

JIANYUAN WANG

Webpage: <https://jytime.github.io> ◇ Email: jianyuan@robots.ox.ac.uk

EDUCATION

University of Oxford, Visual Geometry Group (VGG)

Jan 2023 – Present

Doctor of Philosophy in Engineering Science

Joint PhD Program with Meta AI, fully funded by Facebook AI Research Scholarship

Supervised by Christian Rupprecht, David Novotny, and Andrea Vedaldi

Australian National University

Mar 2019

Bachelor of Engineering, First Class Honours

EXPERIENCE

Facebook AI Research (FAIR) London, Research Assistant

Oct 2022 – Present

Full-time researcher operating under a dual-affiliation PhD program with Oxford

Chinese University of Hong Kong, Research Assistant

Jun 2021 – Sep 2022

AWARDS

Best Paper Award, Computer Vision and Pattern Recognition (CVPR) 2025

Jun 2025

Facebook AI Research Scholarship

Jan 2023

SELECTED PUBLICATIONS

-
- **Jianyuan Wang**, Minghao Chen, Nikita Karaev, Andrea Vedaldi, Christian Rupprecht, and David Novotny. “VGGT: Visual Geometry Grounded Transformer”. *Conference on Computer Vision and Pattern Recognition (CVPR)*, 2025, **Best Paper Award**.
 - Oriane Siméoni, Huy V. Vo, Maximilian Seitzer, Federico Baldassarre, Maxime Oquab, Cijo Jose, Vasil Khalidov, Marc Szafraniec, Seungeun Yi, Michaël Ramamonjisoa, Francisco Massa, Daniel Haziza, Luca Wehrstedt, **Jianyuan Wang**, Timothée Darcet, Théo Moutakanni, Leonel Sentana, Claire Roberts, Andrea Vedaldi, Jamie Tolan, John Brandt, Camille Couprie, Julien Mairal, Hervé Jégou, Patrick Labatut, and Piotr Bojanowski. “DINOv3”. *arXiv preprint arXiv:2508.10104*, 2025.
 - **Jianyuan Wang**, Nikita Karaev, Christian Rupprecht, and David Novotny. “VGGSfM: Visual Geometry Grounded Deep Structure from Motion”. *Conference on Computer Vision and Pattern Recognition (CVPR)*, 2024, **Highlight**.
 - Nikita Karaev, Iurii Makarov, **Jianyuan Wang**, Natalia Neverova, Andrea Vedaldi, and Christian Rupprecht. “CoTracker3: Simpler and Better Point Tracking by Pseudo-Labeling Real Videos”. *International Conference on Computer Vision (ICCV)*, 2025, **Highlight**.
 - **Jianyuan Wang**, Christian Rupprecht, and David Novotny. “PoseDiffusion: Solving Pose Estimation via Diffusion-aided Bundle Adjustment”. *International Conference on Computer Vision (ICCV)*, 2023.