Algorithmn HW7

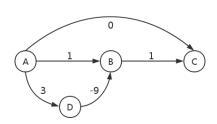
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Problem 8.16

Just change the RELAX part to store the best predecessor of the vertex, and later we can find the shortest path iterately.

- 1: **procedure** Relax(u, v)
- 2: **if** d[v] > d[u] + w(u, v) **then**
- 3: $d[v] \leftarrow d[u] + w(u, v)$
- 4: $pred[v] \leftarrow u$
- 5: end if
- 6: end procedure

Problem 8.19



Considering this case, Dijkstra works like this:

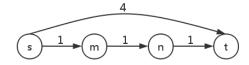
- (1) Starting from A, set d(A) = 0 and $d(others) = +\infty$;
- (2) A out, set d(B) = 1, d(C) = 0 and d(D) = 3;
- (3) C out, with no successor edge;
- (4) B out, with no change (1+1>0);
- (5) D out, updating d(B) = -6, then terminate.

Obviously, d(C) should be -5 instead of 0 in this case, which shows Dijkstra does not work in this case.

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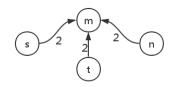
True or False

(a) **False**, originally it's $s \to m \to n \to t$ but after modification it will be $s \to t$



s t t

(b) False, in the DAG on the right, Dijkstra starting at m definitely won't pick vertexes as any of the topological orders.



- (c) False, because in that case, the short path would be either (1) modified to other path-that won't change-or (2) remain the same path-that will increase the short path by exactly x
- (d)**True**, because Bellman-Ford will search every possible edge for every vertex regardless of the order, so it will update later if there is some negative value.

Paths in DAG

```
Require: a DAG G = (V, S)
Ensure: the number of paths in G
 1: procedure COUNTPATH(G)
        topologically sort G.V
        p[s] \leftarrow 1, p[\text{other } v \in G.V] \leftarrow 0
                                                                               \triangleright p[] stores the number of paths
 3:
        for each vertex i in topological sorted sequence do
 4:
            for each vertex j connected with i do
               p[j] \leftarrow p[j] + p[i]
                                                        ▶ The last element will be the total number of paths
 6:
 7:
            end for
        end for
 9: end procedure
We can have the relationship as follows:
initial(u) = u is the last element in topo order? 1:1 + \sum_{(u,v) \in E} u
path(u) = initial(u) + \sum_{(u,v) \in E} path(v)
Since path(u) and initial(u) can be computed in linear time, the algorithm takes O(V+E) time
```

Shortest path tree

17: return True

```
Require: directed graph G = (V, E), a tree T = (V, E'), s \in V and E' \in E
Ensure: whether T is the shortest-path tree of G starting with s
 1: Q \leftarrow [s]
 2: while Q is not empty do
                                                                                              u = Q.pop()
                                                                                      \triangleright Q is a priority queue
 3:
       for each edge (u, v) \in E' do
 4:
           d[v] = d[u] + w(u, v)
                                                                               \triangleright d[] keeps the shortest paths
 5:
           Q.push(v)
 6:
           remove (u, v) from E'
 7:
       end for
 9: end while
10: for each edge (u, v) \in E do
                                                                 ▷ check in the graph whether it is shortest
       temp \leftarrow d[v]
11:
12:
       Relax(u, v)
                                                                ▷ compare the value before and after Relax
       if temp \neq d[v] then
13:
           return False
14:
       end if
15:
16: end for
```