

A Bachelor of Science thesis
Super Learners

and their oracle properties

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Abstract

In this thesis we examine super learners and their applicability to binary regression. We introduce and prove the oracle property for the discrete super learner, which is extended to the ensemble super learner. The oracle results show that from a library of learning algorithms, asymptotically, the super learner will not perform worse than the best learning algorithm in the library. We then compare the performance of the super learner with other regression algorithms including logistic regression and XGBoost on simulated data. The simulations demonstrate that the super learner achieves minimal risk as the number of observations grows. We conclude that the super learner is indeed a valid method for constructing a strong learner from a library of learning algorithms. Finally, a new technique of combining learner predictions in the context of the ensemble super learner is proposed and has shown interesting results.

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Code availability

The code for the simulations conducted in section 5 can be found on GitHub at (Liu 2023).

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1 Introduction

In the context of regression, $O = (Y, X)$ is an observation for $Y \in \mathbb{R}$ being the outcome and $X \in \mathbb{R}^d$ the covariate. A natural goal is to estimate a function θ such that the L^2 -risk or mean squared error $E(Y - \theta(X))^2$ is minimized. It turns out that the conditional mean – called the regression function or regression $x \mapsto E(Y | X = x)$ minimizes the squared error, but consistent estimation of the regression requires a statistical model \mathcal{P} for the data-generating distribution $P \in \mathcal{P}$ for which $O \sim P$ to be specified. We typically make certain assumptions about the statistical model, \mathcal{P} , in which we believe P resides. For instance, we might assume that \mathcal{P} is a parametric family of distributions such as a curved exponential family (Lauritzen 2023). In doing so we can identify the parameters of the distribution P via maximum likelihood and estimate the regression from the parameters.

However, if we are dealing with complex data, there is a risk of misspecifying the model by identifying it as an exponential family. Our assumptions may be wrong. In these situations, it is tempting to utilize non-parametric and data-driven regression methods, such as tree-based algorithms like XGBoost or random forests. Machine learning methods seek to estimate the regression function directly, in contrast to parametric statistics where the parameters of the underlying model are estimated first and a regression function derived as some analytical expression of the parameters and covariates. The assumptions of these machine learning methods regarding the data-generating distribution are not explicitly specified, but it does not pose a problem for estimation of the regression. Indeed, it is not necessary for us to identify P completely if P can be factored into the conditional distribution $P_{Y|X}$ and the distribution over our covariates P_X , here our goal of estimating the regression function is to estimate $P_{Y|X}$.

Given an abundance of different ways we can tackle the problem of estimating the regression, we would like to be able to compare the different methods select the best one. In a practical scenario we might have set of learning algorithms that we can choose from. Cross-validation can help determine the risk of each algorithm by splitting the data into training and validation sets, each algorithm is then fitted on the training set and an empirical risk for the algorithms is calculated by evaluating the fitted models on the validation set. We would run cross-validation using a predefined splitting mechanism for each learning algorithm that we have. A popular choice in machine learning and statistics is K -fold cross-validation. K -fold cross-validation divides the data into K disjoint and exhaustive sets referred to as validation sets. For every $k = 1, \dots, K$ the learning algorithm is trained using all data excluding the k 'th validation set. Subsequently, the risk of the algorithm is computed by applying the fitted model on the validation set that was held out from training. We obtain an estimate of the true risk of the model by repeating this procedure K times and averaging over the risks. The model with the lowest risk is then selected as our candidate estimate of the regression function.

This is the idea behind the cross-validation selector (Laan and Dudoit 2003). The discrete super learner (Laan, Polley, and Hubbard 2007) is simply the learner (fitted model) that is obtained by applying the cross-validation selected algorithm to our data. The cross-validation selector, given a library of learning algorithms and our data, will cross-validate each algorithm in the library and select the one with the lowest risk.

Another method, called the ensemble super learner (Laan, Polley, and Hubbard 2007) seeks to combine the learning algorithms into a single learner by applying a *meta learning algorithm* on the library. One meta algorithm of the ensemble super learner is to fit a weighted average of the learners, where the weights are chosen to minimize the risk of the ensemble. The prediction of the ensemble super learner will then be a weighted sum of

the predictions made by each learner.

As we will demonstrate, given a library of learning algorithms, the super learner is effectively the best estimate of the data-generating regression that we can obtain. It is the best in the sense that it can not perform worse than the best learning algorithm in terms of risk.

To formalize the notion of the best learner in the library, we define the oracle selector. The oracle selector knows P – hence it is called the oracle – and selects the learner with the lowest risk given its knowledge of P . In this thesis we show that the cross-validation selector is asymptotically equivalent to the oracle selector as the sample size goes to infinity.

We adopt the setup and notation similar to those in Vaart, Dudoit, and Laan 2006 and Laan and Dudoit 2003. Our objective is to illustrate the performance of super learning algorithms when applied to binary regression, where we are regressing a binary outcome $Y \in \{0, 1\}$ against covariates X that belong to $\mathcal{X} \subseteq \mathbb{R}^d$. Here the conditional expectation of Y given X exactly becomes the conditional probability $P(Y | X)$. The simulation results in Section 5 show that the super learner achieves the minimum risk with increasing training samples. The simulation is conducted by first defining the data-generating distribution explicitly, from which we can sample from using standard sampling methods that are available in R. We assess a library of learning algorithms consisting of logistic regression and XGBoost, from which we construct the super learner and evaluate its performance in relation to the algorithms in the library.

The choice to focus on binary regression stems from its significance in various fields. For instance, in biomedicine, researchers might want to predict patient mortality upon administering a specific drug. The survival indicator for the patient is a binary outcome, and the regression $x \mapsto P(Y = 1 | X = x)$ could represent the probability of the patient’s survival.

2 Background

Our setup and notation is similar to Vaart, Dudoit, and Laan 2006 and Laan and Dudoit 2003: Let a statistical model \mathcal{P} be given on the measurable space $(\mathcal{O}, \mathcal{A})$ where $\mathcal{O} = \{0, 1\} \times \mathcal{X}$ is our sample space for some $\mathcal{X} \subseteq \mathbb{R}^d$. We will consider the parameter set $\Theta = \{\theta | \theta : \mathcal{X} \rightarrow [0, 1] \text{ measurable}\}$, which represents the set of *regression functions* that map from our covariates to the probability interval. We define the quadratic loss and the corresponding risk that we wish to minimize.

Definition 1 (Quadratic loss). The quadratic loss or L^2 -loss, $L : \mathcal{O} \times \Theta \rightarrow [0, \infty)$, for an observation $(y, x) = o \in \mathcal{O}$ and a regression function $\theta \in \Theta$ is defined as

$$L(o, \theta) = L((y, x), \theta) = (y - \theta(x))^2.$$

A natural aim would be to find the optimal parameter value $\theta^* \in \Theta$ that minimizes the expected quadratic loss, or risk $R : \theta \rightarrow \mathbb{R}$ given by

$$R(\theta, P) := \int L(o, \theta) dP(o). \quad (1)$$

Theorem 2 shows that the minimum risk is achieved by the conditional probability $x \mapsto P(Y = 1 | X = x)$; we also say that the quadratic loss is *strictly proper* (Gneiting and Raftery 2007).

Theorem 2. Let $(\mathcal{O}, \mathcal{A}, P)$ be a probability space for some probability measure $P \in \mathcal{P}$. Let Θ be the set of regression functions. Let the loss function be the L^2 -loss $L(o, \theta) = (y - \theta(x))^2$, then for the optimum θ^* defined as

$$\theta^* := \arg \min_{\theta \in \Theta} R(\theta, P) = \arg \min_{\theta \in \Theta} \int L(o, \theta) dP(o),$$

it holds for an observation $O = (Y, X) \sim P$ that

$$\theta^*(x) = E(Y | X = x).$$

Proof. Proof emulated from (Györfi et al. 2002)[ch. 1]. Let $\theta \in \Theta$ be arbitrary and $m(x) = E(Y | X = x)$, we have

$$\begin{aligned} E|\theta(X) - Y|^2 &= E|\theta(X) - m(X) + m(X) - Y|^2 \\ &= E|\theta(X) - m(X)|^2 + E|m(X) - Y|^2 + 2E[(\theta(X) - m(X))(m(X) - Y)]. \end{aligned}$$

We see that the last term is zero, see that by using the tower rule we have

$$\begin{aligned} E[(\theta(X) - m(X))(m(X) - Y)] &= E[E[(\theta(X) - m(X))(m(X) - Y) | X]] \\ &= E[(\theta(X) - m(X))E((m(X) - Y) | X)] \\ &= E[(\theta(X) - m(X))(m(X) - E(Y | X))] \\ &= E[(\theta(X) - m(X))(m(X) - m(X))] \\ &= 0. \end{aligned}$$

We conclude that

$$\int L(o, \theta) dP(o) = E|\theta(X) - m(X)|^2 + E|m(X) - Y|^2.$$

The first term after the equality is always positive and is 0 only when $\theta = m$, this proves that m minimizes the expression above. \square

It follows immediately that if Y is binary, then $E(Y | X = x) = P(Y = 1 | X = x)$. Our goal is to estimate θ^* , which means to *learn* the true regression function from our data. We will introduce the terminology *learning algorithm* and *learner* in the context of learning from our data.

2.1 Learning algorithms and learners

We will denote $O_1, \dots, O_n \in \mathcal{O}$ and $D_n = (O_1, \dots, O_n)$ as our observations and data respectively.

Definition 3 (Learning algorithm). A learning algorithm is a measurable map $\psi : \mathcal{O}^n \rightarrow \Theta$ for $n \in \mathbb{N}$.

We will throughout assume that the learning algorithm is well defined for each $n \in \mathbb{N}$, and that permuting the observations have no effect on the outcome, i.e., the algorithm is symmetric in the observations.

Definition 4 (Learner or fitted learner). Given a learning algorithm ψ . A learner is a stochastic variable in Θ representing the outcome of applying the learning algorithm to our data $\theta = \psi(D_n)$.

Formally $\psi(D_n)$ is a stochastic variable since D_n is stochastic. In practice, we would observe $O_1 = o_1, \dots, O_n = o_n$, following which we can employ a learning algorithm on the observed data. In machine learning, the process of applying an algorithm on the data is referred to as *model training* or *fitting*, the outcome of the training is a *trained model* or simply a *fit*. We will refer to the trained model as a learner which naturally depends on the observed data.

Example 1 (Parametric and nonparametric learning algorithms). An example of a parametric learning algorithm is logistic regression. In logistic regression we assume that the conditional probability, $P(Y = 1 | X = x)$, can be expressed as $\theta(x) = \text{expit}(\beta x)$ for some $\beta \in \mathbb{R}^d$ which is estimated via maximum likelihood.

Nonparametric learning algorithms such as gradient boosting – most notably XGBoost – can also be used to estimate the regression function. XGBoost has a number of hyperparameters that can be tuned. These parameters include the number of boosted trees, depth of each tree, learning rates, and others. However, the most critical parameter is the internal loss objective which could for example be log-loss or mean squared error. XGBoost aims to iteratively refine the fitted learner by approximating the data $x \mapsto f_m(x)$ at each step m . It does so by introducing a new tree $h_m(x)$, which is trained on the error of $f_m(x)$, such that $f_{m+1}(x) = f_m(x) + h_m(x)$. The internal loss of the updated learner, f_{m+1} , evaluated on the training data, is lower than that of the previous learner due to the inclusion of the new tree (Chen and Guestrin 2016).

The parameters of the fitted XGBoost are not directly interpretable. Despite this, XGBoost has demonstrated its ability to model very complex datasets (Chen and Guestrin 2016).

We will denote the empirical measure obtained from the data D_n as

$$P_n(A) = \frac{1}{n} \sum_{i=1}^n \delta_{O_i}(A) \quad \text{for } A \in \mathcal{A},$$

where δ_{O_i} is the Dirac measure over O_i . When the observations are independent and identically distributed, then there is a one-to-one correspondence between the empirical measures obtained from n observations and D_n . We can, therefore, write $\psi(P_n)$ as an alternative representation of the learner $\psi(D_n)$, by adjusting the notation slightly without introducing ambiguity. The motivation for using this notation will become clearer in the subsequent section, where we introduce the discrete super learner.

2.2 Library of learners

We would like to consider the scenario where we have a set of learning algorithms, ψ_1, \dots, ψ_k . From these algorithms, we can define the *library of learning algorithms*

$$\Psi = \{\psi_q \mid 1 \leq q \leq k\},$$

of size k . Our natural goal is to find $\tilde{\psi} \in \Psi$ such that $\tilde{\psi}(P_n)$ that achieves the lowest possible risk

$$\tilde{\psi} = \arg \min_{\psi \in \Psi} R(\psi(P_n), P).$$

However, we cannot compute the risk of a learner directly as it depends on P . We seek to provide an estimate for $\tilde{\psi}$ which we will denote as $\hat{\psi}$.

3 The Discrete Super Learner

3.1 Cross-validation methodology

To provide the estimate $\hat{\psi}$ we will proceed via cross validation. Cross-validation randomly splits our data into a *training set* and a *test set* that our algorithms are trained and evaluated on. Let the random binary vector – referred to as the *split variable* or just *split* – $S^n = (S_1^n, \dots, S_n^n) \in \{0, 1\}^n$ be independent of D_n such that $S_i^n = 0$ indicates that O_i should be in the training set and $S_i^n = 1$ indicates that O_i belongs to the test set. The split S^n depends on n as it is a tuple in $\{0, 1\}^n$, here the superscript n is used to indicate that. We can define the empirical distributions over these two subsets, P_{n,S^n}^0 and P_{n,S^n}^1 as

$$P_{n,S^n}^0 = \frac{1}{n_0} \sum_{i:S_i^n=0} \delta_{O_i},$$

$$P_{n,S^n}^1 = \frac{1}{n_1} \sum_{i:S_i^n=1} \delta_{O_i},$$

where $n_1 = \sum_{i=1}^n S_i^n$, $n_0 = 1 - n_1$ identifies the number of observations in the test and training set respectively.

Example 2 (Random splits). For n observations we have 2^n ways of choosing which observations should be in the training set and in the test set. It might not be desirable to define the discrete probabilities for S^n over $\{0, 1\}^n$ simply as $\frac{1}{2^n}$ for each possible combination of training/test data, since that would also include the combination where $n_1 = 0$. To ensure that there is always a certain amount of observations in our test set, let $0 < n_1 < n$ be given, we see that there are $\binom{n}{n_1}$ ways of choosing both the test and training set. We can therefore define the distribution of S^n as

$$P(S^n = s^n) = \binom{n}{n_1}^{-1} \quad \text{for each } s^n \in \{0, 1\}^n \text{ where } \sum_i s_i^n = n_1,$$

this procedure is also known as Monte Carlo cross-validation (Laan and Dudoit 2003). In practice one would have a hard time validating over all $\binom{n}{n_1}$ combinations as it can be very large, for $n = 100$ and $n_1 = 10$ corresponding to 10% of the data being in the validation set, the number of combinations is around $1.7 \cdot 10^{13}$. One would instead approximate by randomly sampling possible combinations. However, by doing random sampling there is the possibility that some observations will not be in any of the sampled validation sets. The probability of this happening will become small as we sample multiple times.

3.2 K-fold cross validation

The idea behind K -fold cross-validation is to split the data into K equally sized folds, where the candidate learners are fitted on $K - 1$ folds and their performance is evaluated on the remaining fold. We index the folds by $s \in \{1, \dots, K\}$ and let $s(i)$ indicate the fold that observation i belongs to. We will let $P_{n,s}^0$ denote the empirical measure over the observations that are not in fold s – the training set, and let $P_{n,s}^1$ denote the empirical measure over the observations that are in the fold s – the validation set.

K -fold cross-validation amounts to looking at a single split variable S^n whose probability mass is equally distributed on the binary vectors indexed by s . In practice one would select a K and use a random splitting procedure to generate K binary vectors such that the entire dataset is the disjoint union of the folds specified by each vector. It is also possible to run K -fold cross-validation multiple times which amounts to multiple calls to the random splitting procedure.

3.3 Risks and selectors

In the context where a learning algorithm is applied on the training data, we write $\psi(P_{n,S^n}^0)$ for the fitted learner. The performance of the learner is then evaluated on the test data. Given that the risk eq. (1) was the integral of the loss function with respect to data-generating distribution P , we can define the empirical risk of a learner as the integral of the loss with respect to the empirical measure of the test data, as follows

$$R(\psi(P_{n,S^n}^0), P_{n,S^n}^1) = \int L(o, \psi(P_{n,S^n}^0)) dP_{n,S^n}^1(o),$$

where S^n is some split for our data D_n . Our motivation for defining the empirical risk is that we can compare it with the true risk of the learner where we integrate with respect to the data-generating distribution

$$R(\psi(P_{n,S^n}^0), P) = \int L(o, \psi(P_{n,S^n}^0)) dP(o).$$

The following definitions are analogous to what is stated in section 1 and 2 of (Laan and Dudoit 2003).

Definition 5 (Risk averaged over splits (Vaart, Dudoit, and Laan 2006)). Given the data D_n , a split-variable S^n and a library Ψ . Let $\psi \in \Psi$ be a learning algorithm. The risk for the learner, $\psi(P_{n,S^n}^0)$, created from applying ψ on the training data, averaged over S^n is

$$E_{S^n} R(\psi(P_{n,S^n}^0), P),$$

where P is the data-generating distribution.

The expectation E_{S^n} is a simple average since S^n is discrete. Therefore, for a given ψ we have

$$E_{S^n} R(\psi(P_{n,S^n}^0), P) = \sum_{s \in \{0,1\}^n} R(\psi(P_{n,s}^0), P) \cdot P(S^n = s).$$

Definition 6 (Oracle selector (Laan and Dudoit 2003)). Given the data D_n , a split variable S^n and a library Ψ , the learning algorithm $\psi \in \Psi$ with the lowest averaged risk is the *oracle selected algorithm* for n observations

$$\tilde{\psi}_n := \arg \min_{\psi \in \Psi} E_{S^n} R(\psi(P_{n,S^n}^0), P).$$

The cross-validation selector replaces P with P_{n,S^n}^1 in the second argument of R .

Definition 7 (Cross-validation risk). Given the data D_n , a split-variable S^n and a library Ψ . Let $\psi \in \Psi$ be a learning algorithm. The cross-validation risk for the learner, $\psi(P_{n,s}^0)$, created from applying ψ on the training data, averaged over S^n is

$$E_{S^n} R(\psi(P_{n,S^n}^0), P_{n,S^n}^1),$$

where P_{n,S^n}^1 is the test data as specified by the split-variable.

Definition 8 (Cross-validation selector (Laan and Dudoit 2003)). Given the data D_n , a split variable S^n and a library Ψ , the learning algorithm $\psi \in \Psi$ with the lowest cross-validation risk is the *cross-validation selected algorithm* for n observations

$$\hat{\psi}_n := \arg \min_{\psi \in \Psi} E_{S^n} R(\psi(P_{n,S^n}^0), P_{n,S^n}^1).$$

The oracle selector and cross-validation selector are what chooses a learning algorithm from the library. Alternatively, one can first define the oracle selector as the index, \tilde{q} , of the algorithm in the library with the lowest risk, then the oracle selected algorithm would naturally be $\psi_{\tilde{q}}$.

3.4 Discrete super learner

Definition 9 (Discrete super learner). The *discrete super learner*, $\hat{\psi}_n(P_n)$, created from a library Ψ is the cross-validation selected algorithm fitted to the entire dataset

$$\mathcal{X} \ni x \mapsto \hat{\psi}_n(P_n)(x).$$

Formally, the map above is a random map as P_n is stochastic. The discrete super learner is not a specific learner among the learners in the library, but the resulting algorithm from applying the cross-validation selector, fitted to the dataset.

3.5 Oracle property

We introduce the notation Pf for the integral $\int f dP$ of an integrable function f with respect to P . Additionally, if P_n represents the empirical measure of O_1, \dots, O_n , we denote the empirical process indexed over an appropriate class of functions \mathcal{F} as $G_n f = \sqrt{n}(P_n f - Pf)$. Furthermore, we extend this notation to $G_{n,S^n}^v f = \sqrt{n}(P_{n,S^n}^v f - Pf)$ for the empirical processes that correspond to applying the empirical measure over either the training data or test data, $v = 0$ or $v = 1$.

In the following results we assume that a proper loss function $L : \mathcal{O} \times \Theta \rightarrow \mathbb{R}$ has been given.

Lemma 10 (Lemma 2.1 in (Vaart, Dudoit, and Laan 2006)). *Let G_n be the empirical process of an i.i.d. sample of size n from the distribution P and Ψ a library of learning algorithms. Furthermore, let $\hat{\psi}_n$ and $\tilde{\psi}_n$ denote the cross-validation- and oracle selected algorithms from Ψ respectively. For $\delta > 0$ it holds that*

$$\begin{aligned} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P) &\leq (1 + 2\delta) E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &\quad + E_{S^n} \frac{1}{\sqrt{n}} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d((1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n}P)(o) \\ &\quad + E_{S^n} \frac{1}{\sqrt{n}} \max_{\psi \in \Psi} \int -L(o, \psi(P_{n,S^n}^0)) d((1 + \delta)G_{n,S^n}^1 + \delta\sqrt{n}P)(o). \end{aligned}$$

Proof. See appendix. □

To control the bounds for the risk we introduce Bernstein pairs

Definition 11 (Bernstein pair (Vaart, Dudoit, and Laan 2006)). Given a measurable function $f : \mathcal{O} \rightarrow \mathbb{R}$, the tuple $(M(f), v(f))$ is a Bernstein pair if

$$M(f)^2 P \left(e^{|f|/M(f)} - 1 - \frac{|f|}{|M(f)|} \right) \leq \frac{1}{2} v(f). \quad (2)$$

Proposition 12. *If f is uniformly bounded, then $(\|f\|_\infty, \frac{3}{2}Pf^2)$ is a Bernstein pair.*

Proof. The following proof is due to (Vaart, Dudoit, and Laan 2006)[ch. 8.1].

$$\begin{aligned} \|f\|_\infty^2 P \left(e^{|f|/\|f\|_\infty} - 1 - \frac{|f|}{\|f\|_\infty} \right) &= \|f\|_\infty^2 \sum_{k \geq 2}^{\infty} P \frac{|f|^k}{\|f\|_\infty^k k!} = Pf^2 \sum_{k \geq 2}^{\infty} P \frac{|f|^{k-2}}{\|f\|_\infty^{k-2} k!} \\ &\leq Pf^2 \sum_{k \geq 2}^{\infty} \frac{\|f\|_\infty^{k-2}}{\|f\|_\infty^{k-2} k!} = Pf^2 \sum_{k \geq 2}^{\infty} \frac{1}{k!} \\ &= Pf^2(e-2) \leq \frac{3}{4}Pf^2 = \frac{1}{2} \left(\frac{3}{2}Pf^2 \right). \end{aligned}$$

In the first inequality we replace the absolute value of f with the uniform norm, which is larger. \square

Example 3 (Binary regression). Consider binary regression with quadratic loss. Let $\theta \in \Theta$ be arbitrary, then a Bernstein pair for the function $f_\theta(o) = L(o, \theta) = (Y - \theta(X))^2$ can be found by applying Proposition 12. By requiring that $\theta(x) \in [0, 1]$, then it is clear that f is bounded between 0 and 1 for all $o \in \mathcal{O}$ since $Y \in \{0, 1\}$. We also note that the Bernstein pair for f_θ satisfies $0 \leq \|f_\theta\|_\infty \leq 1$ and $0 \leq \frac{3}{2}Pf_\theta^2 \leq 1$, so they are bounded.

Lemma 13 (Lemma 2.2 in (Vaart, Dudoit, and Laan 2006)). *Let G_n be the empirical process of an i.i.d. sample of size n from the distribution P and assume that $Pf \geq 0$ for every $f \in \mathcal{F}$ in some set of measurable functions \mathcal{F} on \mathcal{O} . Then, for any Bernstein pair $(M(f), v(f))$ and for any $\delta > 0$ and $1 \leq p \leq 2$,*

$$E_{D_n} \max_{f \in \mathcal{F}} (G_n - \delta \sqrt{n}P)f \leq \frac{8}{n^{1/p-1/2}} \log(1 + \#\mathcal{F}) \max_{f \in \mathcal{F}} \left[\frac{M(f)}{n^{1-1/p}} + \left(\frac{v(f)}{(\delta Pf)^{2-p}} \right)^{1/p} \right].$$

The same upper bound is valid for $E_{D_n} \max_{f \in \mathcal{F}} (G_n + \delta \sqrt{n}P)(-f)$.

The expectation E_{D_n} is taken with respect to the joint probability measure over our observations, here we have that $D_n \sim P_O^n = P_{O_1} \otimes P_{O_2} \otimes \dots \otimes P_{O_n}$.

Theorem 14 (Theorem 2.3 in (Vaart, Dudoit, and Laan 2006)). *Let Ψ be a library of learning algorithms of size k . For $\theta \in \Theta$ let the numbers $(M(\theta), v(\theta))$ be a Bernstein pair for the function $o \mapsto L(o, \theta)$ and assume that $R(\theta, P) \geq 0$ for every $\theta \in \Theta$. Then for $\delta > 0$ and $1 \leq p \leq 2$ it holds that*

$$\begin{aligned} E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P) &\leq (1 + 2\delta) E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) + \\ &(1 + \delta) E_{S^n} \left(\frac{16}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta, P)^{2-p}} \right)^{1/p} \left(\frac{1+\delta}{\delta} \right)^{2/p-1} \right] \right). \end{aligned}$$

Where $\hat{\psi}_n$ and $\tilde{\psi}_n$ are the cross-validation- and the oracle selected algorithms from Ψ .

In the expectations above, we are taking the expectation with respect to the random split-variable S^n as well as the joint distribution of our observations. In a more verbose manner one would write

$$E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P) = \int R(\hat{\psi}_n(P_{n,S^n}^0), P) d(P_{S^n} \otimes P_O^n).$$

Proof. We will apply Lemma 13 to the second and third terms on the left hand side of the inequality in Lemma 10. Let $\mathcal{F} = \{o \mapsto L(o, \psi(P_{n,S^n}^0)) \mid \psi \in \Psi\}$, be the collection of functions obtained by applying the loss L to the algorithms in our library Ψ fitted on the training data. Note that $\mathcal{F} \subseteq \{o \mapsto L(o, \theta) \mid \theta \in \Theta\}$, and since $R(\theta, P) \geq 0$ for every $\theta \in \Theta$ it follows that $Pf \geq 0$ for every $f \in \mathcal{F}$.

First, we take the expectation with respect to D_n on both sides in Lemma 10. For the second term we have

$$\begin{aligned} & E_{D_n} E_{S^n} \frac{1}{\sqrt{n_1}} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d((1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P)(o) \\ &= E_{D_n} E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d(G_{n,S^n}^1 - \frac{\delta}{1 + \delta}\sqrt{n_1}P)(o) \\ &= E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} E_{D_n} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d(G_{n,S^n}^1 - \frac{\delta}{1 + \delta}\sqrt{n_1}P)(o). \end{aligned}$$

Where we use Fubini in the last equality. Recall that $S^n \perp\!\!\!\perp D_n$, so we can consider n_1 as fixed given D_n , now applying Lemma 13 to the expression above with $n = n_1$ yields

$$\begin{aligned} & E_S^n \frac{1 + \delta}{\sqrt{n_1}} E_{D_n} \max_{\psi \in \Psi} \int L(o, \psi(P_{n,S^n}^0)) d(G_{n,S^n}^1 - \frac{\delta}{1 + \delta}\sqrt{n_1}P)(o) \\ &\leq E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} \frac{8}{n_1^{1/p-1/2}} \log(1 + k) \max_{\psi \in \Psi} \left[\frac{M(\psi(P_{n,S^n}^0))}{n_1^{1-1/p}} + \left(\frac{v(\psi(P_{n,S^n}^0))}{(\frac{\delta}{1+\delta})^{2-p} R(\psi(P_{n,S^n}^0), P)^{2-p}} \right)^{1/p} \right] \\ &\leq E_{S^n} \frac{1 + \delta}{\sqrt{n_1}} \frac{8}{n_1^{1/p-1/2}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{(\frac{\delta}{1+\delta})^{2-p} R(\theta, P)^{2-p}} \right)^{1/p} \right] \\ &= (1 + \delta) E_{S^n} \frac{8}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta, P)^{2-p}} \right)^{1/p} \left(\frac{1 + \delta}{\delta} \right)^{2/p-1} \right]. \end{aligned}$$

Where for the third inequality we take the sup over Θ . We can also bound the third term with the same expression above as Lemma 13 is also valid for $-L$. It is now immediate from Lemma 10 that

$$\begin{aligned} & E_{D_n} E_{S^n} \int L(o, \hat{\psi}_n(P_{n,S^n}^0)) dP(o) \leq (1 + 2\delta) E_{D_n} E_{S^n} \int L(o, \tilde{\psi}_n(P_{n,S^n}^0)) dP(o) \\ &+ (1 + \delta) E_{S^n} \frac{8}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta, P)^{2-p}} \right)^{1/p} \left(\frac{1 + \delta}{\delta} \right)^{2/p-1} \right] \\ &+ (1 + \delta) E_{S^n} \frac{8}{n_1^{1/p}} \log(1 + k) \sup_{\theta \in \Theta} \left[\frac{M(\theta)}{n_1^{1-1/p}} + \left(\frac{v(\theta)}{R(\theta, P)^{2-p}} \right)^{1/p} \left(\frac{1 + \delta}{\delta} \right)^{2/p-1} \right]. \end{aligned}$$

The second and third terms above are identical, meaning that they can be combined into one term where the numerator in the first fraction is 16 instead of 8. \square

Remark. One might notice that S^n still appears in the remainder of the bound above, but the only variable in the remainder that depends on S^n is n_1 . It is, therefore, completely possible to drop the expectation with respect to S^n if n_1 is deterministic, for example, if it is a fraction of n .

In the following corollary we assume that the Bernstein pairs $(M(\theta), v(\theta))$ are bounded over Θ , thus taking the supremum over Θ will not result in the remainder being infinite. The assumption is indeed valid for binary regression as we have remarked upon in Example 3.

Corollary 15 (Asymptotic equivalence). *If there exists an $\varepsilon > 0$ such that*

$$E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) > \varepsilon \quad \text{for all } n \in \mathbb{N},$$

and if $n_1 \rightarrow \infty$ as $n \rightarrow \infty$, then the risk of the super learner is asymptotically equivalent to the risk of the oracle selected learner, that is

$$\lim_{n \rightarrow \infty} \frac{E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)} = 1.$$

For the sake of simplicity and the previous remark we will consider n_1 as a sequence of numbers polynomial in n , this will allow us to remove E_{S^n} in the remainder term.

Proof. We let δ depend on n , define $\delta_n := 1/\log(n)$. By choosing $p = 1$ in Theorem 14 and substituting δ with δ_n , we obtain

$$\begin{aligned} E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P) &\leq (1 + 2\delta_n) E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &\quad + (1 + \delta_n) \frac{16}{n_1} \log(1 + k) \sup_{\theta \in \Theta} \left[M(\theta) + \frac{v(\theta)}{R(\theta, P)} \cdot \frac{1 + \delta_n}{\delta_n} \right] \\ &= (1 + 2\delta_n) E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &\quad + (1 + \delta_n) \frac{16}{n_1} \log(1 + k) \sup_{\theta \in \Theta} \left[M(\theta) + \frac{v(\theta)}{R(\theta, P)} \cdot (\log(n) + 1) \right]. \end{aligned}$$

In the above inequality the remainder term goes to 0 as n_1 increases. The $\log(n)$ term in the supremum will be dominated by the $1/n_1$ that is multiplied in the front. By dividing the oracle risk on both sides, we obtain

$$\begin{aligned} \frac{E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)} &\leq 1 + 2\delta_n \\ &\quad + \frac{(1 + \delta_n) \frac{16}{n_1} \log(1 + k) \sup_{\theta \in \Theta} \left[M(\theta) + \frac{v(\theta)}{R(\theta, P)} \cdot (\log(n) + 1) \right]}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)}. \end{aligned}$$

The fraction on the right hand side will converge to 0 as $n \rightarrow \infty$, since n_1 is polynomial in n and the oracle risk is bounded away from 0 by assumption. The entire right hand side will therefore converge to 1 as $\delta_n \rightarrow 0$. Note also that by the definition of the oracle, we have

$$E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \leq E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P),$$

implying that

$$1 \leq \frac{E_{D_n} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)}{E_{D_n} E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P)},$$

applying the squeeze theorem thus yields the desired result. \square

In the proof of the asymptotic result we have chosen $\delta_n = 1/\log(n)$, in doing so, the remainder converges to 0 at a rate of $\log(n)/n$. An immediate consequence of this is that if we have a library of parametric learning algorithms and one of them corresponds to the true regression, then the oracle risk might very well converge at a rate of $1/n$, implying that

the risk of the discrete super learner achieves an almost parametric rate of convergence of $\log(n)/n$ to the oracle (Laan, Polley, and Hubbard 2007). For the asymptotic equivalence to hold, we must have that $n_1 \rightarrow \infty$ as $n \rightarrow \infty$. This is a reasonable assumption for cross-validation schemes such as K -fold cross-validation or if $n_1 = np$ for $p \in (0, 1)$ where the test size increases with the amount of available data. Note that the condition is not satisfied for leave-one-out cross-validation since n_1 is equal to 1 for every n .

Example 4 (Regression). In the context of a regression problem with quadratic loss, the risk for a learner can never be zero unless the outcome is deterministic given x . We may begin by noting that the risk of $\theta^*(x) = E(Y | X = x)$ is always positive,

$$\int (Y - E(Y | X))^2 dP \geq 0.$$

Since the integrand is positive, the integral is zero if and only if $Y = E(Y | X)$ almost surely. That is only the case when Y is deterministic given X , i.e. Y is X -measurable. Assuming, therefore, that Y is not deterministic given X , then we note that by the fact that the quadratic loss is strictly proper due to Theorem 2, it holds for any $\theta \in \Theta$ that

$$R(\theta, P) \geq R(\theta^*, P) > 0,$$

thus showing that the risk of any learner is strictly positive.

4 The Ensemble Super Learner

The idea behind the *ensemble super learner* is to combine the predictions made by each learner, $\psi_1(P_n), \dots, \psi_k(P_n)$, into a single prediction. The idea of combining learners was examined in Breiman 1996 which considered how a linear combination of the learners in the library could be formed. This approach, also known as *stacked regression* or *stacking* is a variant of the ensemble super learner. The ensemble super learner, however, does not limit itself to linear combinations but uses a *meta learning algorithm* on the *level 1 data* – the predictions made by the learners. It is a broad approach of balancing the weaknesses of each learner by forming an ensemble. However, as we will see, K -fold cross-validation is integral in forming the ensemble super learner.

We will proceed to give the definitions and setup necessary to define the ensemble super learner.

4.1 Level 1 data

Let D_n be our data and let Ψ be a library of learning algorithms. The *level 1 covariates* of Ψ applied to D_n as specified by a K -fold cross validation procedure is

$$\mathcal{Z} = \{Z_i = (\psi_1(P_{n,s(i)}^0)(X_i), \dots, \psi_k(P_{n,s(i)}^0)(X_i))\}_{i=1}^n \subseteq [0, 1]^k,$$

which is the set of possible outcomes by applying the learners on the observed X_i 's.

Definition 16 (Level 1 data). The *level 1 data* is given by concatenating our observed Y_i 's with the level 1 covariates, i.e.

$$\mathcal{L}_n = \{(Y_i; Z_i) = (Y_i; \psi_1(P_{n,s(i)}^0)(X_i), \dots, \psi_k(P_{n,s(i)}^0)(X_i))\}_{i=1}^n \subseteq \{0, 1\} \times \mathcal{Z}.$$

The level 1 data is exactly the predictions made by the learners on the observations that they were not trained on. Thus, *level 0 data* is what we refer to as D_n . We now define \mathcal{M} as the class of all measurable functions that map from \mathcal{Z} to $[0, 1]$ which we will refer to as *meta learners*.

4.2 Meta learners

Definition 17 (Meta learner). The *meta learner* is a function $\phi : \mathcal{Z} \rightarrow [0, 1]$ in \mathcal{M} that maps the output of the candidate learners to a prediction.

The goal is to estimate the regression of Y given the predictions made by our learners, $\mathcal{Z} \ni z \mapsto E(Y | Z = z)$, which is an element in \mathcal{M} . We accomplish this by applying a *meta learning algorithm* to the level 1 data.

Definition 18 (Meta learning algorithm). A *meta learning algorithm* Φ is a measurable map that creates a meta learner from our level 1 data $\mathcal{L}_n \mapsto \Phi(\mathcal{L}_n) \in \mathcal{M}$.

A meta learning algorithm seeks to estimate $E(Y | Z)$. It can for example be a parametric learning algorithm such as logistic regression. If a parametric learning algorithm is used, it is important to take into account that the level 1 covariates Z_i are highly correlated and that multicollinearity can occur. Breiman 1996 suggests ridge regression as a possible way to shrink the coefficients. Another method is to use a non-negativity constraint, where we specify that the coefficients are positive and must sum to 1 in the case of a simple linear combination.

4.3 Ensemble super learner

Definition 19 (Ensemble super learner (Laan, Polley, and Hubbard 2007)). Let a library of learning algorithms Ψ be given and let \mathcal{L}_n be the level 1 data obtained by fitting each learning algorithm according to some K -fold cross validation procedure. Let $\phi = \Phi(\mathcal{L}_n)$ be the outcome of applying a meta learning algorithm to the level 1 data, then the map

$$x \mapsto \Sigma(P_n)(x) = \phi(\psi_1(P_n)(x), \dots, \psi_k(P_n)(x)),$$

is called the *ensemble super learner* and we will denote it by $\Sigma(P_n)$.

Here the P_n indicates that each learner $\psi \in \Psi$ is fitted on the entire data set. A meta learner, ϕ , is used to combine the predictions made by each learner.

4.4 Oracle property

The meta learning algorithm, Φ , fits the meta learner that best estimates $E(Y | Z)$, a way of formalizing the notion of ‘fitting’ is that Φ seeks to select the meta learner with the lowest risk among a indexed set of meta learners. Let \mathcal{A} be a parameter set (for example Euclidean), for each $a \in \mathcal{A}$ let ϕ_a be a meta learner. In a practical setting, one might consider ϕ_a as the learner obtained by instantiating it with the parameter a . Given our level 1 data \mathcal{L}_n , define

$$\hat{a} := \arg \min_{a \in \mathcal{A}} \frac{1}{n} \sum_{i=1}^n L((Y_i, Z_i), \phi_a) = \arg \min_{a \in \mathcal{A}} \frac{1}{n} \sum_{i=1}^n (Y_i - \phi_a(Z_i))^2. \quad (3)$$

The meta learning algorithm applied to \mathcal{L}_n returns $\phi_{\hat{a}}$, which is the meta learner with the lowest empirical risk on the level 1 data. We will now consider a subset $\mathcal{A}_n \subseteq \mathcal{A}$

such that the number of elements in the subset, $k(n) = |\mathcal{A}_n|$, depends on n . Denote the ensemble super learner that uses the meta learner ϕ_a as

$$\Sigma_a(P_n) := \phi_a(\psi_1(P_n), \dots, \psi_k(P_n)).$$

Let the cross-validation- and oracle selector of a be

$$\begin{aligned}\hat{a}_n &:= \arg \min_{a \in \mathcal{A}_n} \frac{1}{K} \sum_{s=1}^K R(\Sigma_a(P_{n,s}^0), P_{n,s}^1), \\ \tilde{a}_n &:= \arg \min_{a \in \mathcal{A}_n} \frac{1}{K} \sum_{s=1}^K R(\Sigma_a(P_{n,s}^0), P),\end{aligned}$$

where P is the data-generating distribution in our level 0 data. Note that for each s' up to K

$$\Sigma_a(P_{n,s'}^0)(X_i) = \phi_a(\psi_1(P_{n,s'}^0)(X_i), \dots, \psi_k(P_{n,s'}^0)(X_i)) = \phi_a(Z_i).$$

holds true for each i if $s(i)$ equals s' , i.e. when X_i is in the validation set s' . By using the fact that the K folds are disjoint and exhaustive, we can express \hat{a}_n as

$$\hat{a}_n = \arg \min_{a \in \mathcal{A}_n} \frac{1}{K} \sum_{s'=1}^K \frac{1}{n} \sum_{i:s(i)=s'} (Y_i - \Sigma_a(P_{n,s'}^0)(X_i))^2 = \arg \min_{a \in \mathcal{A}_n} \frac{1}{n} \sum_{i=1}^n (Y_i - \phi_a(Z_i))^2. \quad (4)$$

Equation (4) shows that the cross-validation selector, \hat{a}_n , is exactly the objective of the meta learning algorithm defined in (3).

The way that \hat{a}_n and \tilde{a}_n are defined fit directly into our existing framework for the discrete super learner. Recall that the cross-validation selector selected the algorithm that had the lowest cross-validation risk averaged across some split variable S^n . By using a K -fold cross-validation scheme, the averaged risk over S^n becomes the averaged risk over the K folds, which is exactly the above definition of \hat{a}_n . In the case of the ensemble super learner, the learning algorithm, ϕ_a , is determined by the parameter a , so the selection problem reduces to selecting the most optimal parameter over a finite parameter set \mathcal{A}_n . The parameter set \mathcal{A}_n indexes the meta learning algorithms, and is what the cross-validation selector acts upon. It is, therefore, possible to think of \mathcal{A}_n as approximating the entire parameter set \mathcal{A} using a grid of points such that the approximation becomes finer as the number of points increase. The key difference lies in the fact that the ensemble super learner is a completely new learner, whereas the discrete super learner is an algorithm selected from the library Ψ fitted on the dataset.

The following finite sample oracle inequality is a direct consequence of the oracle inequality for the discrete super learner, Theorem 14.

Theorem 20 (Finite sample oracle inequality). *Let Ψ be a library of learning algorithms of size k . Let $\Sigma_{\hat{a}_n}$ be the ensemble super learner over Ψ obtained by applying the cross-validation selector over a finite parameter space \mathcal{A}_n using the K -fold cross-validation scheme. Let $\Sigma_{\tilde{a}_n}$ be the oracle ensemble learner obtained by applying the oracle selector over the same set of parameters. If the conditions of Theorem 14 are satisfied, then the following oracle inequality holds*

$$\begin{aligned}\frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\hat{a}_n}(P_{n,s}^0), P) &\leq (1 + 2\delta) \frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\tilde{a}_n}(P_{n,s}^0), P) \\ &\quad + (1 + \delta) \frac{16K}{n} \log(1 + k(n)) \sup_{\theta \in \Theta} \left[M(\theta) + \frac{v(\theta)}{R(\theta, P)} \frac{1 + \delta}{\delta} \right].\end{aligned}$$

Proof. Replace E_{S^n} in Theorem 14 with the average over the K folds and n_1 with n/K , then by using $p = 1$ the desired result is obtained. \square

Corollary 21 (Asymptotic equivalence). *If the number of points in the parameter sets \mathcal{A}_n grows at most at a polynomial rate, that is $k(n) \leq n^p$ for some $p \in \mathbb{N}$, then the ensemble super learner $\Sigma_{\hat{a}_n}$ is asymptotically equivalent to the oracle ensemble learner $\Sigma_{\tilde{a}_n}$, i.e.*

$$\lim_{n \rightarrow \infty} \frac{\frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\hat{a}_n}(P_{n,s}^0), P)}{\frac{1}{K} \sum_{s=1}^K E_{D_n} R(\Sigma_{\tilde{a}_n}(P_{n,s}^0), P)} = 1.$$

Proof. The proof is analogous to Corollary 15. We will replace δ with $\delta_n = 1/\log(n)$. Note that in the remainder, the $\log(1+k(n))$ term is less than $1+\log(k(n)) = 1+p\log(n)$, which is of lower order than n . The $(1+\delta_n)/\delta_n$ term simplifies to become $1+\log(n)$, and when multiplied with the $\log(1+k(n))$ term, becomes of order $\log(n)^2$ that is still of lower order than n . Thus the remainder term goes to zero as $n \rightarrow \infty$ and the asymptotic result is implied. \square

4.5 Choice of meta learning algorithm

Given the level 1 data, \mathcal{L}_n , the meta learning algorithm seeks to optimize over the parameter set $\mathcal{A}_n \subseteq \mathcal{A}$. The interpretation of \mathcal{A} depends on the chosen learning algorithm. If a parametric learning algorithm is used, for example logistic regression, then \mathcal{A} is \mathbb{R}^k where k is the number of learners in Ψ . The learner ϕ_a for $a \in \mathcal{A}$ will then be the map $z \mapsto \text{expit}(az)$. Laan, Polley, and Hubbard 2007 mentions that it is also possible to use a non-parametric learning algorithm as the meta learning algorithm, or even apply a super learning algorithm on the level 1 data. In this case \mathcal{A} could be measurable functions from \mathcal{Z} to $[0, 1]$. The learner ϕ_a for $a \in \mathcal{A}$ will then be the map $z \mapsto a(z)$.

Constrained regression and the $(k - 1)$ -simplex

Here we examine a simple meta learning algorithm which is to do a constrained regression on the level 1 data. The reason for examining this particular meta learning algorithm is because the discrete super learner is a special case of the ensemble super learner that utilizes this algorithm. The goal is to fit a weighted combination of the learners, such that the weights sum to 1. We can achieve this by parametrizing \mathcal{A} as the $(k - 1)$ -simplex given by

$$\mathcal{A} = \left\{ a \in \mathbb{R}^k \mid \sum_{q=1}^k a_q = 1, a_q \geq 0 \text{ for } 1 \leq q \leq k \right\},$$

where $k = |\Psi|$ is the number of algorithms in our library. The meta learner ϕ_a for $a \in \mathcal{A}$ is then the map $z \mapsto z \cdot a$. By Cauchy-Schwarz we have $z \cdot a \leq \|z\| \|a\| \leq 1$ meaning that the range of ϕ_a is $[0, 1]$. The ensemble super learner that applies the meta learner ϕ_a is, therefore, a valid learner in Θ . To apply the oracle results, we will cover \mathcal{A} with equidistant points on the simplex surface. For every n , we specify $\mathcal{A}_n \subseteq \mathcal{A}$ such that the number of points in \mathcal{A}_n increases with n at a polynomial rate, and that for any $a \in \mathcal{A}$ we have

$$\min_{b_n \in \mathcal{A}_n} \|a - b_n\| \leq \frac{1}{n}.$$

This is clearly possible by Figure 1. It thus follows that we can find a sequence of points $b_n \in \mathcal{A}_n$ such that $\phi_{b_n} \rightarrow \phi_a$ for any $a \in \mathcal{A}$. The conclusion is that if \tilde{a} specified the learner $\phi_{\tilde{a}}$ with the minimum risk, then by applying the cross-validation selector and letting $n \rightarrow \infty$, the meta learner adopted by the ensemble super learner will eventually converge to $\phi_{\tilde{a}}$.

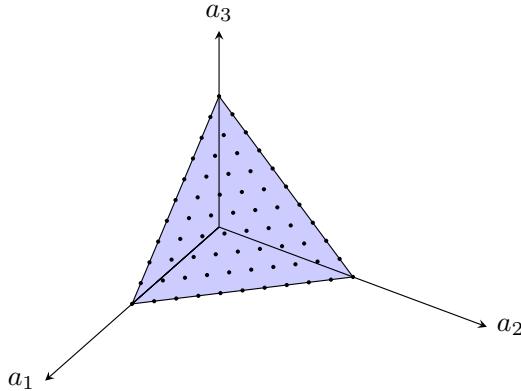


Figure 1: The parameter set \mathcal{A} of learner weights visualized as a 2-simplex for library of size $k = 3$. The k axes span the weight combinations for the library where the weight combinations that sum to 1 lie on the simplex. Here the discrete approximation \mathcal{A}_n is visualized as points on the simplex.

The discrete super learner is essentially a special case of the ensemble super learner that utilizes constrained regression. If $a_q = 1$ for any $1 \leq q \leq k$ then the ensemble super learner predicts the same as the q 'th learner. The discrete super learner can, therefore, be seen as constrained regression optimizing for a over the vertices of the $(k - 1)$ -simplex. Given that the training data is representative of the data-generating distribution, the ensemble learner that uses constrained regression should outperform the discrete super learner at minimizing risk since it optimizes over the entire $(k - 1)$ -simplex.

5 Simulations

In the following section we show the results of applying the two super learners to a simulated dataset. The simulations are carried out using the R programming language and the corresponding source code can be found on the GitHub repository for this project (Liu 2023). The simulated dataset consists of a binary outcome, Y , which depends on two covariates X_1 and X_2 . The setup is as follows

$$\begin{aligned} X_1 &\sim \text{Unif}(0.5, 15), \\ X_2 | X_1 = x_1 &\sim \mathcal{N}(3.5 - 0.03x_1, 1), \\ Y | X_1 = x_1, X_2 = x_2 &\sim \text{Ber}(\theta_0(x_1, x_2)), \end{aligned}$$

for $\theta_0(x_1, x_2) = \text{expit}(-3.5 - 0.3x_1 + 0.85x_2 + 0.35x_1x_2)$ which is the data-generating regression function. It is in fact possible to visualize the regression function explicitly as a 2-dimensional heat map in the covariates. In Figure 2 we have applied the true regression across the grid of (x_1, x_2) covariate pairs in $(0, 15) \times (0, 7)$ where the spacing is 0.5 horizontally and vertically between each pair. The probabilities are colored from 0 to 1 in the plot.

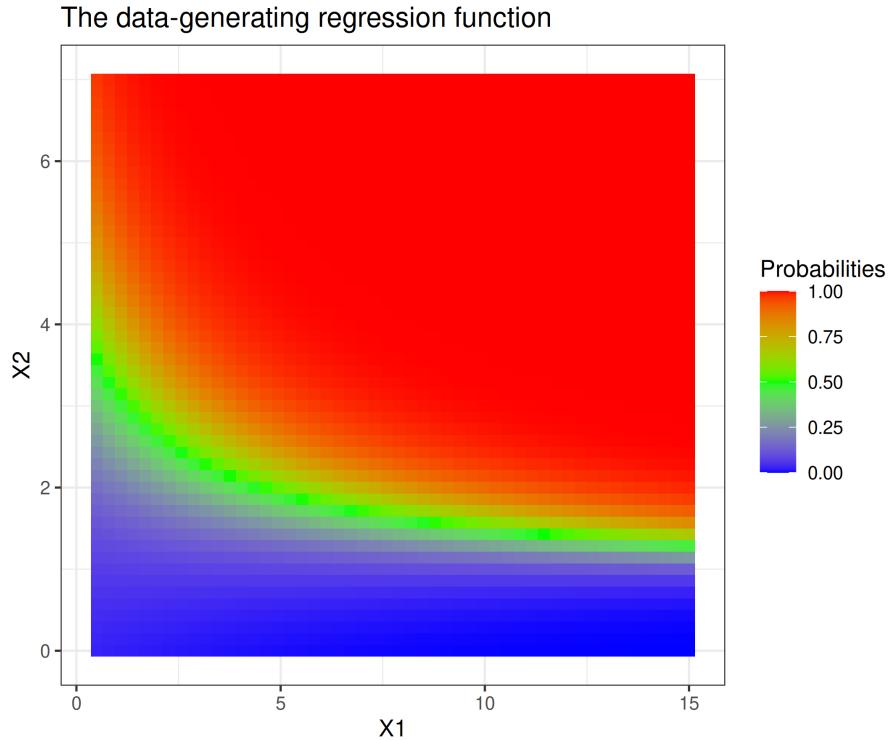


Figure 2: The data-generating regression plotted as a heat map. The two covariates X_1 and X_2 are mapped by the regression function θ_0 to a probability as indicated by the colors.

The regression is captured by the logistic regression model with interaction terms. We will use the following library of learning algorithms as an illustrative example:

1. Intercept only logistic regression: $E[Y | X_1, X_2] = \text{expit}(\beta_0)$
2. Logistic regression with main effects: $E[Y | X_1, X_2] = \text{expit}(\beta_0 + \beta_1 X_1 + \beta_2 X_2)$
3. XGBoost with hyperparameters: `max_depth=3, eta=0.3, n_rounds=100, objective='binary:logistic', booster='dart', nthread=5`

The intercept only logistic regression is included as a baseline, the predicted probability by the intercept model is simply the sample average over the observed Y_i 's.

We can visualize the predictions of the learning algorithms in the library in the same way as we have done for the data-generating regression. In Figure 3 we visualize the predictions of the main effects logistic regression and XGBoost fitted using 1000 observations sampled from the distribution. The plot for the intercept model is omitted, as its appearance is as one would expect – the plot is simply an orange square.

From Figure 3 we can observe a clear difference in the predicted probabilities between the logistic regression and the tree-based XGBoost. The main effects logistic regression is a parametric model that assumes that the regression function is a smooth transformation of the linear predictor $X\beta$. XGBoost, in contrast, is made up of many decision trees, which explains the patchwork pattern in its prediction plot. For small samples and as we will see in the simulations, XGBoost has a high risk in comparison to the misspecified main effects logistic regression. However, XGBoost becomes increasingly better at approximating the regression when the number of observations becomes large as seen in Figure 4.

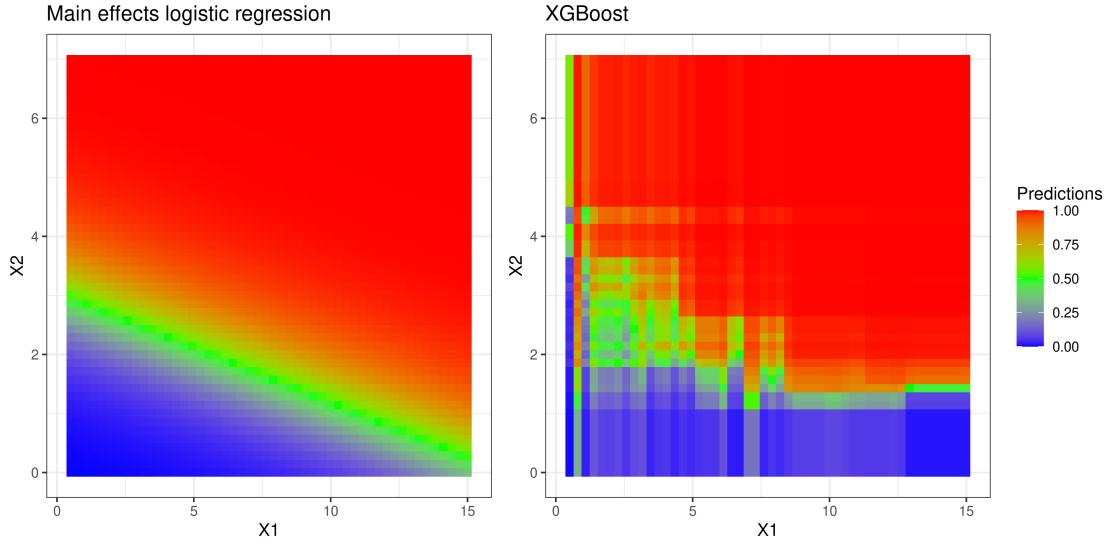


Figure 3: The predictions of the main effects logistic regression and XGBoost fitted on 1000 observations.

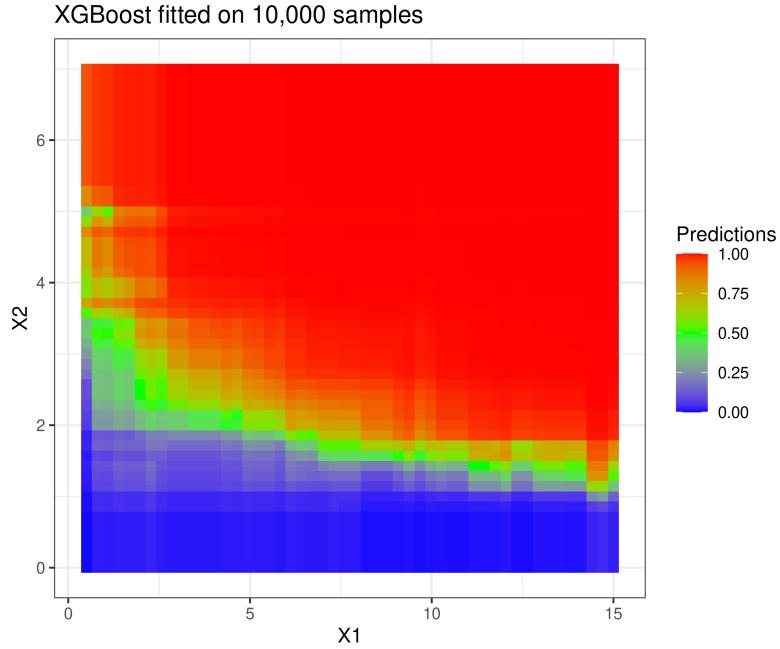


Figure 4: XGBoost becoming better at approximating the regression as the sample size increases. Here the predictions of XGBoost is visualized for a training sample size of 10 000. They appears to be more stable in comparison to Figure 3.

5.1 Discrete super learner

By applying the discrete super learning algorithm to the library, we will see that the discrete super learner is able to qualitatively assess and select the best learning algorithm to apply given the amount of data at hand. The discrete super learner uses the main effects logistic regression in the beginning with few training samples, but as the predictions of XGBoost become more stable with more observations, it shifts its preference towards XG-

Boost. The performance of the discrete super learner will be compared with the learning algorithms in the library on the simulated dataset, we show that:

1. As the sample size increases, the discrete super learner achieves the minimum risk
2. The variance of the discrete super learner's prediction for a single new observation does not always exhibit a steady descent and depends on the other learners in the library

The discrete super learner in our simulations uses 10-fold cross-validation and the internal loss function will be the quadratic loss. While it is possible to do repeated K -fold cross-validation, in our simulations the super learner will only run the cross-validation procedure once given the training data. The following snippet is pseudocode for the discrete super learner algorithm:

Algorithm 1 Discrete super learner

```

1: Input:  $P_n$ : dataset,  $V$ : number of folds,  $\Psi$ : library of learning algorithms of size  $k$ ,  

    $L$ : loss function
2: Output: discrete super learner  $\hat{\psi}_n(P_n)$ 
3:  $s \leftarrow$  create random folds( $P_n, V$ )            $\triangleright$  Randomly assign observations to folds
4:  $\ell \leftarrow$  empty array of dimensions  $V \times k$            $\triangleright$  Array of risks
5: for  $s \in \{1, \dots, V\}$  do
6:    $P_{n,s}^1 \leftarrow \{O_i \in D_n \mid s(i) = s\}$ 
7:    $P_{n,s}^0 \leftarrow D_n \setminus P_{n,s}^1$ 
8:   for  $\psi \in \Psi$  do
9:      $\psi(P_{n,s}^0) \leftarrow \text{fit}(\psi, P_{n,s}^0)$ 
10:     $\ell[s, \psi] \leftarrow R(\psi(P_{n,s}^0), P_{n,s}^1) = \frac{V}{n} \sum_{O_i \in P_{n,s}^1} L(O_i, \psi(P_{n,s}^0))$ 
11:   end for
12: end for
13: for  $\psi \in \Psi$  do
14:    $\ell_{\text{avg}}(\psi) \leftarrow \frac{1}{V} \sum_{s=1}^V \ell[s, \psi]$ 
15: end for
16:  $\hat{\psi}_n \leftarrow \arg \min_{\psi \in \Psi} \ell_{\text{avg}}(\psi)$ 
17:  $\hat{\psi}_n(P_n) \leftarrow \text{fit}(\hat{\psi}_n, P_n)$ 
18: return  $\hat{\psi}_n(P_n)$ 

```

Discrete super learner performance

The true regression achieves a risk of 0.059 using the quadratic loss function on a validation set of size 10^6 . This risk represents the minimum achievable risk for any learning algorithm operating on this dataset. The intercept model – which is equivalent to predicting an average of the outcomes – achieves a risk of 0.11, which serves a basic benchmark if no effort was made to learn from the data at all. If any learning algorithm performs worse than the benchmark, then it should naturally be discarded from the library.

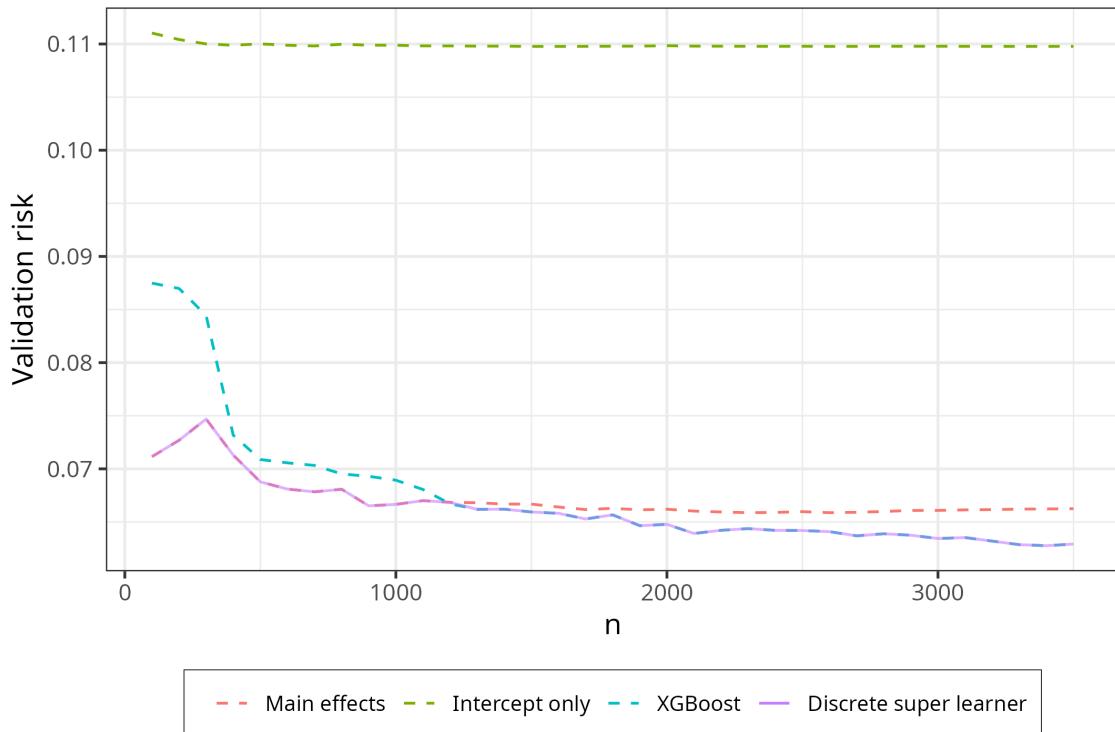


Figure 5: The risk of the discrete super learner compared to other algorithms where the number of training samples are $n = 100, 200, \dots, N = 3500$. For each n , each learning algorithm is fitted and their validation risks are calculated on a validation set of 10^6 observations.

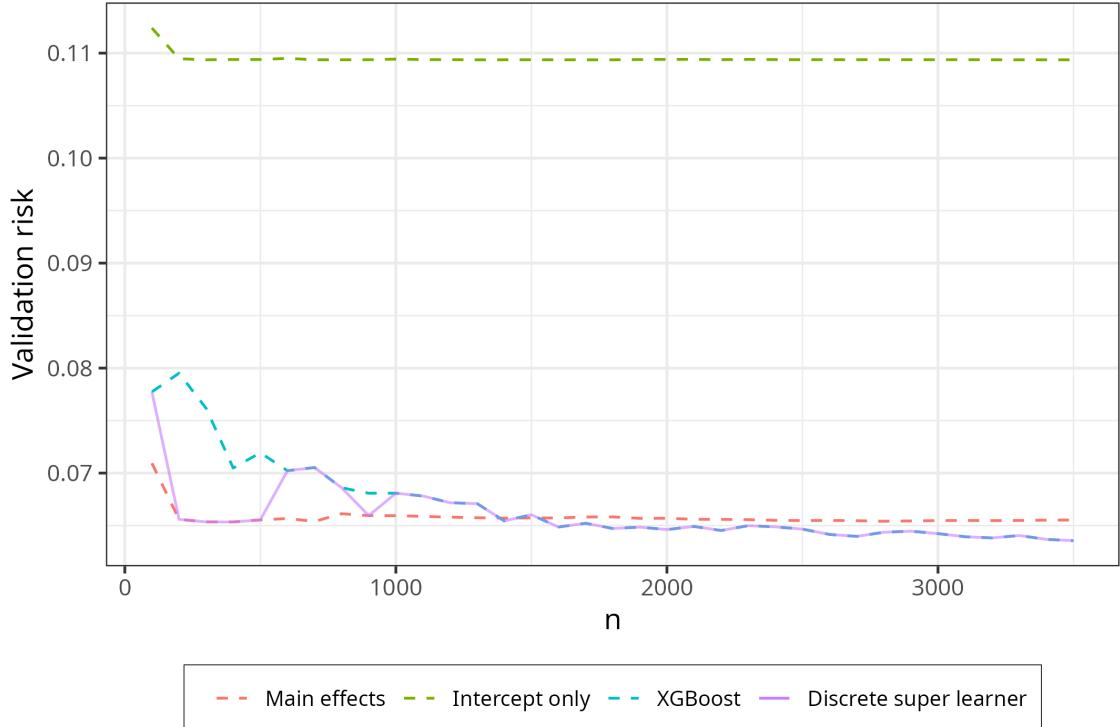


Figure 6: Same experiment as illustrated in Figure 5 but in another run. The training data is drawn from the data-generating distribution and is therefore subject to seed randomness, the resulting fitted learners will not be the same the two runs.

Figures 5 and 6 illustrate how the discrete super learner performs in comparison to the learners in terms of loss over number of training samples. The plots are generated for two runs where the algorithms are fitted on $n = 100, 200, \dots, N = 3500$ observations, as indicated by the horizontal axis. Then the validation risk is calculated by evaluating each fitted learner on a fixed validation set of 10^6 observations which was sampled from the data-generating distribution. The risk for XGBoost is around 0.062 when it is trained on 3500 observations. While it is above the optimal risk of 0.059, it surpasses the main effects model that has a risk of 0.066. When compared to the benchmark intercept model that has a risk of 0.11, XGBoost clearly superior. The first run perfectly illustrates how the discrete super learner is able to achieve the minimum risk. For small training sample sizes, the machine learning method XGBoost has a higher risk than the main effects logistic regression, and it is therefore more desirable for the discrete super learner to select logistic regression despite that it is misspecified. The discrete super learner consequently achieves the same risk as the logistic regression in the beginning, but for $n > 1200$ the risk of the discrete super learner becomes smaller. Here XGBoost begins to achieve a lower risk than the misspecified logistic regression, and so the discrete super learner chooses to use XGBoost instead.

The second run shows that the discrete super learner might be unable to determine the learner with the lowest risk when the training sample size is small, which results in it moving in a zig-zag pattern between two learners that have quite similar risks. However, we see that the discrete super learner eventually chooses XGBoost as the number of training samples grows.

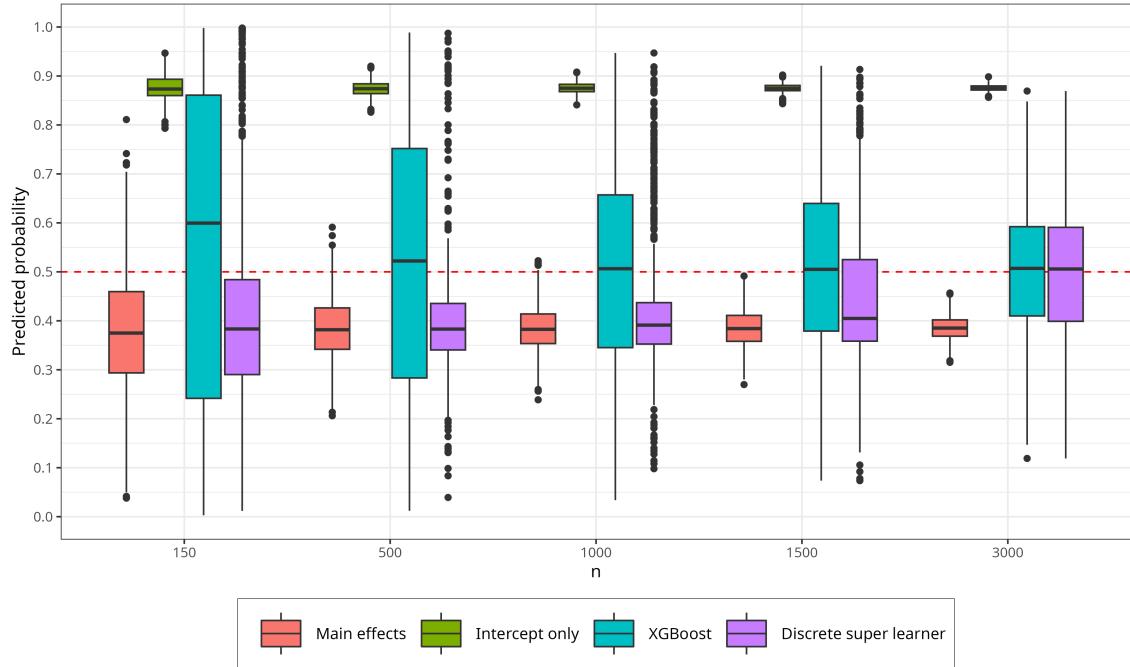


Figure 7: Variances of learner predictions for a single observation. Each learning algorithm is fitted $K = 1000$ on n samples. Each time they are fitted, they are used to predict on a single fixed observation whose true probability is 0.5.

Figure 7 illustrates the variance in the predictions by each learner for a single observation, whose true probability is indicated by the red dashed line at $p = 0.5$. Each learner has been trained $K = 1000$ times on $n = 150, 500, \dots, 3000$ samples taken from the distribution and is used to predict K times after each training. The box plots are created from the K predictions.

We observe that the machine learning model, XGBoost, has the highest prediction variance across all training sample sizes. Recall that we only had two covariates, here having 1500 observations limits the range of predictions of our main effects model to be between 0.27 and 0.46, whereas for XGBoost it can vary from below 0.1 to above 0.9. While XGBoost is extremely efficient at minimizing loss, its predictions have a high variance unless one has a lot of training data.

The discrete super learner achieves a lower variance than XGBoost for all training sample sizes, which can be attributed to its preference of the main effects logistic regression when the training sample size is small, that has a lower variance than XGBoost. However, the variance of the discrete super learner increases when $n \geq 1000$ and the box plots become wider. This is due to the discrete super learner predicting the same as XGBoost since around these numbers of training samples since XGBoost begins to achieve a lower risk in comparison to the main effects logistic regression.

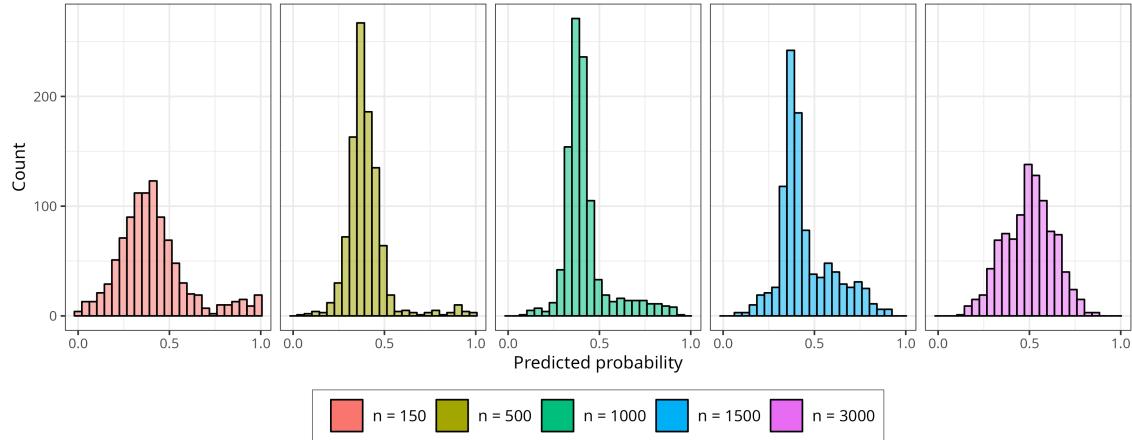


Figure 8: Predictions for a single observation by the discrete super learner varied over number of training samples. The predictions made by the discrete super learner from Figure 7 is extracted and plotted as histograms.

By examining Figure 8, we see that the distribution of the predictions by the discrete super learner changes with the number of training samples. The figure explains the outlier points that for the discrete super learner box plots in Figure 7. The conclusion here is a reiteration of what we have already pointed out before. In the beginning for $n = 150$ to $n = 500$ the discrete super learner prefers the predictions made by the main effects logistic regression which results in a spiked distribution that is centered around $p = 0.4$. The discrete super learner assigns more importance to XGBoost predictions when $n \geq 1000$, which leads to more predictions for $p > 0.4$ and forms a tail distribution. At some point between $n = 1500$ and $n = 3000$, the discrete super learner is no longer uncertain that XGBoost achieves the lowest risk, and so it begins predicting the same as XGBoost.

5.2 Ensemble super learner

We will compare the performance of the ensemble super learner with the discrete super learner on the simulated dataset from before, we show that by using the constrained regression meta learning algorithm

1. The ensemble super learner achieves lower risk than the discrete super learner
2. The ensemble super learner has a lower prediction variance on a single new observations than the discrete super learner

The ensemble super learner will use the same library of algorithms as the discrete super learner, they are the intercept only logistic regression (baseline), the main effects logistic regression and the gradient boosting algorithm XGBoost. The ensemble super learner does internal 10-fold cross-validation similarly to the discrete super learner, except that the out-of-fold predictions are saved in order to create the level 1 dataset. The following snippet is the pseudocode for the ensemble super learner algorithm:

Algorithm 2 Ensemble super learner

```

1: Input:  $P_n$ : dataset,  $V$ : number of folds,  $\Phi$ : meta learning algorithm,  $\Psi$ : library of
   learning algorithms of size  $k$ 
2: Output: ensemble super learner  $\Sigma(P_n)$ 
3:  $\mathcal{L}_n \leftarrow$  empty array of dimensions  $n \times (k + 1)$                                  $\triangleright$  Level 1 data
4:  $s \leftarrow$  create random folds( $P_n, V$ )                                          $\triangleright$  Randomly assign observations to folds
5: for  $s \in \{1, \dots, V\}$  do
6:    $P_{n,s}^1 \leftarrow \{O_i \in P_n \mid s(i) = s\}$ 
7:    $P_{n,s}^0 \leftarrow P_n \setminus P_{n,s}^1$ 
8:   for  $\psi \in \Psi$  do
9:      $\psi(P_{n,s}^0) \leftarrow \text{fit}(\psi, P_{n,s}^0)$ 
10:    for  $(Y_i, X_i) = O_i \in P_{n,s}^1$  do
11:       $\mathcal{L}_n[i, 1] \leftarrow Y_i$ 
12:       $\mathcal{L}_n[i, \psi] \leftarrow Z_{i,\psi} = \psi(P_{n,s}^0)(X_i)$                                 $\triangleright$  Save out-of-fold predictions
13:    end for
14:   end for
15: end for
16:  $\phi \leftarrow \text{fit}(\Phi, \mathcal{L}_n)$                                           $\triangleright$  Fit meta learning algorithm on level 1 data
17: for  $\psi \in \Psi$  do
18:    $\psi(P_n) \leftarrow \text{fit}(\psi, P_n)$                                           $\triangleright$  Fit each learning algorithm on all data
19: end for
20:  $\Sigma(P_n) \leftarrow (x \mapsto \phi(\psi_1(P_n)(x), \psi_2(P_n)(x), \dots, \psi_k(P_n)(x)))$ 
21: return  $\Sigma(P_n)$ 

```

We visualize the predictions made by the ensemble super learner as we have done in Figure 3. Figure 9 displays the predictions of the ensemble super learner fitted on 1000 and 10 000 observations using the constrained regression meta algorithm. To do constrained regression we use the R package *lse1* (Wang, Lawson, and Hanson 2020), which is used to solve the quadratic programming problem under constraints.

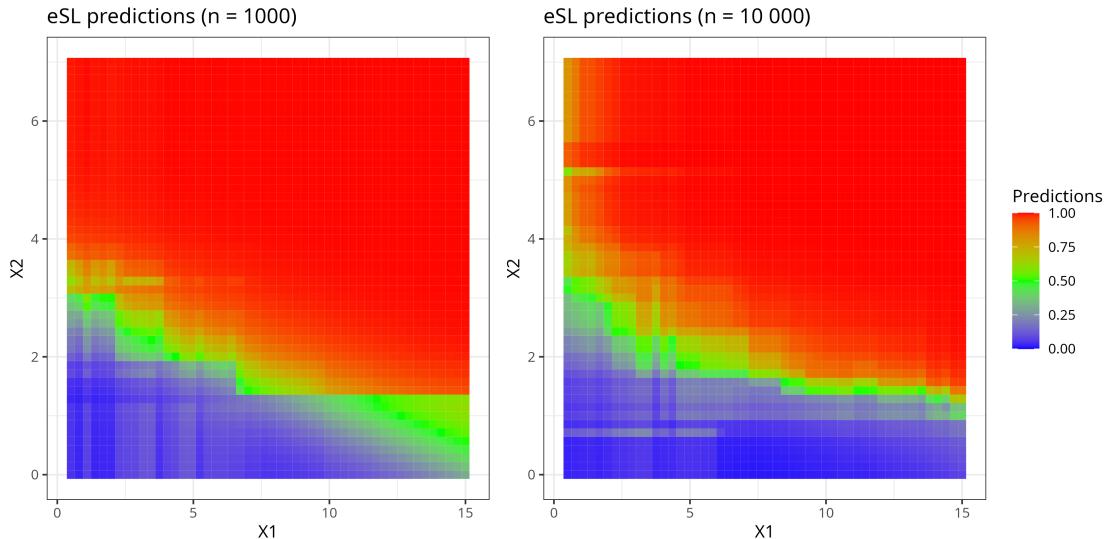


Figure 9: The predictions by the ensemble super learner using the constrained regression meta learning algorithm fitted on 1000 and 10 000 observations

The predictions of the ensemble super learner is a weighted combination of the predictions made by the learners in the library. The contribution from XGBoost is apparent in the patchy pattern that characterize tree-based algorithms which we touched on before. However, we see that there is a clear gradient in the predictions for $n = 1000$ when crossing from $p < 0.5$ to $p > 0.5$, this is likely due to the contribution from the main effects model, which predicts $p = 0.5$ along a negatively sloped line through the plot. The weights of the constrained regression can be extracted, in this simulation with $n = 1000$ and $n = 10\,000$ the fitted weights are

Learner	$n = 1000$	$n = 10\,000$
Intercept	0.008560352	0.000109466
Main effects	0.598493218	0.136615961
XGBoost	0.392946430	0.863274573

Table 1: Combined Table

From the weights we see that the predictions of intercept only logistic regression is not important at all for the ensemble super learner. For $n = 1000$ the predictions of main effects model has the highest weight, which is not surprising in light of our investigations with the discrete super learner, where we saw that the main effects model was more likely to be selected for small samples. Whereas for $n = 10\,000$ the main effects is weighted a lot less than XGBoost. Note that these weights depend on the data, so they are not necessarily the same when the data is sampled each time.

Ensemble super learner performance

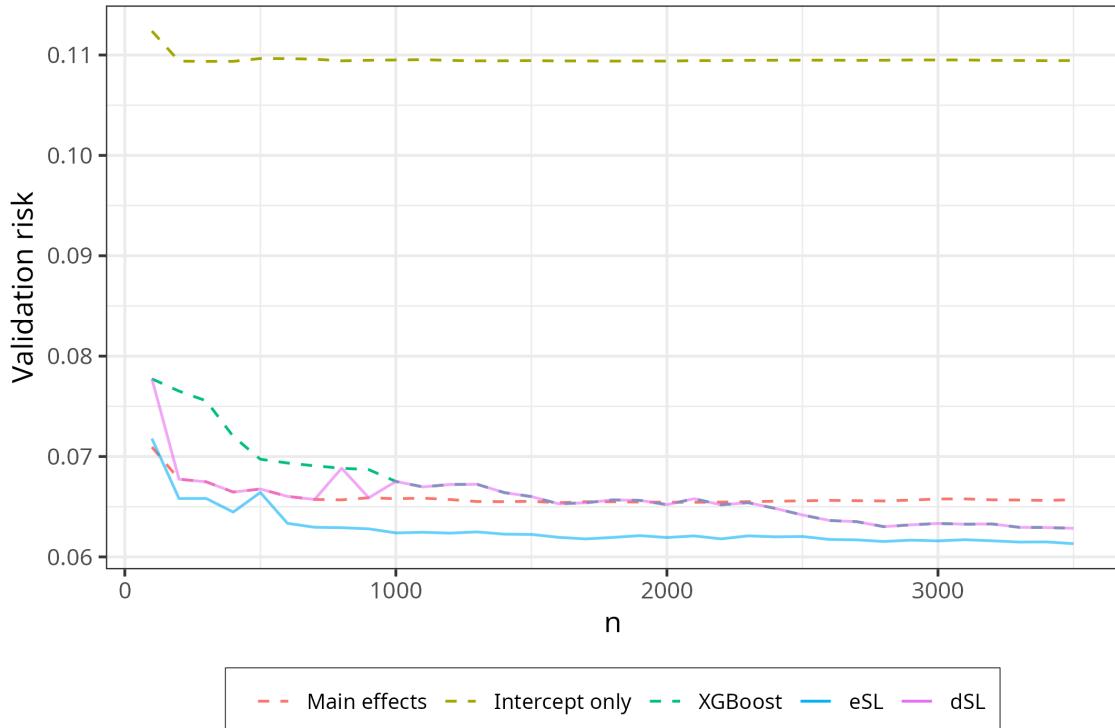


Figure 10: The risk of the ensemble super learner compared to other algorithms where the number of training samples are $n = 100, 200, \dots, N = 3500$.

Figure 10 shows that the ensemble super learner achieves a lower loss than any of the learners, including the discrete super learner. The result agrees with the conclusion in Section 4.5, where we argued that because the ensemble super learner optimizes over the entire k -simplex, its risk is lower compared to the discrete super learner. However we must keep in mind that when examining finite samples, the conclusion is that the ensemble super learner will achieve the lowest risk on the training data, it is, therefore, not necessarily the case that the validation risk is always lower for the ensemble super learner. Suppose that the library contains the regression. Limited samples might prevent the ensemble super learner from assigning it full weight. The discrete super learner which selects the learning algorithm with the lowest cross-validation risk, might choose the true regression, consequently achieving a lower validation risk than the ensemble super learner.

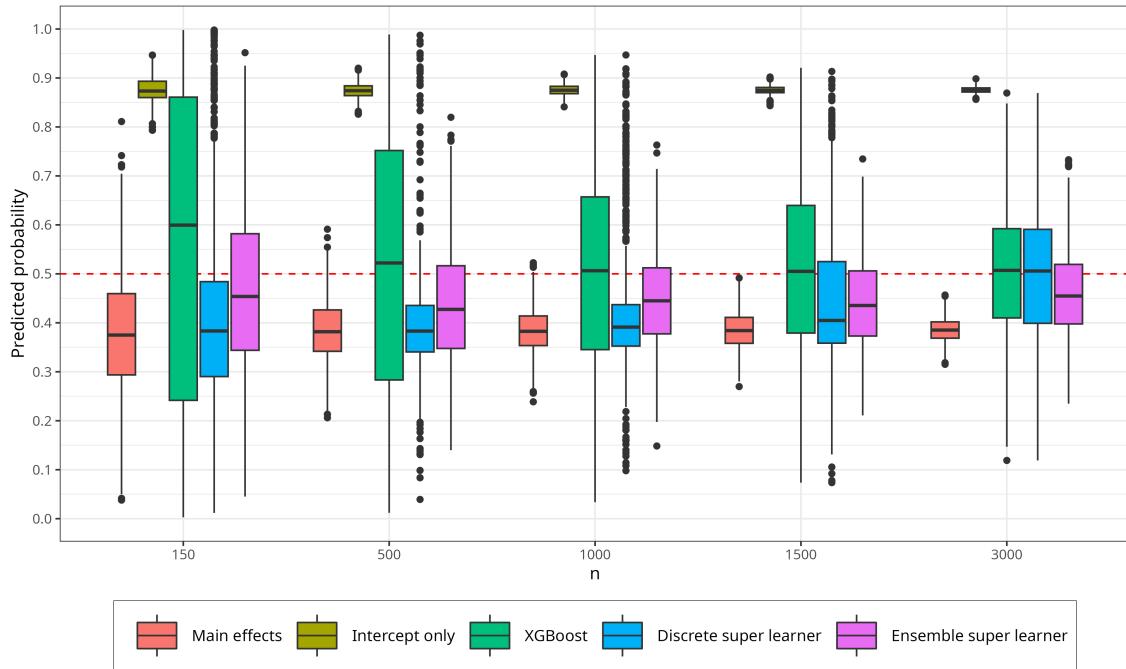


Figure 11: The variance of the ensemble super learner compared to other learners, each algorithm is fitted $K = 1000$ times on n samples and used to evaluate K times on a single observation.

Figure 11 compares the variances of the ensemble super learner to the other learners. The ensemble super learner does not exhibit the same behavior as the discrete super learner, which tends to predict many outliers; its distribution seems to be consistently centered, as evidenced in Figure 12. This aligns with the fact that the ensemble super learner is a continuous combination of different learners. We also note that the ensemble super learner achieves a lower variance than both the XGBoost and the discrete super learner, but has a variance than the parametric logistic regression models.

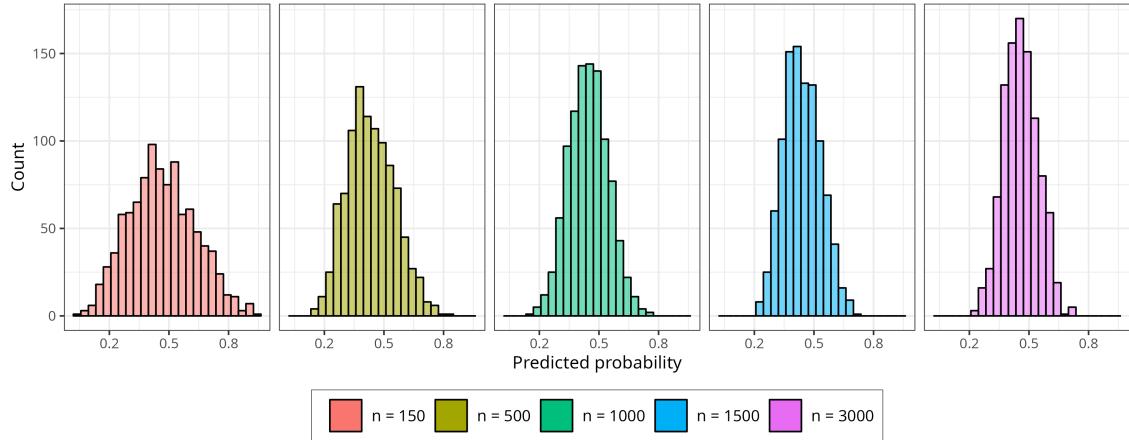


Figure 12: Predictions for a single observation by the ensemble super learner varied over number of training samples. The histograms display the same data as ensemble super learner box plots in Figure 11.

Figure 12 shows the predictions of the ensemble super learner for a single observation varied over number of training samples. We see that the distribution of predictions is much more centered and that the variance seems to also decrease steadily with more samples.

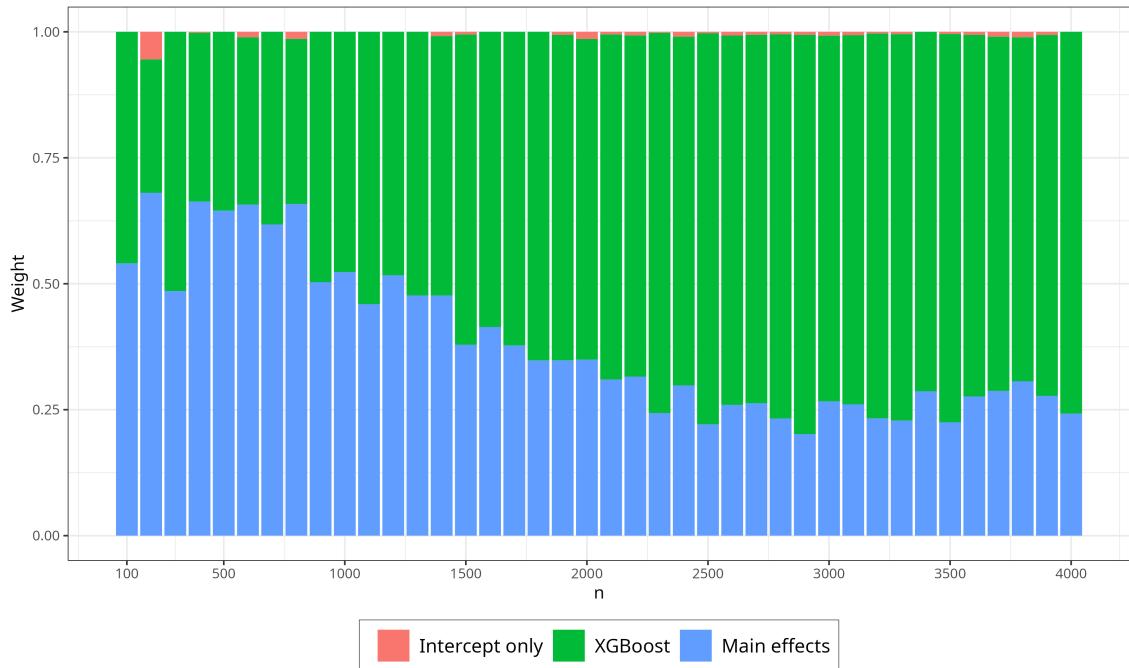


Figure 13: Weighting of the 3 different learners selected by the ensemble super learner varied over number of training samples. The ensemble super learner uses the constrained regression meta algorithm as described in Section 4.5, the weights sum to 1.

The weighting of the different learners by the ensemble super learner is visualized in Figure 13. We see that the weighting of the intercept only model is very low, and that the main effects model has more weight than XGBoost for small samples, however, this trend reverses as the number of training samples increases. An interesting observation is that XGBoost begins to outweigh the main effects logistic regression when the training size is

between 1000 and 1500, which coincides with when XGBoost begins to achieve a lower loss compared to the main effects model as seen in Figures 5 and 6.

5.3 Locally weighted ensemble super learner

By using the ensemble super learner with the constrained regression meta learning algorithm we can combine different learners to achieve a lower risk than any of the learners in the library. However, the resulting ensemble is a global combination of the learners, meaning that the weights are the same when predicting on all covariates. In this section I will consider a meta learning algorithm where k -means clustering is used to cluster the covariates into groups and a local weighted combination is fitted for each group.

Motivation

By examining the level 1 data obtained from the K -fold cross-validation, it is possible to compare the predictions of each learner against each other as in Figure 14

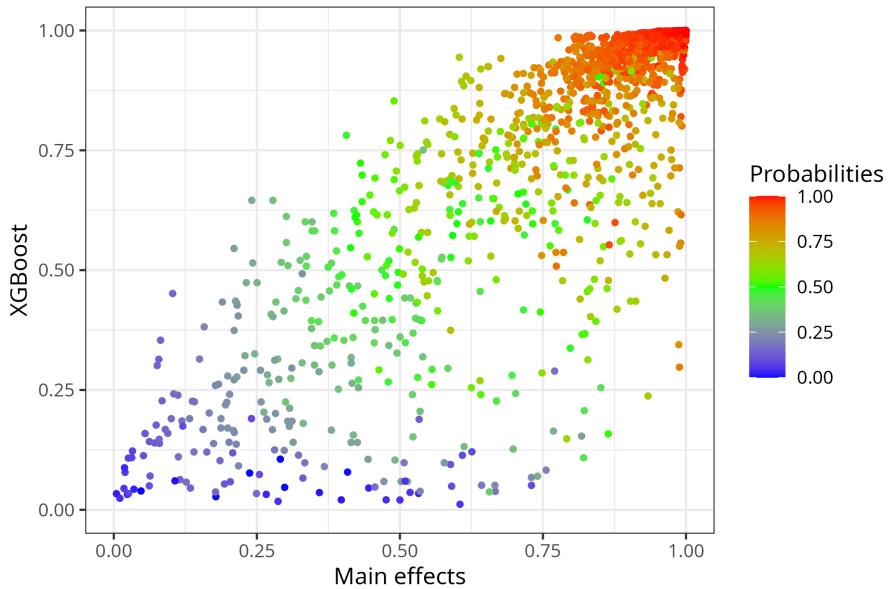


Figure 14: Predictions of XGBoost vs main effects model, colors indicate the true probability. The learners' prediction on a single observation represent a point in the unit square, the point is colored by the probability obtained by applying the true regression function on that observation.

We notice that the main effects model does not predict the same as the XGBoost. If they had predicted the same, then the predictions would lie on the identity line. There is significant disagreement between the two algorithms, as seen in the lower right corner where the main effects model predicts certain observations to have a probability of over 0.7, while XGBoost assigns these a probability of less than 0.1. An idea is to group the covariates based on the predicted probabilities such that for certain groups certain algorithms are weighed more than others. The naive approach implements k -means clustering to group the covariates into $k = 4$ groups as shown in Figure 15

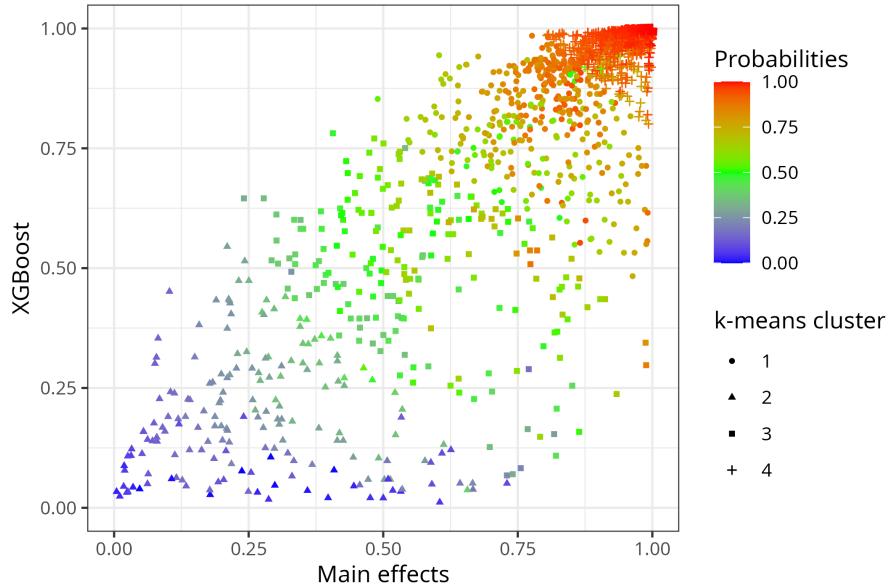


Figure 15: Same as Figure 14, except that the observations are clustered into 4 groups using k -means clustering.

Figures 14 and 15 plot the predictions by two learners against each other, but the procedure is valid also when there are more learners, resulting in clustering within a high dimensional space. For each group, a weighted combination of the learners would be found by fitting on the level 1 data of that group. To predict using the ensemble super learner we will apply the learners to the new data and determine which of the clusters the level 1 covariates belong to. Once that has been determined, the predictions will be combined according to the weighted combination in that group.

Simulation results

The locally weighted ensemble super learner examined in this section is implemented with $k = 4$ clusters and the same library in the previous section. The number clusters was chosen arbitrarily, the results are shown in Figure 16

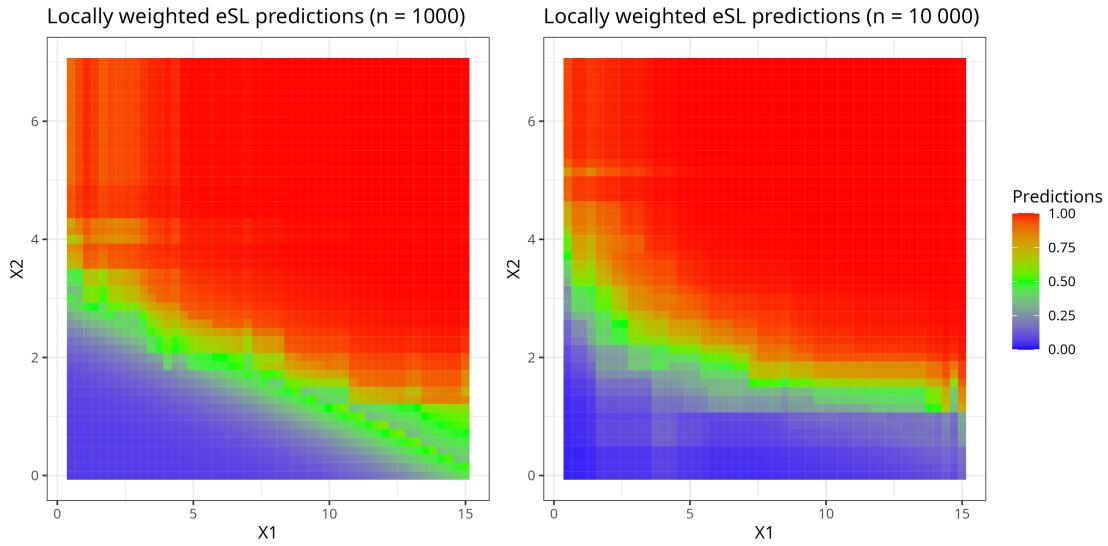


Figure 16: Predictions by the locally weighted ensemble super learner fitted on 1000 and 10 000 observations.

For each point in covariates grid as visualized in Figure 16, the prediction on that point comes stems some cluster with a particular weighting scheme. It is therefore possible to give a visual representation of which learner was weighted most in each prediction. Figure 17 visualizes the predictions on each grid point but also shows which learner contributed most to the prediction. We observe that the predictions are segregated into two groups depending on whether the predicted probability is above or below $p = 0.5$. XG-Boost appears to have the highest weight for predictions where the predicted probability is greater than 0.5, whereas the main effects model is favored when the predictions are below 0.5.

The segregation explains the behavior of the super learner when $n = 1000$ in Figure 16 where it appears that the predictions are smoother when the predicted probabilities are less than 0.5. The explanation is that the super learner weighted the logistic regression the most when $p < 0.5$, and since it is a smooth parametric model, the predicted probabilities will assume a gradient.

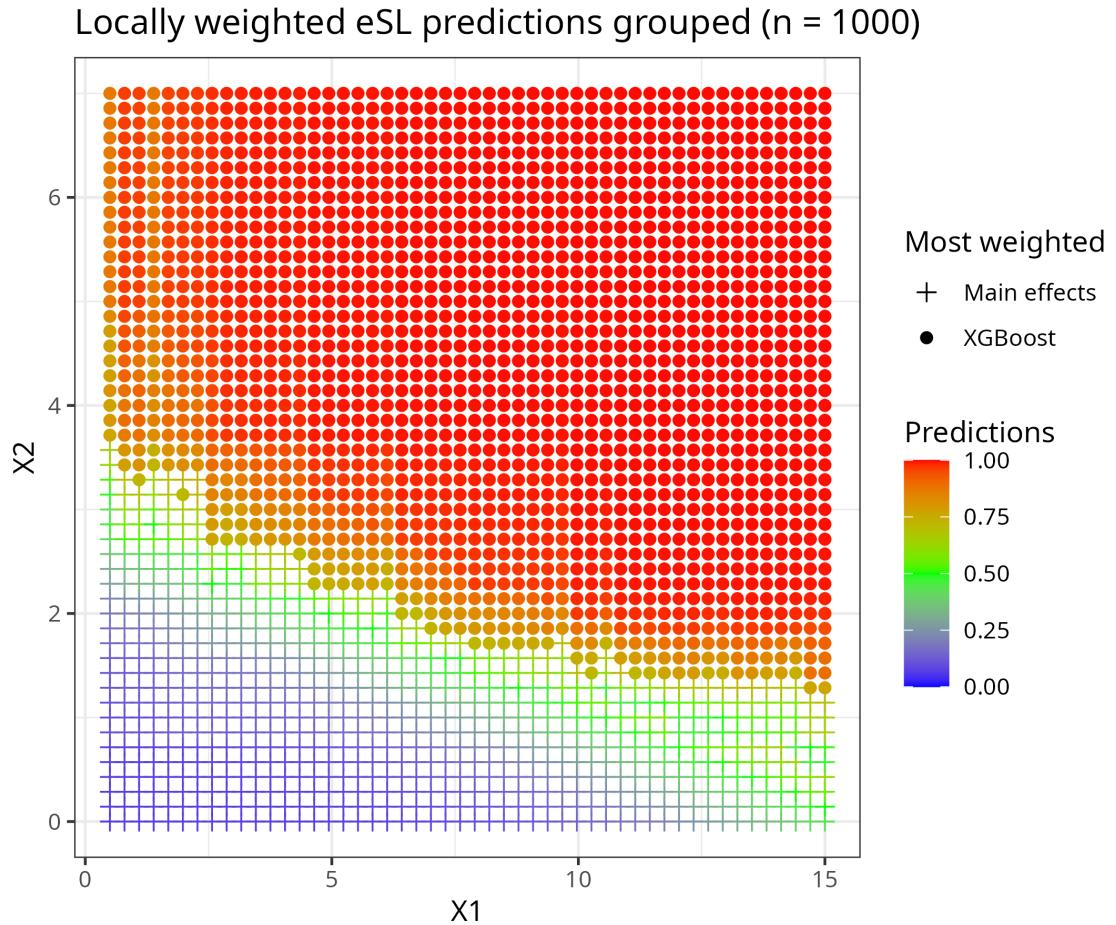


Figure 17: Predictions by the locally weighted ensemble super learner fitted on 1000 observations, grouped according to the learner with the highest weight. Each colored prediction is the weighted sum of the learner predictions.

A plot of the non-stratified predictions displayed in Figure 17 can be found in the appendix. We also include numerous other examples of predicted probabilities using the locally weighted ensemble super learner.

Figure 18 shows that the locally weighted ensemble super learner has a slightly higher risk than the ensemble super learner, but a lower risk than the discrete super learner.

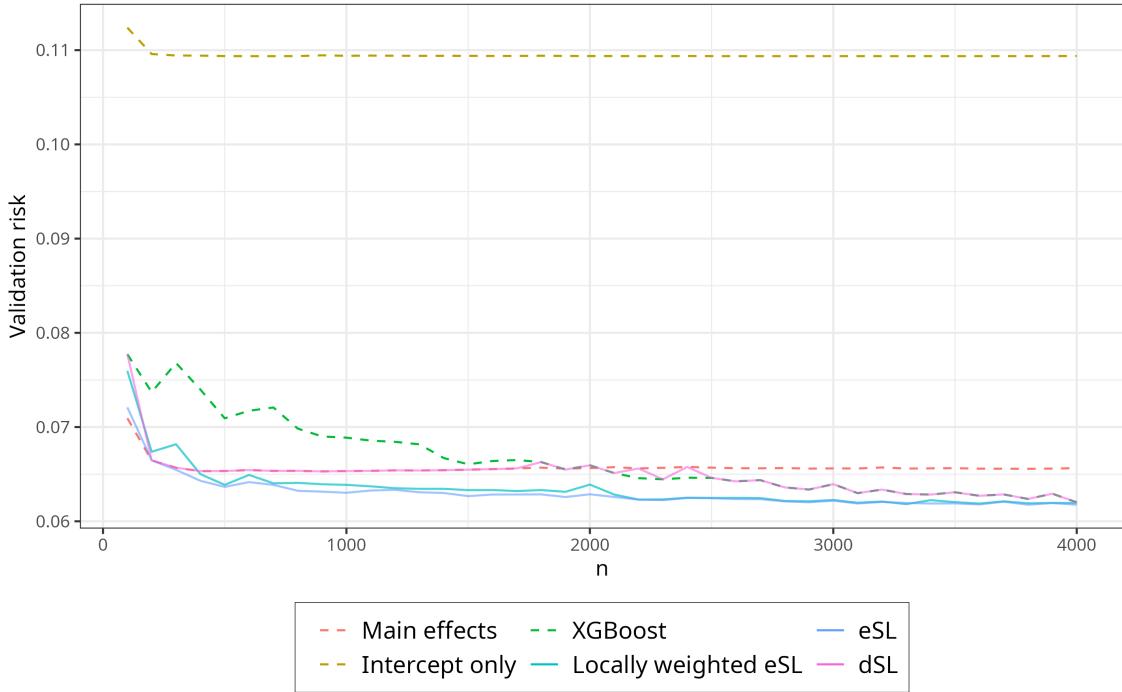


Figure 18: The risk of the locally weighted ensemble super learner compared to other algorithms where the number of training samples are $n = 100, 200, \dots, N = 4000$ and $k = 4$ local clusters.

The risk of the locally weighted ensemble super learner can depend on the number of k clusters that are used to segregate the level 1 data. The connection between the number of clusters and the risk has not been investigated in this thesis. Nevertheless, the risk of a learner does not tell the full picture as we have witnessed with XGBoost, which, despite its design of minimizing loss, displays the highest variance. It might be relevant to consider other metrics that can evaluate the learners on the stability and variance of their predictions.

6 Discussion

In this thesis super learners and their applicability to binary regression have been investigated. Theoretical results, namely Corollaries 15 and 21, prove that super learners are asymptotically equivalent with the oracle selectors that selects the best learning algorithm based on its knowledge of the data-generating distribution P . We conclude that super learning is a valid method for creating a strong learner by combining a library of different learning algorithms. The two super learners that were examined – the discrete and ensemble super learner – have been benchmarked and compared to a library consisting of logistic regression and XGBoost. They are shown to outperform these algorithms in terms of validation risk. Furthermore, we see that while the variance in super learner predictions are higher than parametric logistic regression, they are still less than the variance of the machine learning method XGBoost. Finally, a new meta algorithm for combining learner predictions has been proposed which has shown to achieve acceptable results.

6.1 Local weighting of learners

Section 5.3 introduces a new meta algorithm for combining learner predictions. The locally weighted ensemble super learner is a minor extension of the constrained regression ensemble super learner, which fits a constrained least squares on the level 1 data such that the fitted coefficients are positive and sum to 1. The locally weighted ensemble groups the level 1 data into clusters, and for each cluster the constrained regression problem is solved. The idea is that in certain regions of the level 1 data, certain algorithms are likely to perform better than others. Therefore by segregating the level 1 data one might to fit a locally weighted ensemble pertaining to each segregated region. The naive implementation applies k -means clustering to the level 1 data, and seems to be capable of segregating the predictions into regions as seen in Figures 19 to 23 in the appendix.

Another motivation for this procedure is to find a way to ‘smoothen’ the patchwork pattern in the predictions of tree methods such as XGBoost as seen in Figure 3. The patchy pattern in the predictions is undesirable for two reasons. One, the predicted probabilities of neighbouring covariates can be very different, and likely do not model the actual data-generating distribution that well. One can imagine if one of the covariates was age and the outcome was whether one has a certain disease, then it does not make sense that the predicted probability of having the disease given age would be 0.5 when age is < 7 or > 9 but 0 when it is between 7 and 9. This behavior simply does not model the actual biological process. Second, the patchiness is an indication that the tree method has not been trained on enough observations, and thus the prediction variance will be very high as seen in Figure 7. The ensemble super learner should, preferably, combine the predictions from a smooth parametric model with the loss-minimizing machine learning method to create a learner that minimizes loss, but also sanely models the data-generating distribution. The locally weighted ensemble super learner is an attempt at doing that, and the results show promise that this is attainable. By examining Figures 20 and 21 in the appendix, we see that the patchiness is reduced around the edges of strip where $p = 0.5$ due to the fact that the main effects model is weighted higher in those regions.

Further work is, however, required to investigate the performance of the locally weighted ensemble super learner with other learning algorithms and with more covariates. Currently, the k -means method has a hyperparameter k which can be tuned, the results presented in the appendix considers when $k = 4$, but it is possible that this number is not optimal. The k -means method also has the downside that it is blind, namely it is an unsupervised method which does not take the outcome into consideration. We observe in Figure 15 that in the lower left corner both the main effects and XGBoost model predicts close to the truth, but k -means clustering groups those predictions together with the predictions in the lower middle where the main effects model predicts worse.

6.2 Grid vs continuous optimization

In Section 4.5 we investigated the constrained regression and how the optimal weighting could be found by optimizing over the $(k - 1)$ -simplex where k was the size of our library. The oracle result for the ensemble super learner, Corollary 21, requires that we optimize over a parameter set \mathcal{A}_n where the number of elements in that set is at most polynomial in n . This is, however, not how we would find the optimal parameter in practice. One can argue that the optimization procedure available on our hardware indeed only searches over some finite subset of \mathcal{A} which is perhaps fixed. The finite subset is determined by the floating-point precision of the processor, and perhaps also the internal parameters of the optimization procedure itself. For example, gradient descent algorithms usually have

a hyperparameter such as ‘step size’ or ‘learning rate’ which controls how large of a step the algorithm takes in the direction of the minimum. In reality we are never able to search over the uncountable parameter space since the number of atoms in our processor is very much countable.

The dependency of parameter set \mathcal{A}_n on n , does not reflect our actual optimization procedure. We do not choose some grid of points polynomial in the number of observations, evaluating the risk for each point and then choosing the minimum. Rather, the optimization is over all feasible points, for instance if the risk is convex, then the minimum can sometimes be solved explicitly or there will exist procedures that guarantee convergence to the minimum.

6.3 Bias-variance tradeoff

The variance plots

7 Perspectives

The local weighting procedure investigated in Section 5.3 can be optimized by considering other clustering algorithms which takes the outcome into account. Another approach could be to separate the level 1 into 3 groups, one that lie above the diagonal, one that lie below, and the one that where the predictions are close to the diagonal. Supervised clustering algorithms might be preferred in order to group the predictions into groups that can have qualitative interpretations such as: “In group 5, XGBoost predicts has a lower residual than main effects”. The goal here is to create a method that can combine the flexibility of machine learning algorithms while maintaining a consistent model of the data-generating distribution. We see that XGBoost is capable of learning the distribution given that the training sample sizes are in the ten thousands (Figure 4). However, depending on the application, that number of observations is too many in comparison to parametric models that achieve a much lower variance despite the number training samples being 10 times less. An optimal super learning algorithm should balance the loss-minimizing property of machine learning methods with the stability seen in parametric models.

8 Appendix

8.1 Proof of lemma 10

Proof. We first note that the minimizing property of $\hat{\psi}_n$ (definition 8) implies that

$$E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) \leq E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1). \quad (5)$$

We can write (5) as

$$\begin{aligned} E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) &\leq (1 + 2\delta) E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &+ E_{S^n} \frac{1}{\sqrt{n_1}} R(\tilde{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P) \\ &- E_{S^n} \frac{1}{\sqrt{n_1}} R(\hat{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 + \delta\sqrt{n_1}P). \end{aligned}$$

Indeed, by examining the risk in the second term on the right hand we obtain

$$\begin{aligned} R(\tilde{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P) &= (1 + \delta)R(\tilde{\psi}_n(P_{n,S^n}^0), G_{n,S^n}^1) - \delta\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta) \left[\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P) \right] - \delta\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta)\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - (1 + 2\delta)\sqrt{n_1}R(\tilde{\psi}_n(P_{n,S^n}^0), P). \end{aligned}$$

And for the third term

$$\begin{aligned} R(\hat{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 + \delta\sqrt{n_1}P) &= (1 + \delta)R(\hat{\psi}_n(P_{n,S^n}^0), G_{n,S^n}^1) + \delta\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta) \left[\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \right] + \delta\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \\ &= (1 + \delta)\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P). \end{aligned}$$

The $\sqrt{n_1}$ in each term will disappear after we multiply with $\frac{1}{\sqrt{n_1}}$. We now add the first and second term on the right hand side

$$\begin{aligned} (1 + 2\delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) + E_{S^n} \frac{1}{\sqrt{n_1}} R(\tilde{\psi}_n(P_{n,S^n}^0), (1 + \delta)G_{n,S^n}^1 - \delta\sqrt{n_1}P) \\ = (1 + 2\delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P) + E_{S^n} \left[(1 + \delta)R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - (1 + 2\delta)R(\tilde{\psi}_n(P_{n,S^n}^0), P) \right] \\ = (1 + \delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1). \end{aligned}$$

Now by combining all terms on the right hand side we get

$$\begin{aligned} (1 + \delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) &- E_{S^n} \frac{1}{\sqrt{n_1}} \left[(1 + \delta)\sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - \sqrt{n_1}R(\hat{\psi}_n(P_{n,S^n}^0), P) \right] \\ &= (1 + \delta)E_{S^n} R(\tilde{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) - (1 + \delta)E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P_{n,S^n}^1) + E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P). \end{aligned}$$

By the minimizing property the difference between the second and first term must be positive. Since we are adding a positive number to $E_{S^n} R(\hat{\psi}_n(P_{n,S^n}^0), P)$, it follows that it must be less than whatever is on the right. In the final lemma we replace $\hat{\psi}_n$ and $\tilde{\psi}_n$ by the maximum over Ψ .

□

8.2 Locally weighted ensemble super learner plots

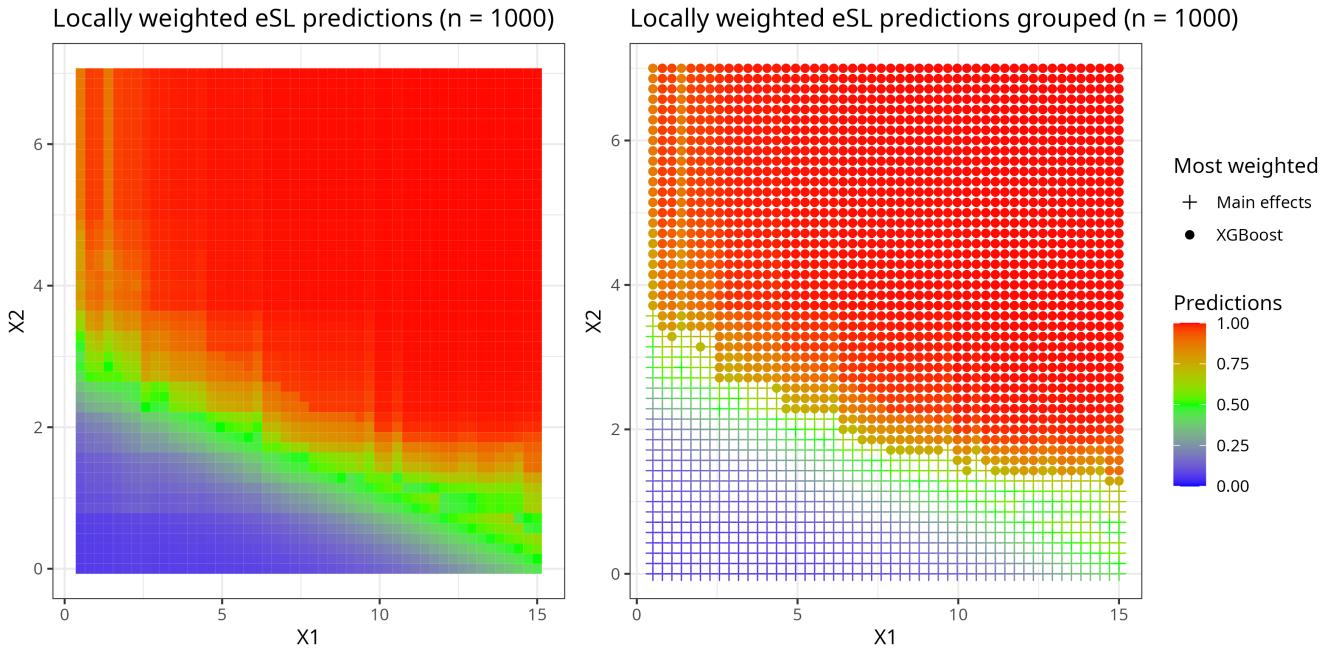


Figure 19: Raw predictions vs stratified according to the learner with highest weight as seen in Figure 17

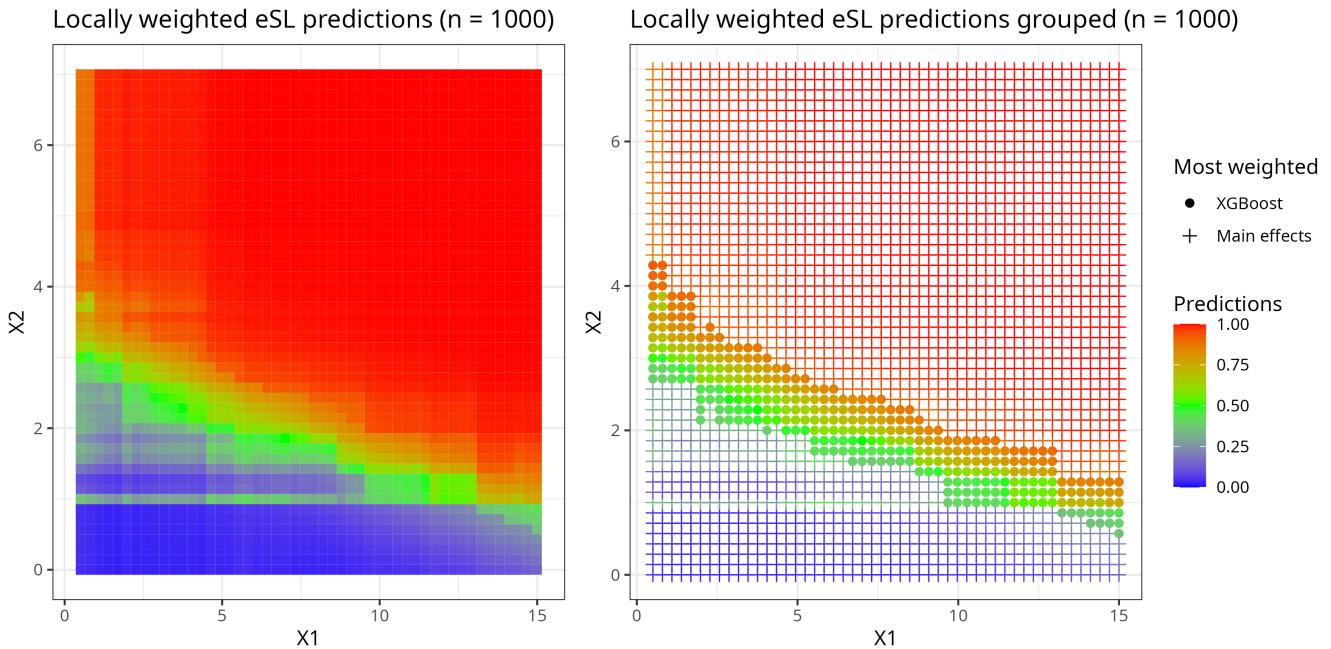


Figure 20: Example where XGBoost seems to be more preferred when the predicted probability is around 0.5

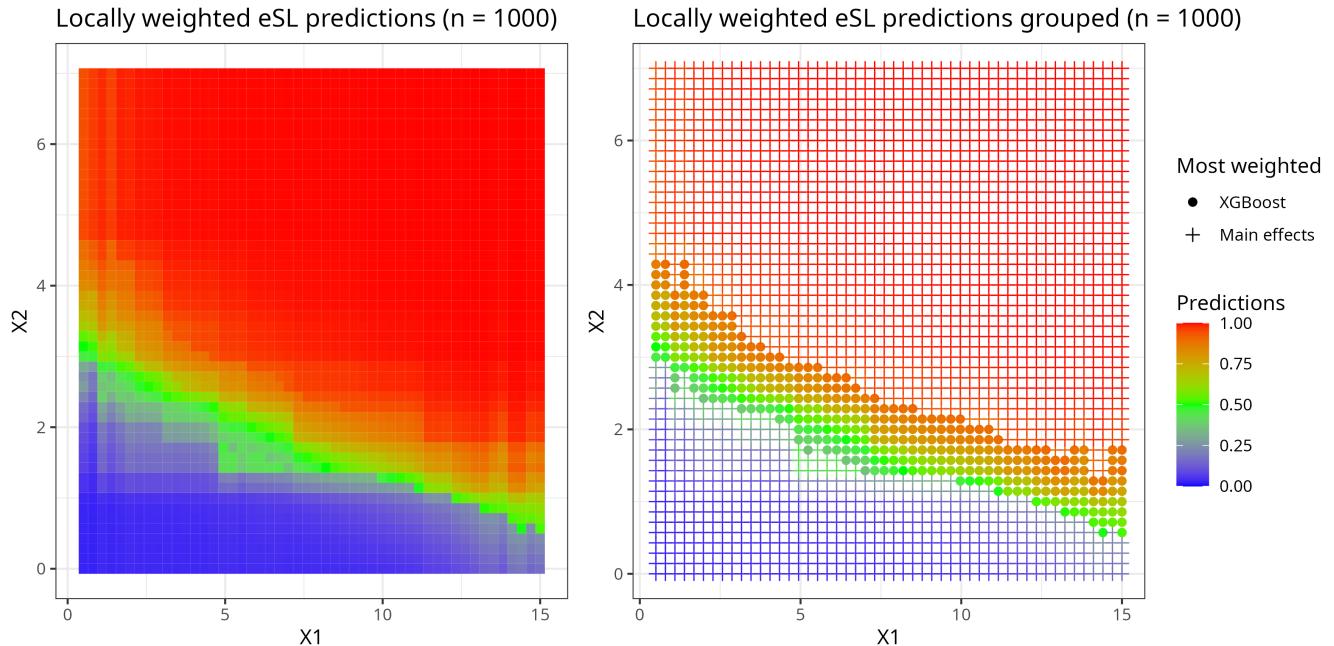


Figure 21: Another example similar to the previous

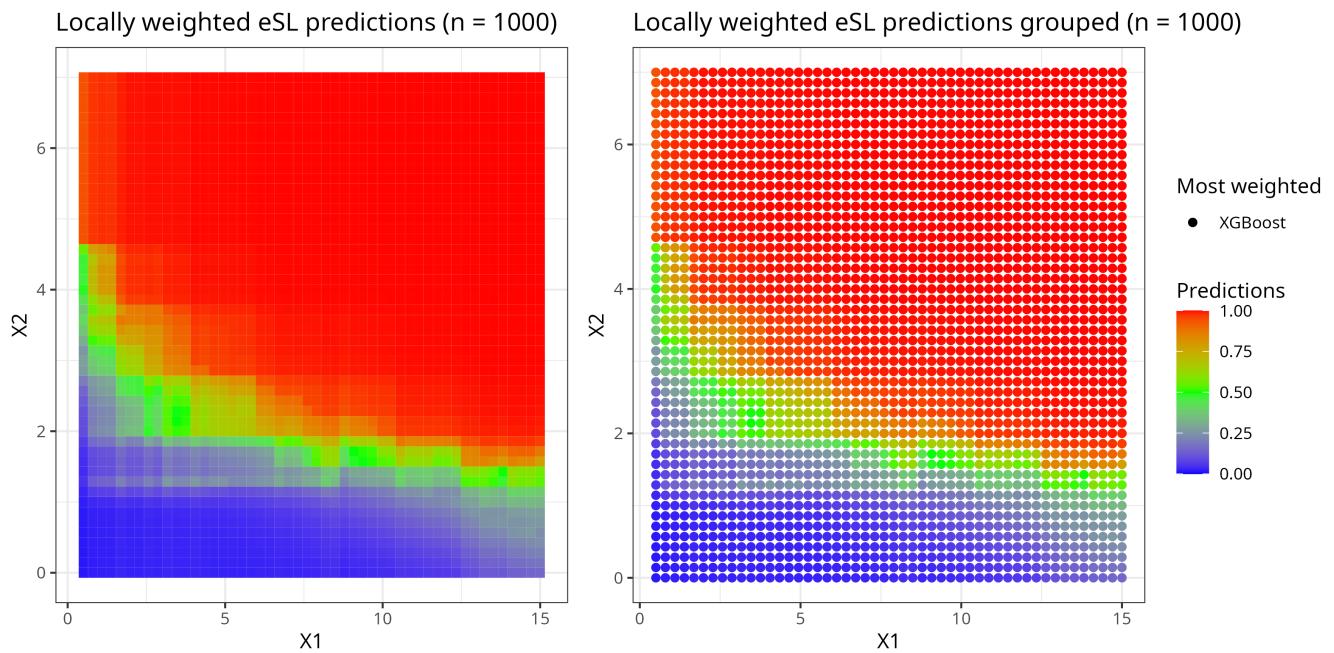


Figure 22: Example where XGBoost is the highest weighted learner globally

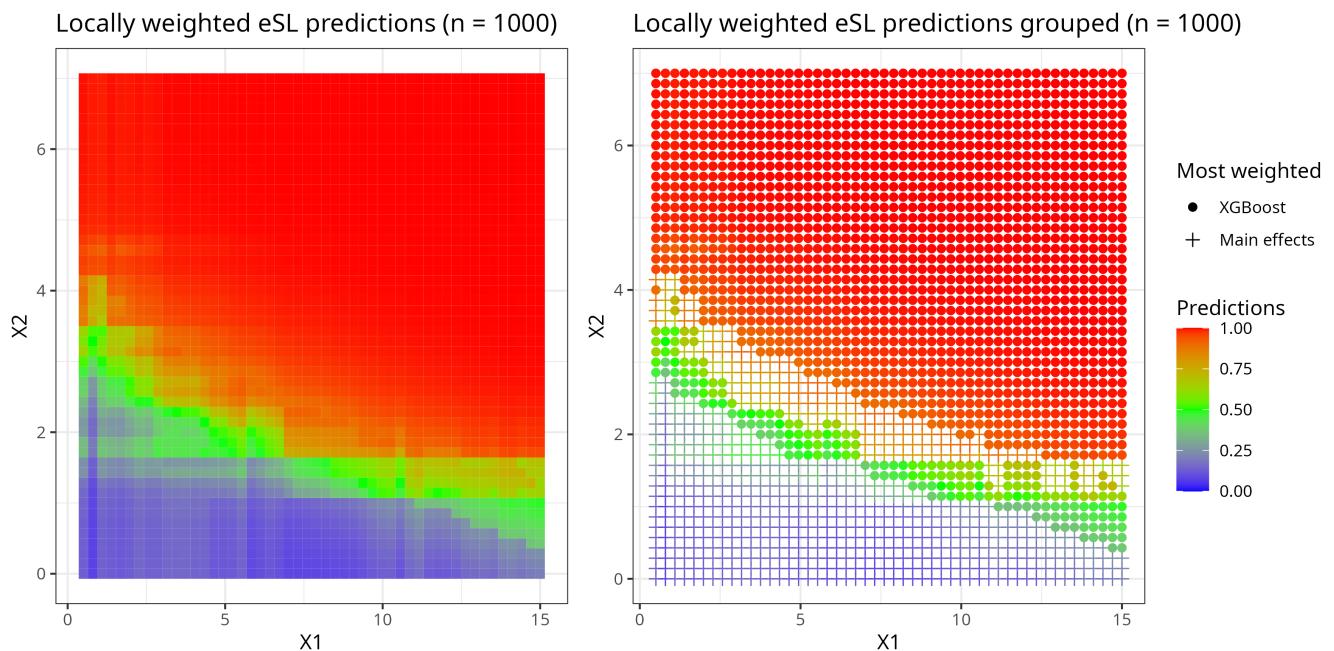


Figure 23: Example where XGBoost is weighted the highest when the predicted probabilities are around $p = 0.5$ and above 0.7

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