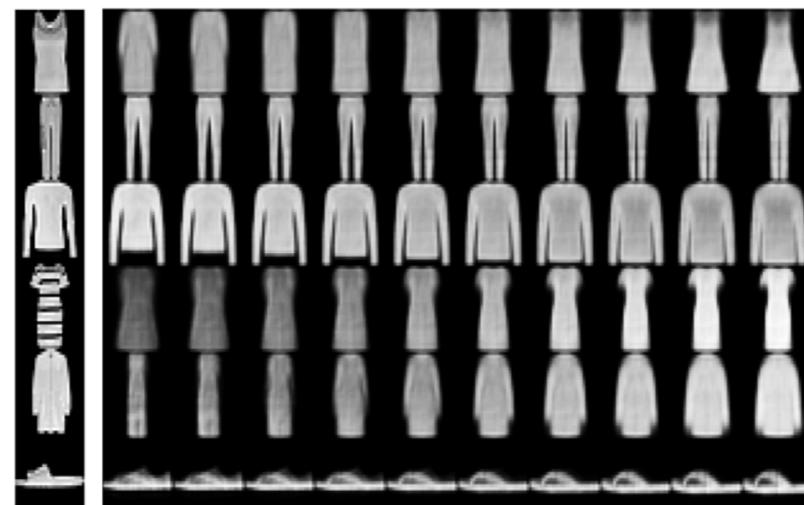
Both objectives learn (some) interpretable features

# Results: MNIST and FMNIST

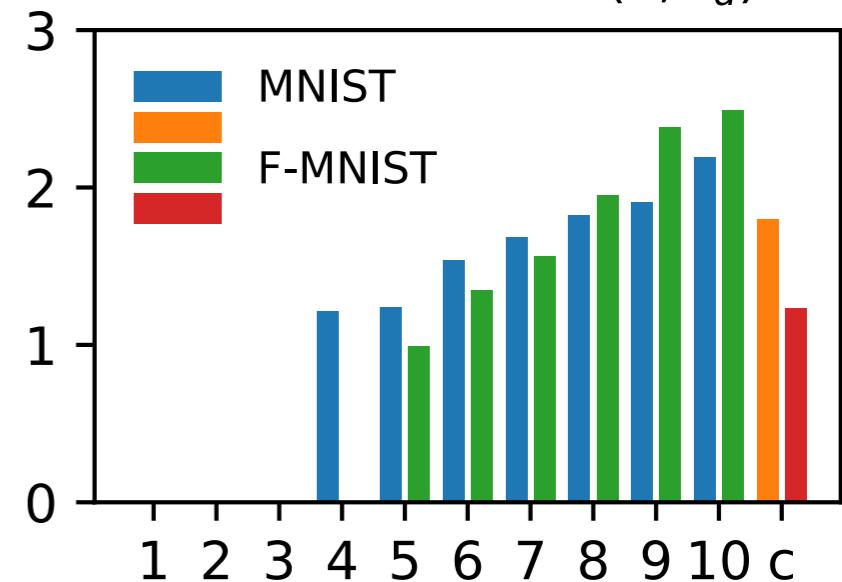
MNIST HFVAE ( $\beta=12, \gamma=4$ )



FMNIST HFVAE ( $\beta=12, \gamma=4$ )

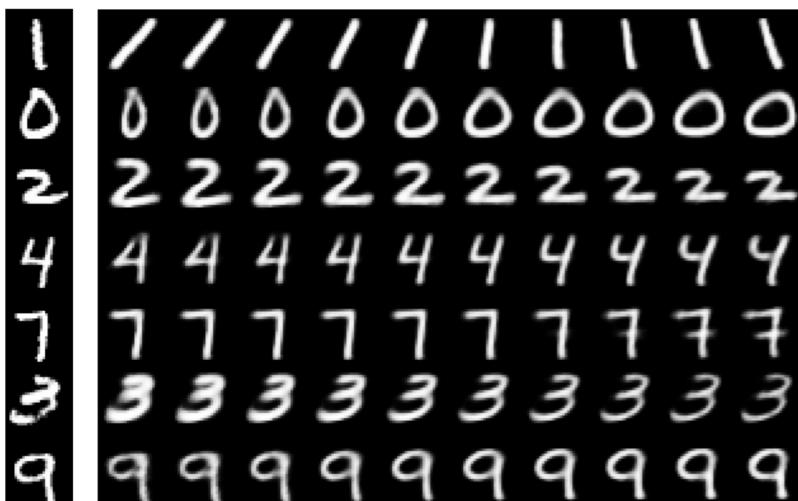


MNIST F-MNIST  $I(x; z_d)$

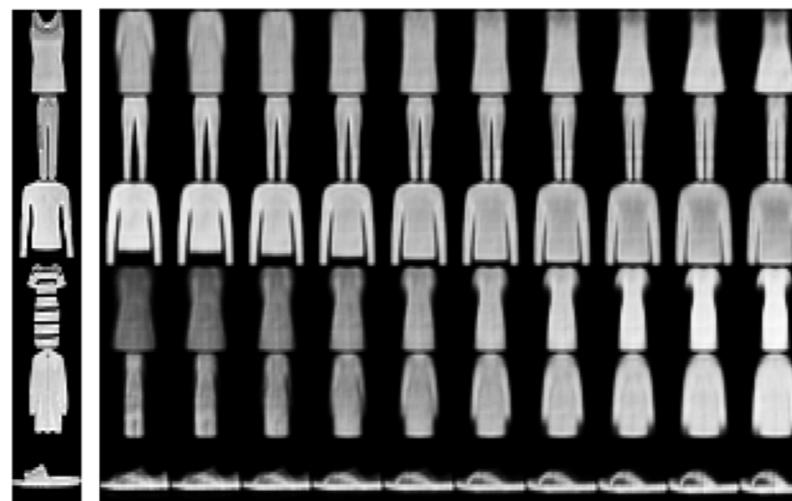


# Results: MNIST and FMNIST

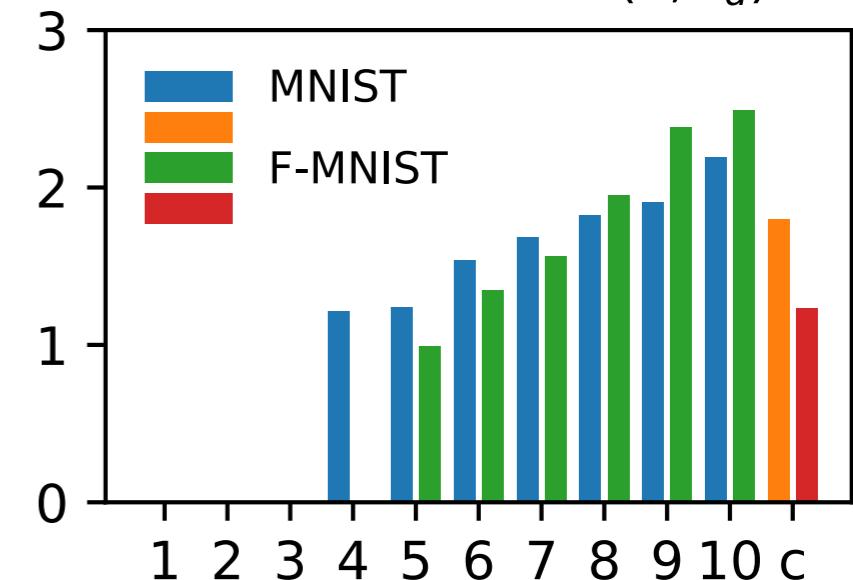
MNIST HFVAE ( $\beta=12, \gamma=4$ )



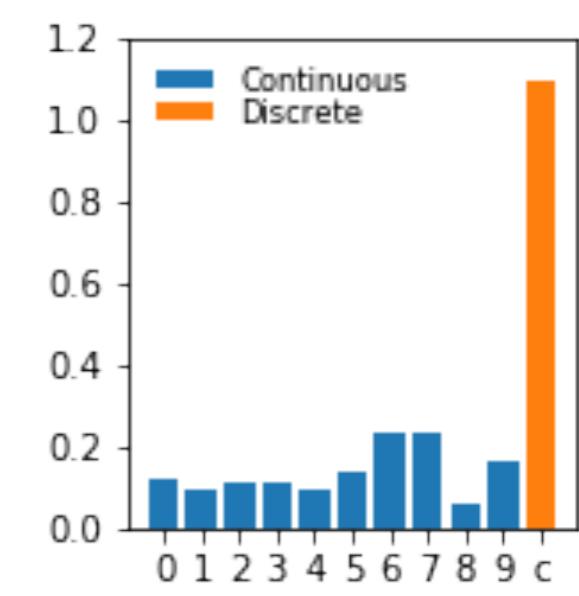
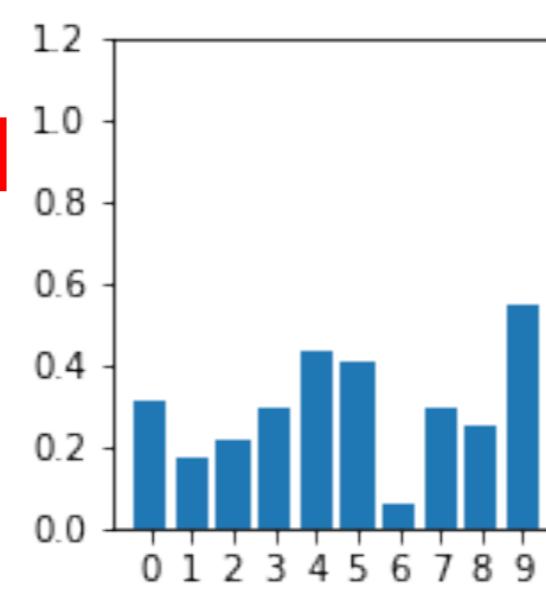
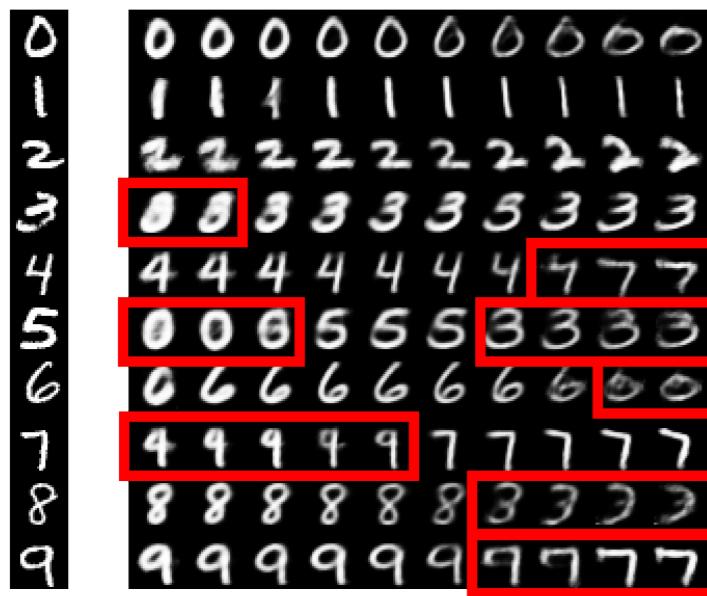
FMNIST HFVAE ( $\beta=12, \gamma=4$ )



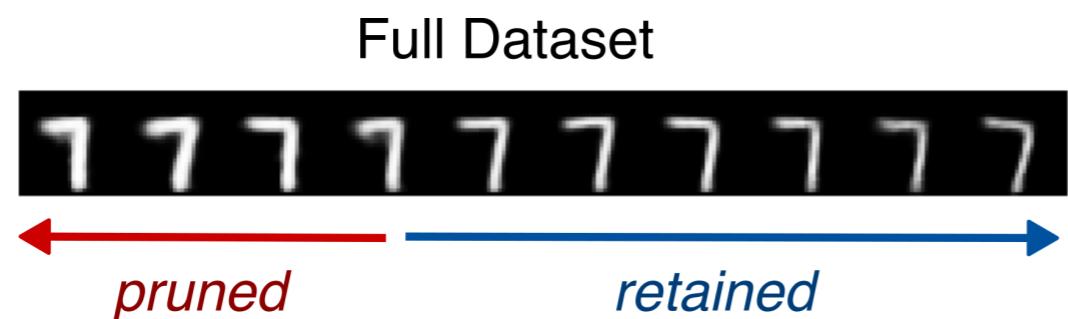
MNIST F-MNIST  $I(x; z_d)$



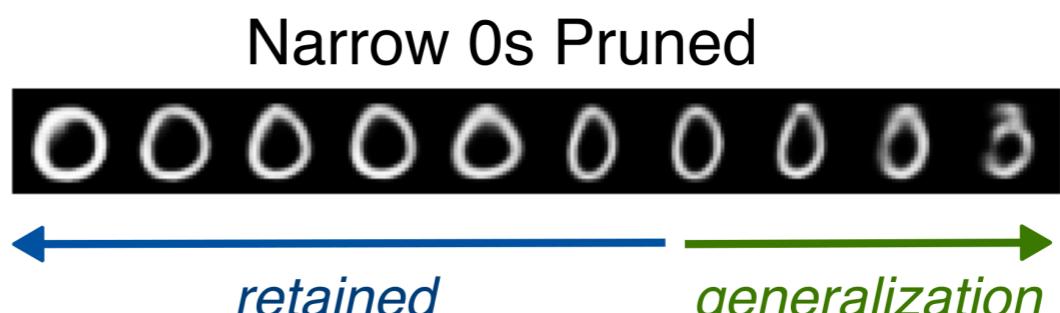
Input	$\beta$ -VAE ( $\beta = 4$ )	HFVAE ( $\beta = 12, \gamma = 4$ )	$I(y; z)$ ( $\beta$ -VAE, $\beta = 4$ )	$I(y; z)$ (HFVAE, $\beta = 12, \gamma = 4$ )
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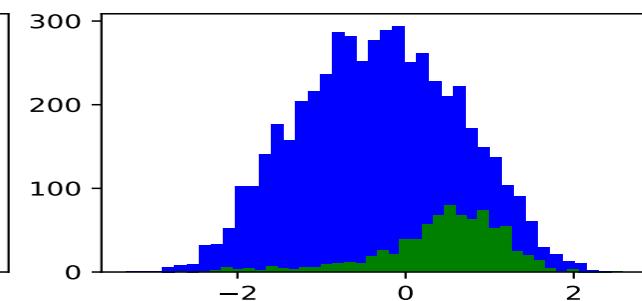
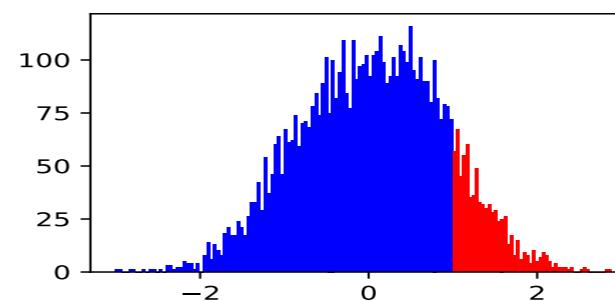
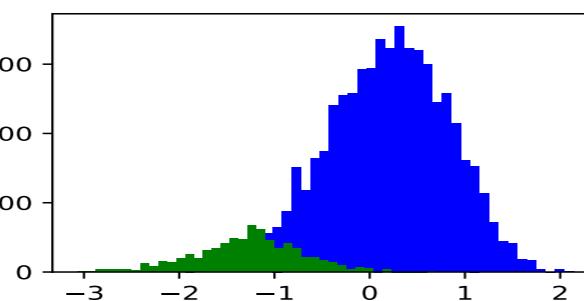
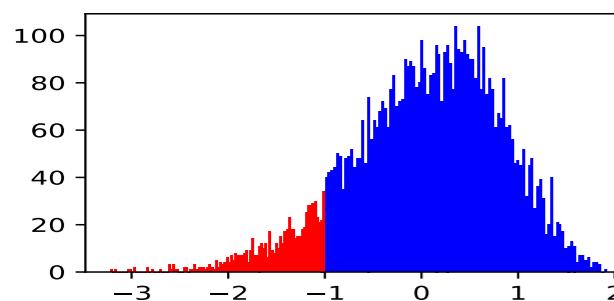
# Results: Generalization



Pruning      Generalization

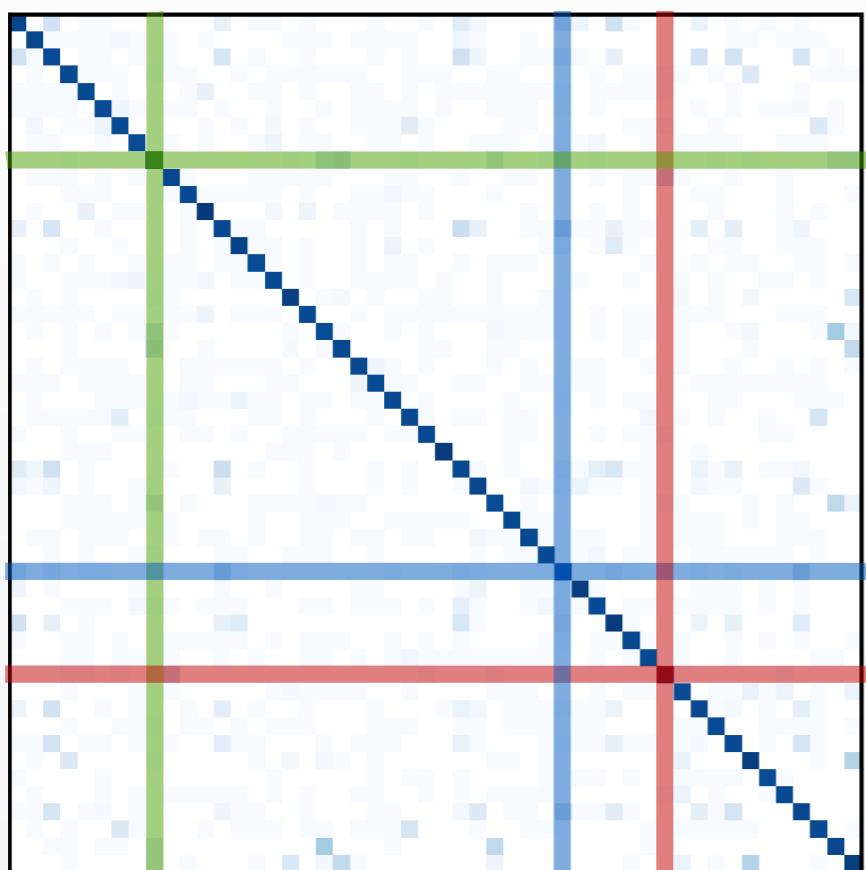


Pruning      Generalization

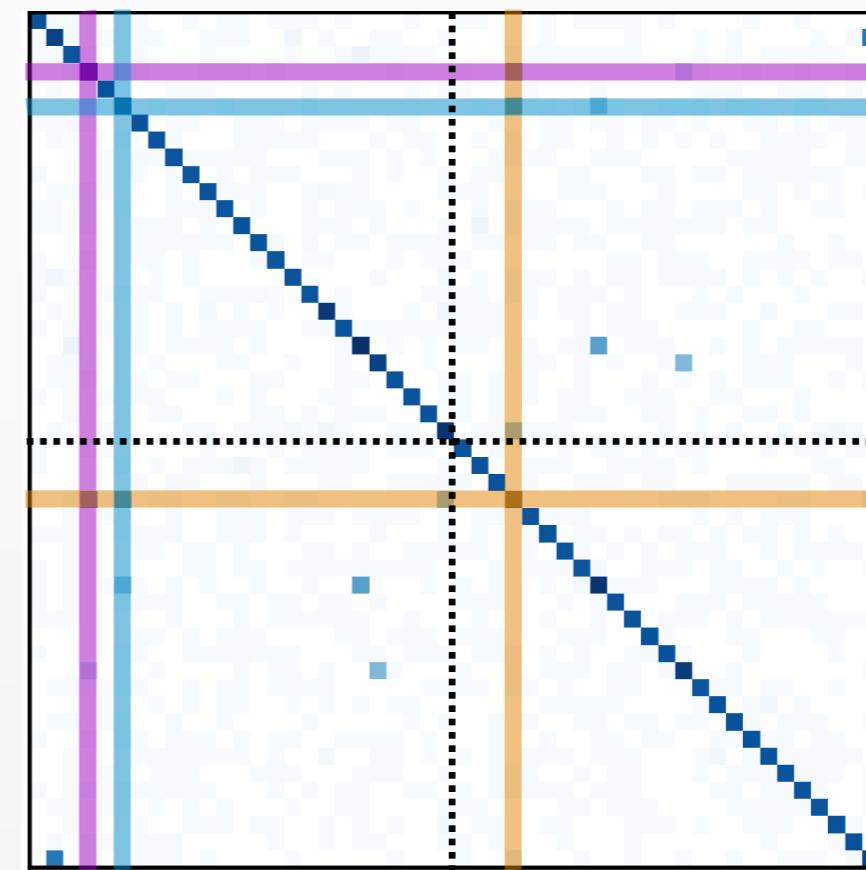


# Bonus: Learning Correlations Between Topics

VAE (50 topics)



HFVAE (25 + 25 topics)



## Top Words

jesus, scripture, god, christ, bible,  
sin, christian, doctrine, faith, church

team, game, player, score, league,  
play, leafs, hockey, season, nhl

scsi, ide, controller, drive, bus, subject,  
lines, organization, card, problem

## NPMI

0.41

0.37

0.14

## Top 3 Most Correlated Topics

armenian, turk, civilian, turkish, soldier,  
kill, extermination, armenia, israel, jew

jesus, belief, god, christian, christ,  
faith, scripture, moral, truth, sin

gun, crime, people, law, defense,  
government, criminal, shoot, assault, fire

## NPMI

0.40

0.35

0.26

# Deep Learning + Probabilistic Programming

Deep  
Learning

Probabilistic  
Programming

# Deep Learning + Probabilistic Programming

Deep  
Learning

Discriminative  
(Data → Features)

Probabilistic  
Programming

Generative  
(Variables → Data)

# Deep Learning + Probabilistic Programming

Deep  
Learning

Discriminative  
(Data → Features)

Large Data,  
Low Uncertainty

Probabilistic  
Programming

Generative  
(Variables → Data)

Small Data,  
High Uncertainty

# Deep Learning + Probabilistic Programming

Deep  
Learning

Discriminative  
(Data → Features)

Large Data,  
Low Uncertainty

Stochastic Gradient  
Descent

Probabilistic  
Programming

Generative  
(Variables → Data)

Small Data,  
High Uncertainty

Many Inference  
Methods

# Deep Learning + Probabilistic Programming

Deep  
Learning

Discriminative  
(Data → Features)

Large Data,  
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Stochastic Gradient  
Descent

Representation  
Learning

Probabilistic  
Programming

Generative  
(Variables → Data)

Small Data,  
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Many Inference  
Methods

Model-based  
Reasoning

# Deep Learning + Probabilistic Programming

## Deep Learning

Discriminative  
(Data → Features)

Large Data,  
Low Uncertainty

Stochastic Gradient  
Descent

Representation  
Learning

## Integrated Approaches

## Probabilistic Programming

Generative  
(Variables → Data)

Small Data,  
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Methods

Model-based  
Reasoning

# Deep Learning + Probabilistic Programming

## Deep Learning

Discriminative  
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Stochastic Gradient  
Descent

Representation  
Learning

## Integrated Approaches

Decision Making

## Probabilistic Programming

Generative  
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# Deep Learning + Probabilistic Programming

## Deep Learning

Discriminative  
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Stochastic Gradient  
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Representation  
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## Integrated Approaches

Autoencoders

Decision Making

## Probabilistic Programming

Generative  
(Variables → Data)

Small Data,  
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# Deep Learning + Probabilistic Programming

## Deep Learning

Discriminative  
(Data → Features)

Large Data,  
Low Uncertainty

Stochastic Gradient  
Descent

Representation  
Learning

## Integrated Approaches

Autoencoders

Decision Making

Variational  
Inference

## Probabilistic Programming

Generative  
(Variables → Data)

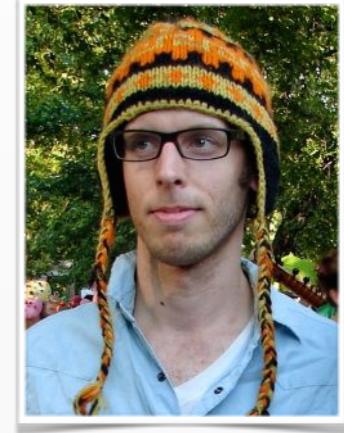
Small Data,  
High Uncertainty

Many Inference  
Methods

Model-based  
Reasoning

# Thank You!

Northeastern University



Babak Esmaeli

Hao Wu

Sarthak Jain

Alican Bozkurt

Siddharth N.

Brooks Paige

## Papers

### *Structured Disentangled Representations*

B. Esmaeli, H. Wu, S. Jain, A. Bozkurt, N. Siddharth, B. Paige, D. H. Brooks, J. Dy, J.-W. van de Meent  
ArXiv [<https://arxiv.org/abs/1804.02086>]

### *Learning disentangled representations with semi-supervised deep generative models*

N. Siddharth, B. Paige, J.-W. van de Meent, A. Desmaison, F. Wood, N.D. Goodman, P. Kohli, P.H.S. Torr  
NIPS 2017 [<https://bit.ly/probtorch-nips-2017>]

## Code

<https://github.com/probtorch/probtorch>