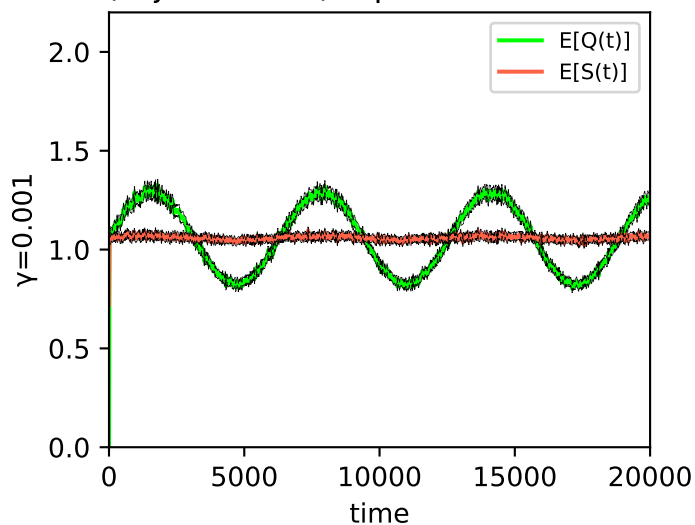


$G_t/G_t/1/PS$, Target sojourn time = 1.0, Arrival=Erlang, Service=Erlang

(sojourn time) Square-root control



Proportional difference control

