



A Bachelor of Science thesis

Super Learners

and their oracle properties

Jinyang Liu

Supervised by Prof. Thomas Gerds
Co-supervised by Prof. Niels Richard Hansen
Department of Mathematical Sciences
University of Copenhagen, Denmark

Submitted: May 27, 2023

Contents

1	Introduction	3
2	Background	4
2.1	Learning algorithms and learners	5
3	The Discrete Super Learner	6
3.1	Library of learners	6
3.2	Cross-validation methodology	7
3.3	K-fold cross validation	7
3.4	Risks and selectors	8
3.5	Discrete super learner	9
3.6	Oracle property	9
4	The Ensemble Super Learner	13
4.1	Level 1 data	13
4.2	Meta learners	14
4.3	Ensemble super learner	14
4.4	Oracle property	14
4.5	Choice of meta learning algorithm	16
5	Simulations	17
5.1	The discrete super learner	20
5.2	The ensemble super learner	24
5.3	Discussion	24
6	Appendix	25
6.1	Proof of lemma 10	25

1 Introduction

In the context of regression, $O = (Y, X)$ is an observation for $Y \in \mathbb{R}$ being the outcome and $X \in \mathbb{R}^d$ the covariate. A natural goal is to estimate a regression function θ such that the L^2 -risk or mean squared error $E(Y - \theta(X))^2$ is minimized. It turns out that the conditional mean – called the regression function or regression $x \mapsto E(Y \mid X = x)$ minimizes the squared error, but consistent estimation of the regression requires us to specify a statistical model \mathcal{P} for the data-generating distribution $P \in \mathcal{P}$ for which $O \sim P$. We typically make certain assumptions about the statistical model, \mathcal{P} , in which we believe P resides. For instance, we might assume that \mathcal{P} is a parametric family of distributions, for example a curved exponential family (Lauritzen 2023). In doing so we are able to identify the parameters of the distribution P via maximum likelihood and compute the regression from the estimated parameters.

However, if we are dealing with complex data, there is a risk of misspecifying the model by identifying it as an exponential family. Our assumptions may be wrong. In such situations, it is tempting to utilize non-parametric and data-driven regression methods, such as tree-based algorithms like XGBoost or random forests. Machine learning methods seek to estimate regression function directly, in contrast to parametric statistics where the parameters of the underlying model are estimated first, then a regression function derived as some analytical expression of these parameters and the covariates. The assumptions of these machine learning methods regarding the data-generating distribution are not explicitly specified, but it does not pose a problem for us in achieving our goal. Indeed, it is not necessary for us to identify P completely if P can be factored into the conditional distribution $P_{Y|X}$ and the distribution over our covariates P_X , here our goal of estimating the regression function is to estimate $P_{Y|X}$.

Given an abundance of different ways we can tackle the problem of estimating the regression, we would like to be able to compare the different methods select the best one. In a practical scenario we might have set of different learning algorithms from which we can choose from. Cross-validation can then help determine the risk of each algorithm by splitting the data into training and validation sets, each algorithm would then be fitted on the training set and an empirical risk for each fitted model is then calculated by evaluating the model on the validation set. We would run cross-validation using a predefined splitting mechanism for each learning algorithm that we have. A popular choice in machine learning and statistics is K -fold cross-validation. K -fold cross-validation divides the data into K disjoint and exhaustive sets referred to as validation sets. For every $k = 1, \dots, K$ the learning algorithm is trained using all data excluding the k 'th validation set. Subsequently, the risk of the fitted model is computed by applying it on the validation set that was held out from training. We obtain an estimate of the true risk of the model by repeating this procedure K times and then averaging the risks. The model with the lowest risk is then selected as our candidate estimate of the regression function.

This is the idea behind the cross-validation selector (Laan and Dudoit 2003). The discrete super learner (Laan, Polley, and Hubbard 2007) is simply the learner (fitted model) that is created by applying the result of the cross-validation selector to our data. The cross-validation selector, given a library of learning algorithms and our data, applies cross-validation to each algorithm in the library.

Another method, called the ensemble super learner (Laan, Polley, and Hubbard 2007) seeks to combine the learning algorithms into a single learner by applying a *meta learning algorithm* on the library. One way to fit the ensemble super learner is by taking a weighted average of the each learner, where the weights are chosen to minimize the risk of the

ensemble. A prediction made by an ensemble super learner will then be a weighted sum of the predictions made by the individual learners.

As we will demonstrate in this thesis, given a library of learning algorithms, the super learner is effectively the best estimate of the data-generating regression that we can obtain. It is the best in the sense that it can not perform worse than the best learner created from our library in terms of risk.

To formalize the notion of the best learner in the library, we will define the oracle selector. The oracle selector knows P – hence it is called the oracle – and selects the learner with the lowest risk relative to P . In this thesis we demonstrate that the cross-validation selector is asymptotically equivalent to the oracle selector.

Our setup and notation is similar to Vaart, Dudoit, and Laan 2006 and Laan and Dudoit 2003. The focus in the thesis will to demonstrate the effectiveness of the super learner applied to binary regression. More specifically, we focus on the case where we regress on a binary outcome $Y \in \{0, 1\}$. The conditional expectation of Y given X exactly becomes the conditional probability $P(Y = 1 \mid X = x)$. The simulation results in section 5 shows that the super learner is able to achieve the minimum risk as the number of training samples increases. The simulation is conducted by first defining the data-generating distribution explicitly, from which we can sample from using standard sampling methods that are available in R. We evaluate a collection of learning algorithms, including logistic regression and XGBoost. From this library, we create the super learner and compare its performance against the individual algorithms.

The choice to focus on binary regression stems from its significance in various fields. For instance, in biomedicine, researchers might want to predict patient mortality upon administering a specific drug. The survival indicator for the patient is a binary outcome, and the regression $P(Y = 1 \mid X = x)$ could represent the probability of the patient’s survival.

2 Background

Our setup and notation is similar to Vaart, Dudoit, and Laan 2006 and Laan and Dudoit 2003: Let a statistical model \mathcal{P} be given on the measurable space $(\mathcal{O}, \mathcal{A})$ where $\mathcal{O} = \{0, 1\} \times \mathcal{X}$ is our sample space for some $\mathcal{X} \subseteq \mathbb{R}^d$. We will consider the parameter set $\Theta = \{\theta \mid \theta : \mathcal{X} \rightarrow [0, 1]\}$, which represents the set of *regression functions* that map from our covariates to the probability interval. We define the quadratic loss and the corresponding risk that we wish to minimize.

Definition 1 (Quadratic loss). The quadratic loss or L^2 -loss, $L : \mathcal{O} \times \Theta \rightarrow [0, \infty)$, for an observation $o \in \mathcal{O}$ and a regression function $\theta \in \Theta$ is defined as

$$L(o, \theta) = L((y, x), \theta) = (y - \theta(x))^2.$$

A natural aim would be to find the optimal parameter value $\theta^* \in \Theta$ that minimizes the expected L^2 -loss, or conditional risk $R : \theta \rightarrow \mathbb{R}$ given by

$$R(\theta, P) := \int L(o, \theta) dP(o). \tag{1}$$

Theorem 2 shows that the minimum risk is achieved by the conditional probability $x \mapsto P(Y = 1 \mid X = x)$.

Theorem 2. Let $(\mathcal{O}, \mathcal{A}, P)$ be a probability space for some probability measure $P \in \mathcal{P}$. Let Θ be the set of regression functions of the form $\theta : \mathcal{X} \rightarrow [0, 1]$. Let the loss function be the L^2 -loss $L(o, \theta) = (y - \theta(x))^2$, then for the optimum θ^* defined as

$$\theta^* := \arg \min_{\theta \in \Theta} R(\theta, P) = \arg \min_{\theta \in \Theta} \int L(o, \theta) dP(o),$$

it holds for an observation $O = (Y, X) \sim P$ that

$$\theta^*(x) = E(Y \mid X = x).$$

Proof. Proof emulated from (Györfi et al. 2002)[ch. 1].

Let $\theta \in \Theta$ be arbitrary and $m(x) = E(Y \mid X = x)$, we have

$$\begin{aligned} E|\theta(X) - Y|^2 &= E|\theta(X) - m(X) + m(X) - Y|^2 \\ &= E|\theta(X) - m(X)|^2 + E|m(X) - Y|^2 + 2E[(\theta(X) - m(X))(m(X) - Y)]. \end{aligned}$$

We see that the last term is zero, see that by using the tower rule we have

$$\begin{aligned} E[(\theta(X) - m(X))(m(X) - Y)] &= E[E[(\theta(X) - m(X))(m(X) - Y) \mid X]] \\ &= E[(\theta(X) - m(X))E((m(X) - Y) \mid X)] \\ &= E[(\theta(X) - m(X))(m(X) - E(Y \mid X))] \\ &= E[(\theta(X) - m(X))(m(X) - m(X))] \\ &= 0. \end{aligned}$$

We conclude that

$$\int L(o, \theta) dP(o) = E|\theta(X) - m(X)|^2 + E|m(X) - Y|^2.$$

The first term after the equality is always positive and is 0 only when $\theta = m$, this proves that m minimizes the expression above. \square

It follows immediately that if Y is binary, then $E(Y \mid X = x) = P(Y = 1 \mid X = x)$. As we do not have access to the data-generating distribution P , our goal is to estimate θ^* , this means to *learn* the true regression function from our data. We will therefore introduce the terminology *learning algorithm* and *learner* in the context of learning from our data.

2.1 Learning algorithms and learners

We will denote $O_1, \dots, O_n \in \mathcal{O}$ and $D_n = (O_1, \dots, O_n)$ as our observations and data respectively.

Definition 3 (Learning algorithm). A learning algorithm is a measurable map $\psi : \mathcal{O}^n \rightarrow \Theta$ for $n \in \mathbb{N}$.

We will throughout assume that the learning algorithm is well defined for each $n \in \mathbb{N}$, and that permuting the observations have no effect on the outcome, i.e., the algorithm is symmetric in the observations.

Definition 4 (Learner (or fitted learner)). Given a learning algorithm ψ . A learner is a stochastic variable in Θ representing the outcome of applying the learning algorithm to our data $\theta = \psi(D_n)$.

Formally $\psi(D_n)$ is a stochastic variable since D_n is stochastic. In practice, we would have observed $O_1 = o_1, \dots, O_n = o_n$, and can then apply our learning algorithm on the observed data. In machine learning, the procedure of applying an algorithm on the data is referred to as *model training* or *fitting*, the outcome of the training is a *trained model* or simply a *fit*. We will refer to the trained model as a learner which naturally depends on our data that we have observed.

Example 1 (Parametric and nonparametric learning algorithms). An example of a parametric learning algorithm is logistic regression. In logistic regression we assume that the conditional probability, $P(Y = 1 \mid X = x)$, can be expressed as $\theta(x) = \text{expit}(\beta x)$ for some $\beta \in \mathbb{R}^d$. The parameter β can be estimated via maximum likelihood.

Nonparametric learning algorithms such as gradient boosting – most notably XGBoost – can also be used to estimate the regression function. XGBoost has a number of hyperparameters that can be tuned. These parameters include the number of boosted trees, depth of each tree, learning rates, and others. However, the most critical parameter is the internal loss objective which could for example be log-loss or mean squared error. XGBoost aims to iteratively refine the fitted learner by approximating the data $x \mapsto f_m(x)$ at each step m . It does so by introducing a new tree $h_m(x)$, which is trained on the error of $f_m(x)$, such that $f_{m+1}(x) = f_m(x) + h_m(x)$. The internal loss of the updated learner, f_{m+1} , evaluated on the training data, is lower than that of the previous learner due to the inclusion of the new tree (Chen and Guestrin 2016). The parameters of the fitted XGBoost are not directly interpretable. Despite this, XGBoost has demonstrated its ability to model very complex datasets (Chen and Guestrin 2016).

We will denote the empirical measure obtained from the data D_n as

$$P_n(A) = \frac{1}{n} \sum_{i=1}^n \delta_{O_i}(A) \quad \text{for } A \in \mathcal{A},$$

where δ_{O_i} is the Dirac measure over O_i . When the observations are independent and identically distributed, then there is a one-to-one correspondence between the empirical measures obtained from n observations and D_n . We can, therefore, write $\psi(P_n)$ as an alternative representation of the learner $\psi(D_n)$, by adjusting the notation slightly without introducing ambiguity. The motivation for using this notation will become clearer in the subsequent section, where we introduce the discrete super learner.

3 The Discrete Super Learner

3.1 Library of learners

We would now like to consider the scenario where we have a set of learning algorithms, ψ_1, \dots, ψ_k . From these algorithms, we can define the *library of learning algorithms*

$$\Psi = \{\psi_q \mid 1 \leq q \leq k\},$$

of size k . Our natural goal is to find $\tilde{\psi} \in \Psi$ such that $\tilde{\psi}(P_n)$ that achieves the lowest risk among our learners

$$\tilde{\psi} = \arg \min_{\psi \in \Psi} R(\psi(P_n), P).$$

However, we cannot compute the risk of a learner directly as it depends on P . We seek to provide an estimate for $\tilde{\psi}$ which we will denote as $\hat{\psi}$.

3.2 Cross-validation methodology

To provide the estimate $\hat{\psi}$ we will proceed via cross validation. Cross-validation randomly splits our data into a *training set* and a *test set* that our algorithms are trained and evaluated on. Let the random binary vector – referred to as the *split variable* or just *split* – $S^n = (S_1^n, \dots, S_n^n) \in \{0, 1\}^n$ be independent of D_n such that $S_i^n = 0$ indicates that O_i should be in the training set and $S_i^n = 1$ indicates that O_i belongs to the test set. The split S^n depends on n as it is formally a tuple in $\{0, 1\}^n$, here the superscript n is used to indicate that. We can define the empirical distributions over these two subsets, P_{n,S^n}^0 and P_{n,S^n}^1 as

$$P_{n,S^n}^0 = \frac{1}{n_0} \sum_{i:S_i^n=0} \delta_{O_i}$$

$$P_{n,S^n}^1 = \frac{1}{n_1} \sum_{i:S_i^n=1} \delta_{O_i},$$

where $n_1 = \sum_{i=1}^n S_i^n$, $n_0 = 1 - n_1$ identifies the number of observations in the test and training set respectively.

Example 2 (Random splits). For n observations we have 2^n ways of choosing which observations should be in the training set and in the test set. It might not be desirable to define the discrete probabilities for S^n over $\{0, 1\}^n$ simply as $\frac{1}{2^n}$ for each possible combination of training/test data, since that would also include the combination where $n_1 = 0$. To ensure that there is always a certain amount of observations in our test set, let $0 < n_1 < n$ be given, we see that there are $\binom{n}{n_1}$ ways of choosing both the test and training set. We can therefore define the distribution of S^n as

$$P(S^n = s^n) = \binom{n}{n_1}^{-1} \quad \text{for each } s^n \in \{0, 1\}^n \text{ where } \sum_i s_i^n = n_1,$$

this procedure is also known as Monte Carlo cross-validation (Laan and Dudoit 2003).

In practice one would have a hard time validating over all $\binom{n}{n_1}$ combinations as it can be very large, for $n = 100$ and $n_1 = 10$ corresponding to 10% of the data being in the validation set, the number of combinations is around $1.7 \cdot 10^{13}$. One would instead approximate by randomly sampling possible combinations. However, by doing random sampling there is the possibility that some observations will not be in any of the sampled validation sets. The probability of this happening will become lower as we sample more times.

3.3 K-fold cross validation

The idea behind K -fold cross-validation is to split the data into K equally sized folds, where the candidate learners are fitted on $K - 1$ folds and their performance is evaluated on the remaining fold. We index the folds by $s \in \{1, \dots, K\}$ and let $s(i)$ indicate the

fold that observation i belongs to. We will let $P_{n,s}^0$ denote the empirical measure over the observations that are not in fold s – the training set, and let $P_{n,s}^1$ denote the empirical measure over the observations that are in the fold s – the validation set.

K -fold cross-validation amounts to looking at a single split variable S^n whose probability mass is equally distributed on the binary vectors indexed by s . In practice one would select a K and use a random splitting procedure to generate K binary vectors such that the entire dataset is the disjoint union of the folds specified by each vector. It is also possible to run K -fold cross-validation multiple times which amounts to multiple calls to the random splitting procedure.

3.4 Risks and selectors

We now provide the formal definitions for the expected loss associated with our learners. Recall that the expected L^2 -loss (1) was the integral of the loss with respect to data-generating distribution P . Consider a learner or regression function θ . Upon observing our data D_n , we can define the empirical risk as the integral of the loss function with respect to P_n , as follows

$$R(\theta, P_n) = \int L(o, \theta) dP_n(o).$$

For example, if S^n is a split for our data D_n , the risk of our learner on the cross-validation test data can be expressed as

$$R(\theta, P_{n,S^n}^1) = \int L(o, \theta) dP_{n,S^n}^1(o).$$

The following definitions are analogous to what is stated in section 1 and 2 of (Laan and Dudoit 2003).

Definition 5 (Expected loss averaged over splits (Vaart, Dudoit, and Laan 2006)). Given the data D_n , a split-variable S^n and a library Ψ . Let $\psi \in \Psi$ be a learning algorithm. The expected loss for the learner, $\psi(P_{n,S^n}^0)$, created from applying ψ on the training data, averaged over S^n is

$$E_{S^n} R(\psi(P_{n,S^n}^0), P),$$

where P is the data-generating distribution.

The expectation E_{S^n} is a simple average since S^n is discrete. Therefore, for a given ψ we have

$$E_{S^n} R(\psi(P_{n,S^n}^0), P) = \sum_{s^n \in \{0,1\}^n} R(\psi(P_{n,s^n}^0), P) \cdot P(S^n = s^n).$$

Definition 6 (Oracle selector (Laan and Dudoit 2003)). Given the data D_n , a split variable S^n and a library Ψ , the learning algorithm $\psi \in \Psi$ with the lowest averaged expected loss is the *oracle selected algorithm* for n observations

$$\tilde{\psi}_n := \arg \min_{\psi \in \Psi} E_{S^n} R(\psi(P_{n,S^n}^0), P).$$

Estimating $\tilde{\psi}_n$ via cross-validation amounts to replacing P with P_{n,S^n}^1 in the second argument of R .

Definition 7 (Cross-validation expected loss). Given the data D_n , a split-variable S^n and a library Ψ . Let $\psi \in \Psi$ be a learning algorithm. The cross-validation expected loss for the learner, $\psi(P_{n,s}^0)$, created from applying ψ on the training data, averaged over S^n is

$$E_{S^n} R(\psi(P_{n,S^n}^0), P_{n,S^n}^1),$$

where P_{n,S^n}^1 is the test data as specified by the split-variable.

Definition 8 (Cross-validation selector (Laan and Dudoit 2003)). Given the data D_n , a split variable S^n and a library Ψ , the learning algorithm $\psi \in \Psi$ with the lowest cross-validation risk is the *cross-validation selected algorithm* for n observations

$$\hat{\psi}_n := \arg \min_{\psi \in \Psi} E_{S^n} R(\psi(P_{n,S^n}^0), P_{n,S^n}^1).$$

The oracle selector and cross-validation selector are simply what chooses a learning algorithm from the library. Alternatively, one can first define the oracle selector as the index, \tilde{q} , of the algorithm in the library with the lowest risk, then the oracle selected algorithm would naturally be $\psi_{\tilde{q}}$.

3.5 Discrete super learner

Definition 9 (Discrete super learner). The *discrete super learner*, $\hat{\psi}_n(P_n)$, created from a library Ψ is the cross-validation selected algorithm fitted to the entire dataset

$$\mathcal{X} \ni x \mapsto \hat{\psi}_n(P_n)(x).$$

Formally, the map above is a random map as P_n is stochastic. The discrete super learner is not a specific learner among the learners in the library, but the result of applying the cross-validation selector to the library.

3.6 Oracle property

We introduce the notation Pf for the integral $\int f dP$ of an integrable function f with respect to P . Additionally, if P_n represents the empirical measure of O_1, \dots, O_n , we denote the empirical process indexed over an appropriate class of functions \mathcal{F} as $G_n f = \sqrt{n}(P_n f - Pf)$. Furthermore, we extend this notation to $G_{n,S^n}^i f = \sqrt{n}(P_{n,S^n}^i - Pf)$ for the empirical processes that correspond to applying the empirical measure over either the training data or test data, $i = 0$ or $i = 1$.

In the following results we assume that a proper loss function $L : \mathcal{O} \times \Theta \rightarrow \mathbb{R}$ has been given.

Lemma 10 (Lemma 2.1 in (Vaart, Dudoit, and Laan 2006)). *Let G_n be the empirical process of an i.i.d. sample of size n from the distribution P and Ψ a library of learning algorithms. Furthermore, let $\hat{\psi}_n$ and $\tilde{\psi}_n$ denote the cross-validation- and oracle selected algorithms from Ψ respectively. For $\delta > 0$ it holds that*

$$\begin{aligned} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P) &\leq (1 + 2\delta) E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &+ E_{S^n} \frac{1}{\sqrt{n_1}} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d((1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P)(o) \\ &+ E_{S^n} \frac{1}{\sqrt{n_1}} \max_{\psi \in \Psi} \int -L(o, \psi(P_{n,S^n}^0)) d((1 + \delta)G_{n,S^n}^1 + \delta\sqrt{n_1}P)(o). \end{aligned}$$

Proof. See appendix. □

To control the bounds for the expected loss we introduce Bernstein pairs

Definition 11 (Bernstein pair (Vaart, Dudoit, and Laan 2006)). Given a measurable function $f : \mathcal{O} \rightarrow \mathbb{R}$, the tuple $(M(f), v(f))$ is a Bernstein pair if

$$M(f)^2 P \left(e^{|f|/M(f)} - 1 - \frac{|f|}{|M(f)|} \right) \leq \frac{1}{2} v(f). \quad (2)$$

Proposition 12. *If f is uniformly bounded, then $(\|f\|_\infty, \frac{3}{2}Pf^2)$ is a Bernstein pair.*

Proof. Following proof is due to (Vaart, Dudoit, and Laan 2006)[ch. 8.1].

$$\begin{aligned} \|f\|_\infty^2 P \left(e^{|f|/\|f\|_\infty} - 1 - \frac{|f|}{\|f\|_\infty} \right) &= \|f\|_\infty^2 \sum_{k \geq 2} P \frac{|f|^k}{\|f\|_\infty^k k!} = Pf^2 \sum_{k \geq 2} P \frac{|f|^{k-2}}{\|f\|_\infty^{k-2} k!} \\ &\leq Pf^2 \sum_{k \geq 2} \frac{\|f\|_\infty^{k-2}}{\|f\|_\infty^{k-2} k!} = Pf^2 \sum_{k \geq 2} \frac{1}{k!} \\ &= Pf^2(e - 2) \leq \frac{3}{4}Pf^2 = \frac{1}{2} \left(\frac{3}{2}Pf^2 \right). \end{aligned}$$

In the first inequality we replace the absolute value of f with the uniform norm, which is larger. □

Example 3 (Binary regression). Consider binary regression with quadratic loss. Let $\theta \in \Theta$ be arbitrary, then a Bernstein pair for the function $f_\theta(o) = L(o, \theta) = (Y - \theta(X))^2$ can be found by applying proposition 12. By requiring that $\theta(x) \in [0, 1]$, then it is clear that f is bounded between 0 and 1 for all $o \in \mathcal{O}$ since $Y \in \{0, 1\}$. We also note that the Bernstein pair for f_θ satisfies $0 \leq \|f_\theta\|_\infty \leq 1$ and $0 \leq \frac{3}{2}Pf_\theta^2 \leq 1$, so they are bounded.

Lemma 13 (Lemma 2.2 in (Vaart, Dudoit, and Laan 2006)). *Let G_n be the empirical process of an i.i.d. sample of size n from the distribution P and assume that $Pf \geq 0$ for every $f \in \mathcal{F}$ in some set of measurable functions \mathcal{F} on \mathcal{O} . Then, for any Bernstein pair $(M(f), v(f))$ and for any $\delta > 0$ and $1 \leq p \leq 2$,*

$$E_{D_n} \max_{f \in \mathcal{F}} (G_n - \delta \sqrt{n}P)f \leq \frac{8}{n^{1/p-1/2}} \log(1 + \#\mathcal{F}) \max_{f \in \mathcal{F}} \left[\frac{M(f)}{n^{1-1/p}} + \left(\frac{v(f)}{(\delta Pf)^{2-p}} \right)^{1/p} \right].$$

The same upper bound is valid for $E_{D_n} \max_{f \in \mathcal{F}} (G_n + \delta \sqrt{n}P)(-f)$.

The expectation E_{D_n} is taken wrt. the joint probability measure over our observations, here we have that $D_n \sim P_O^n = P_{O_1} \otimes P_{O_2} \otimes \dots \otimes P_{O_n}$.

Theorem 14 (Theorem 2.3 in (Vaart, Dudoit, and Laan 2006)). *Let Ψ be a library of learning algorithms of size k . For $\theta \in \Theta$ let the numbers $(M(\theta), v(\theta))$ be a Bernstein pair for the function $o \mapsto L(o, \theta)$ and assume that $R(\theta, P) \geq 0$ for every $\theta \in \Theta$. Then for $\delta > 0$ and $1 \leq p \leq 2$ it holds that*

$$\begin{aligned} E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n, S^n}^0), P) &\leq (1 + 2\delta) E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n, S^n}^0), P) + \\ &\quad (1 + \delta) E_{S^n} \left(\frac{16}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta, P)^{2-p}} \right)^{1/p} \left(\frac{1 + \delta}{\delta} \right)^{2/p-1} \right] \right). \end{aligned}$$

Where $\hat{\psi}_n$ and $\tilde{\psi}_n$ are the cross-validation- and the oracle selected algorithms from Ψ .

In the expectations above, we are taking the expectation wrt. the random split-variable S^n as well as the joint distribution of our observations. In a more verbose manner one would write

$$E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P) = \int R(\hat{\psi}_n(P_{n,S^n}^0), P) d(P_{S^n} \otimes P_O^n).$$

Proof. We will apply lemma 13 to the second and third terms on the left hand side of the inequality in lemma 10. Let $\mathcal{F} = \{o \mapsto L(o, \psi(P_{n,S^n}^0)) \mid \psi \in \Psi\}$, be the collection of functions obtained by applying the loss L to each algorithm in our library Ψ . Note that $\mathcal{F} \subseteq \{o \mapsto L(o, \theta) \mid \theta \in \Theta\}$, and since $R(\theta, P) \geq 0$ for every $\theta \in \Theta$ it follows that $Pf \geq 0$ for every $f \in \mathcal{F}$.

First, we take the expectation wrt. D_n on both sides in lemma 10. For the second term we have

$$\begin{aligned} E_{D_n} E_{S^n} \frac{1}{\sqrt{n_1}} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d((1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P)(o) \\ = E_{D_n} E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d(G_{n,S^n}^1 - \frac{\delta}{1 + \delta}\sqrt{n_1}P)(o) \\ = E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} E_{D_n} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d(G_{n,S^n}^1 - \frac{\delta}{1 + \delta}\sqrt{n_1}P)(o). \end{aligned}$$

Where we use Fubini in the last equality. Recall that $S^n \perp\!\!\!\perp D_n$, so we can always consider n_1 as fixed given D_n , now applying lemma 13 to the expression above with $n = n_1$ yields

$$\begin{aligned} E_S^n \frac{1 + \delta}{\sqrt{n_1}} E_{D_n} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d(G_{n,S^n}^1 - \frac{\delta}{1 + \delta}\sqrt{n_1}P)(o) \\ \leq E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} \frac{8}{n_1^{1/p-1/2}} \log(1 + k) \max_{\psi \in \Psi} \left[\frac{M(\psi(P_{n,S^n}^0))}{n_1^{1-1/p}} + \left(\frac{v(\psi(P_{n,S^n}^0))}{(\frac{\delta}{1+\delta})^{2-p} R(\psi(P_{n,S^n}^0), P)^{2-p}} \right)^{1/p} \right] \\ \leq E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} \frac{8}{n_1^{1/p-1/2}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{(\frac{\delta}{1+\delta})^{2-p} R(\theta, P)^{2-p}} \right)^{1/p} \right] \\ = (1 + \delta) E_{S^n} \frac{8}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta, P)^{2-p}} \right)^{1/p} \left(\frac{1 + \delta}{\delta} \right)^{2/p-1} \right]. \end{aligned}$$

Where for the third inequality we take the sup over Θ . We can also bound the third term with the same expression above as lemma 13 is also valid for $-L$. It is now immediate from lemma 10 that

$$\begin{aligned} E_{D_n} E_{S^n} \int L(o, \hat{\psi}_n(P_{n,S^n}^0)) dP(o) \leq (1 + 2\delta) E_{D_n} E_{S^n} \int L(o, \tilde{\psi}_n(P_{n,S^n}^0)) dP(o) \\ + (1 + \delta) E_{S^n} \frac{8}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta)^{2-p}} \right)^{1/p} \left(\frac{1 + \delta}{\delta} \right)^{2/p-1} \right] \\ + (1 + \delta) E_{S^n} \frac{8}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta)^{2-p}} \right)^{1/p} \left(\frac{1 + \delta}{\delta} \right)^{2/p-1} \right]. \end{aligned}$$

The second and third terms above are identical, meaning that they can be combined into one term where the numerator in the first fraction is 16 instead of 8. \square

Remark. One might notice that S^n still appears in the remainder of the bound above, but the only variable in the remainder that depends on S^n is n_1 . It is, therefore, completely possible to drop the expectation wrt. S^n if n_1 is deterministic, for example, if it is a fraction of n .

In the following corollary we assume that the Bernstein pairs $(M(\theta), v(\theta))$ are bounded over Θ , thus taking the supremum over Θ will not result in the remainder being infinite. The assumption is indeed valid for binary regression as we have commented in example 3.

Corollary 15 (Asymptotic equivalence). *If there exists an $\varepsilon > 0$ such that*

$$E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) > \varepsilon \quad \text{for all } n \in \mathbb{N},$$

and if $n_1 \rightarrow \infty$ as $n \rightarrow \infty$, then the risk of the super learner is asymptotically equivalent to the risk of the oracle selected learner, that is

$$\lim_{n \rightarrow \infty} \frac{E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)} = 1.$$

For the sake of simplicity and the previous remark we will consider n_1 as a sequence of numbers polynomial in n , this will allow us to remove E_{S^n} in the remainder term.

Proof. We let δ depend on n , define $\delta_n := 1/\log(n)$. By choosing $p = 1$ in theorem 14 and substituting δ with δ_n , we obtain

$$\begin{aligned} E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P) &\leq (1 + 2\delta_n) E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &\quad + (1 + \delta_n) \frac{16}{n_1} \log(1 + k) \sup_{\theta \in \Theta} \left[M(\theta) + \frac{v(\theta)}{R(\theta, P)} \cdot \frac{1 + \delta_n}{\delta_n} \right] \\ &= (1 + 2\delta_n) E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &\quad + (1 + \delta_n) \frac{16}{n_1} \log(1 + k) \sup_{\theta \in \Theta} \left[M(\theta) + \frac{v(\theta)}{R(\theta, P)} \cdot (\log(n) + 1) \right]. \end{aligned}$$

In the above inequality the remainder term goes to 0 as n_1 increases. The $\log(n)$ term in the supremum will be dominated by the $1/n_1$ that is multiplied in the front. By dividing the oracle risk on both sides, we obtain

$$\begin{aligned} \frac{E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)} &\leq 1 + 2\delta_n \\ &\quad + \frac{(1 + \delta_n) \frac{16}{n_1} \log(1 + k) \sup_{\theta \in \Theta} \left[M(\theta) + \frac{v(\theta)}{R(\theta, P)} \cdot (\log(n) + 1) \right]}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)}. \end{aligned}$$

The fraction on the right hand side will converge to 0 as $n \rightarrow \infty$, since n_1 is polynomial in n and the oracle risk is bounded away from 0 by assumption. The entire right hand side will therefore converge to 1 as $\delta_n \rightarrow 0$. Note also that by the definition of the oracle, we have

$$E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \leq E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P),$$

implying that

$$1 \leq \frac{E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)},$$

applying the squeeze theorem thus yields the desired result. \square

In the proof of the asymptotic result we have chosen $\delta_n = 1/\log(n)$, in doing so, the remainder converges to 0 at a rate of $\log(n)/n$. An immediate consequence of this is that if we have a library of parametric learning algorithms and one of them corresponds to the true regression, then the oracle risk might very well converge at a rate of $1/n$, implying that the risk of the discrete super learner achieves an almost parametric rate of convergence of $\log(n)/n$ to the oracle (Laan, Polley, and Hubbard 2007). For the asymptotic equivalence to hold, we must have that $n_1 \rightarrow \infty$ as $n \rightarrow \infty$. This is a reasonable assumption for cross-validation schemes such as K -fold cross-validation or if $n_1 = np$ for $p \in (0, 1)$ where the test size increases with the amount of available data. Note that the condition is not satisfied for leave-one-out cross-validation since n_1 is equal to 1 for every n .

Example 4 (Regression). In a regression context with quadratic loss, the risk for a learner can never be zero unless the outcome is deterministic given x . We may begin by noting that the risk of $\theta^*(x) = E(Y | X = x)$ is always positive,

$$\int (Y - E(Y | X))^2 dP \geq 0.$$

Since the integrand is positive, the integral is zero if and only if $Y = E(Y | X)$ almost surely. That is only the case when Y is deterministic given X , i.e. Y is X -measurable. Assuming, therefore, that Y is not deterministic given X , then we note that by the fact that the quadratic loss is strictly proper, then we have for any $\theta \in \Theta$

$$R(\theta, P) \geq R(\theta^*, P) > 0,$$

thus showing that the risk of any learner is strictly positive.

4 The Ensemble Super Learner

The idea behind the *ensemble super learner* is to combine the predictions made by each candidate learner, $\psi_1(P_n), \dots, \psi_k(P_n)$, into a single prediction. The idea of combining learners was examined in Breiman 1996 which considered the construction of an ensemble learner by forming a linear combination of the learners in the library. The method of forming a linear combination of learners is known as *stacked regression* or *stacking*, and is a variant of the ensemble super learner. The ensemble super learner does not restrict to taking a linear combination of the learners but that we are able to apply a *meta learning algorithm* on the *level 1 data*. The ensemble super learner can be thought of as a general method of balancing the weaknesses of each learner by forming an ensemble. However, as we will see, K -fold cross-validation is integral in forming the ensemble super learner.

We will now proceed to give the definitions and setup necessary to define the ensemble super learner.

4.1 Level 1 data

Let D_n be our data and let Ψ be a library of learning algorithms. The *level 1 covariates* of Ψ applied to D_n as specified by a K -fold cross validation procedure is

$$\mathcal{Z} = \{Z_i = (\psi_1(P_{n,s(i)}^0)(X_i), \dots, \psi_k(P_{n,s(i)}^0)(X_i))\}_{i=1}^n \subseteq [0, 1]^k,$$

which is the set of possible outcomes by applying the learners on the observed X_i 's.

Definition 16 (Level 1 data). The *level 1 data* is given by concatenating our observed Y_i 's with the level 1 covariates, i.e.

$$\mathcal{L}_n = \{(Y_i; Z_i) = (Y_i; \psi_1(P_{n,s(i)}^0)(X_i), \dots, \psi_k(P_{n,s(i)}^0)(X_i))\}_{i=1}^n \subseteq \{0, 1\} \times \mathcal{Z}.$$

The level 1 data is exactly the predictions made by the learners on the observations that they were not trained on. Thus, *level 0 data* is what we refer to as D_n . We now define \mathcal{M} as the class of all measurable functions that map from \mathcal{Z} to $[0, 1]$ which we will refer to as *meta learners*.

4.2 Meta learners

Definition 17 (Meta learner). The *meta learner* is a function $\phi : \mathcal{Z} \rightarrow [0, 1]$ in \mathcal{M} that maps the output of the candidate learners to a prediction.

The goal is to estimate the regression of Y given the predictions made by our learners, $\mathcal{Z} \ni z \mapsto E(Y \mid Z = z)$, which is an element in \mathcal{M} . We accomplish this by applying a *meta learning algorithm* to the level 1 data.

Definition 18 (Meta learning algorithm). A *meta learning algorithm* Φ is a measurable map that creates a meta learner from our level 1 data $\mathcal{L}_n \mapsto \Phi(\mathcal{L}_n) \in \mathcal{M}$.

A meta learning algorithm seeks to estimate $E(Y \mid Z)$. It can for example be a parametric learning algorithm such as logistic regression. If a parametric learning algorithm is used, it is important to take into account that the level 1 covariates Z_i are highly correlated and that multicollinearity can occur. Breiman 1996 suggests ridge regression as a possible way to shrink the coefficients. Another method is to use a non-negativity constraint, where we specify that the coefficients must sum to 1 in the case of a simple linear combination.

4.3 Ensemble super learner

Definition 19 (Ensemble super learner (Laan, Polley, and Hubbard 2007)). Let a library of learning algorithms Ψ be given and let \mathcal{L}_n be the level 1 data obtained by fitting each learning algorithm according to some K -fold cross validation procedure. Let $\phi = \Phi(\mathcal{L}_n)$ be the outcome of applying a meta learning algorithm to the level 1 data, then the map

$$x \mapsto \Sigma(P_n)(x) = \phi(\psi_1(P_n)(x), \dots, \psi_k(P_n)(x)),$$

is called the *ensemble super learner* and we will denote it by $\Sigma(P_n)$.

Here the P_n indicates that each learner $\psi \in \Psi$ is fitted on the entire data set. A meta learner, ϕ , is used to combine the predictions made by each learner.

4.4 Oracle property

The meta learning algorithm, Φ , fits the learner that most accurately predicts Y given Z , a way of formalizing the notion of ‘fitting’ is that Φ seeks to select the meta learner with the lowest risk among a indexed set of meta learners. Let \mathcal{A} be a parameter set (for example Euclidean), for each $a \in \mathcal{A}$ let ϕ_a be a meta learner. In a practical setting, one might consider ϕ_a as the learner obtained by instantiating it with the parameter a . Given our level 1 data \mathcal{L}_n , define

$$\hat{a} := \arg \min_{a \in \mathcal{A}} \frac{1}{n} \sum_{i=1}^n L((Y_i, Z_i), \phi_a) = \arg \min_{a \in \mathcal{A}} \frac{1}{n} \sum_{i=1}^n (Y_i - \phi_a(Z_i))^2. \quad (3)$$

The meta learning algorithm applied to \mathcal{L}_n returns $\phi_{\hat{a}}$, which is the meta learner with the empirical lowest risk on the level 1 data. We will now consider $\mathcal{A}_n \subseteq \mathcal{A}$ such that $k(n) = |\mathcal{A}_n|$ depends on n . Denote the ensemble super learner that uses the meta learner ϕ_a as

$$\Sigma_a(P_n) := \phi_a(\psi_1(P_n), \dots, \psi_k(P_n)).$$

Denote the cross-validation- and oracle selector of a as

$$\begin{aligned}\hat{a}_n &:= \arg \min_{a \in \mathcal{A}_n} \frac{1}{K} \sum_{s=1}^K R(\Sigma_a(P_{n,s}^0), P_{n,s}^1), \\ \tilde{a}_n &:= \arg \min_{a \in \mathcal{A}_n} \frac{1}{K} \sum_{s=1}^K R(\Sigma_a(P_{n,s}^0), P),\end{aligned}$$

where P is the distribution of the observations in our level 0 data. Note that for each s' up to K

$$\Sigma_a(P_{n,s'}^0)(X_i) = \phi_a(\psi_1(P_{n,s'}^0)(X_i), \dots, \psi_k(P_{n,s'}^0)(X_i)) = \phi_a(Z_i).$$

holds true for each i if $s(i)$ equals s' , i.e. when X_i is in the validation set s' . By using the fact that the K folds are disjoint and exhaustive, we can express \hat{a}_n as

$$\hat{a}_n = \arg \min_{a \in \mathcal{A}_n} \frac{1}{K} \sum_{s'=1}^K \frac{K}{n} \sum_{i:s(i)=s'} (Y_i - \Sigma_a(P_{n,s'}^0)(X_i))^2 = \arg \min_{a \in \mathcal{A}_n} \frac{1}{n} \sum_{i=1}^n (Y_i - \phi_a(Z_i))^2. \quad (4)$$

Equation (4) shows that the cross-validation selector, \hat{a}_n , is exactly the objective of the meta learning algorithm defined in (3).

The way that \hat{a}_n and \tilde{a}_n are defined fit directly into our existing framework for the discrete super learner. Recall that the cross-validation selector selected the algorithm that had the lowest cross-validation risk averaged across some split variable S^n . By using a K -fold cross-validation scheme, the averaged risk over S^n becomes the averaged risk over the K folds, which is exactly the above definition of \hat{a}_n . In the case of the ensemble super learner, the learning algorithm, ϕ_a , is determined by the parameter a , so the selection problem reduces to selecting the most optimal parameter over a finite parameter set \mathcal{A}_n . The parameter set \mathcal{A}_n indexes the meta learning algorithms, and is what the cross-validation selector acts upon. It is, therefore, possible to think of \mathcal{A}_n as approximating the entire parameter set \mathcal{A} using a grid of points such that the approximation becomes finer as the number of points increase. The key difference lies in the fact that the ensemble super learner is a completely new learner, whereas the discrete super learner is an algorithm selected from the library Ψ fitted on the dataset.

The following finite sample oracle inequality is a direct consequence of the oracle inequality for the discrete super learner, theorem 14.

Theorem 20 (Finite sample oracle inequality). *Let Ψ be a library of learning algorithms of size k . Let $\Sigma_{\hat{a}_n}$ be the ensemble super learner over Ψ obtained by applying the cross-validation selector over a finite parameter space \mathcal{A}_n using the K -fold cross-validation scheme. Let $\Sigma_{\tilde{a}_n}$ be the oracle ensemble learner obtained by applying the oracle selector over the same set of parameters. If the conditions of theorem 14 are satisfied, then the*

following oracle inequality holds

$$\begin{aligned} \frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\hat{a}_n}(P_{n,s}^0), P) &\leq (1 + 2\delta) \frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\tilde{a}_n}(P_{n,s}^0), P) \\ &\quad + (1 + \delta) \frac{16K}{n} \log(1 + k(n)) \sup_{\theta \in \Theta} \left[\frac{M(\theta)K}{n} + \frac{v(\theta)}{R(\theta)} \frac{1 + \delta}{\delta} \right]. \end{aligned}$$

Proof. Replace E_{S^n} in theorem 14 with the average over the K folds and n_1 with n/K , then by using $p = 1$ the desired result is obtained. \square

Corollary 21 (Asymptotic equivalence). *If the number of points in the parameter sets \mathcal{A}_n grows at most at a polynomial rate, that is $k(n) \leq n^p$ for some $p \in \mathbb{N}$, then the ensemble super learner $\Sigma_{\hat{a}_n}$ is asymptotically equivalent to the oracle ensemble learner $\Sigma_{\tilde{a}_n}$, i.e.*

$$\lim_{n \rightarrow \infty} \frac{\frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\hat{a}_n}(P_{n,s}^0), P)}{\frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\tilde{a}_n}(P_{n,s}^0), P)} = 1.$$

Proof. The $\log(1 + k(n))$ term is less than $1 + \log(k(n)) = 1 + p \log(n)$, which is of lower order than \sqrt{n} , thus the remainder term goes to zero as $n \rightarrow \infty$. \square

4.5 Choice of meta learning algorithm

Given the level 1 data, \mathcal{L}_n , the meta learning algorithm seeks to optimize over the parameter set $\mathcal{A}_n \subseteq \mathcal{A}$. The interpretation of \mathcal{A} depends on the chosen learning algorithm. If a parametric learning algorithm is used, for example logistic regression, then \mathcal{A} is \mathbb{R}^k where k is the number of learners in Ψ . The learner ϕ_a for $a \in \mathcal{A}$ will then be the map $z \mapsto \text{expit}(az)$. Laan, Polley, and Hubbard 2007 mentions that it is also possible to use a non-parametric learning algorithm as the meta learning algorithm, or even apply a super learning algorithm on the level 1 data. In this case \mathcal{A} could be measurable functions from \mathcal{Z} to $[0, 1]$. The learner ϕ_a for $a \in \mathcal{A}$ will then be the map $z \mapsto a(z)$.

Constrained regression and the k -simplex

Here we examine a simple meta learning algorithm which is to do a constrained regression on the level 1 data. The reason for examining this particular meta learning algorithm is because the discrete super learner is a special case of the ensemble super learner that utilizes this algorithm. The goal is to fit a weighted combination of the learners, such that the weights sum to 1. We can achieve this by parametrizing \mathcal{A} as the k -simplex given by

$$\mathcal{A} = \left\{ a \in \mathbb{R}^k \mid \sum_{q=1}^k a_q = 1, a_q \geq 0 \text{ for } 1 \leq q \leq k \right\}.$$

The meta learner ϕ_a for $a \in \mathcal{A}$ is then the map $z \mapsto z \cdot a$. By Cauchy-Schwarz we have $z \cdot a \leq \|z\| \|a\| \leq 1$ meaning that the range of ϕ_a is $[0, 1]$. The ensemble super learner that applies ϕ_a is, therefore, a valid learner in Θ . To apply the oracle results, we will cover \mathcal{A} with equidistant points on the simplex surface. For every n , we specify $\mathcal{A}_n \subseteq \mathcal{A}$ such that the number of points in \mathcal{A}_n increases with n at a polynomial rate, and that for any $a \in \mathcal{A}$ we have

$$\min_{b_n \in \mathcal{A}_n} \|a - b_n\| \leq \frac{1}{n}.$$

This is clearly possible by figure 1. It thus follows that we can find a sequence of points $b_n \in \mathcal{A}_n$ such that $\phi_{b_n} \rightarrow \phi_a$ for any $a \in \mathcal{A}$. The conclusion is that if \tilde{a} specified the learner $\phi_{\tilde{a}}$ with the minimum risk, then by applying the cross-validation selector and letting $n \rightarrow \infty$, the meta learner adopted by the ensemble super learner will eventually converge to $\phi_{\tilde{a}}$.

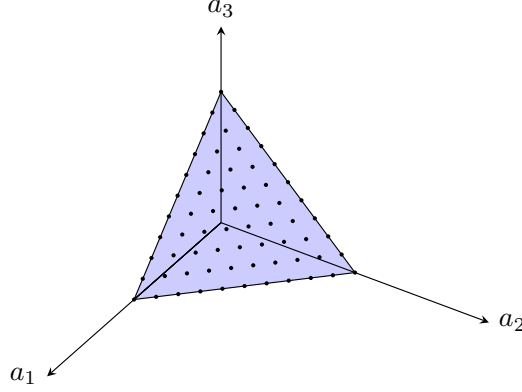


Figure 1: The parameter set \mathcal{A} as a k -simplex for $k = 3$. Here \mathcal{A}_n is visualized as points on the surface.

The discrete super learner is essentially a special case of the ensemble super learner that utilizes constrained regression. If $a_q = 1$ for any $1 \leq q \leq k$ then the ensemble super learner predicts the same as the q 'th learner. The discrete super learner can, therefore, be seen as constrained regression optimizing for a over the vertices of the k -simplex. Consequently we conclude that the ensemble super learner that uses constrained regression must outperform the discrete super learner at minimizing risk since it minimizes over the entire k -simplex.

Remark. In reality the optimization procedure that is available on our hardware can only optimize over finite subset of \mathcal{A} . The finite subset is determined by the floating-point precision of the processor, and perhaps also the internal parameters of the optimization procedure itself. For example, gradient descent algorithms usually have a hyperparameter such as ‘step size’ or ‘learning rate’ which controls how large of a step the algorithm takes in the direction of the minimum. The parameter set \mathcal{A}_n which depends on n also does not correspond to our actual optimization procedure. We do not choose some grid of points in the parameter set that depends on the number of observations such that for each point the risk is evaluated and then the minimum is picked. The minimum is optimized over all feasible points, for example if the risk is convex, then the minimum can sometimes be solved explicitly or there will exist procedures that guarantee convergence to the minimum.

5 Simulations

In the following section we show the results of applying the discrete super learner to a simulated dataset. The simulations are carried out using the R programming language and the corresponding source code can be found on the GitHub repository for this project (Liu 2023). The simulated dataset consists of a binary outcome, Y , which depends on two

covariates X_1 and X_2 . The setup is as follows

$$\begin{aligned} X_1 &\sim \text{Unif}(0.5, 15), \\ X_2 | X_1 = x_1 &\sim \mathcal{N}(3.5 - 0.03x_1, 1), \\ Y | X_1 = x_1, X_2 = x_2 &\sim \text{Ber}(\theta_0(x_1, x_2)), \end{aligned}$$

for $\theta_0(x_1, x_2) = \text{expit}(-3.5 - 0.3x_1 + 0.85x_2 + 0.35x_1x_2)$ which is the data-generating regression function. It is in fact possible to visualize the regression function explicitly as a 2-dimensional heat map in the covariates. In figure 2 we have applied the true regression across the grid of (x_1, x_2) covariate pairs in $(0, 15) \times (0, 7)$ where the spacing is 0.5 horizontally and vertically between each pair. The probabilities are colored from 0 to 1 in the plot.

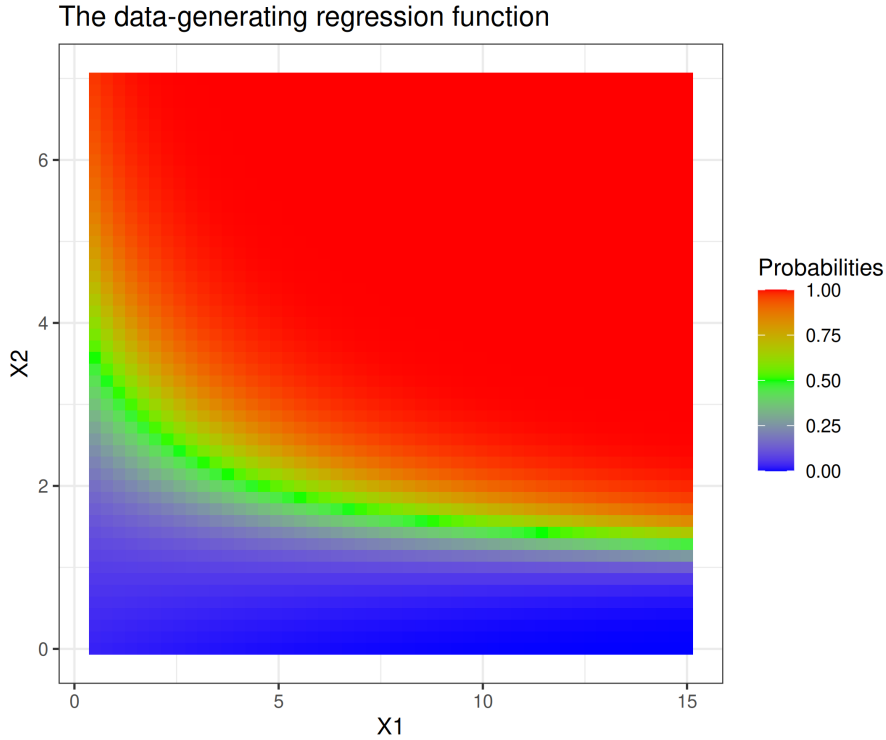


Figure 2: The data-generating regression plotted as a heat map

The regression is captured by the logistic regression model with interaction terms. We will use the following library of learning algorithms as an illustrative example:

1. Intercept only logistic regression: $E[Y | X_1, X_2] = \text{expit}(\beta_0)$
2. Logistic regression with main effects: $E[Y | X_1, X_2] = \text{expit}(\beta_0 + \beta_1X_1 + \beta_2X_2)$
3. XGBoost with hyperparameters: `max_depth=3, eta=0.3, n_rounds=100, objective='binary:logistic', booster='dart', nthread=5`

We can visualize the predictions of the learning algorithms in the library in the same way as we have done for the data-generating regression. In figure 3 we visualize the predictions of the main effects logistic regression and XGBoost fitted using 1000 observations sampled from the distribution.

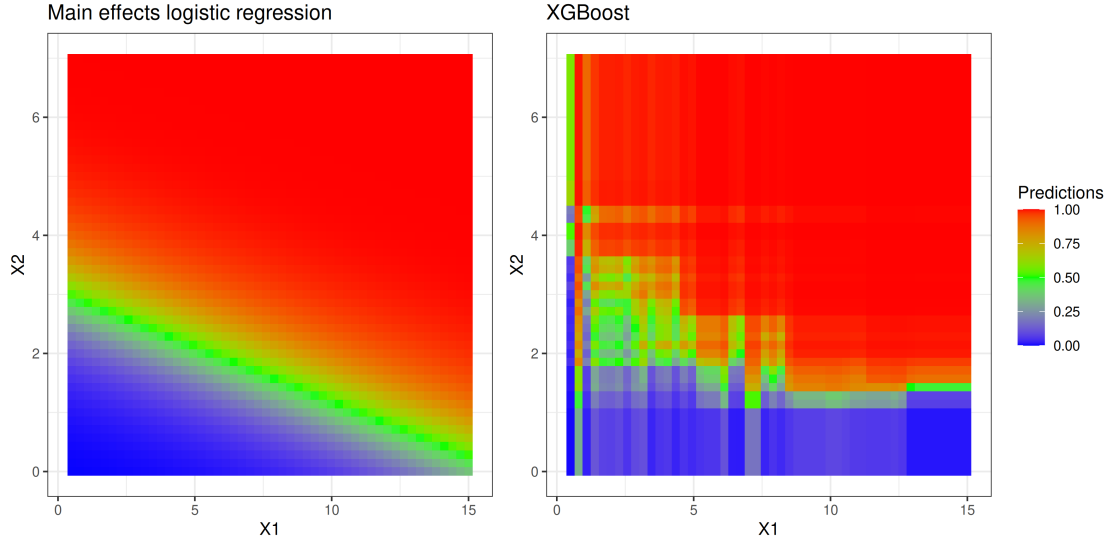


Figure 3: The predictions of the main effects logistic regression and XGBoost fitted on 1000 observations

The plot for the intercept only logistic regression is omitted, as its appearance is as one would expect – the plot is simply an orange square. The intercept only logistic regression is included as a baseline, the predicted probability by the intercept model is simply the sample average over the observed Y_i 's.

From figure 3 we can observe a clear difference in the predicted probabilities between the logistic regression and the tree-based XGBoost. The main effects logistic regression is a parametric model that assumes that the regression function is a smooth transformation of the linear predictor $X\beta$. XGBoost, in contrast, is made up of many decision trees, which explains the patchwork pattern in its prediction plot. For small samples and as we will see in the simulations, XGBoost has a high risk in comparison to the misspecified main effects logistic regression. However, XGBoost becomes increasingly better at approximating the true regression when the number of observations becomes large as seen in figure 4.

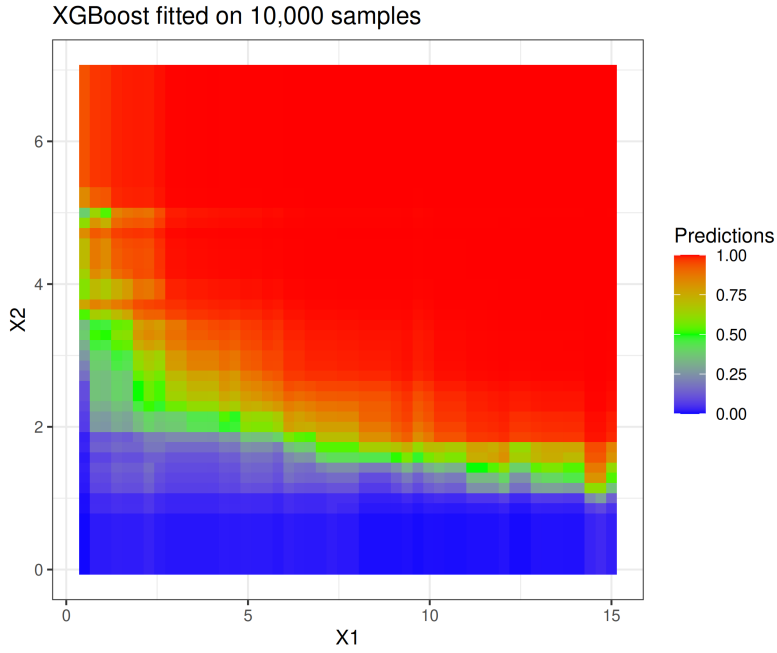


Figure 4: XGBoost becoming better at approximating the true regression as the sample size increases

5.1 The discrete super learner

By applying the discrete super learning algorithm to the library, we will see that the discrete super learner is able to qualitatively assess and select the best learning algorithm to apply given the amount of data at hand. The discrete super learner uses the main effects logistic regression in the beginning with few training samples, but as the predictions of XGBoost become more stable with more observations, it shifts its preference towards XGBoost. The performance of the discrete super learner will be compared with the learning algorithms in the library on the simulated dataset, we show that:

1. As the sample size increases, the discrete super learner achieves the minimum risk
2. The variance in the discrete super learner's prediction for a single new observation does not always exhibit a steady descent and depends on the other learners in the library

The discrete super learner in our simulations uses 10-fold cross-validation and the internal loss function will be the quadratic loss. The super learner will only run the cross-validation procedure once given the training data. The following snippet is psuedocode for the discrete super learner algorithm:

Algorithm 1 Discrete super learner

```
1: Input:  $D_n$ : dataset,  $V$ : number of folds,  $\Psi$ : library of learning algorithms of size  $k$ ,  
    $L$ : loss function  
2: Output: discrete super learner  $\hat{\psi}_n(D_n)$   
3:  $s \leftarrow$  create random folds( $D_n, V$ )  $\triangleright$  Randomly assign observations to folds  
4:  $\ell \leftarrow$  empty array of dimensions  $V \times k$   $\triangleright$  Array of risks  
5: for  $s \in \{1, \dots, V\}$  do  
6:    $D_{n,s}^1 \leftarrow \{O_i \in D_n \mid s(i) = s\}$   
7:    $D_{n,s}^0 \leftarrow D_n \setminus D_{n,s}^1$   
8:   for  $\psi \in \Psi$  do  
9:      $\psi(D_{n,s}^0) \leftarrow \text{fit}(\psi, D_{n,s}^0)$   
10:     $\ell[s, \psi] \leftarrow R(\psi(D_{n,s}^0), D_{n,s}^1) = \frac{V}{n} \sum_{O_i \in D_{n,s}^1} L(O_i, \psi(D_{n,s}^0))$   
11:   end for  
12: end for  
13:  $\ell_{\text{avg}}(\psi) \leftarrow \frac{1}{V} \sum_{s=1}^V \ell[s, \psi]$   
14:  $\hat{\psi}_n \leftarrow \arg \min_{\psi \in \Psi} \ell_{\text{avg}}(\psi)$   
15: return  $\text{fit}(\hat{\psi}_n, D_n)$ 
```

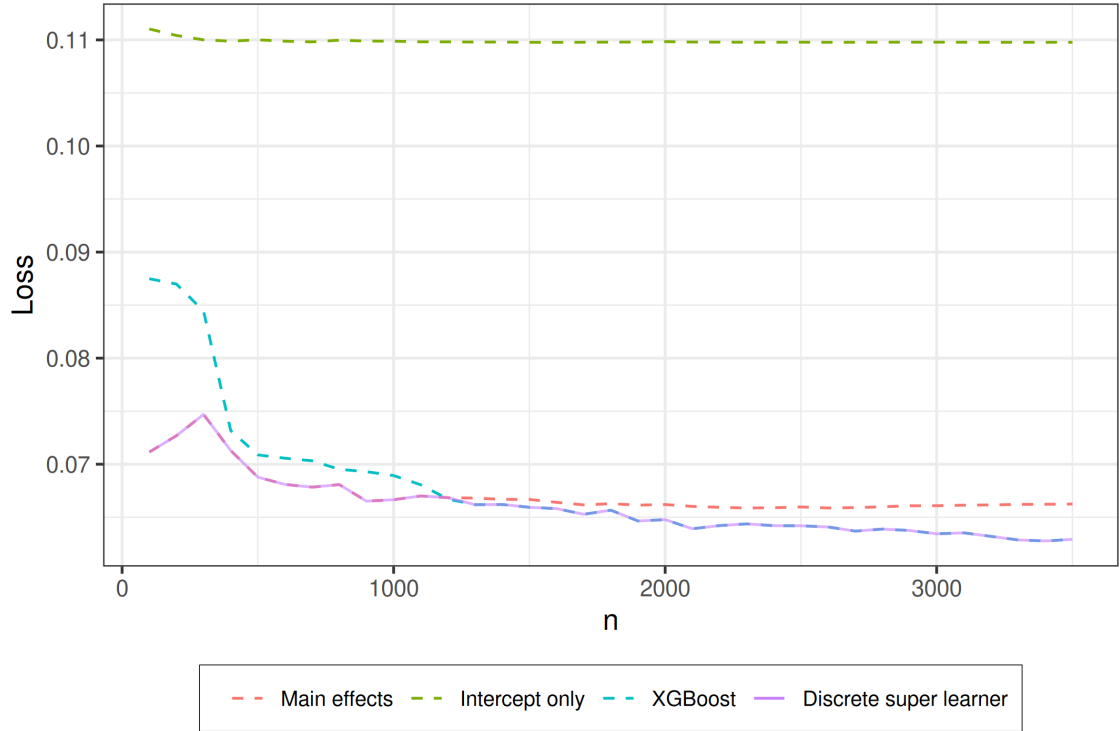


Figure 5: The risk of the discrete super learner compared to other learners. $N = 3500$

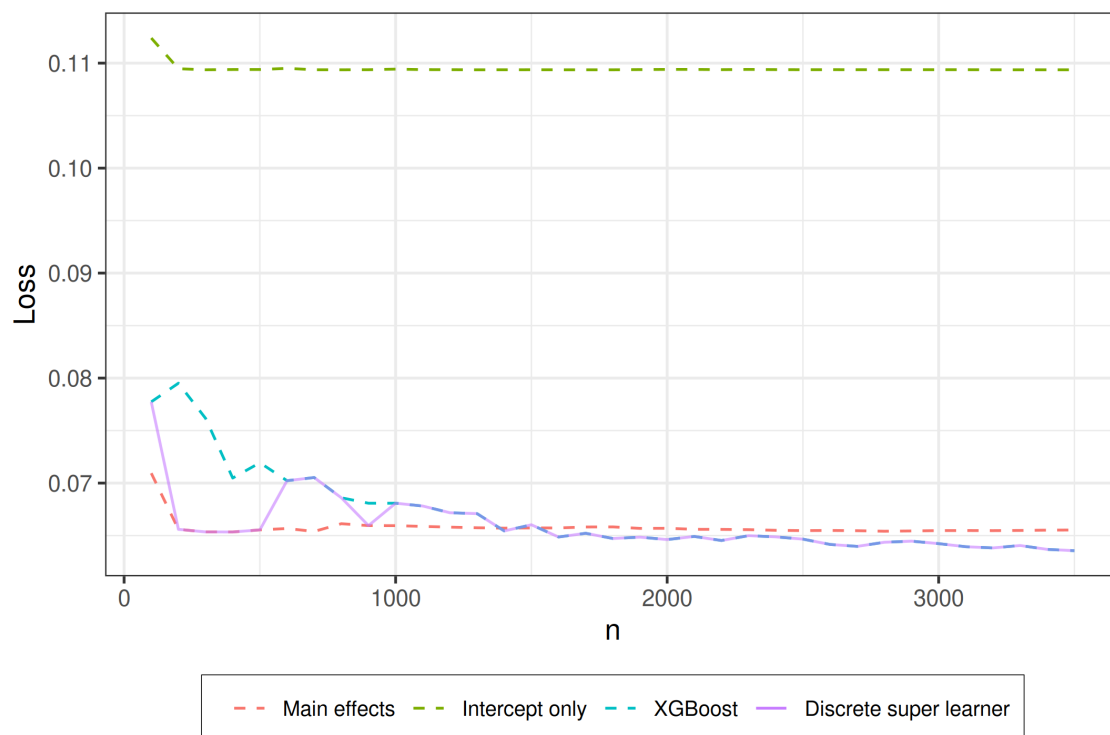


Figure 6: The risk of the discrete super learner compared to other learners. $N = 3500$

Figures 5 and 6 illustrate how the discrete super learner performs in comparison to the learners in terms of loss over number of training samples. The plots are generated for two runs where the model is fitted on $n = 100, 200, \dots, 3500$ observations, as indicated on the x -axis, then the empirical risk is calculated by evaluating each fitted learner on a fixed test sample of size of 10^6 . The test data is sampled from the data-generating distribution. The first run perfectly illustrates how the discrete super learner is able to achieve the minimum risk. For small training sample sizes, the machine learning method XGBoost has a higher risk than the main effects logistic regression, and it is therefore more desirable for the discrete super learner to choose logistic regression despite that it is misspecified. The discrete super learner consequently achieves the same risk as the logistic regression in the beginning, but for $n > 1200$ the risk of the discrete super learner becomes smaller than the logistic regression. Here XGBoost begins to achieve a lower risk than the misspecified logistic regression, and so the discrete super learner chooses to use XGBoost instead. The second run shows that the discrete super learner might be unable to determine the learner with the lowest risk when the training sample size is small, which results in it moving in a zig-zag pattern between two learners that have quite similar risks. However, we see that the discrete super learner eventually chooses XGBoost as the number of training samples grows.

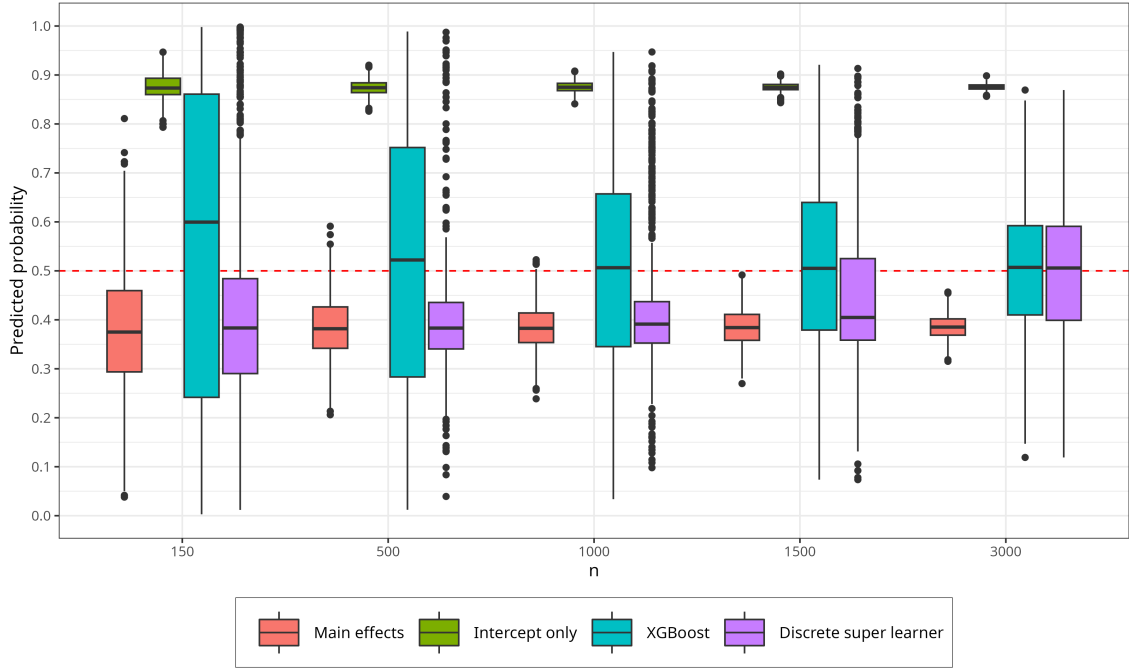


Figure 7: Variances of learner predictions for a single observation, each trained on n samples and evaluated $K = 1000$ times on a single observation

Figure 7 illustrates the variance in the predictions of each learner for a single observation, whose true probability is indicated by the red dashed line at $p = 0.5$. Each learner has been trained $K = 1000$ times on $n = 150, 500, \dots, 3000$ samples taken from the distribution and is used to predict K times after each training. The box plots are created from the K predictions.

We observe that the machine learning model, XGBoost, has the highest prediction variance across all training sample sizes. Recall that we only had two covariates, here having 1500 observations limits the range of predictions of our main effects model to be between 0.27 and 0.46, whereas for XGBoost it can vary from below 0.1 to above 0.9. While XGBoost is extremely efficient at minimizing loss, its predictions have a high variance unless one has a lot of training data.

The discrete super learner is able to achieve a lower variance than XGBoost for all training sample sizes. This is because the discrete super learner is able to choose the main effects logistic regression when the training sample size is small, which has a lower variance than XGBoost. However, the variance of the discrete super learner increases when $n \geq 1000$ and the boxplots become wider. This is due to the discrete super learner predicting the same as XGBoost since around these numbers of training samples since GBoost begins to achieve a lower risk in comparison to the main effects logistic regression.

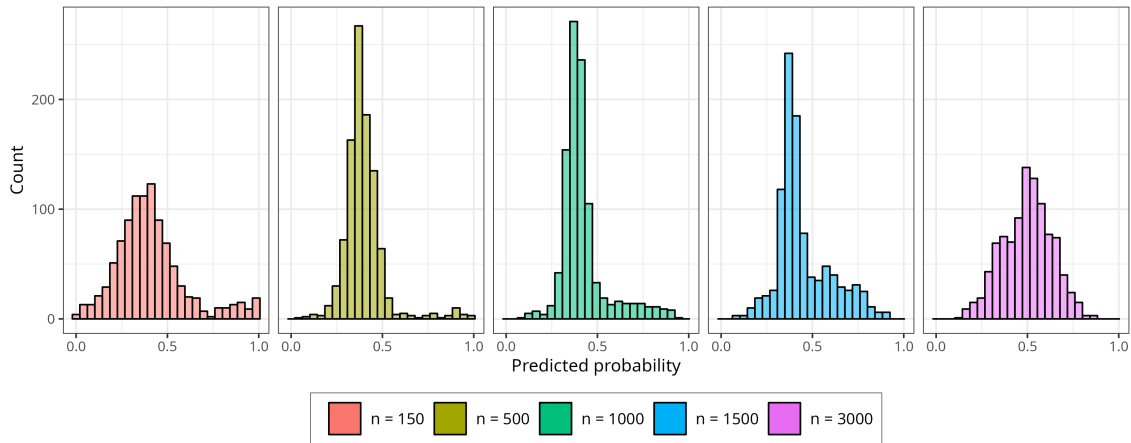


Figure 8: Predictions for a single observation by the discrete super learner varied over number of training samples

By examining figure 8, we see that the distribution of the predictions by the discrete super learner changes with the number of training samples. The figure explains the outlier points that for the discrete super learner boxplots in figure 7. The conclusion here is a reiteration of what we have already pointed out before. In the beginning for $n = 150$ to $n = 500$ the discrete super learner prefers the predictions made by the main effects logistic regression which results in a spikey distribution that is centered around $p = 0.4$. The discrete super learner assigns more importance to XGBoost predictions when $n \geq 1000$, which leads to more predictions for $p > 0.4$ and forms a tail distribution. At some point between $n = 1500$ and $n = 3000$, the discrete super learner is no longer uncertain that XGBoost achieves the lowest risk, and so it begins predicting the same as XGBoost.

5.2 The ensemble super learner

5.3 Discussion

6 Appendix

6.1 Proof of lemma 10

Proof. We first note that the minimizing property of $\hat{\psi}_n$ (definition 8) implies that

$$E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) \leq E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1). \quad (5)$$

We can write (5) as

$$\begin{aligned} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) &\leq (1 + 2\delta) E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &\quad + E_{S^n} \frac{1}{\sqrt{n_1}} R(\tilde{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P) \\ &\quad - E_{S^n} \frac{1}{\sqrt{n_1}} R(\hat{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 + \delta\sqrt{n_1}P). \end{aligned}$$

Indeed, by examining the risk in the second term on the right hand we obtain

$$\begin{aligned} &R(\tilde{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P) \\ &= (1 + \delta)R(\tilde{\psi}_n(P_{n,S^n}^0), G_{n,S^n}^1) - \delta\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta) \left[\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P) \right] - \delta\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta)\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - (1 + 2\delta)\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P). \end{aligned}$$

And for the third term

$$\begin{aligned} &R(\hat{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 + \delta\sqrt{n_1}P) \\ &= (1 + \delta)R(\hat{\psi}_n(P_{n,S^n}^0), G_{n,S^n}^1) + \delta\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta) \left[\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \right] + \delta\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta)\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P). \end{aligned}$$

The $\sqrt{n_1}$ in each term will disappear after we multiply with $\frac{1}{\sqrt{n_1}}$. We now add the first and second term on the right hand side

$$\begin{aligned} &(1 + 2\delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) + E_{S^n} \frac{1}{\sqrt{n_1}} R(\tilde{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P) \\ &= (1 + 2\delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) + E_{S^n} \left[(1 + \delta)R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - (1 + 2\delta)R(\tilde{\psi}_n(P_{n,S^n}^0), P) \right] \\ &= (1 + \delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1). \end{aligned}$$

Now by combining all terms on the right hand side we get

$$\begin{aligned} &(1 + \delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) \\ &\quad - E_{S^n} \frac{1}{\sqrt{n_1}} \left[(1 + \delta)\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \right] \\ &= (1 + \delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - (1 + \delta)E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) + E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P). \end{aligned}$$

By the minimizing property the difference between the second and first term must be positive. Since we are adding a positive number to $E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)$, it follows that it must be less than whatever is on the right. In the final lemma we replace $\hat{\psi}_n$ and $\tilde{\psi}_n$ by the maximum over Ψ .

□

References

- [1] Leo Breiman. “Stacked regressions”. In: *Machine learning* 24 (1996), pp. 49–64.
- [2] László Györfi et al. *A distribution-free theory of nonparametric regression*. Vol. 1. Springer, 2002.
- [3] Mark J. van der Laan and Sandrine Dudoit. “Unified Cross-Validation Methodology For Selection Among Estimators and a General Cross-Validated Adaptive Epsilon-Net Estimator: Finite Sample Oracle Inequalities and Examples”. In: *UC Berkeley Division of Biostatistics Working Paper Series* (Jan. 2003).
- [4] Aad W. van der Vaart, Sandrine Dudoit, and Mark J. van der Laan. In: *Statistics & Decisions* 24.3 (2006), pp. 351–371. DOI: [doi:10.1524/stnd.2006.24.3.351](https://doi.org/10.1524/stnd.2006.24.3.351). URL: <https://doi.org/10.1524/stnd.2006.24.3.351>.
- [5] Mark J. van der Laan, Eric C Polley, and Alan E Hubbard. “Super learner”. In: *Statistical applications in genetics and molecular biology* 6.1 (2007).
- [6] Tianqi Chen and Carlos Guestrin. “XGBoost: A scalable tree boosting system”. In: *Proceedings of the 22nd acm sigkdd international conference on knowledge discovery and data mining*. 2016, pp. 785–794.
- [7] Steffen Lauritzen. *Fundamentals of Mathematical Statistics*. CRC Press, 2023.
- [8] Jinyang Liu. *Source code for simulations*. 2023. URL: <https://github.com/jyliuu/bachelor-thesis>.