

Name

M#

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## Models

- Mixing in Tanks <https://xkcd.com/2974/>
  - $y' = Ay + f$  with  $y(0) = y_0$  given.
  - Conservation of volume  $V$  and salt  $S$  for each tank
    - $v'(t) = \text{rate in} - \text{rate out}$
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- Probes in Earth-Moon system. CR3BP <https://orbital-mechanics.space/the-n-body-problem/circular-restricted-three-body-problem.html>
  - With  $M = 1/82.45$  and  $E = 1 - M$  and  $r_1(x, y) = \sqrt{(x + M)^2 + y^2}$  and  $r_2 = \sqrt{(x - E)^2 + y^2}$ 
$$\begin{aligned}x'' &= 2y' + x - \frac{E(x+M)}{r_1^3} - \frac{M(x-E)}{r_2^3} \\ y'' &= -2x' + y - \frac{Ey}{r_1^3} - \frac{My}{r_2^3}\end{aligned}$$
with  $y(0), x(0), x'(0), y'(0)$  given
- RLC circuits [https://en.wikipedia.org/wiki/RLC\\_circuit](https://en.wikipedia.org/wiki/RLC_circuit)
  - [https://en.wikipedia.org/wiki/File:RLC\\_series\\_circuit\\_v1.svg](https://en.wikipedia.org/wiki/File:RLC_series_circuit_v1.svg)
  - Lots of possible configurations are. We are going to learn how to think about such circuits!
  - Circuit Rules: [https://en.wikipedia.org/wiki/Kirchhoff%27s\\_circuit\\_laws](https://en.wikipedia.org/wiki/Kirchhoff%27s_circuit_laws)
    - Current  $i$  is the rate of change of charge  $q$  through a wire.
    - Voltage drops due to resistors ( $V_R = iR$ ), capacitors ( $V_C = \frac{q}{C}$ ), inductors ( $V_L = L di/dt$ ), and voltage sources sum to zero around a circuit loop.
    - Currents sum to zero at a junction
- Population models [https://en.wikipedia.org/wiki/Population\\_model](https://en.wikipedia.org/wiki/Population_model)
  - Growth of population  $p$ 
    - $p'(t) = \text{birth rate} - \text{death rate}$
  - Predator (wolf  $w$ ) prey (moose  $m$ ) [https://en.wikipedia.org/wiki/Lotka%E2%80%93Volterra\\_equations](https://en.wikipedia.org/wiki/Lotka%E2%80%93Volterra_equations)
    - $w'(t) = \text{birth rate} - \text{death rate}$  (Assume wolf birth rate proportional to wolf and moose population)
    - $m'(t) = \text{birth rate} - \text{death rate}$  (Assume moose death rate proportional to wolf and moose population)

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## First order ODE: Analytical Solutions

- A separable scalar ODE has the form  $y'(t) = g(t)h(y)$ .

You solved these in Calculus II by separating variables and integrating

$$dy/dt = g(t) h(y) \implies \int \frac{dy}{h(y)} = \int g(t) dt + C$$

An initial condition  $y(0) = y_0$  would let you solve for the one constant of integration.

- A linear 1st order ODE has the standard form  $y'(t) + p(t)y(t) = f(t)$ . Solve by computing the IF  $v(t) = e^{\int_0^t p(\tau) d\tau}$  and solve the separable ODE  $(vy)' = vf$ .
- A 1st order ODE of the form  $\frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial y} dy = 0$  is exact with general solution  $f(t, y) = C$ .
  - $M(t, y) dt + N(t, y) dy = 0$  is exact if and only if  $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial t}$
  - To solve compute  $f(t, y) = \int M(t, y) dt + h(y) \implies h'(y) = N(t, y) - \frac{\partial}{\partial y} [\int M(t, y) dt]$  then integrate  $h'(y)$  and write down the general solution  $f(t, y) = C$
- 2.7 Substitution. Some ODEs look nicer in other variables. For example
  - 2.7.4 Bernoulli:  $y' + p(t)y = q(t)y^n$ . The substitution  $u = y^{-n}$  gives a linear equation in  $u$ .