### M2R Oral Presentation

# Manifolds and homogeneous spaces (M2R2)

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### Outline

- Brief definitions
  - Group actions on sets
  - Homeomorphism
  - Charts and atlases
  - Paracompactness
- Manifolds
  - Topological Manifolds
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 $S^n \subset \mathbb{R}^{n+1}$  is defined as the set:  $\{x \in \mathbb{R}^{n+1} : \|x\| = 1\}$ , and can also be called the **n-sphere**.



There are 9 transitive actions on a n-sphere...

There are 9 transitive actions on a *n*-sphere...

Group	SO(n)	U(n), SU(n)	Sp(n)Sp(1),
			Sp(n)U(1),
			Sp(n)
Sphere	S <sup>n-1</sup>	$S^{2n-1}$	S <sup>4n-1</sup>

$G_2$	Spin(7)	Spin(9)
S <sup>6</sup>	S <sup>7</sup>	S <sup>15</sup>

# Homeomorphism

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A **diffeomorphism** is a smooth homeomorphism whose inverse is also smooth.

### Charts and atlases

#### Definition

A **chart**  $(U,\varphi)$  for a topological space X is a homeomorphism  $\varphi$  from an open U is a subset of X to an open subset  $\tilde{U}$  contained in  $\mathbb{R}$ , that is  $\varphi:U\to \tilde{U}$ .

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An **atlas** for a topological space X is the collection of charts for X which covers X.

# Example

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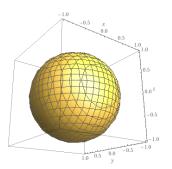


Figure: An atlas of the 2-sphere

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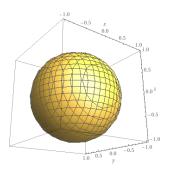


Figure: An atlas of the 2-sphere

$$\varphi_{\mathit{front}}\big(x,y,z\big) = \big(x,z\big), \ \ \varphi_{\mathit{left}}\big(x,y,z\big) = \big(y,z\big), \ \ \varphi_{\mathit{top}}\big(x,y,z\big) = \big(x,y\big)...$$

### Definition

A topological space X is **paracompact** if every open cover of X has a locally finite open refinement.

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For a cover  $C = \{U_{\alpha} : \alpha \in A\}$  of a topological space X, a **refinement**  $D = \{V_{\beta} : \beta \in B\}$  of the cover C is a subcover such that for all  $V_{\beta}$  in D, exists  $U_{\alpha}$  in C such that  $V_{\beta} \subseteq U_{\alpha}$ .

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An open cover C of X is called **locally finite** if for all x in X, exists B(x) in X where B(x) is a neighbourhood of x such that B(x) intersects a finite number of subsets of C.

### Proposition

Every compact space is paracompact.

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However, the Euclidean space  $\mathbb{R}^n$  is paracompact but not compact!

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Recall definition of charts. Every point in locally Euclidean space is contained in some charts.



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- Second countable: M has a countable basis, which means there exists a countable collection B of open subsets of M such that for any open subset U of M and point p in U, there is an open set B ∈ B such that p ∈ B ⊂ U.
- **Solution Locally Euclidean**: For every point  $p \in M$ , there exists a neighbourhood N of p such that N is homeomorphic to an open subset of .

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#### Proposition

Subspace of Hausdorff and second-countable space is also Hausdorff and second-countable.

Another example is the **unit n-sphere**  $S^n = \{x \in \mathbb{R}^{n+1} : |x| = 1\}.$ 

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$$S^n = \{x \in \mathbb{R}^{n+1} : |x| = 1\}.$$
  
Let  $U_i = \{(x_1, x_{n+1}) \in S^n : x_i > 0\}$  and  $V_i = \{(x_1, x_{n+1}) \in S^n : x_i < 0\}$ 

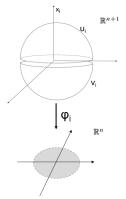


Figure: projection of charts of n-sphere

## Transition map

#### Definition

For two charts  $(U,\varphi)$  and  $(V,\psi)$  in a topological manifold, we say if U and V are not disjoint then the composition map  $\varphi \circ \psi^{-1} : \psi(U \cap V) \to \varphi(U \cap V)$ , or  $\psi \circ \varphi^{-1} : \varphi(U \cap V) \mapsto \psi(U \cap V)$  defined on the intersection of U and V is a **transition map**.

## Transition map

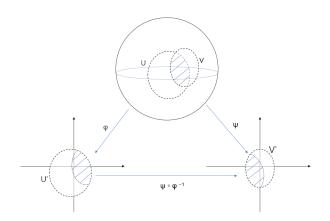


Figure: transition map

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#### Definition

An atlas is a **smooth atlas** if every chart of it is smoothly compatible with each other.

### Smooth manifolds

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Examples:  $\mathbb{R}^n$ , n-sphere, $\mathsf{GL}_n(\mathbb{R})$ ,...

### Intuition

What are Lie groups?

## Lie Groups

#### Definition

A Lie group is a group G that is also a smooth manifold and the map  $G \to G$ ,  $(g,h) \mapsto gh^{-1}$ , with  $g,h \in G$  is smooth.

## Lie Groups

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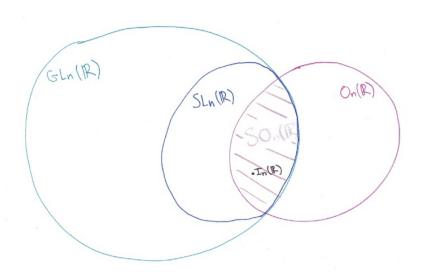
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Result from Analysis 2: the composition of smooth maps is itself a smooth map

### Some results:

We have a few results already

- $GL_n(\mathbb{R})$  is a smooth manifold
- The determinant map:  $\det : GL_n(\mathbb{R}) \to \mathbb{R}$  is a smooth map
- Taking the inverse of a matrix is a smooth map
- Matrix multiplication is a smooth map
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- The preimage of a continuous function on a closed set is also a closed set

#### E. Cartan Closed subgroup Theorem

Any closed subgroup H of a Lie group G is a Lie subgroup and hence a submanifold of G.



- Matrix multiplication, taking the inverse is smooth
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- Apply E. Cartan's Closed subgroup theorem
- **SL**<sub>n</sub>( $\mathbb{R}$ ) is a Lie subgroup and submanifold of  $GL_n(\mathbb{R})$
- Matrix multiplication and taking inverse are smooth maps in  $SL_n(\mathbb{R}) \Longrightarrow SL_n(\mathbb{R})$  is also a smooth manifold

#### Definition: $O_n(\mathbb{R})$

 $O_n(\mathbb{R})$  is the set of all matrices, that, when multiplied by their own inverse, give the identity matrix

#### Definition: $SO_n(\mathbb{R})$

 $SO_n(\mathbb{R})$  is the set of all  $n \times n$  invertible matrices with det = 1 and the inverse of each matrix is itself.

#### Example: $SO_n(\mathbb{R})$

- $\bigcirc$  SO<sub>n</sub>( $\mathbb{R}$ ) is a subgroup of SL<sub>n</sub>( $\mathbb{R}$ )
- $O: SL_n(\mathbb{R}) \to SL_n(\mathbb{R}), \ O(A) = AA^{\top}$  also acts on  $SO_n(\mathbb{R})$  (as determinant 1 is preserved),
- $SO_n(\mathbb{R}) = O^{-1}(\{I_n\})$ . As  $\{I_n\}$  is closed in  $SL_n(\mathbb{R})$ , the preimage  $SO_n(\mathbb{R})$  is also (topologically) closed
- Apply E. Cartan's Closed subgroup theorem
- **SO**<sub>n</sub>( $\mathbb{R}$ ) is a Lie subgroup and submanifold of  $SL_n(\mathbb{R})$
- Matrix multiplication and taking inverse are smooth maps in  $SO_n(\mathbb{R}) \Longrightarrow SO_n(\mathbb{R})$  is also a smooth manifold



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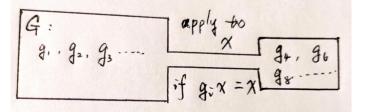
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The main result here is the special linear group SO(n) is the isotropy group of SO(n+1).



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An example of homogeneous space would be  $S^n$ 

Proof is straight-forward using results from previous slides, but note that it's slightly different from the definition, the ingredients we need:

- 1. Lie group action acts transitively on G.
- 2.  $S^n$  is a smooth manifold.

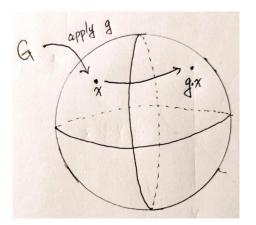


Figure: Homogeneous space

First, definition of a fiber bundle:

#### Definition

For E (total space), B (base fiber), F (fiber) topological spaces and a continuous map  $\pi: E \to B$  form a **fiber bundle with fiber F** if:

- B is a connected topological space.
- **②** The natural projection map  $\pi: E \to B$  is surjective.
- **②** Each element in the base fiber has an open neighbourhood contained within the base fiber. That is for all  $x \in B$ , ∃ open neighbourhood  $U_x ⊂ B$ , there exists a homeomorphism  $\varphi : \pi^{-1}(U_x) \to U_x \times F$ , that is a topological isomorphism.

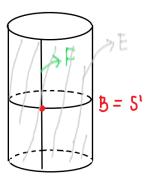


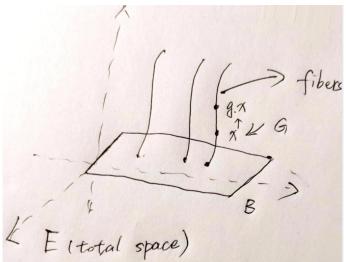
Figure: Fiber bundle

Principal bundle is the special case of fiber bundle, and here's the definition of principal bundles:

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#### Definition

**Principal bundles**: A principal G-bundle with a topological space G, is a fiber bundle  $\pi: E \to B$ , together with a continuous right action  $\omega: E \times G \to E$ , and that  $\tilde{\pi}:= E \times G \xrightarrow{\mu} E \xrightarrow{\pi} B$  and  $E \times G \xrightarrow{\pi \times C} B \times \{e\} \xrightarrow{\sim} B$  commutes with the map C, a map from everything to identity. And given a point  $x \in B$ , G acts freely and transitively on the fiber  $F_x$ .



## **Applications**

- Take isotropy group to be a fiber
- $G/G_{iso} \times G_{iso}$

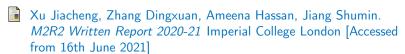
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- Connections and parallel transport across manifolds

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- Take isotropy group to be a fiber
- $G/G_{iso} \times G_{iso}$
- Connections and parallel transport across manifolds
- More applied areas, e.g. Mathematical gauge theory

### References



Andreas Cap. Geometry of homogeneous spaces [Lecture] University of Vienna. Spring 2019