CS5805 : Machine Learning I Lecture # 14

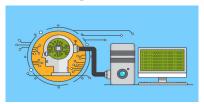
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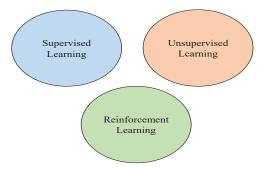
- 1. Machine Learning & Applications
- 2. Machine Learning Algorithms
- 3. Multilayer Perceptron MLP
- 4. Perceptron Learning rule
- 5. Practical Example
- 6. Demo

- A discipline within the field of Artificial Intelligence, by means
 of algorithms, provides computers with the ability to identify
 patterns from mass data in order to make predictions.
- Learning is the process of gaining knowledge or skills through experience.
- The input to this learning process is training data and the output is some expertise that can perform some task.



- Autopilot
- Intelligent vehicles
 - Driverless cars.
- Social networks
 - Spam detection.
- Medicine
 - Early breast cancer detection.
- Computer vision
 - Object detection.
- Speech
 - Translation from one language to another

• Machine Learning algorithms are divided into three categories:



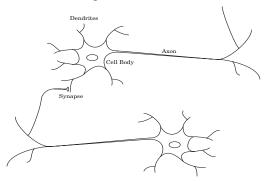
Learning rules

• Supervised learning: Network is provided with a set of examples of proper network behavior inputs and targets. $\{p_1, t_1\}, \{p_2, t_2\}, ..., \{p_O, t_O\}$

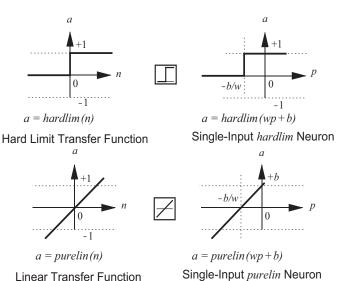
• Unsupervised learning: Only network inputs are available to the learning algorithm. Network learns to categorize (cluster) the inputs.

Brain Function

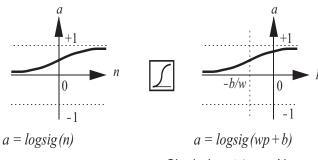
- Neurons Respond Slowly
 - 10^{-3} s compared to to 10^{-9} s for electrical circuits.
- The brain uses massively parallel comptation
 - $\approx 10^{11}$ neurons in the brain.
 - $\sim 10^4$ connections per neurons.



Transfer function



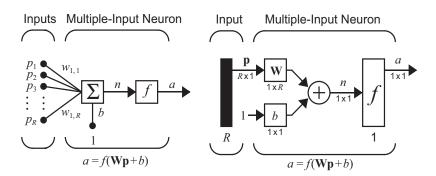
Transfer function



Log-Sigmoid Transfer Function

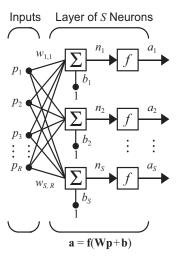
Single-Input *logsig* Neuron

Multiple input neuron

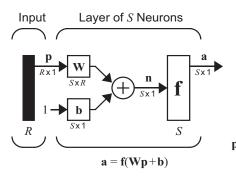


Abreviated Notation

Layer of neurons



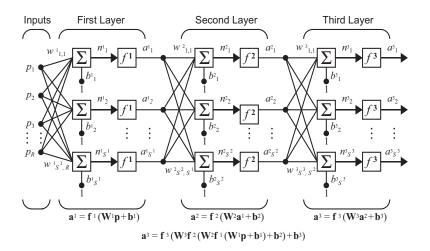
Abbreviated notation



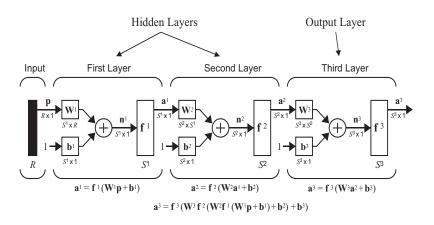
$$\mathbf{W} = \begin{bmatrix} w_{1,1} & w_{1,2} & \cdots & w_{1,R} \\ w_{2,1} & w_{2,2} & \cdots & w_{2,R} \\ \vdots & \vdots & & \vdots \\ w_{S,1} & w_{S,2} & \cdots & w_{S,R} \end{bmatrix}$$

$$\mathbf{p} = \begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_R \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_S \end{bmatrix} \quad \mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_S \end{bmatrix}$$

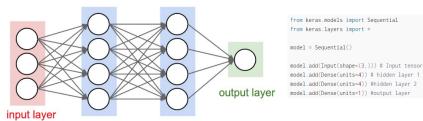
Multilayer network



Abbreviated notation

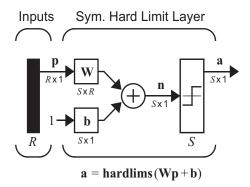


- input layer = 3 units (feature space dimension)
- hidden layer 1 = 4 units
- hidden layer 2 = 4 units
- output layer = 2 units

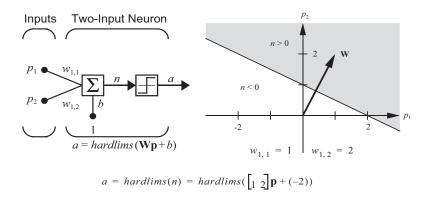


hidden layer 1 hidden layer 2

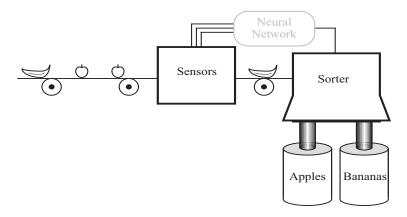
Perceptron



Two input case



$$\mathbf{W}\mathbf{p} + b = 0 \qquad \begin{bmatrix} 1 & 2 \end{bmatrix} \mathbf{p} + (-2) = 0$$



Prototype vectors

Measurement Vector

$$\mathbf{p} = \begin{bmatrix} \text{shape} \\ \text{texture} \\ \text{weight} \end{bmatrix}$$

Shape: {1 : round ; -1 : eliptical} Texture: {1 : smooth ; -1 : rough} Weight: $\{1 :> 1 \text{ lb.}; -1 :< 1 \text{ lb.}\}$

Prototype Banana

Prototype Apple

$$\mathbf{p}_1 = \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}$$

$$\mathbf{p}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$$

Apple banana example

$$a = hardlims \begin{bmatrix} w_{1,1} & w_{1,2} & w_{1,3} \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \\ p_3 \end{bmatrix} + b$$

$$p_1$$

$$p_2 \text{ (apple)}$$

$$p_1 \text{ (banana)}$$

- The decision boundary should separate the prototype vectors
- $p_1 = 0$
- The weight vector should be orthogonal to the decision boundary, and should point in the direction of the vector which should produce an output of 1. The bias determines the position of the boundary.

Testing the network

Banana:

$$a = hardlims \left[\begin{bmatrix} -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + 0 \right] = 1(banana)$$

Apple:

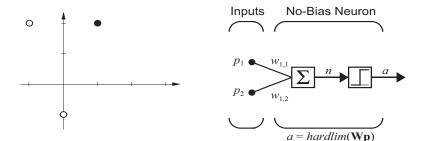
$$a = hardlims \left[\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} + 0 \right] = -1 \text{ (apple)}$$

"Rough" Banana:

$$a = hardlims \left[\begin{bmatrix} -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix} + 0 \right] = 1 \text{(banana)}$$

Learning rule test problem

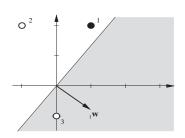
$$\begin{aligned} & \{\mathbf{p}_1, \mathbf{t}_1\}, \ \{\mathbf{p}_2, \mathbf{t}_2\}, \ \dots, \ \{\mathbf{p}_Q, \mathbf{t}_Q\} \\ \\ & \left\{\mathbf{p}_1 = \begin{bmatrix} 1\\2 \end{bmatrix}, t_1 = 1 \right\} \qquad \left\{\mathbf{p}_2 = \begin{bmatrix} -1\\2 \end{bmatrix}, t_2 = 0 \right\} \qquad \left\{\mathbf{p}_3 = \begin{bmatrix} 0\\-1 \end{bmatrix}, t_3 = 0 \right\} \end{aligned}$$



Starting point

Random initial weight:

$$_{1}\mathbf{w} = \begin{bmatrix} 1.0 \\ -0.8 \end{bmatrix}$$



Present \mathbf{p}_1 to the network:

$$a = hardlim({}_{1}\mathbf{w}^{T}\mathbf{p}_{1}) = hardlim\left[\begin{bmatrix} 1 & 0 & -0.8 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}\right]$$
$$a = hardlim(-0.6) = 0$$

Incorrect Classification.

Tentative learning rule

$$\begin{array}{ccc}
\operatorname{Set}_{1}\mathbf{w} \text{ to } \mathbf{p}_{1} \\
-\operatorname{Not stable}
\end{array} \times$$

$$\begin{array}{c}
\bullet \\
\bullet \\
\bullet \\
\bullet \\
\bullet
\end{array}$$

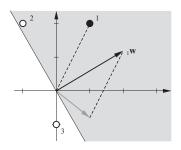
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\end{array}$$

If t = 1 and a = 0, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} + \mathbf{p}$ Tentative Rule:

$$_{1}\mathbf{w}^{new} = {_{1}}\mathbf{w}^{old} + \mathbf{p}_{1} = \begin{bmatrix} 1.0 \\ -0.8 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2.0 \\ 1.2 \end{bmatrix}$$



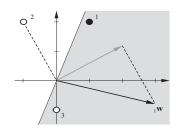
Second input vector

$$a = hardlim({}_{1}\mathbf{w}^{T}\mathbf{p}_{2}) = hardlim\left[\begin{bmatrix} 2.0 & 1.2\end{bmatrix}\begin{bmatrix} -1\\ 2\end{bmatrix}\right]$$

 $a = hardlim(0.4) = 1$ (Incorrect Classification)

Modification to Rule: If t = 0 and a = 1, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} - \mathbf{p}$

$$_{1}\mathbf{w}^{new} = _{1}\mathbf{w}^{old} - \mathbf{p}_{2} = \begin{bmatrix} 2.0\\1.2 \end{bmatrix} - \begin{bmatrix} -1\\2 \end{bmatrix} = \begin{bmatrix} 3.0\\-0.8 \end{bmatrix}$$



Third input vector

$$a = hardlim({}_{1}\mathbf{w}^{T}\mathbf{p}_{3}) = hardlim\left[\begin{bmatrix} 3.0 & -0.8 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \end{bmatrix}\right]$$

$$a = hardlim(0.8) = 1 \qquad \text{(Incorrect Classification)}$$

$$_{1}\mathbf{w}^{new} = _{1}\mathbf{w}^{old} - \mathbf{p}_{3} = \begin{bmatrix} 3.0 \\ -0.8 \end{bmatrix} - \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 3.0 \\ 0.2 \end{bmatrix}$$

Patterns are now correctly classified.

If
$$t = a$$
, then $\mathbf{w}^{new} = \mathbf{w}^{old}$.

Unified learning rule

If
$$t = 1$$
 and $a = 0$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} + \mathbf{p}$
If $t = 0$ and $a = 1$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} - \mathbf{p}$
If $t = a$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old}$
 $e = t - a$
If $e = 1$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} + \mathbf{p}$
If $e = -1$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} - \mathbf{p}$
If $e = 0$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old}$

$$_{1}\mathbf{w}^{new} = {_{1}\mathbf{w}^{old}} + e\mathbf{p} = {_{1}\mathbf{w}^{old}} + (t-a)\mathbf{p}$$

$$b^{new} = b^{old} + e$$

A bias is a weight with an input of 1.

To update the ith row of the weight matrix:

$${}_{i}\mathbf{w}^{new} = {}_{i}\mathbf{w}^{old} + e_{i}\mathbf{p}$$
$$b_{i}^{new} = b_{i}^{old} + e_{i}$$

Matrix form:

$$\mathbf{W}^{new} = \mathbf{W}^{old} + \mathbf{ep}^T$$

$$\mathbf{b}^{new} = \mathbf{b}^{old} + \mathbf{e}$$

Apple banana example

Training Set

$$\left\{\mathbf{p}_1 = \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}, t_1 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, t_2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}\right\}$$

Initial Weights

$$\mathbf{W} = \begin{bmatrix} 0.5 & -1 & -0.5 \end{bmatrix} \qquad b = 0.5$$

First Iteration

$$a = hardlim(\mathbf{W}\mathbf{p}_{1} + b) = hardlim \begin{bmatrix} 0.5 - 1 & -0.5 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + 0.5$$

$$a = hardlim(-0.5) = 0 \qquad e = t_{1} - a = 1 - 0 = 1$$

$$\mathbf{W}^{new} = \mathbf{W}^{old} + e\mathbf{p}^{T} = \begin{bmatrix} 0.5 & -1 & -0.5 \end{bmatrix} + (1) \begin{bmatrix} -1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} -0.5 & 0 & -1.5 \end{bmatrix}$$

$$b^{new} = b^{old} + e = 0.5 + (1) = 1.5$$

$$a = hardlim (\mathbf{W}\mathbf{p}_2 + b) = hardlim (\begin{bmatrix} -0.5 & 0 & -1.5 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} + (1.5))$$

$$a = hardlim (2.5) = 1$$

$$e = t_2 - a = 0 - 1 = -1$$

$$b^{new} = b^{old} + e = 1.5 + (-1) = 0.5$$

 $\mathbf{W}^{new} = \mathbf{W}^{old} + e\mathbf{p}^T = \begin{bmatrix} -0.5 & 0 & -1.5 \end{bmatrix} + (-1)\begin{bmatrix} 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} -1.5 & -1 & -0.5 \end{bmatrix}$

$$a = hardlim\left(\mathbf{W}\mathbf{p}_{1} + b\right) = hardlim\left(\begin{bmatrix} -1.5 & -1 & -0.5 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + 0.5\right)$$
$$a = hardlim\left(1.5\right) = 1 = t_{1}$$

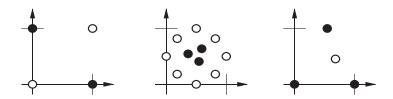
$$a = hardlim (\mathbf{W}\mathbf{p}_2 + b) = hardlim \left(\begin{bmatrix} 1 \\ -1.5 & -1 & -0.5 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} + 0.5 \right)$$
$$a = hardlim (-1.5) = 0 = t_2$$

Perceptron limitations

Linear Decision Boundary

$$_{\mathbf{1}}\mathbf{w}^{T}\mathbf{p}+b=0$$

Linearly Inseparable Problems



- Generate two sets of normally distributed dataset [random].
- Label the dataset with target value of 0 and 1.
- Implement the perceptron rule that classifies the dataset and draw the decision boundary.

