EECS373

Lab5

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For this lab, I made changes to my launch file and try to allow users to choose whether they want to run lab5.xacro or robot.xacro. However, I encounter some difficulties and I cannot get my launch work. I think the logic of my launch file code is correct. Then I added the lasers in the rviz and save the changes in config file. Finally, I think my virtual box does not have map\_server. I cannot run all of the code related to map\_server in my terminal. It keeps saying “package map\_server not found”.