

Name

M#

Definitions

- An Ordinary Differential Equation ODE is an equation containing ordinary (not partial) derivatives.
 - We need to find and plot a function $y(t)$ that solves (or approximately solves) the ODE.
 - An ODE describing a physical situation is an ODE model.
 - A constant solution of an ODE model is an equilibrium solution of the ODE.
 - Almost all science and engineering is described by ODE models. They are flexible, cheap and accurate.
 - The ODE model describes how the system changes. They need Initial Conditions IC that say how the system starts.
 - An Initial Value Problem IVP is an ODE with a suitable IC to give a single solution.
 - Almost all interesting ODEs are systems because they involve more than one unknown function.
 - An ODE is autonomous if time t does not appear explicitly.
- The order of an ODE is the highest derivative appearing.
 - ODEs describing water tank mixing are 1st order.
 - Suitable ICs are the state of the tanks at $t = 0$.
 - Most ODEs describing motion are second order. The a in $f = ma$ is a second derivative!
 - Suitable ICs are all positions and velocities at $t = 0$.
- An ODE is non-linear in y if there are any nonlinear terms in y and its derivatives e.g. y^3 , $\sin(y)$, $y y'$, y_1^2 , etc.
- An ODE is linear in y if there are no nonlinear terms in y and its derivatives. Note: $t^2 y''$ is linear in y
 - Nonlinear ODE models can be approximated by linear ODE models.
 - Any first order linear ode can be written as $a_1(t) y' + a_0(t) y = b(t)$
 - Standard form is $y' + p(t) y = f$
 - You know how to solve the homogeneous linear ODE $y' + p(t) y = 0$.

Models

- Solutions of IVPs can be plotted. Our first two examples of ODE models are
 - Mixing in Tanks <https://xkcd.com/2974/>
 - $y' = Ay + f$ with $y(0) = y_0$ given.

- Probes in Earth-Moon system. CR3BP <https://orbital-mechanics.space/the-n-body-problem/circular-restricted-three-body-problem.html>

- With $M = 1/82.45$ and $E = 1 - M$ and $r_1(x, y) = \sqrt{(x + M)^2 + y^2}$ and $r_2 = \sqrt{(x - E)^2 + y^2}$

$$\begin{aligned} x'' &= 2y' + x - \frac{E(x+M)}{r_1^3} - \frac{M(x-E)}{r_2^3} \\ y'' &= -2x' + y - \frac{Ey}{r_1^3} - \frac{My}{r_2^3} \end{aligned}$$
 with $y(0), x(0), x'(0), y'(0)$ given

Linear Algebra Review

- Linear algebra is the language of ODE systems.
 - You need understand what solving a linear system $Ax = b$ means.
 - You need to be able to verify solutions.
 - You need to understand how to compute all solutions.
If $Ax_p = b$ and $\{x_1, x_2\}$ is a basis for $\text{Null}(A)$ then $x = c_1 x_1 + c_2 x_2 + x_p$
 - You need understand what $Av = \lambda v$ means.
 - You need to be able to verify partial solutions.
 - You need to be able to compute eigenvalues and eigenvectors.

2.3: First Order Linear ODE

- A separable scalar ODE has the form $y'(t) = g(t)h(y)$.

You solved these in Calculus II by separating variables and integrating

$$dy/dt = g(t)h(y) \implies \int \frac{dy}{h(y)} = \int g(t) dt + C$$

An initial condition $y(0) = y_0$ would let you solve for the one constant of integration.

- A linear 1st order ODE has the standard form $y'(t) + p(t)y(t) = f(t)$.

- Separable if $f(t) = 0$

- $\frac{dy}{dt} + p(t)y = 0 \implies \int \frac{dy}{y} = -\int p(t) dt \implies \ln(y) = -\int p(t) dt + C \implies y = y_0 e^{-\int_0^t p(\tau) d\tau}$

- Multiply by the integrating factor (IF) $v(t) = e^{\int_0^t p(\tau) d\tau}$ satisfies $v'(t) = v(t)p(t)$.

- $v(t)y'(t) + v(t)p(t)y(t) = v(t)f(t) \implies v(t)y'(t) + v'(t)y(t) = v(t)f(t) \implies (v(t)y(t))' = v(t)f(t)$

- Integrating gives $v(t)y(t) = \int v(t)f(t) dt + C \implies y(t) = \frac{1}{v(t)} \left(C + \int v(t)f(t) dt \right)$

- Summary: To solve $y'(t) + p(t)y = f(t)$ compute the IF $v(t) = e^{\int_0^t p(\tau) d\tau}$ and solve the separable ODE $(vy)' = vf$.