Modelling Higher-Order Network Dynamics in the Presence of Triadic Interactions Generated by Doxygen 1.9.7

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Chapter 1

Namespace Index

1.1 Namespace List

Here is a list of all documented namespaces with brief descriptions:

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triadic_interaction.model	13
triadic, interaction visualization	13

2 Namespace Index

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:	
triadic_interaction.model.NDwTls	19

4 Class Index

Chapter 3

Namespace Documentation

3.1 triadic_interaction Namespace Reference

Namespaces

- namespace computation
- · namespace model
- · namespace visualization

3.1.1 Detailed Description

Triadic Interactions Package.

This package contains a Node Dynamics with Triadic Interaction class and a set of functions for computations a

3.2 triadic_interaction.computation Namespace Reference

Functions

- create_node_edge_incidence_matrix (edge_list)
- extract_by_std (X, std=3.0)
- freedman_diaconis_rule (data, power=1./3., factor=2., trim=1)
- discretise (X, n_bins='fd')
- estimate_pdf (data, bins='fd')
- estimate_pdf_joint (data, bins='fd')
- estimate_pdf_conditional (data, data_cond, val_cond, bins='fd')
- pdf_evolution (X, t_max, n_x_resolution=50)
- · covariance (data)
- conditional_expectation (X, Y, Z, bins='fd')
- conditional_variance (X, Z, bins='fd')
- conditional_covariance (X, Y, Z, bins='fd')
- conditional_correlation (X, Y, Z, bins='fd', method='default')
- entropy (pdf, x)
- entropy_joint (pdf_joint, x)
- conditional_mutual_information (X, Y, Z, bins='fd')

3.2.1 Detailed Description

```
Computation module.
```

This module provides functions for computations.

3.2.2 Function Documentation

3.2.2.1 conditional_correlation()

```
triadic_interaction.computation.conditional_correlation (
              Χ,
              Υ,
              Z,
              bins = 'fd',
              method = 'default' )
Compute the conditional variance.
Parameter
X : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data.
Y : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data.
Z : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data. (condition)
\ensuremath{\mathsf{bins}} : int or str, optional
    (default = 'fd')
    The number of bins or the method to compute the number of bins.
    - 'fd' : Freedman-Diaconis rule
method : str, optional
    (default = 'default')
    The method to compute the conditional correlation.
    - 'default' : Pearson correlation coefficient
    - ' manual' : manual computation
Returns
corr_cond : numpy.ndarray of shape (n_bins,)
   The conditional correlation.
z : numpy.ndarray of shape (n_bins,)
    The bin values of the conditional variable.
corr_cond_err : numpy.ndarray of shape (n_bins,)
    The standard error of the conditional correlation.
```

3.2.2.2 conditional covariance()

```
Compute the conditional variance.
Parameter
X : numpy.ndarray of shape (n_timesteps, n_samples)
   The time series data.
Y : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data.
Z : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data. (condition)
bins : int or str, optional
    (default = 'fd')
    The number of bins or the method to compute the number of bins.
    - 'fd' : Freedman-Diaconis rule
Returns
cov_cond : numpy.ndarray of shape (n_bins,)
    The conditional covariance.
z : numpy.ndarray of shape (n_bins,)
    The bin values of the conditional variable.
```

3.2.2.3 conditional expectation()

```
triadic_interaction.computation.conditional_expectation (
              Χ,
              Y,
              Z_{\bullet}
              bins = 'fd')
Conditional expectation.
Parameter
X : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data.
Y : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data.
Z : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data. (condition)
bins : int or str, optional
    (default = 'fd')
    The number of bins or the method to compute the number of bins.
    - 'fd' : Freedman-Diaconis rule
    - n (int) : The number of bins.
Returns
z_bins : numpy.ndarray of shape (n_bins,)
   The bin values of the conditional variable.
mean : tuple of 2 numpy.ndarray of shape (n_bins,)
    The conditional expectation of node i and j
        - X1_mean : numpy.ndarray of shape (n_bins,)
            The conditional expectation of node i.
        - X2_mean : numpy.ndarray of shape (n_bins,)
            The conditional expectation of node j.
std : tuple of 2 numpy.ndarray of shape (n_bins,)
    The standard deviation of node i and j
        - X1_std : numpy.ndarray of shape (n_bins,)
            The conditional standard deviation of node i.
        - X2_std : numpy.ndarray of shape (n_bins,)
            The conditional standard deviation of node j.
X3_dig : numpy.ndarray of shape (n_samples,)
    The digitised data of node v3.
```

3.2.2.4 conditional_mutual_information()

```
triadic_interaction.computation.conditional_mutual_information (
              Y,
              Z,
              bins = 'fd' )
Calculate the conditional mutual information between {\tt X} and {\tt Y} given {\tt Z}.
Parameters
X : numpy.ndarray of shape (n_observations, )
    The data.
Y : numpy.ndarray of shape (n_observations, )
    The data.
Z : numpy.ndarray of shape (n_observations, )
    The data to be conditioned.
bins : str or a sequence of int or int, optional
    (default = None)
    The number of bins or the method to compute the number of bins.
    - ^\primefd^\prime : The number of bins is computed using the Freedman-Diaconis rule.
    - n_1, n_2, ..., n_n : The number of bins for each variable.
    - {\rm n} : The number of bins for all variables.
cmi : numpy.ndarray of shape (n_bins, n_samples)
   The conditional mutual information between X and Y given Z=z for each z in Z.
z : numpy.ndarray of shape (n_bins,)
    The z values of the corresponding bins.
3.2.2.5 conditional variance()
triadic_interaction.computation.conditional_variance (
```

```
Χ.
              Z,
              bins = 'fd')
Calculate the conditional variance.
Parameter
X : numpy.ndarray of shape (n_timesteps, n_samples)
    The time series data.
Z : numpy.ndarray of shape (n_timesteps, n_samples)
   The time series data. (condition)
bins : int or str, optional
    (default = 'fd')
    The number of bins or the method to compute the number of bins.
    - 'fd' : Freedman-Diaconis rule
Returns
var_cond : numpy.ndarray of shape (n_bins,)
    The conditional variance.
z : numpy.ndarray of shape (n_bins,)
   The bin values of the conditional variable.
```

3.2.2.6 covariance()

3.2.2.8 discretise()

3.2.2.9 entropy()

```
triadic_interaction.computation.entropy (
              pdf.
              X)
Calculate the entropy of the probability density function.
Parameters
pdf : numpy.ndarray of shape (n_bins,)
   The probability density function.
x : numpy.ndarray of shape (n_bins,)
    The x values of the corresponding bins.
Returns
entropy : float
    The entropy of the probability density function.
3.2.2.10 entropy_joint()
triadic_interaction.computation.entropy_joint (
              pdf_joint,
              x )
Calculate the joint entropy of the probability density function.
Parameters
pdf_joint : numpy.ndarray of shape (n_bins, n_variables)
    The joint probability density function.
x : list of numpy.ndarray of shape (n_bins,)
    The \boldsymbol{x} values of the corresponding bins.
Returns
entropy_joint : float
    The joint entropy of the probability density function.
3.2.2.11 estimate_pdf()
triadic_interaction.computation.estimate_pdf (
              data,
              bins = 'fd' )
Estimate the probability density function of the data by the histogram method.
data : numpy.ndarray of shape (n_observations,) or (n_observations, 1)
   The data.
bins : str or a sequence of int or int, optional
    (default = None)
    The number of bins or the method to compute the number of bins.
    - ^\prime\,\text{fd}^\prime\, : The number of bins is computed using the Freedman-Diaconis rule.
    - n : The number of bins for the variable.
Returns
P : numpy.ndarray of shape (n_bins, n_variables)
    The estimated probability density function of the data.
X : numpy.ndarray of shape (n_bins, n_variables)
    The bin centers for variables.
```

3.2.2.12 estimate_pdf_conditional()

```
triadic_interaction.computation.estimate_pdf_conditional (
              data,
              data_cond,
              val_cond,
              bins = 'fd' )
Estimate the conditional probability density function of the data
   by the histogram method.
Parameters
data : numpy.ndarray of shape (n_observations, n_variables)
   The data.
data_cond : numpy.ndarray of shape (n_observations, n_conditional_variables)
   The data to be conditioned on.
val_cond : int
    The value of the variable to condition on.
bins : str or a sequence of int or int, optional
    (default = None)
    The number of bins or the method to compute the number of bins.
    - 'fd' : The number of bins is computed using the Freedman-Diaconis rule.
    - n_1, n_2, ..., n_n : The number of bins for each variable.
    - n : The number of bins for all variables.
Returns
pdf_conditional : numpy.ndarray of shape (n_bins, n_variables)
    The estimated probability density function of the data.
x : list of numpy.ndarray of shape (n_bins-1,)
    The x values of the corresponding bins.
3.2.2.13 estimate pdf_joint()
triadic_interaction.computation.estimate_pdf_joint (
              bins = 'fd' )
Estimate the joint probability density function of the data by the histogram method.
Parameters
data : numpy.ndarray of shape (n_observations, n_variables)
   The data.
bins : str or a sequence of int or int or list, optional
    (default = None)
    The number of bins or the method to compute the number of bins.
    - 'fd' : The number of bins is computed using the Freedman-Diaconis rule.
    - n_1, n_2, ..., n_n: The number of bins for each variable.
    - n : The number of bins for all variables.
```

```
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```

Returns

- list : The bin edges for each variable.

x : list of numpy.ndarray of shape (n_bins-1,)
 The x values of the corresponding bins.

pdf_joint : numpy.ndarray of shape (n_bins, n_variables)
 The estimated probability density function of the data.

```
3.2.2.14 extract_by_std()
triadic_interaction.computation.extract_by_std (
              std = 3.0)
Extract the data within a given number of standard deviations from its mean.
Parameters
X : numpy.ndarray of shape (n_observations,)
   The data.
std : float, optional
    (default = 3.0)
    The number of standard deviations to extract.
X_min : float
   The minimum value of the core range.
X_{\max}: float
    The maximum value of the core range.
3.2.2.15 freedman diaconis rule()
triadic_interaction.computation.freedman_diaconis_rule (
              data.
              power = 1. / 3.,
              factor = 2.,
              trim = 1)
Compute the number of bins using the Freedman-Diaconis rule.
Parameters
```

```
data : numpy.ndarray of shape (n_observations,)
   The data.
power : float, optional
   (default = 1. / 3.)
   The power of the number of observations in the denominator.
factor : float, optional
    (default = 2.)
   The factor to multiply the width of bins.
trim : int, optional
    (default = 1)
    The ratio of the number of observations to trim from each end of the data.
Returns
bins_edges : numpy.ndarray of shape (n_bins,)
   The bins edges.
```

3.2.2.16 pdf_evolution()

```
triadic_interaction.computation.pdf_evolution (
              Χ,
              t_max,
              n_x_resolution = 50 )
```

```
Estimate the time evolution of the probability density function of the data.
Parameters
X : numpy.ndarray of shape (n_nodes, n_timesteps, n_variables)
   The data.
t max : float
   The maximum time.
n_x_resolution : int, optional
    (default = 50)
    The number of bins to estimate the probability density function.
Returns
time_evolution : numpy.ndarray of shape (n_nodes, n_x_resolution, n_timesteps)
    The time evolution of the probability density function.
x_grid : numpy.ndarray of shape (n_x_resolution,)
   The x values of the corresponding bins.
time_grid : numpy.ndarray of shape (n_timesteps,)
    The time steps.
```

3.3 triadic interaction.model Namespace Reference

Classes

class NDwTls

3.3.1 Detailed Description

```
Node Dynamics with Triadic Interactions Class.

This class implements the model of node dynamics with triadic interactions.
```

3.4 triadic_interaction.visualization Namespace Reference

Functions

- plot_timeseries (X, output_file, t_max, n_samples=1, separate=False, theory=None)
- plot_pdf (probs, bins, output_file, f_theory=None, logscale=False, parallel=False)
- plot_covariance (cov, output_file, theory=None)
- plot_conditional_expectation (Xgrids, cond_exps, stds, orders, output_file=None, theory=None)
- plot_conditional_correlation (Xgrids, cond_corr, order, output_file, std=False, Xrange=None, theory=None, f_supplement=None, threshold=None)
- plot_conditional_mutual_information (Xgrids, cmi, order, output_file, std=False, theory=None)
- visualise evolution (evolution data, x grid, time grid, output file)

Variables

dict MPL CONFIG

3.4.1 Detailed Description

Visualization module.

This module contains functions for visualizing the results of the node dynamics with triadic interactions.

3.4.2 Function Documentation

3.4.2.1 plot conditional correlation()

```
triadic_interaction.visualization.plot_conditional_correlation (
              Xgrids,
              cond_corr,
              order,
              output_file,
              std = False,
              Xrange = None,
              theory = None,
              f\_supplement = None,
              threshold = None)
Plot the conditional correlation.
Parameter
Xgrids: numpy.ndarray of shape (n_bins,) or list of numpy.ndarray of shape (n_bins,)
   The grid of the conditional variable.
cond_corr : numpy.ndarray of shape (n_bins, n_samples) or list of numpy.ndarray of shape (n_bins, n_samples)
   The conditional correlation.
order : tuples or list of tuples
   The order of the nodes.
output_file : str
    The output file name.
std : bool or list of numpy.ndarray of shape (n_bins, n_samples), optional
     (default = False)
    If False, do not plot the standard error.
   If list, plot the standard error.
Xrange: bool or list of tuples, optional
        (default = None)
    If None, do not set the range of the x-axis.
    If list, set the range of the x-axis.
theory : function or list of functions, optional
        (default value = None)
    The theoretical solutions.
f_supplement : function or list of functions, optional
        (default value = None)
    The supplementary functions.
threshold : list of float, optional
        (default value = None)
    The threshold value
Returns
None
```

3.4.2.2 plot_conditional_expectation()

```
Plot the conditional expectation.
Parameter
Xgrids: numpy.ndarray of shape (n_bins,) or list of numpy.ndarray of shape (n_bins,)
   The grid of the conditional variable.
cond_exps : numpy.ndarray of shape (n_bins, n_samples) or list of numpy.ndarray of shape (n_bins, n_samples)
    The conditional expectations.
std : numpy.ndarray of shape (n_bins, n_samples) or list of numpy.ndarray of shape (n_bins, n_samples)
    The standard deviation of the conditional expectations.
orders : tuples or list of tuples
   The order of the nodes.
output_file : str, optional
    The output file name.
theory : function or list of functions, optional
        (Default value = None)
    The theoretical solutions.
Returns
None
```

3.4.2.3 plot conditional mutual information()

```
triadic_interaction.visualization.plot_conditional_mutual_information (
             Xgrids,
              cmi,
              order,
              output_file,
              std = False,
              theory = None )
Plot conditional mutual information.
Parameter
Xgrids: numpy.ndarray of shape (n_bins,) or list of numpy.ndarray of shape (n_bins,)
    The grid of the conditional variable.
cmi : numpy.ndarray of shape (n_bins, n_samples) or list of numpy.ndarray of shape (n_bins, n_samples)
   The conditional mutual information.
order : tuples or list of tuples
   The order of the nodes.
output_file : str
    The output file name.
std : bool, optional
     (default = False)
    If True, plot the standard deviation.
theory : function or list of functions, optional
        (Default value = None)
    The theoretical solutions.
Returns
None
```

3.4.2.4 plot covariance()

```
Plot the covariance matrix.

Parameters
-----
cov : numpy.ndarray of shape (n_nodes, n_nodes)
    The covariance matrix.

output_file : str
    The output file name.

theory : function, optional
    (Default value = None)
    The theoretical solution.

Returns
-----
None
```

3.4.2.5 plot pdf()

```
triadic_interaction.visualization.plot_pdf (
             probs,
              bins,
              output_file,
              f\_theory = None,
              logscale = False,
              parallel = False )
Plot the probability distributions.
Parameters
probs : list of numpy.ndarray of shape (n_nodes, n_bins)
   The probability distributions for all nodes.
bins : list of numpy.ndarray of shape (n_nodes, n_bins)
   The bins for all nodes.
output_file : str
    The output file name.
f_theory : function, optional
     (Default value = None)
    The theoretical solution.
logscale : bool, optional
     (Default value = False)
    If True, plot the log scale.
parallel : bool, optional
     (Default value = False)
    If True, plot each node separately.
Returns
None
```

3.4.2.6 plot_timeseries()

```
Plot the timeseries.
Parameters
X : numpy.ndarray of shape (n_nodes, n_timesteps, n_samples)
   The timeseries data.
output_file : str
   The output file name.
t_max : float
    The maximum time span.
n_samples : int, optional
    (Default value = 1)
    The number of samples.
separate : bool, optional
    (Default value = False)
    If True, plot each node separately.
theory : function, optional
    (Default value = None)
    The theoretical solution.
Returns
None
```

3.4.2.7 visualise evolution()

```
triadic_interaction.visualization.visualise_evolution (
              evolution_data,
              x_grid,
              time_grid,
              output_file )
Visualise the evolution of probability density function.
Parameters
evolution_data : numpy.ndarray of shape (n_nodes, n_bins, n_times)
   The evolution of probability density function.
x\_grid : numpy.ndarray of shape (n\_bins,)
    The grid of the variable.
time_grid : numpy.ndarray of shape (n_times,)
    The time grid.
output_file : str
   The output file name.
Returns
None
```

Chapter 4

Class Documentation

4.1 triadic_interaction.model.NDwTls Class Reference

Public Member Functions

- __init__ (self, B, K, w_pos, w_neg, threshold, alpha, noise_std, external_force=None, x_init=None, dt=0.01, t_max=1.)
- getLaplacian (self, x)
- derivative (self, x, t)
- noise (self, x, t)
- integrate (self, deterministic=False)
- run (self, deterministic=False)

Public Attributes

- в
- · n_nodes
- n_edges
- K
- · w_pos
- w_neg
- n_hyperedges
- n_pos_regulators
- n_reg_regulators
- · alpha
- · threshold
- · noise_std
- · external_force
- dt
- t_max
- · n_timesteps
- x_init

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4.1.1 Detailed Description

```
Node Dynamics with Triadic Interactions.
Parameters
B : numpy.ndarray of shape (n_nodes, n_edges)
   the boundary operator of the structural network
K : numpy.ndarray of shape (n_edges, n_nodes)
    the regulator network (structure of triadic interactions)
w_pos : float
   the weight of positive regulator
w_neg : float
   the weight of negative regulator
threshold : float
    the threshold parameter
alpha : float
   the coefficient of the triadic Laplacian
noise_std : float
   the standard deviation of the Gaussian noise
external_force : function, default = None
    the external force as a function of time
x_init : numpy.ndarray, default = None
   the initial states of nodes
dt : float, default = 0.01
   the time step size of the evolution
t_max : float, default = 1.
   the time duration of the evolution
Returns
Attributes
n_nodes : int
    the number of nodes in the structural network
n_edges : int
   the number of edges in the structural network
n_hyperedges : int
    the number of triadic interactions
n\_pos\_regulators : int
    the number of positive regulators
n_neg_regulators : int
   the number of negative regulators
n_timesteps : int
    the number of timesteps
```

4.1.2 Constructor & Destructor Documentation

4.1.2.1 __init__()

```
external_force = None,
              x_{init} = None,
              dt = 0.01,
              t_max = 1. )
Initialise the triadic interaction null model.
Parameters
B : numpy.ndarray of shape (n_nodes, n_edges)
    The boundary operator of the structural network.
K : numpy.ndarray of shape (n_edges, n_nodes)
    The regulator network.
w_pos : float
    The weight of positive regulator.
w_neg : float
   The weight of negative regulator.
threshold : float
    The threshold parameter.
alpha : float
    The coefficient of the triadic Laplacian.
noise_std : float
   The standard deviation of the Gaussian noise.
external_force : function, optional (default = None)
    The external force as a function of time.
x_init : numpy.ndarray, optional (default = None)
    The initial states of nodes.
dt : float, optional (default = 0.01)
   The time step size of the evolution.
t_max : float, optional (default = 1)
    The time duration of the evolution.
```

4.1.3 Member Function Documentation

4.1.3.1 derivative()

4.1.3.2 getLaplacian()

```
\label{triadic_interaction.model.NDwTIs.getLaplacian} \begin{tabular}{ll} self, \\ x \end{tabular}
```

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```
Compute the Laplacian of the states.
Parameters
x : numpy.ndarray of shape (n_nodes,)
                The states of nodes.
Returns
L : numpy.ndarray of shape (n_nodes, n_nodes) \[ \frac{1}{2} + \frac{1}{
                  The Laplacian of the states.
4.1.3.3 integrate()
triadic_interaction.model.NDwTIs.integrate (
                                                            self,
                                                              deterministic = False )
Evolve the system.
Parameters
deterministic : bool, optional (default = False)
                If True, the integration is deterministic. (Default value = False)
Returns
timeseries : numpy.ndarray of shape (n_nodes, n_timesteps)
                The time series of the states.
4.1.3.4 noise()
triadic_interaction.model.NDwTIs.noise (
                                                            self,
                                                             х,
                                                              t)
The coeficients of the noise term.
Parameters
x : numpy.ndarray of shape (n_nodes,)
                The states of nodes.
 t : float
                 The time.
Returns
noise : numpy.ndarray of shape (n_nodes, n_nodes)
                The coeficients of the noise term.
```

4.1.3.5 run()

The documentation for this class was generated from the following file:

· model.py

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