

Name

M#

- An Ordinary Differential Equation ODE is an equation containing ordinary (not partial) derivatives.
  - We need to find and plot a function  $y(t)$  that solves (or approximately solves) the ODE.
  - An ODE describing a physical situation is an ODE model.
  - A constant solution of an ODE model is an equilibrium solution of the ODE.
  - Almost all science and engineering is described by ODE models. They are flexible, cheap and accurate.
  - The ODE model describes how the system changes. They need Initial Conditions IC that say how the system starts.
  - An Initial Value Problem IVP is an ODE with a suitable IC to give a single solution.
  - Almost all interesting ODEs are systems because they involve more than one unknown function.
  - An ODE is autonomous if time  $t$  does not appear explicitly.
- The order of an ODE is the highest derivative appearing.
  - ODEs describing water tank mixing are 1st order.
    - Suitable ICs are the state of the tanks at  $t = 0$ .
  - Most ODEs describing motion are second order. The  $a$  in  $f = ma$  is a second derivative!
    - Suitable ICs are all positions and velocities at  $t = 0$ .
- An ODE is non-linear in  $y$  if there are any nonlinear terms in  $y$  and its derivatives e.g.  $y^3$ ,  $\sin(y)$ ,  $y y'$ ,  $y_1^2$ , etc.
- An ODE is linear in  $y$  if there are no nonlinear terms in  $y$  and its derivatives. Note:  $t^2 y''$  is linear in  $y$ 
  - Nonlinear ODE models can be approximated by linear ODE models.
  - Any first order linear ode can be written as  $a_1(t) y' + a_0(t) y = b(t)$
  - Standard form is  $y' + p(t) y = f$
  - You know how to solve the homogeneous linear ODE  $y' + p(t) y = 0$ .
- Solutions of IVPs can be plotted. Our first two examples of ODE models are
  - Mixing in Tanks <https://xkcd.com/2974/>
    - $y' = Ay + f$  with  $y(0) = y_0$  given.
  - Probes in Earth-Moon system. CR3BP <https://orbital-mechanics.space/the-n-body-problem/circular-restricted-three-body-problem.html>
    - With  $M = 1/82.45$  and  $E = 1 - M$  and  $r_1(x, y) = \sqrt{(x + M)^2 + y^2}$  and  $r_2 = \sqrt{(x - E)^2 + y^2}$ 
$$x'' = 2y' + x - \frac{E(x+M)}{r_1^3} - \frac{M(x-E)}{r_2^3}$$
$$y'' = -2x' + y - \frac{Ey}{r_1^3} - \frac{My}{r_2^3}$$
with  $y(0)$ ,  $x(0)$ ,  $x'(0)$ ,  $y'(0)$  given

- Linear algebra is the language of ODE systems.
  - You need understand what solving a linear system  $Ax = b$  means.
    - You need to be able to verify solutions.
    - You need to understand how to compute all solutions.
  - You need understand what  $Av = \lambda v$  means.
    - You need to be able to verify partial solutions.
    - You need to be able to compute eigenvalues and eigenvectors.