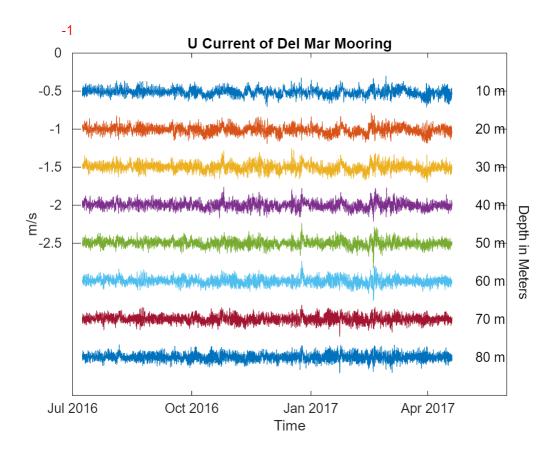
```
clear
close all
load DelMar_data.mat
whos
```

```
Bytes Class
                                                  Attributes
Name
              Size
                                109456 double
              1x13682
Т
readme
              1x93
                                  186 char
          13682x1
                                109456 datetime
t
              8x13682
                                875648 double
V
              8x13682
                                875648 double
              8x1
                                   64 double
Z
```

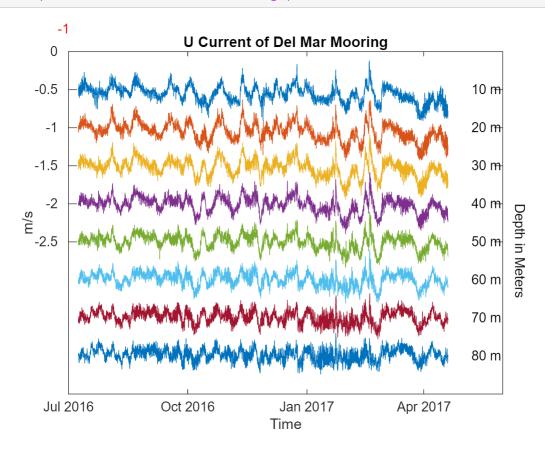
## Plot time series of u (positive east, Figure 1) current components for all depths.

```
figure(1);
clf;
for i = 1:height(u)
    plot(t,u(i,:)+z(i)*0.05);
    text(t(end)+18,-(i-1)*.5-.5,[num2str(abs(z(i))),' m'])
    hold on
end
text(t(1)-15,2.5-1.3,[num2str(1)], 'Color', 'r')
text(t(1)-16,1.5-1.2,[num2str(-1)], 'Color', 'r')
hold off;
datetick;
h = text(t(end)+55,-3*.5-.5, 'Depth in Meters');
set(h, 'Rotation', 270);
set(gca, 'YTick', -2.5:0.5:3.5);
set(gca, 'YTickLabel', num2str((-2.5:0.5:3.5)'));
xlabel('Time')
datetick('x', 'mmm yyyy', 'keeplimits');
ylabel('m/s')
title('U Current of Del Mar Mooring')
```



## Plot time series of v (positive north, Figure 2) current components for all depths.

```
figure(2);
clf
for i = 1:height(v)
    plot(t,v(i,:)+z(i)*0.05);
    text(t(end)+18,-(i-1)*.5-.5,[num2str(abs(z(i))),' m'])
    hold on
end
text(t(1)-15,2.5-1.3,[num2str(1)], 'Color', 'r')
text(t(1)-16,1.5-1.2,[num2str(-1)], 'Color', 'r')
hold off;
datetick;
h = text(t(end)+55,-3*.5-.5, 'Depth in Meters');
set(h, 'Rotation', 270);
set(gca, 'YTick', -2.5:0.5:3.5);
set(gca, 'YTickLabel', num2str((-2.5:0.5:3.5)'));
xlabel('Time')
datetick('x', 'mmm yyyy', 'keeplimits');
ylabel('m/s')
```



## Q1: Describe qualitatively the time-depth variability of u and v.

The time-depth variability of the u and v current components shows consistent oscillations with some fluctuations across the depths (10–80 m) from July 2016 to May 2017. Both components display consistent wave-like amplitude fluctuations, with the currents closer to the surface responding more visibly to atmospheric forces, while deeper currents show a more damped or delayed response, possibly due to reduced energy transfer. At times, bursts of stronger currents occur. Overall, the current patterns are mostly uniform.

## Compute EOFs of the combined u and v currents.

Plot the mode number (x-axis) vs the percentage of total variance explained by each mode (y-axis) (Figure 3).

```
combined_data = [u; v];
C = cov(combined_data'); % Transpose to get time series as columns

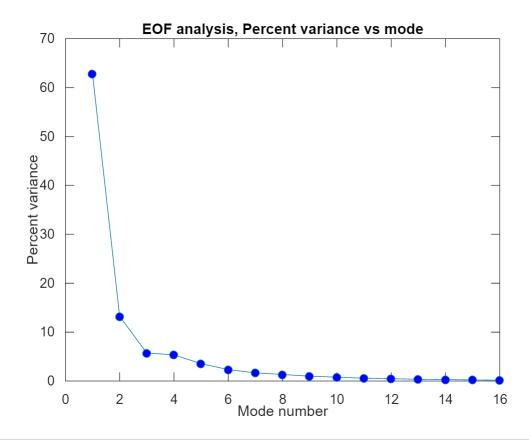
% Perform EOF analysis (Eigen decomposition)
[eigenvectors, eigenvalues] = eig(C);
lambda = diag(eigenvalues); % Extract eigenvalues into a vector

% Sort eigenvalues and corresponding eigenvectors in descending order
[lambda, sorted_indices] = sort(lambda, 'descend');
```

```
eigenvectors = eigenvectors(:, sorted_indices);

percent_var = (lambda / sum(lambda)) * 100;

figure(3);
plot(1:length(percent_var), percent_var, '-o', 'MarkerFaceColor', 'b');
xlabel('Mode number');
ylabel('Percent variance');
title('EOF analysis, Percent variance vs mode');
xlim([0 16]);
```



# Plot the PCs (temporal expansions) of the first 4 modes and indicate the total variance explained by each mode (Figure 4).

```
PCs = eigenvectors'* combined_data;

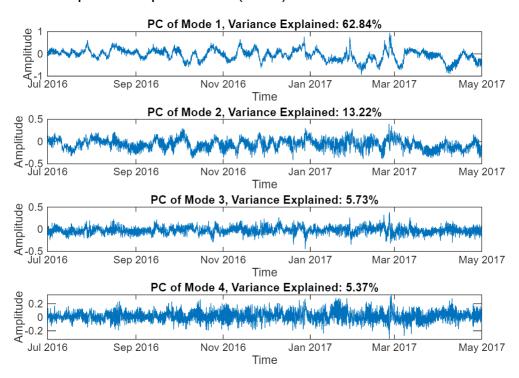
start_date = datetime(2016, 7, 1);
end_date = datetime(2017, 5, 1);
time_vector = linspace(start_date, end_date, size(PCs, 2));

figure(4);
for i = 1:4
    subplot(4, 1, i); % Subplots for each mode
    plot(time_vector, PCs(i, :));
```

```
title(['PC of Mode ' num2str(i) ', Variance Explained: '
num2str(percent_var(i), '%.2f') '%']);
    xlabel('Time');
    ylabel('Amplitude');
end

sgtitle('Temporal Expansions (PCs) of the First 4 Modes');
```

# Temporal Expansions (PCs) of the First 4 Modes



## Plot u and v EOF amplitudes vs depth for the first 4 modes (Figure 5).

```
num_modes = 4;
num_depths = size(u, 1);
depth = linspace(-10, -80, num_depths);

u_eof_amp = eigenvectors(1:num_depths, 1:num_modes); % u EOFs for the first 4 modes
v_eof_amp = eigenvectors(num_depths+1:end, 1:num_modes); % v EOFs for the first 4
modes

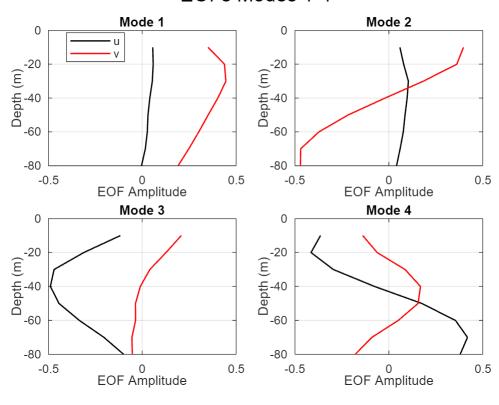
figure (5);
for i = 1:num_modes
    subplot(2, 2, i); % 2x2 grid
    plot(u_eof_amp(:, i), depth, 'k-', 'LineWidth', 1, 'DisplayName', 'u');
    hold on;
    plot(v_eof_amp(:, i), depth, 'r-', 'LineWidth', 1, 'DisplayName', 'v');
    hold off;
```

```
set(gca, 'YDir', 'normal');
xlabel('EOF Amplitude');
ylabel('Depth (m)');
title(['Mode ' num2str(i)]);
xlim([-0.5, 0.5]);
grid on

% Add legend only for the first subplot
if i == 1
    legend('show', 'Location', 'best');
end
end

sgtitle('EOFs Modes 1-4');
```

## EOFs Modes 1-4



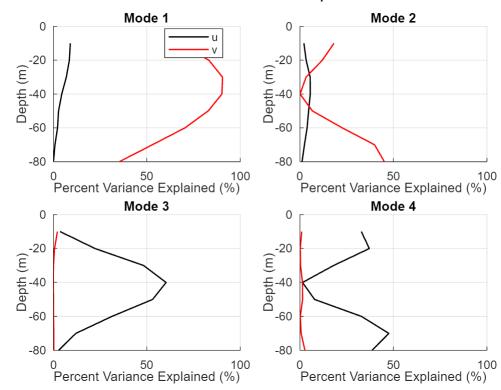
## Plot the percent of and u and v variance explained at each depth for the first 4 modes (Figure 6)

```
Cu=diag(C(1:8,1:8));
Cv=diag(C(9:16,9:16));

figure(6);
clf
for i = 1:4
    u_percent_var(:,i) = u_eof_amp(:,i).^2 * lambda(i)./Cu * 100;
```

```
v_percent_var(:,i) = v_eof_amp(:,i).^2 * lambda(i)./Cv * 100;
    subplot(2, 2, i); % 2x2 grid
    hold on;
    plot(u_percent_var(:, i), depth, 'k-', 'LineWidth', 1, 'DisplayName', 'u'); %
Plot u variance
    plot(v_percent_var(:, i), depth, 'r-', 'LineWidth', 1, 'DisplayName', 'v'); %
Plot v variance
    hold off;
    set(gca, 'YDir', 'normal');
    xlabel('Percent Variance Explained (%)');
   ylabel('Depth (m)');
   title(['Mode ' num2str(i)]);
    xlim([0, 100]);
    grid on
   % Add legend only for the first subplot
        legend('show', 'Location', 'best');
    end
end
sgtitle('Percent Variance at Each Depth for 4 Modes');
```

## Percent Variance at Each Depth for 4 Modes



What current patterns are captured in the first 4 modes? Q2: What do the EOF modes tell you about the time-depth variability of u and v?

- **Mode 1**: The u component shows that as depth increases, the amplitude gradually decreases, indicating a greater influence near the surface. The v component shows an increase in amplitude near the surface (0 to -20m), but then a decrease as the depth increases.
- **Mode 2**: The u component maintains a consistent amplitude as depth increases. The v component, however, shows a significant decrease in amplitude as depth increases.
- **Mode 3**: The u component decreases in amplitude from the surface to a depth of 40 m, then increases from 40 m to 80 m. The v component shows a consistent decrease in amplitude as depth increases.
- **Mode 4**: The u component shows a consistent increase in amplitude as depth increases. The v component initially increases in amplitude from the surface to 40 m, then decreases from 40 m to 80 m.