

quectel\_bc66\_drv

Generated by Doxygen 1.9.1

<b>1 Data Structure Index</b>	<b>1</b>
<b>1 Data Structure Index</b>	<b>1</b>
1.1 Data Structures . . . . .	1
<b>2 File Index</b>	<b>2</b>
2.1 File List . . . . .	2
<b>3 Data Structure Documentation</b>	<b>2</b>
3.1 bc66_at_cmd_t Struct Reference . . . . .	2
3.1.1 Detailed Description . . . . .	2
3.1.2 Field Documentation . . . . .	2
3.2 bc66_ip_add_t Struct Reference . . . . .	3
3.2.1 Detailed Description . . . . .	3
3.2.2 Field Documentation . . . . .	3
3.3 bc66_obj_t Struct Reference . . . . .	4
3.3.1 Field Documentation . . . . .	4
<b>4 File Documentation</b>	<b>6</b>
4.1 /Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.c File Reference . . . . .	6
4.1.1 Detailed Description . . . . .	8
4.1.2 Macro Definition Documentation . . . . .	8
4.1.3 Enumeration Type Documentation . . . . .	9
4.1.4 Function Documentation . . . . .	9
4.1.5 Variable Documentation . . . . .	16
4.2 /Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.h File Reference . . . . .	16
4.2.1 Detailed Description . . . . .	18
4.2.2 Enumeration Type Documentation . . . . .	18
4.2.3 Function Documentation . . . . .	20
<b>Index</b>	<b>29</b>

# 1 Data Structure Index

## 1.1 Data Structures

Here are the data structures with brief descriptions:

<b>bc66_at_cmd_t</b> BC66 Command struct	<b>2</b>
<b>bc66_ip_add_t</b> Struct to store IP ADDRESS	<b>3</b>
<b>bc66_obj_t</b>	<b>4</b>

## 2 File Index

### 2.1 File List

Here is a list of all files with brief descriptions:

<code>/Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.c</code> MIT License	6
<code>/Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.h</code> MIT License	16

## 3 Data Structure Documentation

### 3.1 bc66\_at\_cmd\_t Struct Reference

BC66 Command struct.

#### Data Fields

- `const char * cmd`  
*at command sentence*
- `cmd_flg_t cmd_flags`  
*flags for command implementation (see*
- `char * cmd_rsp`  
*expected command response*
- `uint32_t rsp_timeout`  
*response timeout [ms]*

#### 3.1.1 Detailed Description

BC66 Command struct.

#### 3.1.2 Field Documentation

##### 3.1.2.1 `cmd` `const char* cmd`

at command sentence

### 3.1.2.2 cmd\_flags `cmd_flg_t` `cmd_flags`

flags for command implementation (see  
flags `enum`)

### 3.1.2.3 cmd\_rsp `char*` `cmd_rsp`

expected command response

### 3.1.2.4 rsp\_timeout `uint32_t` `rsp_timeout`

response timeout [ms]

The documentation for this struct was generated from the following file:

- `/Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.c`

## 3.2 bc66\_ip\_add\_t Struct Reference

Struct to store IP ADDRESS.

```
#include <bc66_drv.h>
```

### Data Fields

- `uint8_t` `a1`
- `uint8_t` `a2`
- `uint8_t` `a3`
- `uint8_t` `a4`

### 3.2.1 Detailed Description

Struct to store IP ADDRESS.

### 3.2.2 Field Documentation

#### 3.2.2.1 `a1` `uint8_t` `a1`

**3.2.2.2 a2** `uint8_t a2`

**3.2.2.3 a3** `uint8_t a3`

**3.2.2.4 a4** `uint8_t a4`

The documentation for this struct was generated from the following file:

- [/Users/jcbecerra/dev/fw/iot/quectel\\_bc66\\_driver/src/bc66\\_drv.h](/Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.h)

### 3.3 bc66\_obj\_t Struct Reference

```
#include <bc66_drv.h>
```

#### Data Fields

- `void(* func_init_ptr )()`  
*uart initialize function pointer*
- `void(* func_delay )(uint32_t t)`  
*delay function pointer*
- `int(* func_w_bytes_ptr )(uint8_t *txc, uint16_t len)`  
*write bytes function pointer*
- `int(* func_r_bytes_ptr )(uint8_t *rxc, uint16_t size)`  
*read one-byte function pointer*
- struct {
  - `void(* MDM_PSM_EINT_N )(size_t pin_value)`  
*Function pointer to interface: to handle PSM\_EINT pin.*
  - `void(* MDM_PWRKEY_N )(size_t pin_value)`  
*Function pointer to interface: to handle PWRKEY pin.*
  - `void(* MDM_RESET_N )(size_t pin_value)`  
*Function pointer to interface: to handle RESET pin.*
  - `void(* MDM_RI )()`  
*Function pointer to interface: to handle ring interrupt pin.*
- `control_lines`

#### 3.3.1 Field Documentation

**3.3.1.1** `struct { ... } control_lines`

**3.3.1.2 func\_delay** void(\* func\_delay) (uint32\_t t)

delay function pointer

**3.3.1.3 func\_init\_ptr** void(\* func\_init\_ptr) ()

uart initialize function pointer

**3.3.1.4 func\_r\_bytes\_ptr** int(\* func\_r\_bytes\_ptr) (uint8\_t \*rxc, uint16\_t size)

read one-byte function pointer

**3.3.1.5 func\_w\_bytes\_ptr** int(\* func\_w\_bytes\_ptr) (uint8\_t \*txc, uint16\_t len)

write bytes function pointer

**3.3.1.6 MDM\_PSM\_EINT\_N** void(\* MDM\_PSM\_EINT\_N) (size\_t pin\_value)

Function pointer to interface: to handle PSM\_EINT pin.

**3.3.1.7 MDM\_PWRKEY\_N** void(\* MDM\_PWRKEY\_N) (size\_t pin\_value)

Function pointer to interface: to handle PWRKEY pin.

**3.3.1.8 MDM\_RESET\_N** void(\* MDM\_RESET\_N) (size\_t pin\_value)

Function pointer to interface: to handle RESET pin.

**3.3.1.9 MDM\_RI** void(\* MDM\_RI) ()

Function pointer to interface: to handle ring interrupt pin.

The documentation for this struct was generated from the following file:

- /Users/jbecerra/dev/fw/iot/quectel\_bc66\_driver/src/[bc66\\_drv.h](#)

## 4 File Documentation

### 4.1 /Users/jcbecerra/dev/fw/iot/quectel\_bc66\_driver/src/bc66\_drv.c File Reference

MIT License.

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <stdarg.h>
#include "bc66_drv.h"
```

#### Data Structures

- struct `bc66_at_cmd_t`  
*BC66 Command struct.*

#### Macros

- #define `CMD_END_LINE` `"\r\n"`  
*End of line command chars.*
- #define `RSP_OK` `"\r\nOK\r\n"`  
*Ok response.*
- #define `RSP_ERROR` `"\r\nERROR\r\n"`  
*Error response.*
- #define `RSP_END_OF_LINE` `"\r\n"`  
*End of line response chars.*
- #define `RSP_TIMEOUT` `"BC66_TIMEOUT\r\n"`  
*Answer when a timeout is occurred.*
- #define `RSP_NO_CMD_IMPEMENTED` `"BC66_NO_CMD\r\n"`  
*The command is not implemented.*
- #define `MAX_RSP_SIZE` 64  
*Max AT response size.*

#### Enumerations

- enum `cmd_flg_t` { `TEST` = 0x1 , `READ` = 0x2 , `WRITE` = 0x4 , `EXE` = 0x8 }  
*Command possibilities indicator flags.*

## Functions

- [bc66\\_ret\\_t bc66\\_init \(bc66\\_obj\\_t \\*bc66\\_obj\)](#)  
*Function to initialize bc66 object.*
- [void bc66\\_deinit \(bc66\\_obj\\_t \\*bc66\\_obj\)](#)  
*Function to initialize bc66 object.*
- [bc66\\_ret\\_t bc66\\_send\\_at\\_command \(bc66\\_cmd\\_type\\_t cmd\\_type, const bc66\\_cmd\\_list\\_t cmd\\_lst, const char \\*exp\\_rsp, const char \\*arg\\_fmt,...\)](#)  
*Function to send at command sentence to bc66 module through an external function communication.*
- [char \\* bc66\\_get\\_at\\_response \(char \\*rsp\)](#)  
*Function to get any response stored in the RX buffer.*
- [bc66\\_ret\\_t bc66\\_hw\\_reset \(void\)](#)  
*Reset the module via Hardware PIN.*
- [void bc66\\_power\\_on \(\)](#)  
*Pull down PWRKEY to turn on the module.*
- [void bc66\\_power\\_off \(\)](#)  
*Pull up PWRKEY to turn off the module.*
- [char \\* bc66\\_get\\_last\\_response \(void\)](#)  
*Function to get last modem response.*
- [bool bc66\\_send\\_cmd\\_AT \(void\)](#)  
*Send AT command to sync baud rate.*
- [bc66\\_ret\\_t bc66\\_set\\_echo\\_mode \(bool echo\)](#)  
*Set Command Echo Mode.*
- [bc66\\_ret\\_t bc66\\_set\\_eps \(unsigned int set\)](#)  
*EPS Network Registration Status.*
- [bc66\\_ret\\_t bc66\\_set\\_power\\_saving\\_mode \(int mode\)](#)  
*Power Saving Mode Setting (PSM).*
- [bc66\\_ret\\_t bc66\\_get\\_ipv4\\_address \(bc66\\_ip\\_add\\_t \\*ip\)](#)  
*This function returns the IP address of the device.*
- [bc66\\_ret\\_t bc66\\_set\\_psd\\_conn \(pdp\\_type\\_t pdp\\_type, const char \\*apn, const char \\*user, const char \\*pass\)](#)  
*Set Default PSD Connection.*
- [bc66\\_ret\\_t bc66\\_set\\_mobile\\_bands \(int band\\_number,...\)](#)  
*Set Mobile Operation Band.*
- [bc66\\_ret\\_t bc66\\_is\\_ready \(void\)](#)  
*Enter PIN AT command.*
- [bc66\\_ret\\_t bc66\\_set\\_nbiot\\_event\\_report \(bool enable, bool event\)](#)  
*Enable/Disable NB-IoT Related Event Report.*
- [bc66\\_ret\\_t bc66\\_set\\_sleep\\_mode \(uint8\\_t mode\)](#)  
*Configures the TE's sleep modes.*
- [bc66\\_ret\\_t bc66\\_set\\_mqtt\\_parameters \(uint16\\_t keepalive, bool dataformat, bool session, bool version\)](#)  
*Used to configure optional parameters of MQTT.*
- [bc66\\_ret\\_t bc66\\_open\\_net\\_mqtt\\_client \(const char \\*server\\_ip, uint16\\_t server\\_port\)](#)  
*Open a Network for MQTT Client.*
- [bc66\\_ret\\_t bc66\\_connect\\_mqtt\\_client \(const char \\*client\\_id, const char \\*user, const char \\*pass\)](#)  
*Connect a Client to MQTT Server.*
- [bc66\\_ret\\_t bc66\\_disconn\\_mqtt\\_client \(void\)](#)  
*Disconnect a Client from MQTT Server.*
- [bc66\\_ret\\_t bc66\\_publish\\_msg\\_mqtt \(const char \\*topic, const char \\*msg, int qos\)](#)  
*Publish Messages.*



## Variables

- const `bc66_at_cmd_t bc66_cmds_list []`

*Define AT commands list: order must be equal to commands definition enum `bc66_cmd_list_t`.*

### 4.1.1 Detailed Description

MIT License.

Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions: The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software.

THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.

## Copyright

Juan Cruz Becerra

---

BC66 NB-IoT modem driver. ( <https://www.quectel.com/product/bc66.htm>)

AT Command Syntax The AT or at prefix must be set at the beginning of each command line. Entering <↵> CR> will terminate a command line. Commands are usually followed by a response that includes <CR><↵> LF><response><CR><LF>. Throughout this document, only the responses are presented, <CR><LF> are omitted intentionally.

Types of AT Commands and Responses

- Test Command AT+<x>=?
- Read Command AT+<x>?
- Write Command AT+<x>=<n>
- Execution Command AT+<x>

---

## Date

03/15/2021

---

## Author

Eng. Juan Cruz Becerra

---

## Version

1.0.0

### 4.1.2 Macro Definition Documentation

#### 4.1.2.1 CMD\_END\_LINE `#define CMD_END_LINE "\r\n"`

End of line command chars.

**4.1.2.2 MAX\_RSP\_SIZE** `#define MAX_RSP_SIZE 64`  
Max AT response size.

**4.1.2.3 RSP\_END\_OF\_LINE** `#define RSP_END_OF_LINE "\r\n"`  
End of line response chars.

**4.1.2.4 RSP\_ERROR** `#define RSP_ERROR "\r\nERROR\r\n"`  
Error response.

**4.1.2.5 RSP\_NO\_CMD\_IMPEMENTED** `#define RSP_NO_CMD_IMPEMENTED "BC66_NO_CMD\r\n"`  
The command is not implemented.

**4.1.2.6 RSP\_OK** `#define RSP_OK "\r\nOK\r\n"`  
Ok response.

**4.1.2.7 RSP\_TIMEOUT** `#define RSP_TIMEOUT "BC66_TIMEOUT\r\n"`  
Answer when a timeout is occurred.

### 4.1.3 Enumeration Type Documentation

**4.1.3.1 cmd\_flg\_t** `enum cmd_flg_t`  
Command possibilities indicator flags.

Enumerator

TEST	Command has test possibility.
READ	Command has read possibility.
WRITE	Command has write possibility.
EXE	Command has execute possibility.

### 4.1.4 Function Documentation

**4.1.4.1 bc66\_connect\_mqtt\_client()** `bc66_ret_t bc66_connect_mqtt_client (`  
`const char * client_id,`  
`const char * user,`  
`const char * pass )`

Connect a Client to MQTT Server.

Parameters

<i>client_id</i>	: The client identifier. The max length is 128 bytes.
<i>user</i>	: User name of the client. It can be used for authentication. The max length is 256 bytes.
<i>pass</i>	: Password corresponding to the user name of the client. It can be used for authentication. The max length is 256 bytes.

**Returns**

See `bc66_ret_t` return codes.

**4.1.4.2 `bc66_deinit()`** `void bc66_deinit (`  
`bc66_obj_t * bc66_obj )`

Function to initialize bc66 object.

**Parameters**

<code>bc66_obj</code>	
-----------------------	--

**4.1.4.3 `bc66_disconn_mqtt_client()`** `bc66_ret_t bc66_disconn_mqtt_client (`  
`void )`

Disconnect a Client from MQTT Server.

Used when a client requests a disconnection from MQTT server. A DISCONNECT message is sent from the client to the server to indicate that it is about to close its TCP/IP connection.

**Returns**

See `bc66_ret_t` return codes.

**4.1.4.4 `bc66_get_at_response()`** `char* bc66_get_at_response (`  
`char * rsp )`

Function to get any response stored in the RX buffer.

**Parameters**

<code>rsp</code>	: response to get
------------------	-------------------

**Returns**

Response if found, NULL otherwise

**4.1.4.5 `bc66_get_ipv4_address()`** `bc66_ret_t bc66_get_ipv4_address (`  
`bc66_ip_add_t * ip )`

This function returns the IP address of the device.

Show PDP Addresses.

**Parameters**

<code>ip</code>	: pointer to struct variable to return IP ADDRESS.
-----------------	--

**Returns**

See `bc66_ret_t` return codes.

**4.1.4.6 `bc66_get_last_response()`** `char* bc66_get_last_response (`  
`void )`

Function to get last modem response.

If send a new AT command, the buffer which contain the last response will be erased.

#### Returns

Pointer to RX buffer with last response.

**4.1.4.7 bc66\_hw\_reset()** `bc66_ret_t bc66_hw_reset (`  
`void )`

Reset the module via Hardware PIN.

#### Returns

See `bc66_ret_t` return codes.

**4.1.4.8 bc66\_init()** `bc66_ret_t bc66_init (`  
`bc66_obj_t * bc66_obj )`

Function to initialize bc66 object.

#### Parameters

<code>bc66_obj</code>	
-----------------------	--

#### Returns

See `bc66_ret_t` return codes.

**4.1.4.9 bc66\_is\_ready()** `bc66_ret_t bc66_is_ready (`  
`void )`

Enter PIN AT command.

Return `bc66_ret_success` if Modem is READY.

#### Returns

See `bc66_ret_t` return codes.

**4.1.4.10 bc66\_open\_net\_mqtt\_client()** `bc66_ret_t bc66_open_net_mqtt_client (`  
`const char * server_ip,`  
`uint16_t server_port )`

Open a Network for MQTT Client.

#### Parameters

<code>server_ip</code>	: server ip (string)
<code>server_port</code>	: server port (0 to 65535)

#### Returns

See `bc66_ret_t` return codes.

**4.1.4.11 bc66\_power\_off()** `void bc66_power_off ( )`

Pull up PWRKEY to turn off the module.

#### 4.1.4.12 **bc66\_power\_on()** `void bc66_power_on ( )`

Pull down PWRKEY to turn on the module.

#### 4.1.4.13 **bc66\_publish\_msg\_mqtt()** `bc66_ret_t bc66_publish_msg_mqtt (` `const char * topic,` `const char * msg,` `int qos )`

Publish Messages.

Used to publish messages by a client to a server for distribution to interested subscribers.

##### Parameters

<i>topic</i>	: Topic that the client wants to subscribe to or unsubscribe from. The maximum length is 255 bytes.
<i>msg</i>	: The message that needs to be published. The maximum length is 700 bytes. If in data mode (after > is responded), the maximum length is 1024 bytes
<i>qos</i>	: Integer type. The QoS level at which the client wants to publish the messages. <ul style="list-style-type: none"> <li>• 0 At most once</li> <li>• 1 At least once</li> <li>• 2 Exactly once</li> </ul>

##### Returns

See `bc66_ret_t` return codes.

#### 4.1.4.14 **bc66\_send\_at\_command()** `bc66_ret_t bc66_send_at_command (` `bc66_cmd_type_t cmd_type,` `const bc66_cmd_list_t cmd_lst,` `const char * exp_rsp,` `const char * arg_fmt,` `... )`

Function to send at command sentence to bc66 module through an external function communication.

##### Parameters

<i>cmd_type</i>	: BC66_CMD_TEST, BC66_CMD_READ, BC66_CMD_WRITE or BC66_CMD_EXE type.
<i>cmd_lst</i>	: command to send (see command list).
<i>rsp</i>	: pointer to expected response text.
<i>arg_fmt</i>	: arguments format (like printf function) and must be send all arguments too.

##### Returns

See `bc66_ret_t` return codes.

#### 4.1.4.15 **bc66\_send\_cmd\_AT()** `bool bc66_send_cmd_AT (` `void )`

Send AT command to sync baud rate.

**Returns**

See `bc66_ret_t` return codes.

**4.1.4.16 `bc66_set_echo_mode()`** `bc66_ret_t bc66_set_echo_mode (`  
     `bool echo )`

Set Command Echo Mode.

This Execution Command determines whether or not the UE echoes characters received from external MCU during command state.

The command takes effect immediately. Remain valid after deep-sleep wakeup. The configuration will be saved to NVRAM (should execute AT&W after this command is issued).

**Parameters**

<i>echo</i>	<ul style="list-style-type: none"> <li>• false: Echo mode OFF</li> <li>• true: Echo mode ON</li> </ul>
-------------	--

**Returns**

See `bc66_ret_t` return codes.

**4.1.4.17 `bc66_set_eps()`** `bc66_ret_t bc66_set_eps (`  
     `unsigned int set )`

EPS Network Registration Status.

Configures the different unsolicited result codes for EPS Network Registration Status.

**Parameters**

<i>net</i>	<p>: Disable or enable network registration URC.</p> <ul style="list-style-type: none"> <li>• 0 Disable network registration URC</li> <li>• 1 Enable network registration URC: +CEREG: &lt;stat&gt;</li> <li>• 2 Enable network registration and location information URC: +CEREG: &lt;stat&gt;[,&lt;tac&gt;],[&lt;ci&gt;],[&lt;AcT&gt;]]</li> <li>• 3 Enable network registration, location information and EMM cause value information URC: +CEREG: &lt;stat&gt;[,&lt;tac&gt;],[&lt;ci&gt;],[&lt;AcT&gt;],[&lt;cause_type&gt;,&lt;reject_cause&gt;]]</li> <li>• 4 For a UE that requests PSM, enable network registration and location information URC: +CEREG: &lt;stat&gt;[,&lt;tac&gt;],[&lt;ci&gt;],[&lt;AcT&gt;][,&lt;Active-Time&gt;],[&lt;Periodic-TAU&gt;]]]</li> <li>• 5 For a UE that requests PSM, enable network registration, location information and EMM cause value information URC: +CEREG: &lt;stat&gt;[,&lt;tac&gt;],[&lt;ci&gt;],[&lt;AcT&gt;],[&lt;cause_type&gt;],[&lt;reject_cause&gt;],[&lt;Active-Time&gt;],[&lt;Periodic-TAU&gt;]]]</li> </ul>
------------	--

**Returns**

See `bc66_ret_t` return codes.

**4.1.4.18 bc66\_set\_mobile\_bands()** `bc66_ret_t bc66_set_mobile_bands (`  
     `int band_number,`  
     `... )`

Set Mobile Operation Band.

#### Parameters

<i>band_numb</i>	: band quantity.  <ul style="list-style-type: none"> <li>• 0 all bands.</li> <li>• 1 to 16 Number of bands to be locked.</li> </ul>
------------------	---

#### Returns

See `bc66_ret_t` return codes.

**4.1.4.19 bc66\_set\_mqtt\_parameters()** `bc66_ret_t bc66_set_mqtt_parameters (`  
     `uint16_t keepalive,`  
     `bool dataformat,`  
     `bool session,`  
     `bool version )`

Used to configure optional parameters of MQTT.

#### Parameters

<i>keepalive</i>	: Configure the keep-alive time. The range is 0-3600. The default value is 120. Unit: second. It defines the maximum time interval between messages received from a client. If the server does not receive a message from the client within 1.5 times of the keep-alive time period, it disconnects the client as if the client has sent a DISCONNECT message. 0 The client is not disconnected
<i>dataformat</i>	: The format of sent and received data.  <ul style="list-style-type: none"> <li>• 0 Text format</li> <li>• 1 Hex format</li> </ul>
<i>session</i>	: The session type.  <ul style="list-style-type: none"> <li>• 0 The server must store the subscriptions of the client after it is disconnected.</li> <li>• 1 The server must discard any previously maintained information about the client and treat the connection as "clean".</li> </ul>
<i>version</i>	: The version of MQTT protocol.  <ul style="list-style-type: none"> <li>• 0 MQTT v3.1</li> <li>• 1 MQTT v3.1.1</li> </ul>

#### Returns

See `bc66_ret_t` return codes.

**4.1.4.20 bc66\_set\_nbiot\_event\_report()** `bc66_ret_t bc66_set_nbiot_event_report (`  
     `bool enable,`  
     `bool event )`

Enable/Disable NB-IoT Related Event Report.

#### Parameters

<i>enable</i>	: Enable/disable a specific event report. <ul style="list-style-type: none"> <li>• 0 Disable the indication of the specific event</li> <li>• 1 Enable the indication of the specific event by URC +QNBIOTEVENT: &lt;event_value&gt;</li> </ul>
<i>event</i>	: The reported event.

#### Returns

See `bc66_ret_t` return codes.

#### 4.1.4.21 `bc66_set_power_saving_mode()` `bc66_ret_t` `bc66_set_power_saving_mode` ( `int mode` )

Power Saving Mode Setting (PSM).

Power Saving Mode Setting.

#### Parameters

<i>mode</i>	Integer type. Disable or enable the use of PSM in the UE <ul style="list-style-type: none"> <li>• 0 Disable the use of PSM</li> <li>• 1 Enable the use of PSM</li> <li>• 2 Disable the use of PSM and discard all parameters for PSM or, if available, reset to the default values.</li> </ul>
-------------	--

#### Returns

See `bc66_ret_t` return codes.

#### 4.1.4.22 `bc66_set_psd_conn()` `bc66_ret_t` `bc66_set_psd_conn` ( `pdp_type_t pdp_type`, `const char * apn`, `const char * user`, `const char * pass` )

Set Default PSD Connection.

This command sets the PSD connection settings for PDN connection on power-up. When attaching to the NB-IoT network on power-on, a PDN connection setup must be performed. In order to allow this to happen, PDN connection settings must be stored in NVRAM, thus making it to be used by the modem during the attach procedure.

#### Parameters

<i>pdp_type</i>	: Specify the type of packet data protocol.
<i>apn</i>	: A logical name that is used to select the GGSN or the external packet data network. The maximum configurable APN length is 99 bytes.
<i>user</i>	: The user name for accessing to the IP network. (Optional)
<i>pass</i>	: The password for accessing to the IP network. (Optional)



**Returns**

See `bc66_ret_t` return codes.

**4.1.4.23 `bc66_set_sleep_mode()`** `bc66_ret_t bc66_set_sleep_mode (`  
     `uint8_t mode )`

Configures the TE's sleep modes.

**Parameters**

<code>mode</code>	:	<ul style="list-style-type: none"> <li>• 0 Disable sleep modes</li> <li>• 1 Enable light sleep and deep sleep, wakeup by PSM_EINT (falling edge)</li> <li>• 2 Enable light sleep only, wakeup by the Main UART</li> </ul>
-------------------	---	---

**Returns**

See `bc66_ret_t` return codes.

**4.1.5 Variable Documentation**

**4.1.5.1 `bc66_cmds_list`** `const bc66_at_cmd_t bc66_cmds_list[]`

Define AT commands list: order must be equal to commands definition enum `bc66_cmd_list_t`.

**4.2 `/Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.h` File Reference**

MIT License.

```
#include <stdint.h>
#include <stdbool.h>
#include <stddef.h>
```

**Data Structures**

- struct `bc66_obj_t`
- struct `bc66_ip_add_t`

*Struct to store IP ADDRESS.*

**Enumerations**

- enum `bc66_cmd_type_t` { `BC66_CMD_TEST` , `BC66_CMD_READ` , `BC66_CMD_WRITE` , `BC66_CMD_EXE` }

*AT command possibility. Erch command can test and/or read and/or write and/or execute. Use with `bc66_send_at_command(...)` function.*

- enum `bc66_cmd_list_t` {  
     `bc66_cmd_list_AT` , `bc66_cmd_list_ATI` , `bc66_cmd_list_ATE` , `bc66_cmd_list_CEREG` ,  
     `bc66_cmd_list_CESQ` , `bc66_cmd_list_CGATT` , `bc66_cmd_list_CGPADDR` , `bc66_cmd_list_QCGDEFCONT`  
     ,  
     `bc66_cmd_list_QBAND` , `bc66_cmd_list_CIMI` , `bc66_cmd_list_CPIN` , `bc66_cmd_list_CPSMS` ,  
     `bc66_cmd_list_QNBIOTEVENT` , `bc66_cmd_list_QSCLK` , `bc66_cmd_list_QMTCFG` , `bc66_cmd_list_QMTOPE`  
     ,

```
bc66_cmd_list_QMTCLOSE , bc66_cmd_list_QMTCONN , bc66_cmd_list_QMTDISC , bc66_cmd_list_QMTSUB
,
bc66_cmd_list_QMTUNS , bc66_cmd_list_QMTPUB , bc66_cmd_list_size }
```

*This is the commands implemented list.*

- enum `bc66_ret_t` {  
`bc66_ret_success` , `bc66_ret_timeout` , `bc66_ret_error` , `bc66_ret_out_of_range` ,  
`bc66_ret_not_init` , `bc66_ret_no_ip` , `bc66_ret_no_cmd_implemented` }  
*bc66 library api return*
- enum `pdp_type_t` { `pdp_type_ip` , `pdp_type_ipv6` , `pdp_type_ipv4v6` , `pdp_type_non_ip` }  
*Enumeration to specify the type of packet data protocol.*

## Functions

- `bc66_ret_t bc66_init (bc66_obj_t *bc66_obj)`  
*Function to initialize bc66 object.*
- `char * bc66_get_at_response (char *rsp)`  
*Function to get any response stored in the RX buffer.*
- `bc66_ret_t bc66_send_at_command (bc66_cmd_type_t cmd_type, const bc66_cmd_list_t cmd_lst, const char *exp_rsp, const char *arg_fmt,...)`  
*Function to send at command sentence to bc66 module through an external function communication.*
- `bc66_ret_t bc66_hw_reset (void)`  
*Reset the module via Hardware PIN.*
- `void bc66_power_on ()`  
*Pull down PWRKEY to turn on the module.*
- `void bc66_power_off ()`  
*Pull up PWRKEY to turn off the module.*
- `char * bc66_get_last_response (void)`  
*Function to get last modem response.*
- `bool bc66_send_cmd_AT (void)`  
*Send AT command to sync baud rate.*
- `bc66_ret_t bc66_set_echo_mode (bool echo)`  
*Set Command Echo Mode.*
- `bc66_ret_t bc66_set_eps (unsigned int set)`  
*EPS Network Registration Status.*
- `bc66_ret_t bc66_set_power_saving_mode (int mode)`  
*Power Saving Mode Setting.*
- `bc66_ret_t bc66_get_ipv4_address (bc66_ip_add_t *ip)`  
*This function returns the IP address of the device.*
- `bc66_ret_t bc66_set_psd_conn (pdp_type_t pdp_type, const char *apn, const char *user, const char *pass)`  
*Set Default PSD Connection.*
- `bc66_ret_t bc66_set_mobile_bands (int band_number,...)`  
*Set Mobile Operation Band.*
- `bc66_ret_t bc66_is_ready (void)`  
*Enter PIN AT command.*
- `bc66_ret_t bc66_set_nbiot_event_report (bool enable, bool event)`  
*Enable/Disable NB-IoT Related Event Report.*
- `bc66_ret_t bc66_set_sleep_mode (uint8_t mode)`  
*Configures the TE's sleep modes.*
- `bc66_ret_t bc66_set_mqtt_parameters (uint16_t keepalive, bool dataformat, bool session, bool version)`  
*Used to configure optional parameters of MQTT.*
- `bc66_ret_t bc66_open_net_mqtt_client (const char *server_ip, uint16_t server_port)`  
*Open a Network for MQTT Client.*

- [bc66\\_ret\\_t bc66\\_connect\\_mqtt\\_client](#) (const char \*client\_id, const char \*user, const char \*pass)  
*Connect a Client to MQTT Server.*
- [bc66\\_ret\\_t bc66\\_disconn\\_mqtt\\_client](#) (void)  
*Disconnect a Client from MQTT Server.*
- [bc66\\_ret\\_t bc66\\_publish\\_msg\\_mqtt](#) (const char \*topic, const char \*msg, int qos)  
*Publish Messages.*

#### 4.2.1 Detailed Description

MIT License.

Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions: The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software.

THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.

##### Copyright

Juan Cruz Becerra

---

BC66 NB-IoT modem driver. ( <https://www.quectel.com/product/bc66.htm>)

AT Command Syntax The AT or at prefix must be set at the beginning of each command line. Entering <↵> CR> will terminate a command line. Commands are usually followed by a response that includes <CR><↵> LF><response><CR><LF>. Throughout this document, only the responses are presented, <CR><LF> are omitted intentionally.

Types of AT Commands and Responses

- Test Command AT+<x>=?
- Read Command AT+<x>?
- Write Command AT+<x>=<n>
- Execution Command AT+<x>

---

##### Date

03/15/2021

---

##### Author

Eng. Juan Cruz Becerra

---

##### Version

1.0.0

#### 4.2.2 Enumeration Type Documentation

##### 4.2.2.1 [bc66\\_cmd\\_list\\_t](#) enum [bc66\\_cmd\\_list\\_t](#)

This is the commands implemented list.

## Enumerator

bc66_cmd_list_AT	AT command. Use to sync baud rate.
bc66_cmd_list_ATI	Display Product Identification Information.
bc66_cmd_list_ATE	Set Command Echo Mode.
bc66_cmd_list_CEREG	EPS Network Registration Status.
bc66_cmd_list_CESQ	Extended Signal Quality.
bc66_cmd_list_CGATT	PS Attachment or Detachment.
bc66_cmd_list_CGPADDR	Show PDP Addresses.
bc66_cmd_list_QCGDEFCONT	Set Default PSD Connection Settings.
bc66_cmd_list_QBAND	Get and Set Mobile Operation Band.
bc66_cmd_list_CIMI	Request International Mobile Subscriber Identity.
bc66_cmd_list_CPIN	Enter PIN.
bc66_cmd_list_CPSMS	Power Saving Mode Setting.
bc66_cmd_list_QNBIOTEVENT	Enable/Disable NB-IoT Related Event Report.
bc66_cmd_list_QSCLK	Configure Sleep Mode.
bc66_cmd_list_QMTCFG	Configure Optional Parameters of MQTT.
bc66_cmd_list_QMTOPE	Open a Network for MQTT Client.
bc66_cmd_list_QMTCLOSE	Close a Network for MQTT Client.
bc66_cmd_list_QMTCONN	Connect a Client to MQTT Server.
bc66_cmd_list_QMTDISC	Disconnect a Client from MQTT Server.
bc66_cmd_list_QMTSUB	Subscribe to Topics.
bc66_cmd_list_QMTUNS	Unsubscribe from Topics.
bc66_cmd_list_QMTPUB	Publish Messages.
bc66_cmd_list_size	Is not a command. Only to know commands quantity.

**4.2.2.2 bc66\_cmd\_type\_t** enum [bc66\\_cmd\\_type\\_t](#)

AT command possibility. Erch command can test and/or read and/or write and/or execute. Use with `bc66_send_at_command(...)` function.

## Enumerator

BC66_CMD_TEST	Send AT TEST command.
BC66_CMD_READ	Send AT READ command.
BC66_CMD_WRITE	Send AT WRITE command.
BC66_CMD_EXE	Send AT TEST command.

**4.2.2.3 bc66\_ret\_t** enum [bc66\\_ret\\_t](#)

bc66 library api return

## Enumerator

bc66_ret_success	Modem data process successful.
bc66_ret_timeout	Response timeout.
bc66_ret_error	Modem response with error message.
bc66_ret_out_of_range	At least some argument is out of range.
bc66_ret_not_init	
bc66_ret_no_ip	Device has not IP ADDRESS.

#### Enumerator

<code>bc66_ret_no_cmd_implemented</code>	<code>RSP_NO_CMD_IMPEMENTED.</code>
--	-------------------------------------

#### 4.2.2.4 `pdp_type_t` enum `pdp_type_t`

Enumeration to specify the type of packet data protocol.

#### Enumerator

<code>pdp_type_ip</code>	Internet Protocol (IETF STD 5).
<code>pdp_type_ipv6</code>	Internet Protocol version 6 (IETF RFC 2460).
<code>pdp_type_ipv4v6</code>	Dual IP stack (see 3GPP TS 24.301).
<code>pdp_type_non_ip</code>	Transfer of Non-IP data to external packet network (see 3GPP TS 24.301).

### 4.2.3 Function Documentation

**4.2.3.1 `bc66_connect_mqtt_client()`** `bc66_ret_t` `bc66_connect_mqtt_client` (  

```

    const char * client_id,
    const char * user,
    const char * pass )

```

Connect a Client to MQTT Server.

#### Parameters

<i>client_id</i>	: The client identifier. The max length is 128 bytes.
<i>user</i>	: User name of the client. It can be used for authentication. The max length is 256 bytes.
<i>pass</i>	: Password corresponding to the user name of the client. It can be used for authentication. The max length is 256 bytes.

#### Returns

See `bc66_ret_t` return codes.

**4.2.3.2 `bc66_disconn_mqtt_client()`** `bc66_ret_t` `bc66_disconn_mqtt_client` (  

```

    void )

```

Disconnect a Client from MQTT Server.

Used when a client requests a disconnection from MQTT server. A DISCONNECT message is sent from the client to the server to indicate that it is about to close its TCP/IP connection.

#### Returns

See `bc66_ret_t` return codes.

**4.2.3.3 `bc66_get_at_response()`** `char*` `bc66_get_at_response` (  

```

    char * rsp )

```

Function to get any response stored in the RX buffer.

## Parameters

<i>rsp</i>	: response to get
------------	-------------------

## Returns

Response if found, NULL otherwise

**4.2.3.4 bc66\_get\_ipv4\_address()** `bc66_ret_t bc66_get_ipv4_address (`  
`bc66_ip_add_t * ip )`

This function returns the IP address of the device.

Show PDP Addresses.

## Parameters

<i>ip</i>	: pointer to struct variable to return IP ADDRESS.
-----------	--

## Returns

See `bc66_ret_t` return codes.

**4.2.3.5 bc66\_get\_last\_response()** `char* bc66_get_last_response (`  
`void )`

Function to get last modem response.

If send a new AT command, the buffer which contain the last response will be erased.

## Returns

Pointer to RX buffer with last response.

**4.2.3.6 bc66\_hw\_reset()** `bc66_ret_t bc66_hw_reset (`  
`void )`

Reset the module via Hardware PIN.

## Returns

See `bc66_ret_t` return codes.

**4.2.3.7 bc66\_init()** `bc66_ret_t bc66_init (`  
`bc66_obj_t * bc66_obj )`

Function to initialize bc66 object.

## Parameters

<i>bc66_obj</i>	
-----------------	--

## Returns

See `bc66_ret_t` return codes.

**4.2.3.8 bc66\_is\_ready()** `bc66_ret_t bc66_is_ready ( void )`

Enter PIN AT command.

Return `bc66_ret_success` if Modem is READY.

#### Returns

See `bc66_ret_t` return codes.

**4.2.3.9 bc66\_open\_net\_mqtt\_client()** `bc66_ret_t bc66_open_net_mqtt_client ( const char * server_ip, uint16_t server_port )`

Open a Network for MQTT Client.

#### Parameters

<i>server_ip</i>	: server ip (string)
<i>server_port</i>	: server port (0 to 65535)

#### Returns

See `bc66_ret_t` return codes.

**4.2.3.10 bc66\_power\_off()** `void bc66_power_off ( )`

Pull up PWRKEY to turn off the module.

**4.2.3.11 bc66\_power\_on()** `void bc66_power_on ( )`

Pull down PWRKEY to turn on the module.

**4.2.3.12 bc66\_publish\_msg\_mqtt()** `bc66_ret_t bc66_publish_msg_mqtt ( const char * topic, const char * msg, int qos )`

Publish Messages.

Used to publish messages by a client to a server for distribution to interested subscribers.

#### Parameters

<i>topic</i>	: Topic that the client wants to subscribe to or unsubscribe from. The maximum length is 255 bytes.
<i>msg</i>	: The message that needs to be published. The maximum length is 700 bytes. If in data mode (after > is responded), the maximum length is 1024 bytes
<i>qos</i>	: Integer type. The QoS level at which the client wants to publish the messages. <ul style="list-style-type: none"> <li>• 0 At most once</li> <li>• 1 At least once</li> <li>• 2 Exactly once</li> </ul>

### Returns

See `bc66_ret_t` return codes.

**4.2.3.13 `bc66_send_at_command()`** `bc66_ret_t bc66_send_at_command (`  
    `bc66_cmd_type_t cmd_type,`  
    `const bc66_cmd_list_t cmd_lst,`  
    `const char * exp_rsp,`  
    `const char * arg_fmt,`  
    `... )`

Function to send at command sentence to bc66 module through an external function communication.

### Parameters

<i>cmd_type</i>	: BC66_CMD_TEST, BC66_CMD_READ, BC66_CMD_WRITE or BC66_CMD_EXE type.
<i>cmd_lst</i>	: command to send (see command list).
<i>rsp</i>	: pointer to expected response text.
<i>arg_fmt</i>	: arguments format (like printf function) and must be send all arguments too.

### Returns

See `bc66_ret_t` return codes.

**4.2.3.14 `bc66_send_cmd_AT()`** `bool bc66_send_cmd_AT (`  
    `void )`

Send AT command to sync baud rate.

### Returns

See `bc66_ret_t` return codes.

**4.2.3.15 `bc66_set_echo_mode()`** `bc66_ret_t bc66_set_echo_mode (`  
    `bool echo )`

Set Command Echo Mode.

This Execution Command determines whether or not the UE echoes characters received from external MCU during command state.

The command takes effect immediately. Remain valid after deep-sleep wakeup. The configuration will be saved to NVRAM (should execute AT&W after this command is issued).

### Parameters

<i>echo</i>	<ul style="list-style-type: none"><li>• false: Echo mode OFF</li><li>• true: Echo mode ON</li></ul>
-------------	---

### Returns

See `bc66_ret_t` return codes.



**4.2.3.16 bc66\_set\_eps()** `bc66_ret_t bc66_set_eps (`  
     `unsigned int set )`

EPS Network Registration Status.

Configures the different unsolicited result codes for EPS Network Registration Status.

#### Parameters

<i>net</i>	: Disable or enable network registration URC.
------------	---

- 0 Disable network registration URC
- 1 Enable network registration URC: +CEREG: <stat>
- 2 Enable network registration and location information URC: +CEREG: <stat>[, [<tac>],[<ci>],[<AcT>]]
- 3 Enable network registration, location information and EMM cause value information URC: +CEREG: <stat>[, [<tac>],[<ci>],[<AcT>]][, <cause\_type>,<reject\_cause>]]
- 4 For a UE that requests PSM, enable network registration and location information URC: +CEREG: <stat>[, [<tac>],[<ci>],[<AcT>]][, [, [<Active-Time>],[<Periodic-TAU>]]]
- 5 For a UE that requests PSM, enable network registration, location information and EMM cause value information URC: +CEREG: <stat>[, [<tac>],[<ci>],[<AcT>]][, [<cause\_type>],[<reject\_cause>]][, [, [<Active-Time>],[<Periodic-TAU>]]]

#### Returns

See `bc66_ret_t` return codes.

**4.2.3.17 bc66\_set\_mobile\_bands()** `bc66_ret_t bc66_set_mobile_bands (`  
     `int band_number,`  
     `... )`

Set Mobile Operation Band.

#### Parameters

<i>band_numb</i>	: band quantity.
------------------	------------------

- 0 all bands.
- 1 to 16 Number of bands to be locked.

#### Returns

See `bc66_ret_t` return codes.

**4.2.3.18 bc66\_set\_mqtt\_parameters()** `bc66_ret_t bc66_set_mqtt_parameters (`  
     `uint16_t keepalive,`  
     `bool dataformat,`  
     `bool session,`  
     `bool version )`

Used to configure optional parameters of MQTT.

## Parameters

<i>keepalive</i>	: Configure the keep-alive time. The range is 0-3600. The default value is 120. Unit: second. It defines the maximum time interval between messages received from a client. If the server does not receive a message from the client within 1.5 times of the keep-alive time period, it disconnects the client as if the client has sent a DISCONNECT message. 0 The client is not disconnected
<i>dataformat</i>	: The format of sent and received data. <ul style="list-style-type: none"> <li>• 0 Text format</li> <li>• 1 Hex format</li> </ul>
<i>session</i>	: The session type. <ul style="list-style-type: none"> <li>• 0 The server must store the subscriptions of the client after it is disconnected.</li> <li>• 1 The server must discard any previously maintained information about the client and treat the connection as "clean".</li> </ul>
<i>version</i>	: The version of MQTT protocol. <ul style="list-style-type: none"> <li>• 0 MQTT v3.1</li> <li>• 1 MQTT v3.1.1</li> </ul>

## Returns

See `bc66_ret_t` return codes.

**4.2.3.19 `bc66_set_nbiot_event_report()`** `bc66_ret_t` `bc66_set_nbiot_event_report` (  
     `bool enable`,  
     `bool event` )

Enable/Disable NB-IoT Related Event Report.

## Parameters

<i>enable</i>	: Enable/disable a specific event report. <ul style="list-style-type: none"> <li>• 0 Disable the indication of the specific event</li> <li>• 1 Enable the indication of the specific event by URC +QNBIOTEVENT: &lt;event_value&gt;</li> </ul>
<i>event</i>	: The reported event.

## Returns

See `bc66_ret_t` return codes.

**4.2.3.20 `bc66_set_power_saving_mode()`** `bc66_ret_t` `bc66_set_power_saving_mode` (  
     `int mode` )

Power Saving Mode Setting.

**Parameters**

<i>mode</i>	Integer type. Disable or enable the use of PSM in the UE <ul style="list-style-type: none"> <li>• 0 Disable the use of PSM</li> <li>• 1 Enable the use of PSM</li> <li>• 2 Disable the use of PSM and discard all parameters for PSM or, if available, reset to the default values.</li> </ul>
-------------	--

**Returns**

See `bc66_ret_t` return codes.

Power Saving Mode Setting.

**Parameters**

<i>mode</i>	Integer type. Disable or enable the use of PSM in the UE <ul style="list-style-type: none"> <li>• 0 Disable the use of PSM</li> <li>• 1 Enable the use of PSM</li> <li>• 2 Disable the use of PSM and discard all parameters for PSM or, if available, reset to the default values.</li> </ul>
-------------	--

**Returns**

See `bc66_ret_t` return codes.

**4.2.3.21 `bc66_set_psd_conn()`** `bc66_ret_t bc66_set_psd_conn (`  
`pdp_type_t pdp_type,`  
`const char * apn,`  
`const char * user,`  
`const char * pass )`

Set Default PSD Connection.

This command sets the PSD connection settings for PDN connection on power-up. When attaching to the NB-IoT network on power-on, a PDN connection setup must be performed. In order to allow this to happen, PDN connection settings must be stored in NVRAM, thus making it to be used by the modem during the attach procedure.

**Parameters**

<i>pdp_type</i>	: Specify the type of packet data protocol.
<i>apn</i>	: A logical name that is used to select the GGSN or the external packet data network. The maximum configurable APN length is 99 bytes.
<i>user</i>	: The user name for accessing to the IP network. (Optional)
<i>pass</i>	: The password for accessing to the IP network. (Optional)

**Returns**

See `bc66_ret_t` return codes.

**4.2.3.22 bc66\_set\_sleep\_mode()** `bc66_ret_t bc66_set_sleep_mode (`  
`uint8_t mode )`

Configures the TE's sleep modes.

#### Parameters

<i>mode</i>	:	<ul style="list-style-type: none"><li>• 0 Disable sleep modes</li><li>• 1 Enable light sleep and deep sleep, wakeup by PSM_EINT (falling edge)</li><li>• 2 Enable light sleep only, wakeup by the Main UART</li></ul>
-------------	---	---

#### Returns

See `bc66_ret_t` return codes.



## Index

`/Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.c`, [bc66\\_drv.h](#), [19](#)  
[6](#)  
`/Users/jcbecerra/dev/fw/iot/quectel_bc66_driver/src/bc66_drv.h`, [bc66\\_drv.h](#), [19](#)  
[16](#)  
  
a1  
    [bc66\\_ip\\_add\\_t](#), [3](#)  
a2  
    [bc66\\_ip\\_add\\_t](#), [3](#)  
a3  
    [bc66\\_ip\\_add\\_t](#), [4](#)  
a4  
    [bc66\\_ip\\_add\\_t](#), [4](#)  
  
[bc66\\_at\\_cmd\\_t](#), [2](#)  
    [cmd](#), [2](#)  
    [cmd\\_flags](#), [2](#)  
    [cmd\\_rsp](#), [3](#)  
    [rsp\\_timeout](#), [3](#)  
BC66\_CMD\_EXE  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_AT](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_ATE](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_ATI](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_CEREG](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_CESQ](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_CGATT](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_CGPADDR](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_CIMI](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_CPIN](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_CPSMS](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QBAND](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QCGDEFCONT](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QMTCFG](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QMTCLOSE](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QMTCONN](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QMTDISC](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QMTOPEN](#)  
    [bc66\\_drv.h](#), [19](#)  
[bc66\\_cmd\\_list\\_QMTPUB](#)  
  
    [bc66\\_cmd\\_list\\_QMTSUB](#)  
    [bc66\\_cmd\\_list\\_QMTUNS](#)  
        [bc66\\_drv.h](#), [19](#)  
    [bc66\\_cmd\\_list\\_QNBIOTEVENT](#)  
        [bc66\\_drv.h](#), [19](#)  
    [bc66\\_cmd\\_list\\_QSCLK](#)  
        [bc66\\_drv.h](#), [19](#)  
    [bc66\\_cmd\\_list\\_size](#)  
        [bc66\\_drv.h](#), [19](#)  
    [bc66\\_cmd\\_list\\_t](#)  
        [bc66\\_drv.h](#), [18](#)  
    BC66\_CMD\_READ  
        [bc66\\_drv.h](#), [19](#)  
    BC66\_CMD\_TEST  
        [bc66\\_drv.h](#), [19](#)  
    [bc66\\_cmd\\_type\\_t](#)  
        [bc66\\_drv.h](#), [19](#)  
    BC66\_CMD\_WRITE  
        [bc66\\_drv.h](#), [19](#)  
    [bc66\\_cmds\\_list](#)  
        [bc66\\_drv.c](#), [16](#)  
    [bc66\\_connect\\_mqtt\\_client](#)  
        [bc66\\_drv.c](#), [9](#)  
        [bc66\\_drv.h](#), [20](#)  
    [bc66\\_deinit](#)  
        [bc66\\_drv.c](#), [10](#)  
    [bc66\\_disconn\\_mqtt\\_client](#)  
        [bc66\\_drv.c](#), [10](#)  
        [bc66\\_drv.h](#), [20](#)  
    [bc66\\_drv.c](#)  
        [bc66\\_cmds\\_list](#), [16](#)  
        [bc66\\_connect\\_mqtt\\_client](#), [9](#)  
        [bc66\\_deinit](#), [10](#)  
        [bc66\\_disconn\\_mqtt\\_client](#), [10](#)  
        [bc66\\_get\\_at\\_response](#), [10](#)  
        [bc66\\_get\\_ipv4\\_address](#), [10](#)  
        [bc66\\_get\\_last\\_response](#), [10](#)  
        [bc66\\_hw\\_reset](#), [11](#)  
        [bc66\\_init](#), [11](#)  
        [bc66\\_is\\_ready](#), [11](#)  
        [bc66\\_open\\_net\\_mqtt\\_client](#), [11](#)  
        [bc66\\_power\\_off](#), [11](#)  
        [bc66\\_power\\_on](#), [12](#)  
        [bc66\\_publish\\_msg\\_mqtt](#), [12](#)  
        [bc66\\_send\\_at\\_command](#), [12](#)  
        [bc66\\_send\\_cmd\\_AT](#), [12](#)  
        [bc66\\_set\\_echo\\_mode](#), [13](#)  
        [bc66\\_set\\_eps](#), [13](#)  
        [bc66\\_set\\_mobile\\_bands](#), [13](#)  
        [bc66\\_set\\_mqtt\\_parameters](#), [14](#)  
        [bc66\\_set\\_nbiot\\_event\\_report](#), [14](#)  
        [bc66\\_set\\_power\\_saving\\_mode](#), [15](#)  
        [bc66\\_set\\_psd\\_conn](#), [15](#)

- bc66\_set\_sleep\_mode, 16
- CMD\_END\_LINE, 8
- cmd\_flg\_t, 9
- EXE, 9
- MAX\_RSP\_SIZE, 8
- READ, 9
- RSP\_END\_OF\_LINE, 9
- RSP\_ERROR, 9
- RSP\_NO\_CMD\_IMPEMENTED, 9
- RSP\_OK, 9
- RSP\_TIMEOUT, 9
- TEST, 9
- WRITE, 9
- bc66\_drv.h
  - BC66\_CMD\_EXE, 19
  - bc66\_cmd\_list\_AT, 19
  - bc66\_cmd\_list\_ATE, 19
  - bc66\_cmd\_list\_ATI, 19
  - bc66\_cmd\_list\_CEREG, 19
  - bc66\_cmd\_list\_CESQ, 19
  - bc66\_cmd\_list\_CGATT, 19
  - bc66\_cmd\_list\_CGPADDR, 19
  - bc66\_cmd\_list\_CIMI, 19
  - bc66\_cmd\_list\_CPIN, 19
  - bc66\_cmd\_list\_CPSMS, 19
  - bc66\_cmd\_list\_QBAND, 19
  - bc66\_cmd\_list\_QCGDEFCONT, 19
  - bc66\_cmd\_list\_QMTCFG, 19
  - bc66\_cmd\_list\_QMTCLOSE, 19
  - bc66\_cmd\_list\_QMTCONN, 19
  - bc66\_cmd\_list\_QMTDISC, 19
  - bc66\_cmd\_list\_QMTOPEM, 19
  - bc66\_cmd\_list\_QMTPUB, 19
  - bc66\_cmd\_list\_QMTSUB, 19
  - bc66\_cmd\_list\_QMTUNS, 19
  - bc66\_cmd\_list\_QNBIOTEVENT, 19
  - bc66\_cmd\_list\_QSCLK, 19
  - bc66\_cmd\_list\_size, 19
  - bc66\_cmd\_list\_t, 18
  - BC66\_CMD\_READ, 19
  - BC66\_CMD\_TEST, 19
  - bc66\_cmd\_type\_t, 19
  - BC66\_CMD\_WRITE, 19
  - bc66\_connect\_mqtt\_client, 20
  - bc66\_disconn\_mqtt\_client, 20
  - bc66\_get\_at\_response, 20
  - bc66\_get\_ipv4\_address, 21
  - bc66\_get\_last\_response, 21
  - bc66\_hw\_reset, 21
  - bc66\_init, 21
  - bc66\_is\_ready, 21
  - bc66\_open\_net\_mqtt\_client, 22
  - bc66\_power\_off, 22
  - bc66\_power\_on, 22
  - bc66\_publish\_msg\_mqtt, 22
  - bc66\_ret\_error, 19
  - bc66\_ret\_no\_cmd\_implemented, 20
  - bc66\_ret\_no\_ip, 19
  - bc66\_ret\_not\_init, 19
  - bc66\_ret\_out\_of\_range, 19
  - bc66\_ret\_success, 19
  - bc66\_ret\_t, 19
  - bc66\_ret\_timeout, 19
  - bc66\_send\_at\_command, 23
  - bc66\_send\_cmd\_AT, 23
  - bc66\_set\_echo\_mode, 23
  - bc66\_set\_eps, 23
  - bc66\_set\_mobile\_bands, 24
  - bc66\_set\_mqtt\_parameters, 24
  - bc66\_set\_nbiot\_event\_report, 25
  - bc66\_set\_power\_saving\_mode, 25
  - bc66\_set\_psd\_conn, 26
  - bc66\_set\_sleep\_mode, 26
  - pdp\_type\_ip, 20
  - pdp\_type\_ipv4v6, 20
  - pdp\_type\_ipv6, 20
  - pdp\_type\_non\_ip, 20
  - pdp\_type\_t, 20
  - bc66\_get\_at\_response
    - bc66\_drv.c, 10
    - bc66\_drv.h, 20
  - bc66\_get\_ipv4\_address
    - bc66\_drv.c, 10
    - bc66\_drv.h, 21
  - bc66\_get\_last\_response
    - bc66\_drv.c, 10
    - bc66\_drv.h, 21
  - bc66\_hw\_reset
    - bc66\_drv.c, 11
    - bc66\_drv.h, 21
  - bc66\_init
    - bc66\_drv.c, 11
    - bc66\_drv.h, 21
  - bc66\_ip\_add\_t, 3
    - a1, 3
    - a2, 3
    - a3, 4
    - a4, 4
  - bc66\_is\_ready
    - bc66\_drv.c, 11
    - bc66\_drv.h, 21
  - bc66\_obj\_t, 4
    - control\_lines, 4
    - func\_delay, 4
    - func\_init\_ptr, 5
    - func\_r\_bytes\_ptr, 5
    - func\_w\_bytes\_ptr, 5
    - MDM\_PSM\_EINT\_N, 5
    - MDM\_PWRKEY\_N, 5
    - MDM\_RESET\_N, 5
    - MDM\_RI, 5
  - bc66\_open\_net\_mqtt\_client
    - bc66\_drv.c, 11
    - bc66\_drv.h, 22
  - bc66\_power\_off
    - bc66\_drv.c, 11

- bc66\_drv.h, [22](#)
- bc66\_power\_on
  - bc66\_drv.c, [12](#)
  - bc66\_drv.h, [22](#)
- bc66\_publish\_msg\_mqtt
  - bc66\_drv.c, [12](#)
  - bc66\_drv.h, [22](#)
- bc66\_ret\_error
  - bc66\_drv.h, [19](#)
- bc66\_ret\_no\_cmd\_implemented
  - bc66\_drv.h, [20](#)
- bc66\_ret\_no\_ip
  - bc66\_drv.h, [19](#)
- bc66\_ret\_not\_init
  - bc66\_drv.h, [19](#)
- bc66\_ret\_out\_of\_range
  - bc66\_drv.h, [19](#)
- bc66\_ret\_success
  - bc66\_drv.h, [19](#)
- bc66\_ret\_t
  - bc66\_drv.h, [19](#)
- bc66\_ret\_timeout
  - bc66\_drv.h, [19](#)
- bc66\_send\_at\_command
  - bc66\_drv.c, [12](#)
  - bc66\_drv.h, [23](#)
- bc66\_send\_cmd\_AT
  - bc66\_drv.c, [12](#)
  - bc66\_drv.h, [23](#)
- bc66\_set\_echo\_mode
  - bc66\_drv.c, [13](#)
  - bc66\_drv.h, [23](#)
- bc66\_set\_eps
  - bc66\_drv.c, [13](#)
  - bc66\_drv.h, [23](#)
- bc66\_set\_mobile\_bands
  - bc66\_drv.c, [13](#)
  - bc66\_drv.h, [24](#)
- bc66\_set\_mqtt\_parameters
  - bc66\_drv.c, [14](#)
  - bc66\_drv.h, [24](#)
- bc66\_set\_nbiot\_event\_report
  - bc66\_drv.c, [14](#)
  - bc66\_drv.h, [25](#)
- bc66\_set\_power\_saving\_mode
  - bc66\_drv.c, [15](#)
  - bc66\_drv.h, [25](#)
- bc66\_set\_psd\_conn
  - bc66\_drv.c, [15](#)
  - bc66\_drv.h, [26](#)
- bc66\_set\_sleep\_mode
  - bc66\_drv.c, [16](#)
  - bc66\_drv.h, [26](#)
- cmd
  - bc66\_at\_cmd\_t, [2](#)
- CMD\_END\_LINE
  - bc66\_drv.c, [8](#)
- cmd\_flags
  - bc66\_at\_cmd\_t, [2](#)
- cmd\_flg\_t
  - bc66\_drv.c, [9](#)
- cmd\_rsp
  - bc66\_at\_cmd\_t, [3](#)
- control\_lines
  - bc66\_obj\_t, [4](#)
- EXE
  - bc66\_drv.c, [9](#)
- func\_delay
  - bc66\_obj\_t, [4](#)
- func\_init\_ptr
  - bc66\_obj\_t, [5](#)
- func\_r\_bytes\_ptr
  - bc66\_obj\_t, [5](#)
- func\_w\_bytes\_ptr
  - bc66\_obj\_t, [5](#)
- MAX\_RSP\_SIZE
  - bc66\_drv.c, [8](#)
- MDM\_PSM\_EINT\_N
  - bc66\_obj\_t, [5](#)
- MDM\_PWRKEY\_N
  - bc66\_obj\_t, [5](#)
- MDM\_RESET\_N
  - bc66\_obj\_t, [5](#)
- MDM\_RI
  - bc66\_obj\_t, [5](#)
- pdp\_type\_ip
  - bc66\_drv.h, [20](#)
- pdp\_type\_ipv4v6
  - bc66\_drv.h, [20](#)
- pdp\_type\_ipv6
  - bc66\_drv.h, [20](#)
- pdp\_type\_non\_ip
  - bc66\_drv.h, [20](#)
- pdp\_type\_t
  - bc66\_drv.h, [20](#)
- READ
  - bc66\_drv.c, [9](#)
- RSP\_END\_OF\_LINE
  - bc66\_drv.c, [9](#)
- RSP\_ERROR
  - bc66\_drv.c, [9](#)
- RSP\_NO\_CMD\_IMPEMENTED
  - bc66\_drv.c, [9](#)
- RSP\_OK
  - bc66\_drv.c, [9](#)
- RSP\_TIMEOUT
  - bc66\_drv.c, [9](#)
- rsp\_timeout
  - bc66\_at\_cmd\_t, [3](#)
- TEST
  - bc66\_drv.c, [9](#)



## WRITE

bc66\_drv.c, [9](#)