

# JIANYUAN WANG

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## EDUCATION

### University of Oxford, Visual Geometry Group (VGG)

Jan 2023 – Present

Doctor of Philosophy in Engineering Science

Joint PhD Program with Meta AI, fully funded by Facebook AI Research Scholarship

Supervised by Christian Rupprecht, David Novotny, and Andrea Vedaldi

### Australian National University

Mar 2019

Bachelor of Engineering, First Class Honours

## EXPERIENCE

### Facebook AI Research (FAIR) London, Research Assistant

Oct 2022 – Present

Full-time researcher operating under a dual-affiliation PhD program with Oxford

### Chinese University of Hong Kong, Research Assistant

Jun 2021 – Sep 2022

## AWARDS

### Best Paper Award, Computer Vision and Pattern Recognition (CVPR) 2025

Jun 2025

### Facebook AI Research Scholarship

Jan 2023

## SELECTED PUBLICATIONS

• **Jianyuan Wang**, Minghao Chen, Nikita Karaev, Andrea Vedaldi, Christian Rupprecht, and David Novotny. “VG GT: Visual Geometry Grounded Transformer”. *Conference on Computer Vision and Pattern Recognition (CVPR), 2025, Best Paper Award*.

• Oriane Siméoni, Huy V. Vo, Maximilian Seitzer, Federico Baldassarre, Maxime Oquab, Cijo Jose, Vasil Khalidov, Marc Szafraniec, Seungeun Yi, Michaël Ramamonjisoa, Francisco Massa, Daniel Haziza, Luca Wehrstedt, **Jianyuan Wang**, Timothée Darctet, Théo Moutakanni, Leonel Santana, Claire Roberts, Andrea Vedaldi, Jamie Tolan, John Brandt, Camille Couprie, Julien Mairal, Hervé Jégou, Patrick Labatut, and Piotr Bojanowski. “DINOv3”. *arXiv preprint arXiv:2508.10104*, 2025.

• **Jianyuan Wang**, Nikita Karaev, Christian Rupprecht, and David Novotny. “VGG SFM: Visual Geometry Grounded Deep Structure from Motion ”. *Conference on Computer Vision and Pattern Recognition (CVPR), 2024, Highlight*.

• Nikita Karaev, Iurii Makarov, **Jianyuan Wang**, Natalia Neverova, Andrea Vedaldi, and Christian Rupprecht. “CoTracker3: Simpler and Better Point Tracking by Pseudo-Labelling Real Videos”. *International Conference on Computer Vision (ICCV), 2025, Highlight*.

• **Jianyuan Wang**, Christian Rupprecht, and David Novotny. “PoseDiffusion: Solving Pose Estimation via Diffusion-aided Bundle Adjustment”. *International Conference on Computer Vision (ICCV), 2023*.