digit-detection-using-cnn

May 4, 2023

Importing data from Kaggle

```
[1]: ! pip install -q kaggle
     from google.colab import files
     files.upload()
     ! mkdir ~/.kaggle
     ! cp kaggle.json ~/.kaggle/
      chmod 600 ~/.kaggle/kaggle.json
    <IPython.core.display.HTML object>
    Saving kaggle.json to kaggle (2).json
    mkdir: cannot create directory '/root/.kaggle': File exists
[2]: | kaggle datasets download -d devanshusingh/
      ⇔hand-written-digits-for-object-detection
    hand-written-digits-for-object-detection.zip: Skipping, found more recently
```

modified local copy (use --force to force download)

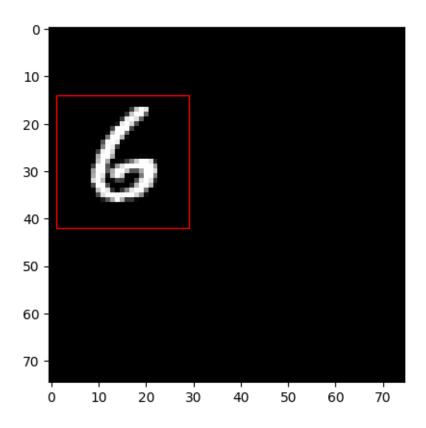
[]: unzip hand-written-digits-for-object-detection.zip

Importing Dependencies

```
[4]: import os
     import cv2 as cv
     import keras
     import numpy as np
     import pandas as pd
     import seaborn as sns
     import matplotlib.pyplot as plt
     import matplotlib.patches as patches
     from sklearn.model_selection import train_test_split
     from keras.layers import Conv2D, MaxPool2D, Dense, GlobalAveragePooling2D, Input
     from keras.models import Sequential, Model
     from sklearn.metrics import mean_absolute_error
```

```
[5]: df = pd.read_csv('/content/train_label.csv')
```

```
[6]: df.head()
 [6]:
        image_path label x_mark y_mark width height
      0
             0.png
                        5
                             23.0
                                      0.0
                                            51.0
                                                    28.0
             1.png
                             43.0
                                     34.0
                                            71.0
                                                    62.0
      1
                        0
      2
                             43.0
                                     23.0
                                            71.0
                                                    51.0
             2.png
                        4
      3
             3.png
                        1
                             3.0
                                     27.0
                                            31.0
                                                    55.0
      4
             4.png
                             32.0
                                     12.0
                                            60.0
                                                    40.0
 [8]: data = {}
                                                          # appending the bbox_
       ⇔cordinates into the data dictionary
      for idx, names in enumerate(df["image_path"]):
        if names not in data:
          data["train/train/" + names] = []
          x1 = int(df["x mark"][idx])
          y1 = int(df["y_mark"][idx])
          x2 = int(df["width"][idx])
          y2 = int(df["height"][idx])
          data["train/train/" + names].append(x1)
          data["train/train/" + names].append(y1)
          data["train/train/" + names].append(x2)
          data["train/train/" + names].append(y2)
 [9]: images = []
                                        # appending the images into the images array
      for keys in data.keys():
        img arr = cv.imread(keys, cv.IMREAD GRAYSCALE)
        images.append(img_arr)
[10]: bbox = []
      for bboxs in data.keys():
        bbox.append(data[bboxs])
[11]: images = np.array(images)
      bbox = np.array(bbox)
[12]: def test_plot(img_number):
          x1 = bbox[img number][0]
          y1 = bbox[img_number][1]
          width = bbox[img number][2]
          height = bbox[img_number][3]
          plt.subplot(1,1,1)
          plt.imshow(images[img_number], cmap='gray')
          plt.gca().add patch(patches.Rectangle((x1, y1), width-x1, height-y1,
       ⇔edgecolor='r', facecolor="none", linewidth=1))
      plt.show()
      test_plot(6000)
```



```
[13]: images = np.expand_dims(images, axis=3)
                                                     # adding a new axis to the images
       \rightarrow array
[14]: images = images/255
                                       # normalising the images
     Splitting and Model Building
[15]: x_train, x_test, y_train, y_test = train_test_split(images, bbox, test_size=0.
       →2, random_state=44)
[16]: model = Sequential()
      model.add(Conv2D(32, (3,3), input_shape=(75,75,1), activation="relu"))
      model.add(MaxPool2D(2,2))
      model.add(Conv2D(64, (3,3), activation="relu"))
      model.add(MaxPool2D(2,2))
      model.add(Conv2D(128, (3,3), activation="relu"))
      model.add(MaxPool2D(2,2))
      model.add(GlobalAveragePooling2D())
      model.add(Dense(256, activation="relu"))
      model.add(Dense(4, activation="relu"))
```

[17]: model.summary()

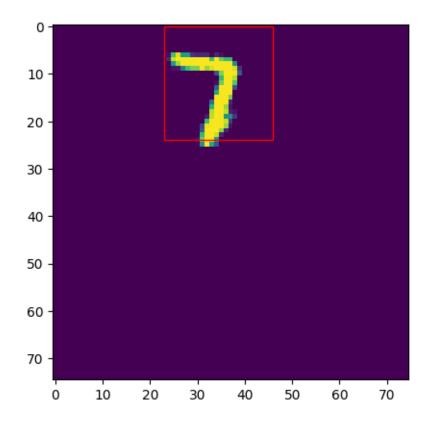
Model: "sequential"

Layer (type)		Param #
conv2d (Conv2D)	(None, 73, 73, 32)	
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 36, 36, 32)	0
conv2d_1 (Conv2D)	(None, 34, 34, 64)	18496
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 17, 17, 64)	0
conv2d_2 (Conv2D)	(None, 15, 15, 128)	73856
<pre>max_pooling2d_2 (MaxPooling 2D)</pre>	(None, 7, 7, 128)	0
<pre>global_average_pooling2d (G lobalAveragePooling2D)</pre>	(None, 128)	0
dense (Dense)	(None, 256)	33024
dense_1 (Dense)	(None, 4)	1028
Total params: 126,724		=======
Trainable params: 126,724		
Non-trainable params: 0		

```
[18]: class CustomCallbacks(keras.callbacks.Callback):
    def on_epoch_end(self,epoch,logs={}):
        num = np.random.randint(0, 10000)
        bbox = model.predict(x_test[num].reshape(1, 75, 75, 1))
        fig, ax = plt.subplots(1)
        ax.imshow(x_test[num])
        x1 = int(bbox[0][0])
        y1 = int(bbox[0][1])
        x2 = int(bbox[0][2])
        y2 = int(bbox[0][3])
        rect = patches.Rectangle((x1, y1), x2-x1, y2-y1, u)
        class CustomCallbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbacks.Callbac
```

1/1 [======] - 1s 517ms/step

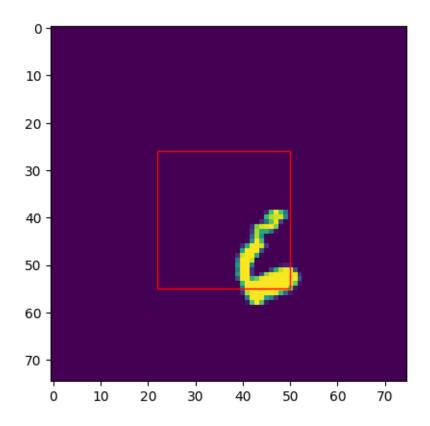
<Figure size 1000x500 with 0 Axes>



1500/1500 [===========] - 23s 12ms/step - loss: 11.0341 - val_loss: 6.7351

Epoch 2/30
1/1 [==========] - 0s 19ms/step

<Figure size 1000x500 with 0 Axes>

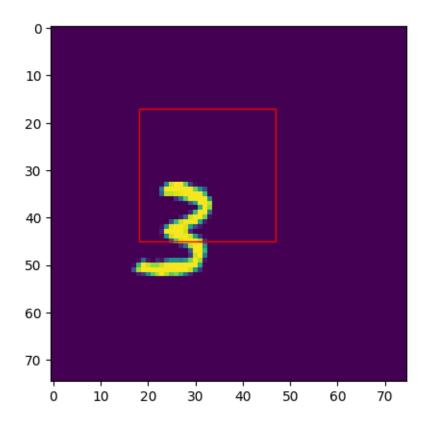


1500/1500 [=========] - 13s 9ms/step - loss: 6.0866 - val_loss: 5.7306

Epoch 3/30

1/1 [=========] - 0s 31ms/step

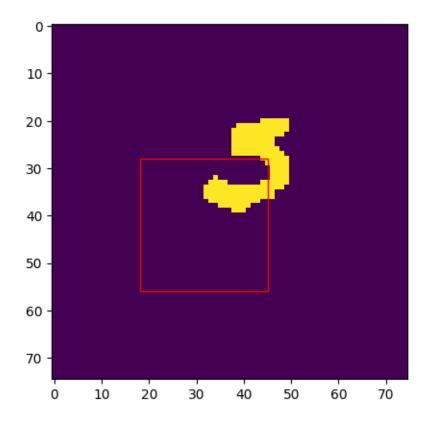
<Figure size 1000x500 with 0 Axes>

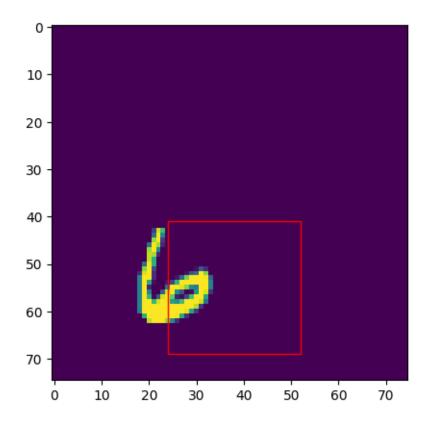


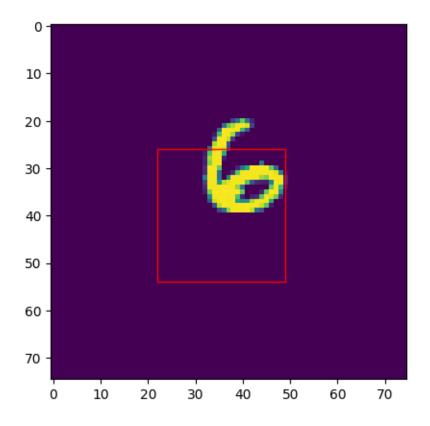
1500/1500 [========] - 10s 7ms/step - loss: 5.2336 - val_loss: 5.1354

Epoch 4/30
1/1 [=========] - 0s 20ms/step

<Figure size 1000x500 with 0 Axes>





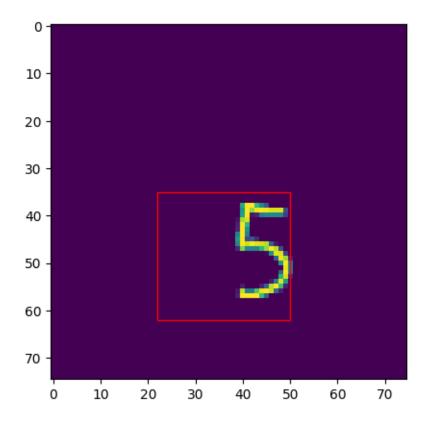


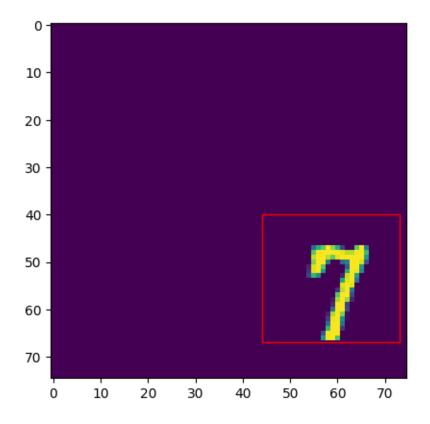
1500/1500 [========] - 11s 7ms/step - loss: 4.3893 - val_loss: 4.4408

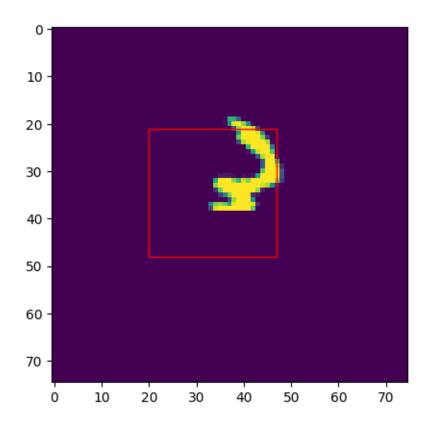
Epoch 7/30

1/1 [========] - 0s 26ms/step

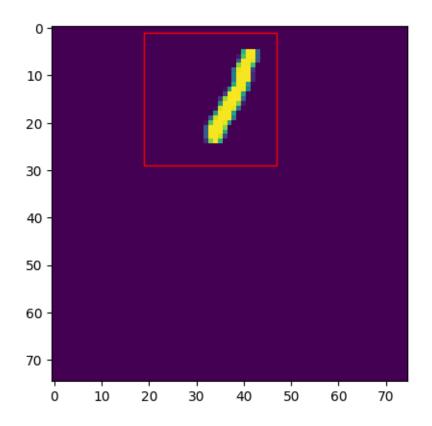
<Figure size 1000x500 with 0 Axes>

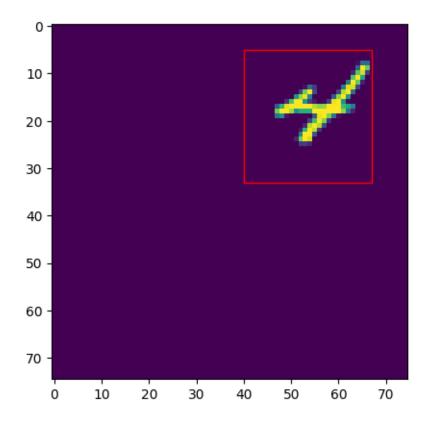


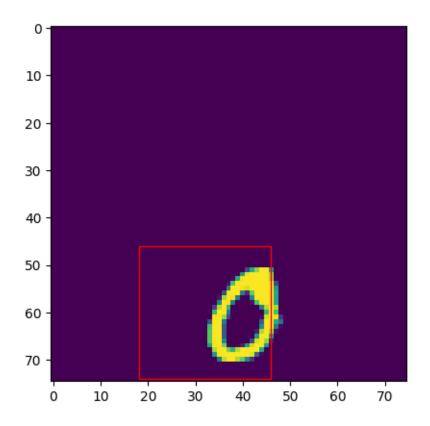




<Figure size 1000x500 with 0 Axes>





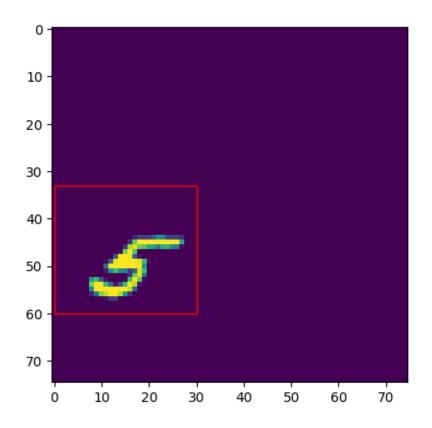


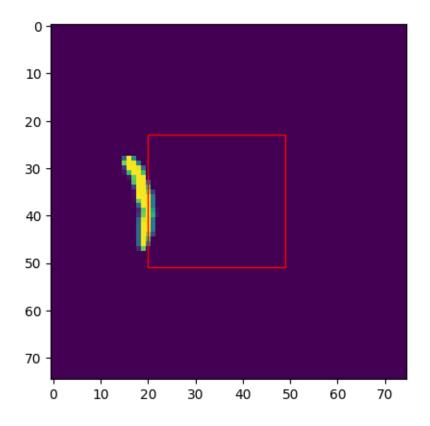
1500/1500 [========] - 11s 8ms/step - loss: 4.0865 - val_loss: 4.0703

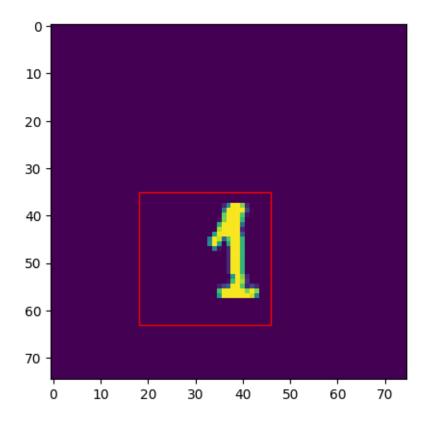
Epoch 13/30

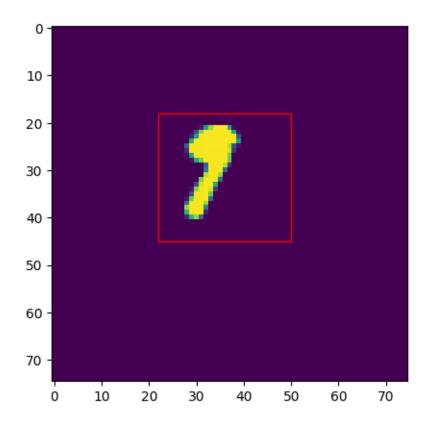
1/1 [=========] - 0s 21ms/step

<Figure size 1000x500 with 0 Axes>







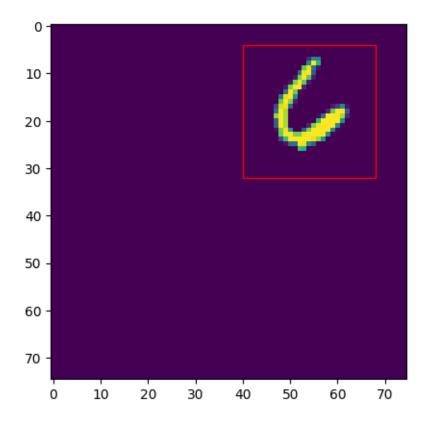


1500/1500 [========] - 11s 7ms/step - loss: 3.9985 - val_loss: 4.0390

Epoch 17/30

1/1 [========] - 0s 18ms/step

<Figure size 1000x500 with 0 Axes>

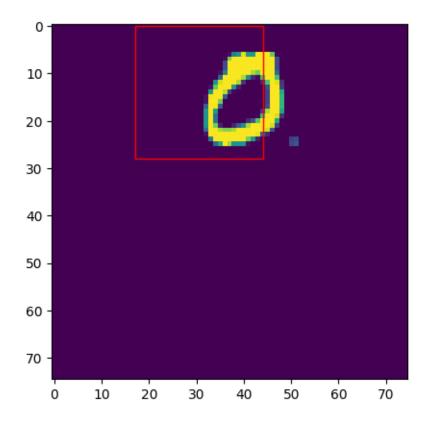


1500/1500 [========] - 11s 7ms/step - loss: 3.9795 - val_loss: 3.9221

Epoch 18/30

1/1 [========] - 0s 27ms/step

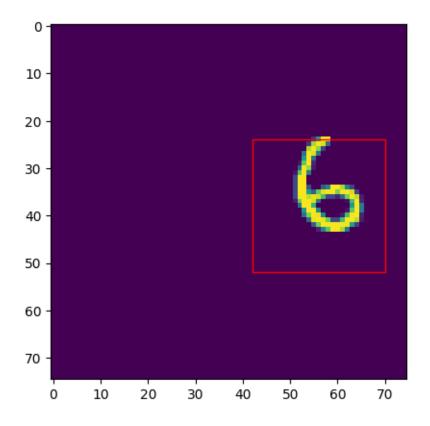
<Figure size 1000x500 with 0 Axes>

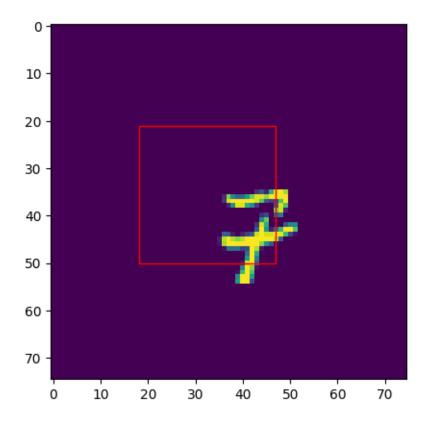


1500/1500 [========] - 11s 7ms/step - loss: 3.9545 - val_loss: 3.9476

Epoch 19/30
1/1 [=========] - 0s 29ms/step

<Figure size 1000x500 with 0 Axes>



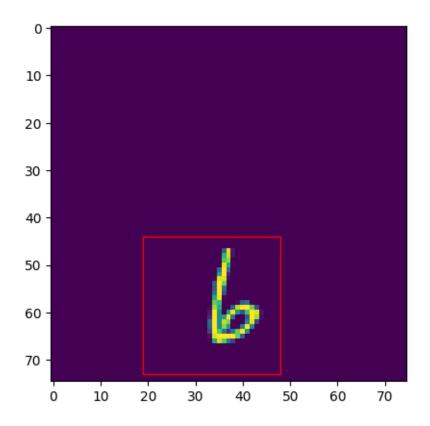


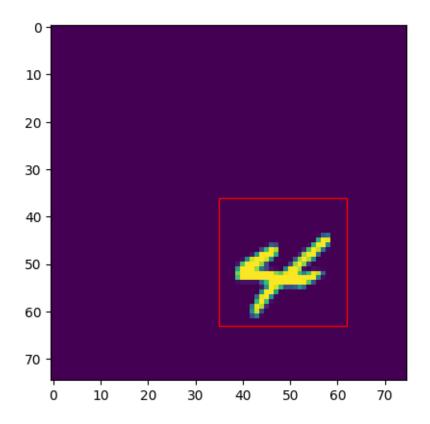
1500/1500 [=========] - 12s 8ms/step - loss: 3.9172 - val_loss: 3.8593

Epoch 21/30

1/1 [===========] - 0s 21ms/step

<Figure size 1000x500 with 0 Axes>



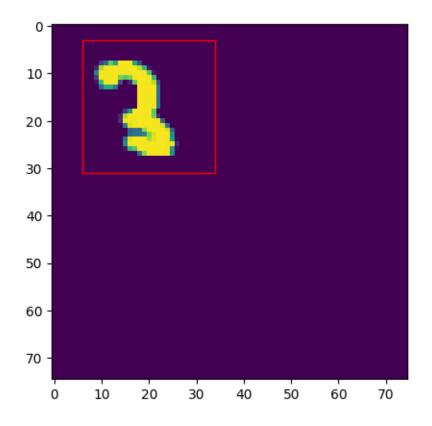


1500/1500 [========] - 12s 8ms/step - loss: 3.8779 - val_loss: 3.9742

Epoch 23/30

1/1 [========] - 0s 19ms/step

<Figure size 1000x500 with 0 Axes>

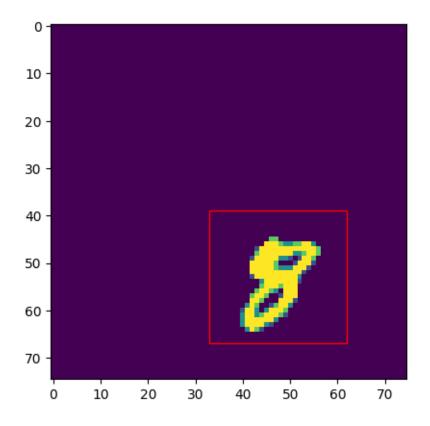


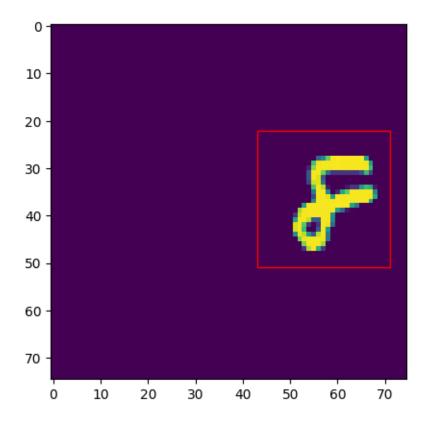
1500/1500 [========] - 11s 8ms/step - loss: 3.8836 - val_loss: 3.8842

Epoch 24/30

1/1 [========] - 0s 20ms/step

<Figure size 1000x500 with 0 Axes>



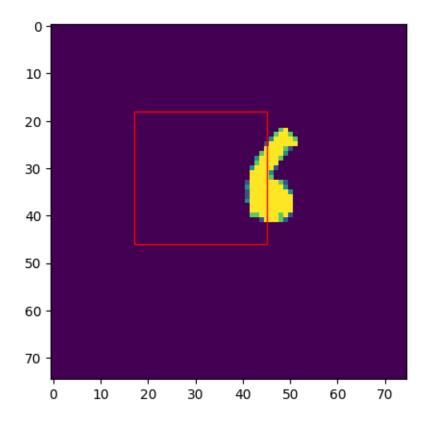


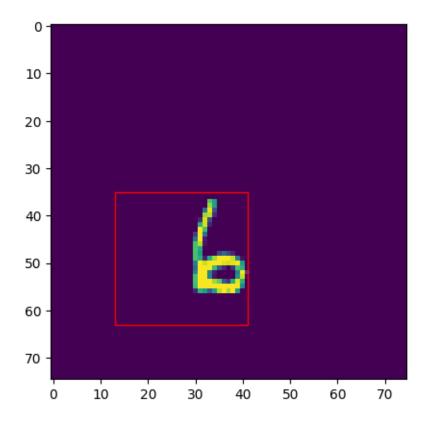
1500/1500 [========] - 11s 8ms/step - loss: 3.8601 - val_loss: 3.8985

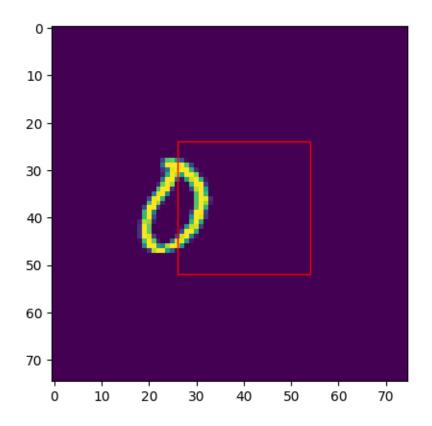
Epoch 26/30

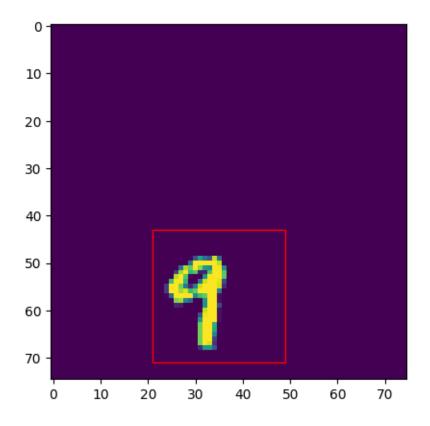
1/1 [=========] - 0s 36ms/step

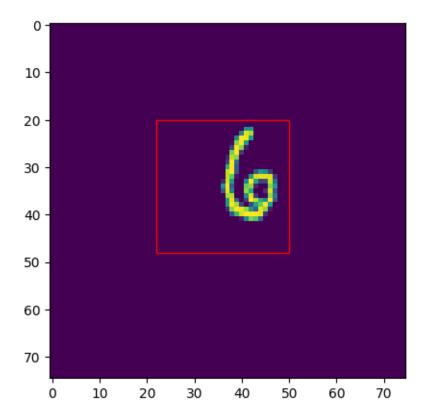
<Figure size 1000x500 with 0 Axes>

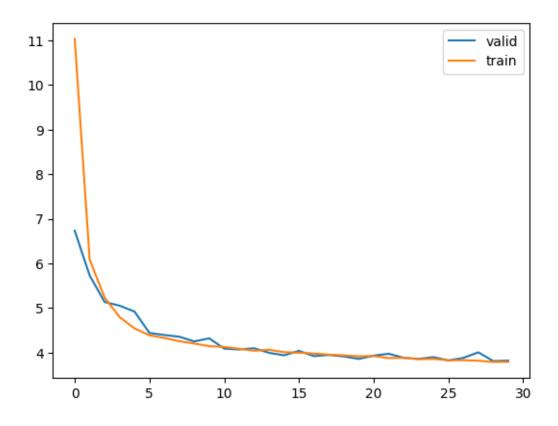












```
def plot_prediction(img_number):
    prediction = model.predict(x_test[img_number].reshape(1, 75, 75, 1))
    x1 = int(prediction[0][0])
    y1 = int(prediction[0][1])
    x2 = int(prediction[0][2])
    y2 = int(prediction[0][3])
    plt.imshow(x_test[img_number])
    plt.gca().add_patch(patches.Rectangle((x1, y1), x2-x1, y2-y1, \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \)
```

1/1 [======] - 0s 19ms/step

