Lecture 14

Advanced Sorting: MergeSort and QuickSort

Last time in relation to sorting:

In Lecture 8, we looked at three simple sorting algorithms: Bubble Sort, Selection Sort, and Insertion Sort.

There are basically two steps involved in these sorting algorithms.

- Compare two items
- Swap two items or copy one item

However, each of them has a different invariant, the condition that remains unchanged as the algorithm proceeds.

- Bubble Sort: values after "out" variable are sorted. (Right-hand side)
- Selection Sort: values less than or equal to "out" variable are sorted. (Left-hand side)
- Insertion Sort: At the end of each round, values less than "out" variable are PARTIALLY sorted. (Left-hand side but partially)

In practice, insertion sort could run faster than the other two mostly because it requires less number of comparisons. However, these three all has its worst-case running time complexity of $O(N^2)$.

We cannot just sit satisfied with the insertion sort. There must be a better way!

Today, we will look at some other sorting algorithms that can run faster than these.

Merge Sort

Merge Sort is an example of divide and conquer algorithm:

- Divide the given problem into simpler versions of itself.
- Conquer each problem using the same process.
- Finally, combine the results of simpler ones to have the final answer.

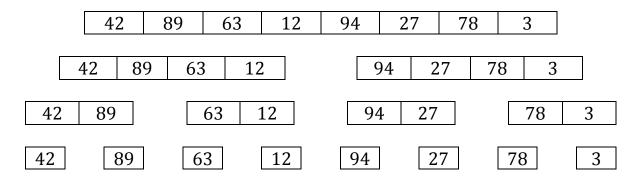
Step 1: Conceptual View

There are three steps involved in merge sort.

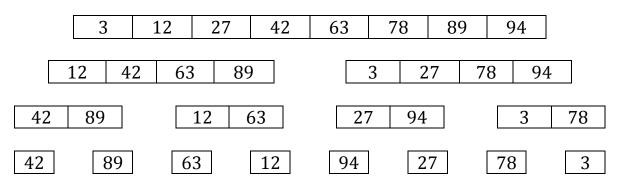
- Sort the first half using merge sort.
- Sort the second half using merge sort.
- Merge the sorted two halves to create the final sorted result.

What do you see here? Do you see recursions happening here?

Dividing processes (from top to bottom)



Merging processes (from bottom to top)



The key algorithm of merge sort is *merging*.

Let's take a closer look at the merging process of the last step in the previous example.

Array a	Array b	Array c	
0 1 2 3	0 1 2 3	0 1 2 3	4 5 6 7
<u>12</u> 42 63 89	3 27 78 94	3	
0 1 2 3		0 1 2 3	4 5 6 7
12 42 63 89	3 <u>27</u> 78 94	3 12	
0 1 2 3 12 42 63 89	0 1 2 3	0 1 2 3 3 12 27	4 5 6 7
12 42 63 89	0 1 2 3 3 27 78 94	3 12 27	
0 1 2 3		0 1 2 3	4 5 6 7
12 42 63 89	3 27 78 94	3 12 27 42	2
0 1 2 3		0 1 2 3	4 5 6 7
12 42 63 89	3 27 78 94	3 12 27 42	63
0 1 2 3 12 42 63 89	0 1 2 3 3 27 78 94	0 1 2 3 3 12 27 42	4 5 6 7
12 42 63 89	3 27 78 94	3 12 27 42	63 78
0 1 2 3		0 1 2 3	4 5 6 7
12 42 63 89	3 27 78 94	3 12 27 42	63 78 89
	_ 		
0 1 2 3	0 1 2 3	0 1 2 3	4 5 6 7
12 42 63 89	3 27 78 94	3 12 27 42	63 78 89 94

This is a snapshot of the final merging process. Remember! This happens recursively!

Step 2: Implementation View

Since *merging* is the major part of the merge sort algorithm, let's try to implement merge() method first.

```
* Merge two arrays into a new array
* Once the merge is done, return the merged array.
private int[] merge(int[] a, int[] b) {
    // Create a new array
    int[] merged = new int[_____];
    // initialize all of the indices
    int index_a=0, index_b=0, index_m=0;
    // add correct values to the new array
    while(index_a < ______ && index_b < ______) {</pre>
         if(a[index_a] < b[index_b]) {</pre>
             merged[index_m] = a[_____];
             index_a = _____;
         } else {
             merged[index_m] = b[_____];
             index_b = _____;
         }
        index_m = _____;
    return merged;
```

Would this work properly?

If no, can you find what the issue is?

What would be the output of the following code using the merge method above?

```
int[] a = {12, 42, 63, 89};
int[] b = {3, 27, 78, 94};
System.out.println(Arrays.toString(merge(a,b)));
```

Let's fix the merge method!

```
* Merge two arrays into a new array
* Once the merge is done, return the merged array.
// Create a new array
    int[] merged = new int[______];
    // initialize all of the indices
    int index_a=0, index_b=0, index_m=0;
    // add correct values to the new array
    while(index_a < ______ && index_b < _____) {</pre>
        if(a[index_a] < b[index_b]) {</pre>
            merged[index_m] = a[_____];
            index_a = _____;
        } else {
            merged[index_m] = b[_____];
            index_b = _____;
        index_m = _____;
    }
    // need to take care of some work
    return merged;
```

Now that we have pretty good merge method, it is finally time to implement the mergeSort() method.

As we said, we will implement it recursively. What do we need to think about first?

That is right! The base case!

How are we going to divide the list?

Left half should be the length of list.length/2

Right half should be the length of list.length-left.length

```
public int[] mergeSort(int[] unsorted) {
    // base case
    if(unsorted.length == ______) return ______;
    int mid = unsorted.length/2;
    // create left array
    int[] left = new int[_____];
    System. arraycopy(unsorted, ____, left, ____, ____);
    // create right array
    int[] right = new int[_____];
    System.arraycopy(unsorted, ____, right, ____);
    // call itself with the left half
    left = _____;
    // call itself with the right half
    right = _____;
    // return the merged array
    return _____;
```

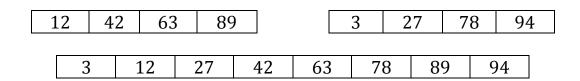
Efficiency of merge sort

Our focus is on the number of copies happening during the merging process.

From the 8 arrays (each with on item) to 4 arrays (each with two items), how many copies do we need?



From the 4 arrays (each with two items) to 2 arrays (each with four items), how many copies do we need?



From the 2 arrays (each with four items) to 1 array (with eight items), how many copies do we need?

How many steps or levels have we done to have one array with 8 items?

As a side note, can you figure out what is the maximum and minimum number of comparisons performed in each step?

Quick Sort

Step 1: Conceptual View

There are three basic steps involved in quick sort

- Partition the array or sub-arrays into left (smaller values) and right (larger values) groups.
- Call itself again to sort the left group.
- Call itself again to sort the right group.

Partitioning is the underlying mechanism of quicksort.

For example, I might want to divide students into two groups; those with grade point averages higher than 3.5 and those with grade point averages lower than 3.5.

The pivot value

It is the value that is used to determine which group a value is placed. So, if I try to divide students based on their GPA of 3.5, 3.5 is the pivot value.

1. Initial array that is not partitioned

42 89 63 12 94 27 78 3 50	36
---------------------------	----

- 2. For now, I decide to choose the last item to be the pivot value: 36
- 3. Conceptually, we have two sub-arrays that are partitioned.

36

4. The result of the first sort

3	27	12	26	(2	0.4	00	70	42	۲O
3	Z /	12	30	03	94	89	78	42	50

5. Choose the last value in the left group as the pivot : 12

3 27 12

6. Conceptually, we again have two sub-arrays that are partitioned.

7. The result of this second sort

Notice that this does not necessarily divide the array in half. It all depends on the pivot value.

Now, when do we stop? More algorithmic thinking!

Step 2: Implementation View

Since partitioning is the major mechanism for quick sort, let's try to implement partition() method first.

This method will partition a given array with the given pivot value

```
private int partition(int[] arr, int left, int right, int pivot){
    int leftPointer = _____;
    int rightPointer = right;

    while(true) {
        while(arr[_______] < pivot);
        while(rightPointer>____ && arr[_____]>pivot);
        if(leftPointer >= ______) break;
        else {
            swap(arr, leftPointer, _____);
        }
        swap(arr, leftPointer, _____);
        return ______;
}
```

```
Initial values and initial call
int[] arr = {12, 10, 18, 2, 15, 13};
int right = arr.length-1;
int pivot = arr[right];
partition(arr, 0, right, pivot);
```

Tracing initial call of partition(arr, 0, 5, 13);

	leftPointer	rightPointer	value	pivot	compared
					to pivot
Initial	-1	5		13	
arr[++leftPointer]	0	5	12	13	12 < 13
arr[++leftPointer]				13	
arr[++leftPointer]				13	
arr[rightPointer]				13	
arr[rightPointer]				13	

leftPointer: 2 < rightPointer: 3</pre>

 $swap(arr, leftPointer, rightPointer); \rightarrow swap(arr, 2, 3);$

arr is now {12, 10, 2, 18, 15, 13}

	leftPointer	rightPointer	value	Pivot	compared
					to pivot
Initial	2	3		13	
arr[++leftPointer]	3	3	18	13	18 > 13
arr[rightPointer]				13	

leftPointer : $3 > \text{rightPointer} : 2 \rightarrow \text{break}$

 $swap(arr, leftPointer, right) \rightarrow swap(arr, 3, 5)$

arr is now {12, 10, 2, 13, 15, 18}

Now what do we see?

All of the values that are smaller than the pivot (13) are where?

All of the values that are bigger than the pivot (13) are where?

Now, how would we call this method to make the whole array sorted?

Recursive quick sort method

Efficiency of quick sort

1) Efficiency of the Partition Algorithm

The two pointers, leftPointer and rightPointer, start at opposite ends of the array and move toward to each other. As they get close to each other, there are stoppings and swappings if necessary.

When they meet, a partition is complete.

If there were twice as many items to partition, it would take twice longer.

So, the running time is proportional to ______.

2) Number of recursive calls in the worst case Assuming that we are using the implementation here, let's take an array, {7, 6, 5, 4, 3, 2, 1}.

The following is a conceptual view.

Call	Pivot
recQuickSort({7, 6, 5, 4, 3, 2, 1})	1
recQuickSort({7, 6, 5, 4, 3, 2})	2
recQuickSort({7, 6, 5, 4, 3})	3
recQuickSort({7, 6, 5, 4})	4
recQuickSort({7, 6, 5})	5
recQuickSort({7, 6})	6
recQuickSort({7})	

As we can see, we need n-1 recursive calls. And, as we saw in the partitioning section, for each recursive call, we need O(k) comparisons to sort a sub-array of size k.

Do you see that this becomes quadratic complexity?

Now, how do we mitigate this?

Let's take a look at the same example with different choice of the pivot value.

Call	Pivot
recQuickSort({7, 6, 5, 4, 3, 2, 1})	4
recQuickSort({3,2,1}) recQuickSort({7,6,5})	2 and 6
recQuickSort({3}), recQuickSort({1}),	
recQuickSort({5}), recQuickSort({7})	

If we always pick the median among the elements in the sub-array, then half of the elements would be less than the median and the other half would be greater than the median.

Which makes sure that we will be guaranteed to have _____recursive calls.

But, it requires additional overhead to compute the median of all of the elements.

What is the solution?

Choosing a random value to be the pivot value would be an option

Or

It is possible to find the median value of three elements (first, last and middle) in an array.

With this improvement, we can finally conclude that the quick sort's running time complexity is O(N*log N)

* Important!

You cannot simply say that the running time complexity of quick sort is O(N*logN). In fact, its worst case running time complexity is $O(N^2)$. It is important for you to know its possibility of degeneration and strategies to mitigate it. We will explore this in the following lab.

To sum it up!

In merge sort, dividing the input array was simple and easy but it was expensive to merge the left and right sub-arrays.

In quick sort, dividing the original problem into sub-problems is more complicated and expensive whereas combing the results from sub-problems together is easy.