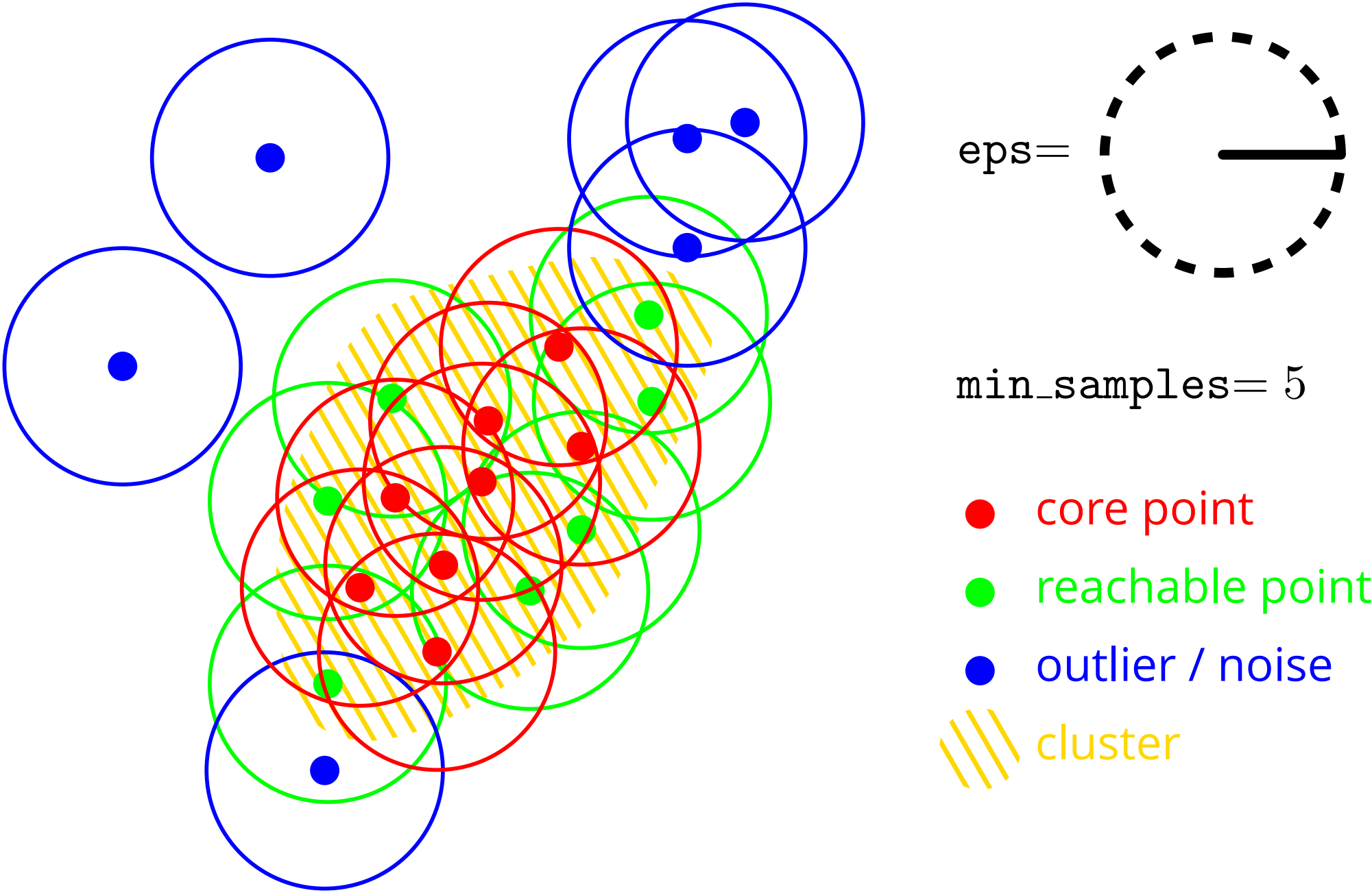
eps=
min_samples= 5
core point
reachable point
outlier / noise
cluster