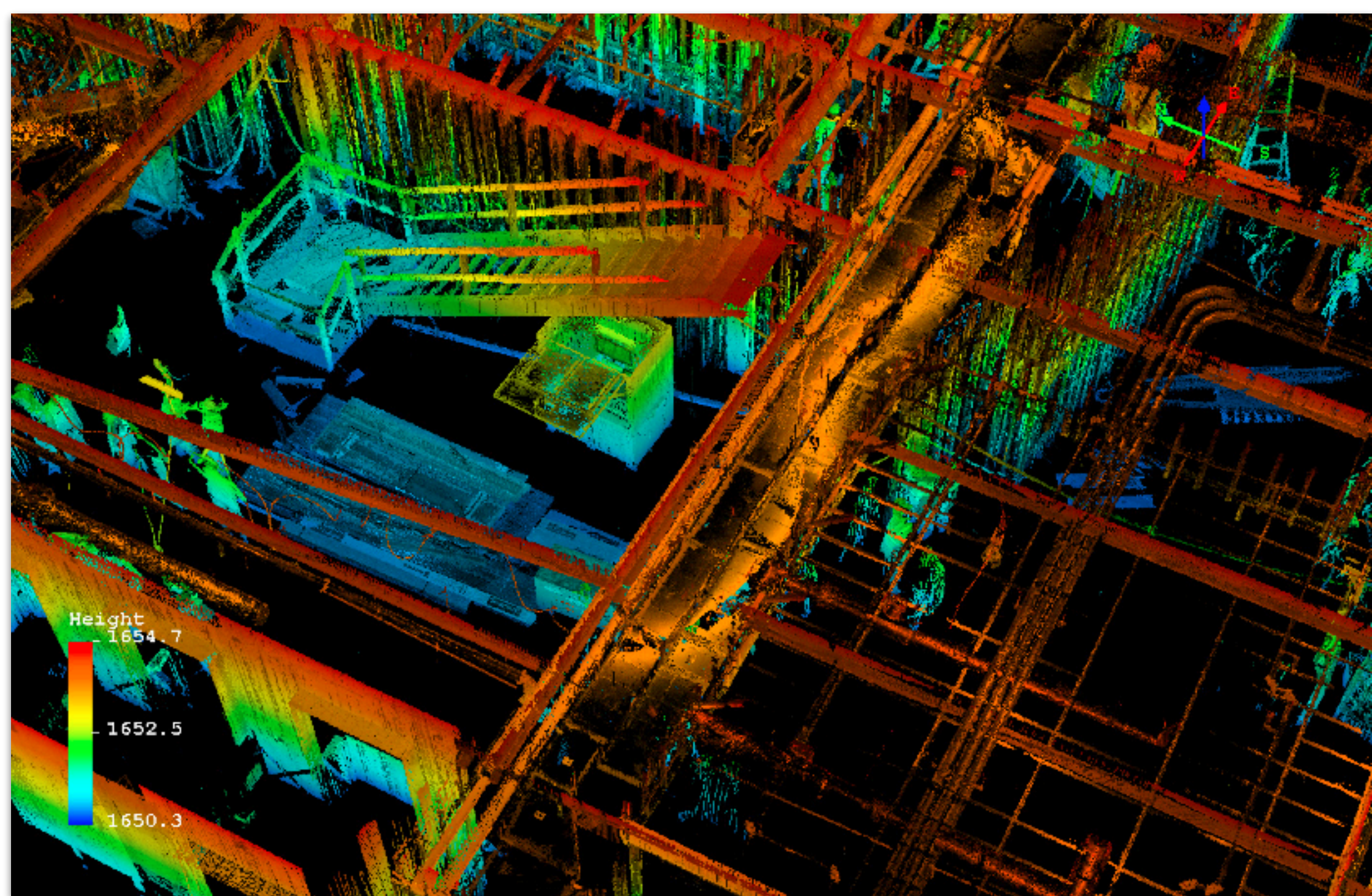


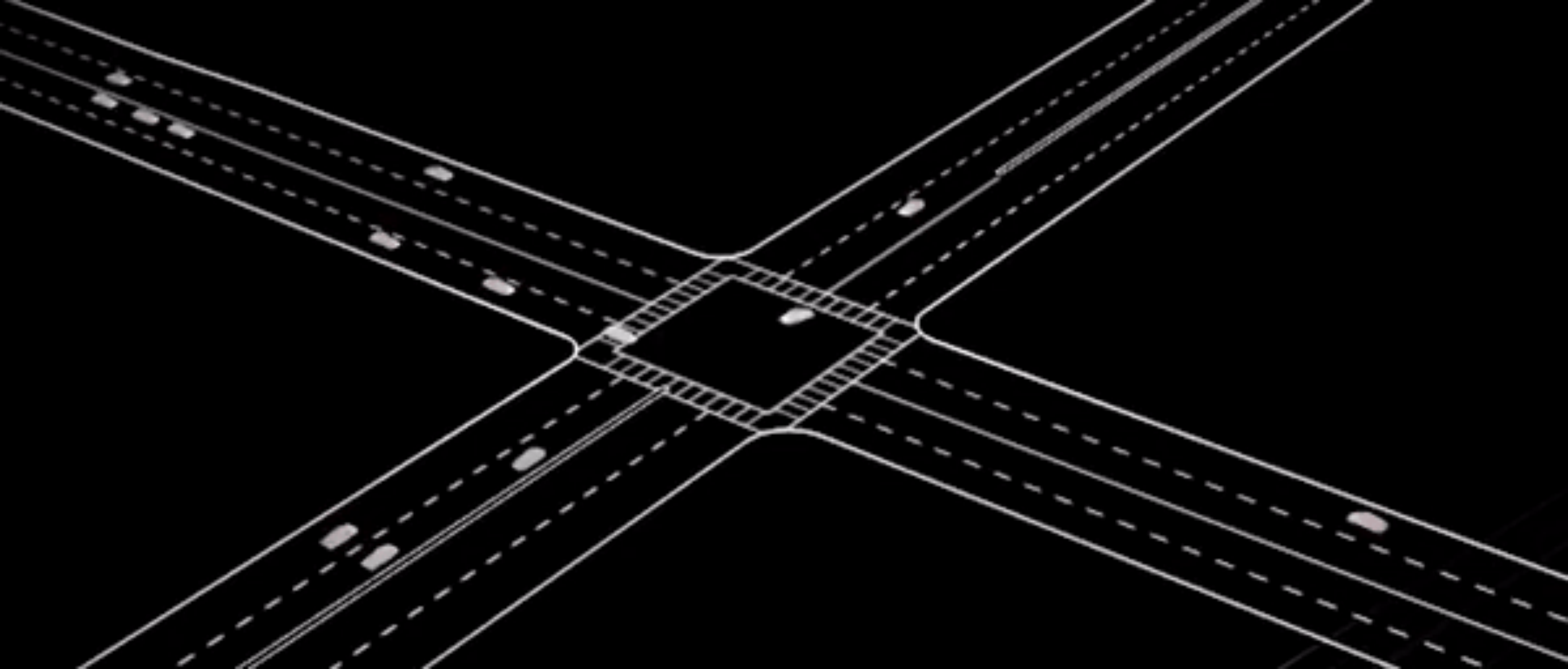
Notivatiön

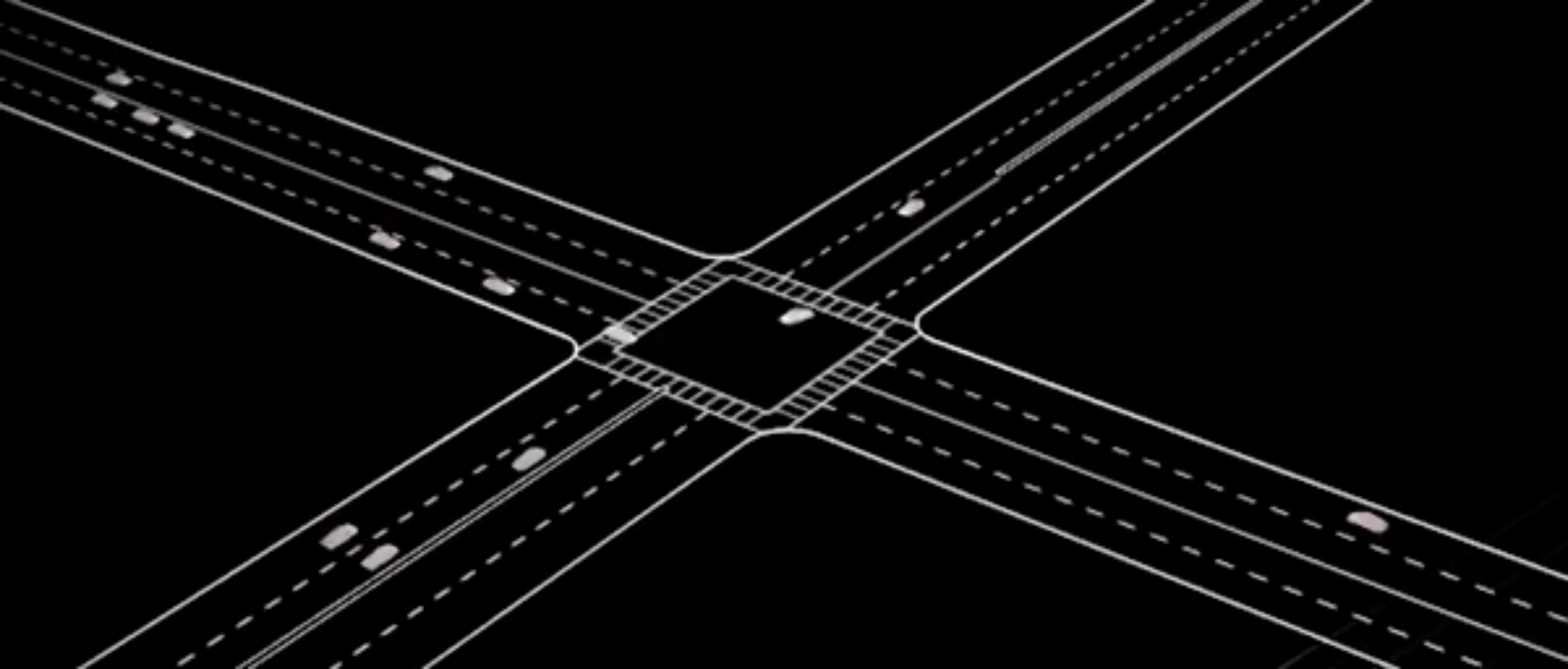


Collaborative Search & Rescue

Collaborative Self Driving

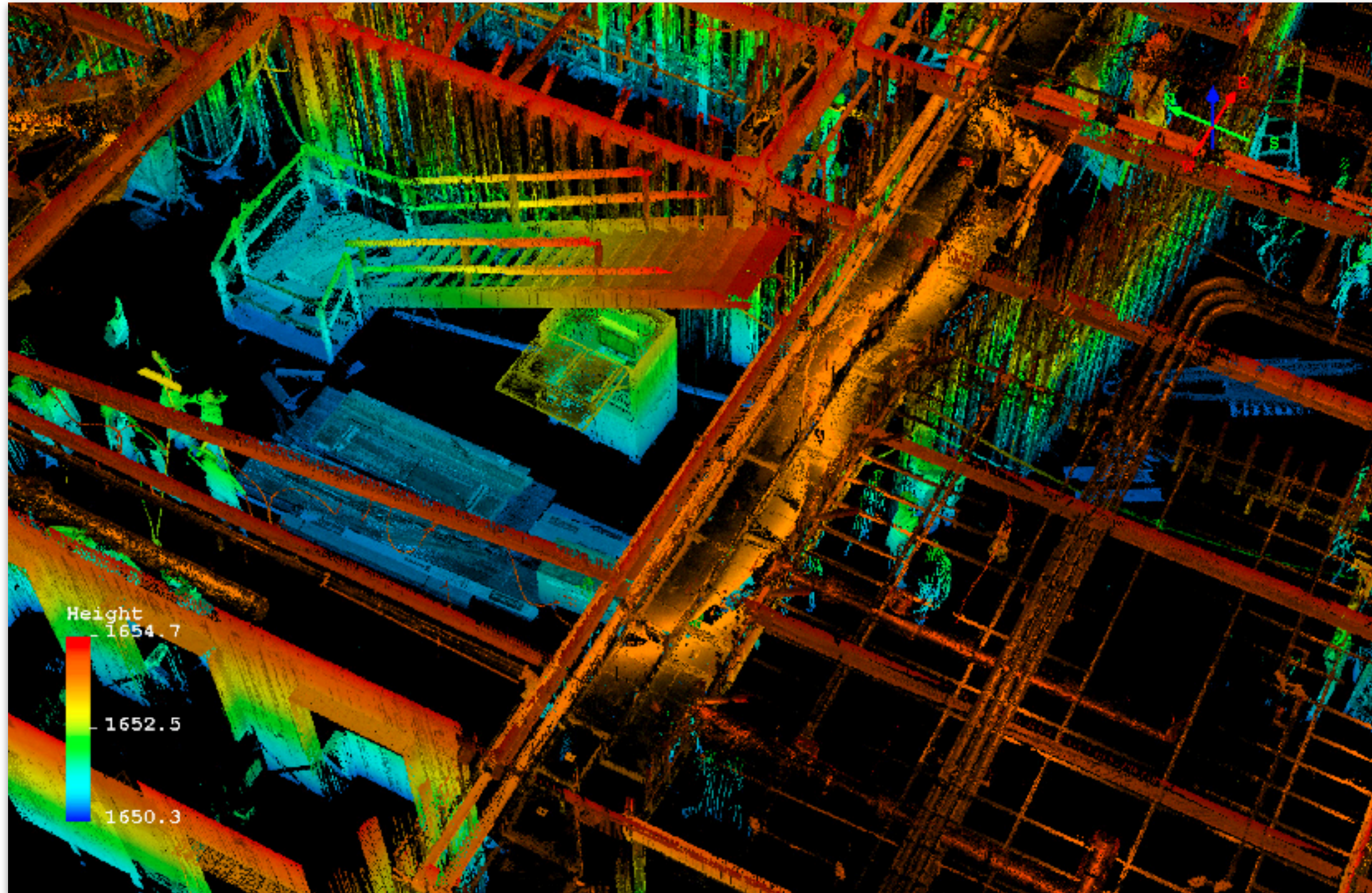




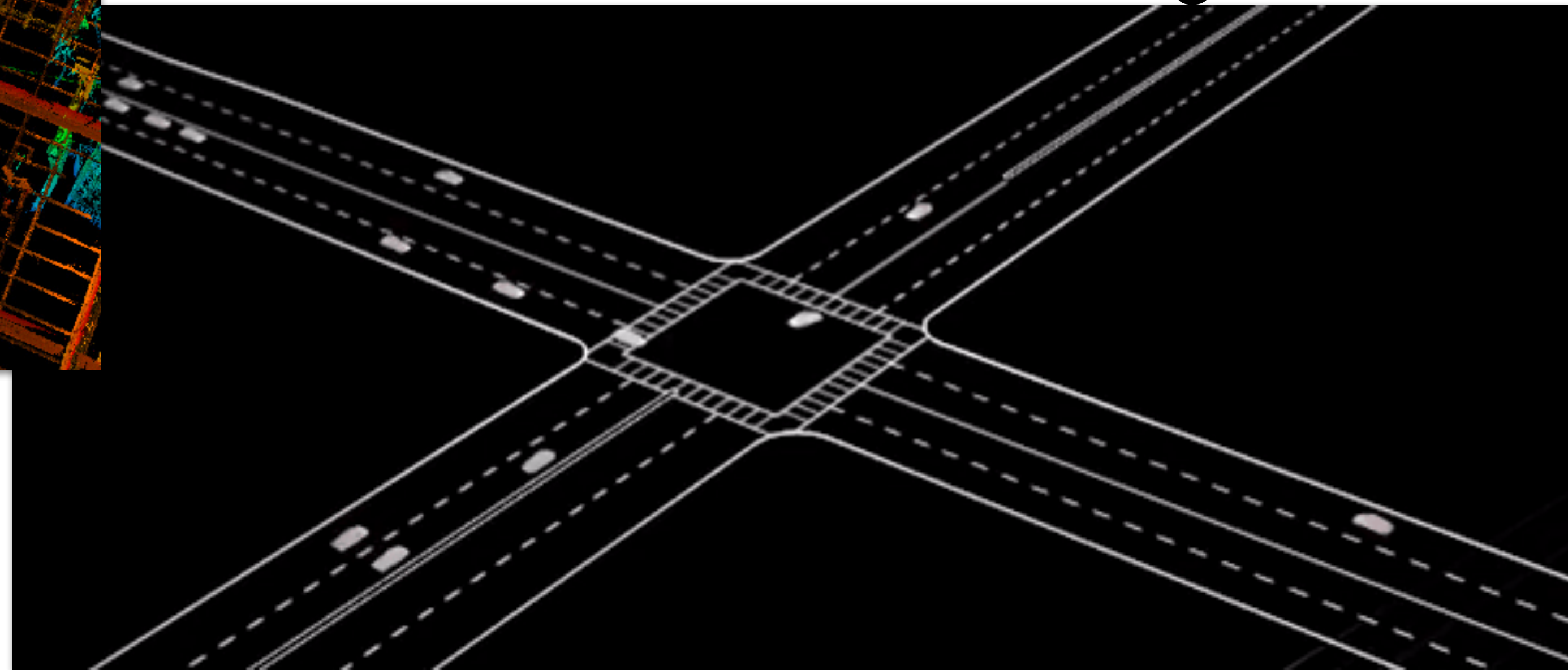


Motivation

Collaborative Search & Rescue



Collaborative Self Driving



Starting Point: ORB-SLAM 3

ORB-SLAM3 as foundation
(cutting edge single agent slam)

“Cutting Edge”

- Doesn't compile
- 50,000+ lines of spaghetti c++
- Multithreaded
- No memory management

