

高等量子力学第四次作业

董建宇 202328000807038

习题 1 受迫谐振子的哈密顿量为:

$$\hat{H} = \hat{H}_0 + \hat{V}; \quad \hat{H}_0 = \hbar\omega(\hat{a}^\dagger\hat{a} + \frac{1}{2}), \quad \hat{V} = \hat{V} = \hbar g(\hat{a} + \hat{a}^\dagger).$$

体系初始时刻处于 \hat{H}_0 的基态 $|0\rangle$ 。

分别在 Schrödinger 绘景、Heisenberg 绘景和 Interaction 绘景下, 计算下列物理量的平均值:

$$\hat{n} = \hat{a}^\dagger\hat{a}, \quad \hat{x} = \frac{1}{\sqrt{2}}(\hat{a} + \hat{a}^\dagger), \quad \hat{p} = \frac{1}{\sqrt{2}i}(\hat{a} - \hat{a}^\dagger).$$

Schrödinger 绘景:

由于体系哈密顿量不显含时间, 则在 t 时刻, 体系量子态可以写作:

$$|\psi(t)\rangle = e^{-i\hat{H}t/\hbar} |0\rangle.$$

记 $\hat{A} = i\hat{H}t/\hbar = i(\omega t(\hat{n} + 1/2) + \sqrt{2}gt\hat{x})$, 可以计算:

$$\begin{aligned} [\hat{n}, \hat{x}] &= -i\hat{p}; \quad [\hat{n}, \hat{p}] = i\hat{x}; \quad [\hat{x}, \hat{p}] = i; \\ [\hat{A}, \hat{n}] &= i[\omega t(\hat{n} + 1/2) + \sqrt{2}gt\hat{x}, \hat{n}] = -\sqrt{2}gt\hat{p}; \\ [\hat{A}, \hat{x}] &= i[\omega t(\hat{n} + 1/2) + \sqrt{2}gt\hat{x}, \hat{x}] = \omega t\hat{p}; \\ [\hat{A}, \hat{p}] &= i[\omega t(\hat{n} + 1/2) + \sqrt{2}gt\hat{x}, \hat{p}] = -\omega t\hat{x} - \sqrt{2}gt. \end{aligned}$$

(a) 对于 $\hat{n} = \hat{a}^\dagger\hat{a}$ 的平均值, 可以先计算 $e^{\hat{A}}\hat{n}e^{-\hat{A}}$ 如下:

$$\begin{aligned} e^{\hat{A}}\hat{n}e^{-\hat{A}} &= \hat{n} + \frac{1}{1!}[\hat{A}, \hat{n}] + \frac{1}{2!}[\hat{A}, [\hat{A}, \hat{n}]] + \dots \\ &= \hat{n} + \frac{1}{1!}(-\sqrt{2}gt\hat{p}) + \frac{1}{2!}(\sqrt{2}\omega gt^2\hat{x} + 2g^2t^2) \\ &\quad + \frac{1}{3!}(\sqrt{2}\omega^2 gt^3\hat{p}) + \frac{1}{4!}(-\sqrt{2}\omega^3 gt^4\hat{x} - 2\omega^2 g^2t^4) + \dots \\ &= \hat{n} + \frac{\sqrt{2}g}{\omega}\hat{x} \left(\frac{1}{2!}(\omega t)^2 - \frac{1}{4!}(\omega t)^4 + \dots \right) \\ &\quad - \frac{\sqrt{2}g}{\omega}\hat{p} \left(\frac{1}{1!}(\omega t) - \frac{1}{3!}(\omega t)^3 + \dots \right) + \frac{2g^2}{\omega^2} \left(\frac{1}{2!}(\omega t)^2 - \frac{1}{4!}(\omega t)^4 + \dots \right) \\ &= \hat{n} + \frac{\sqrt{2}g}{\omega}\hat{x}(1 - \cos(\omega t)) - \frac{\sqrt{2}g}{\omega}\hat{p}\sin(\omega t) + \frac{2g^2}{\omega^2}(1 - \cos(\omega t)). \end{aligned}$$

则有:

$$\langle\psi(t)|\hat{n}|\psi(t)\rangle = \langle 0|e^{\hat{A}}\hat{n}e^{-\hat{A}}|0\rangle = \frac{2g^2}{\omega^2}(1 - \cos(\omega t)).$$

(b) 对于 $\hat{x} = \frac{1}{\sqrt{2}}(\hat{a}^\dagger + \hat{a})$, 可以先计算 $e^{\hat{A}}\hat{x}e^{-\hat{A}}$ 如下:

$$\begin{aligned}
 e^{\hat{A}}\hat{x}e^{-\hat{A}} &= \hat{x} + \frac{1}{1!}[\hat{A}, \hat{x}] + \frac{1}{2!}[\hat{A}, [\hat{A}, \hat{x}]] + \dots \\
 &= \hat{x} + \frac{1}{1!}(\omega t \hat{p}) + \frac{1}{2!}(-(\omega t)^2 \hat{x} - \sqrt{2}g\omega t^2) \\
 &\quad + \frac{1}{3!}(-(\omega t)^3 \hat{p}) + \frac{1}{4!}((\omega t)^4 \hat{x} + \sqrt{2}g\omega^3 t^4) + \dots \\
 &= \hat{x} \left(1 - \frac{1}{2!}(\omega t)^2 + \frac{1}{4!}(\omega t)^4 + \dots \right) + \hat{p} \left(\frac{1}{1!}(\omega t) - \frac{1}{3!}(\omega t)^3 + \dots \right) \\
 &\quad + \frac{\sqrt{2}g}{\omega} \left(-\frac{1}{2!}(\omega t)^2 + \frac{1}{4!}(\omega t)^4 + \dots \right) \\
 &= \hat{x} \cos(\omega t) + \hat{p}(\sin(\omega t)) + \frac{\sqrt{2}g}{\omega}(\cos(\omega t) - 1).
 \end{aligned}$$

则有:

$$\langle \psi(t) | \hat{x} | \psi(t) \rangle = \langle 0 | e^{\hat{A}}\hat{x}e^{-\hat{A}} | 0 \rangle = \frac{\sqrt{2}g}{\omega}(\cos(\omega t) - 1).$$

(c) 对于 $\hat{p} = \frac{1}{\sqrt{2}i}(\hat{a} - \hat{a}^\dagger)$ 的平均值, 可以先计算 $e^{\hat{A}}\hat{p}e^{-\hat{A}}$ 如下:

$$\begin{aligned}
 e^{\hat{A}}\hat{p}e^{-\hat{A}} &= \hat{p} + \frac{1}{1!}[\hat{A}, \hat{p}] + \frac{1}{2!}[\hat{A}, [\hat{A}, \hat{p}]] + \dots \\
 &= \hat{p} + \frac{1}{1!}(-\omega t \hat{x} - \sqrt{2}g t) + \frac{1}{2!}(-(\omega t)^2 \hat{p}) + \frac{1}{3!}((\omega t)^3 \hat{x} + \sqrt{2}g\omega^2 t^3) + \dots \\
 &= \hat{p} \left(1 - \frac{1}{2!}(\omega t)^2 + \dots \right) - \hat{x} \left(-\frac{1}{1!}\omega t + \frac{1}{3!}(\omega t)^3 + \dots \right) - \frac{\sqrt{2}g}{\omega} \left(\omega t - \frac{1}{3!}(\omega t)^3 \right) \\
 &= \hat{p} \cos(\omega t) - \hat{x} \sin(\omega t) - \frac{\sqrt{2}g}{\omega} \sin(\omega t).
 \end{aligned}$$

则有:

$$\langle \psi(t) | \hat{p} | \psi(t) \rangle = \langle 0 | e^{\hat{A}}\hat{p}e^{-\hat{A}} | 0 \rangle = -\frac{\sqrt{2}g}{\omega} \sin(\omega t).$$

Heisenberg 绘景:

对于 Heisenberg 绘景下算符 $\hat{A}_H(t) = U^\dagger(t, 0)\hat{A}_S U(t, 0)$, 满足 Heisenberg 方程:

$$i\hbar \frac{d\hat{A}_H(t)}{dt} = [\hat{A}_H(t), \hat{H}].$$

则对于三个算符可以计算:

$$\begin{aligned}
 i\hbar \frac{d\hat{n}_H(t)}{dt} &= [\hat{n}_H(t), \hat{H}] = -i\sqrt{2}\hbar g \hat{p}_H(t); \\
 i\hbar \frac{d\hat{x}_H(t)}{dt} &= [\hat{x}_H(t), \hat{H}] = i\hbar \omega \hat{p}_H(t); \\
 i\hbar \frac{d\hat{p}_H(t)}{dt} &= [\hat{p}_H(t), \hat{H}] = -i\hbar \omega \hat{x}_H(t) - i\sqrt{2}\hbar g.
 \end{aligned}$$

将第三个方程两侧对时间求导并取平均可得:

$$i\hbar \frac{d^2 p_H(t)}{dt^2} = -i\hbar \omega \frac{dx_H(t)}{dt} = -i\hbar \omega^2 p_H(t).$$

则有:

$$p_H(t) = a_1 \sin(\omega t) + a_2 \cos(\omega t) + a_3.$$

利用 $p_H(0) = 0$, $\frac{dp_H(0)}{dt} = -\sqrt{2}g$, $\frac{d^2 p_H(0)}{dt^2} = 0$ 可得: $a_1 = -\frac{\sqrt{2}g}{\omega}$, $a_2 = a_3 = 0$ 。即有:

$$\langle 0 | \hat{p}_H(t) | 0 \rangle = -\frac{\sqrt{2}g}{\omega} \sin(\omega t).$$

第一个方程两侧取平均有:

$$\frac{dn_H(t)}{dt} = -\sqrt{2}g p_H(t) = \frac{2g^2}{\omega} \sin(\omega t).$$

则有:

$$n_H(t) = -\frac{2g^2}{\omega^2} \cos(\omega t) + b_1.$$

利用 $n_H(0) = 0$, 可得: $b_1 = \frac{2g^2}{\omega^2}$, 则有:

$$n_H(t) = \frac{2g^2}{\omega^2} (1 - \cos(\omega t)).$$

第二个方程两侧取平均有:

$$\frac{dx_H(t)}{dt} = \omega p_H(t) = -\sqrt{2}g \sin(\omega t).$$

则有:

$$x_H(t) = \frac{\sqrt{2}g}{\omega} \cos(\omega t) + c_1$$

利用 $x_H(0) = 0$, 可得: $c_1 = -\frac{\sqrt{2}g}{\omega}$, 则有:

$$x_H(t) = \frac{\sqrt{2}g}{\omega} (\cos(\omega t) - 1).$$

综上所述, 在 Heisenberg 绘景下, 三个算符平均值分别为:

$$\langle 0 | \hat{n}_H(t) | 0 \rangle = \frac{2g^2}{\omega^2} (1 - \cos(\omega t));$$

$$\langle 0 | \hat{x}_H(t) | 0 \rangle = \frac{\sqrt{2}g}{\omega} (\cos(\omega t) - 1);$$

$$\langle 0 | \hat{p}_H(t) | 0 \rangle = -\frac{\sqrt{2}g}{\omega} \sin(\omega t).$$

Interaction 绘景:

在 Interaction 绘景下, 算符 $\hat{A}_I = U_0^\dagger(t, 0) \hat{A}_S U_0(t, 0)$ 满足方程:

$$i\hbar \frac{d\hat{A}_I(t)}{dt} = [\hat{A}_I(t), \hat{H}_0]$$

其中 $U_0(t, 0) = e^{-i\hat{H}_0 t/\hbar}$ 。Interaction 绘景下态矢量满足:

$$i\hbar \frac{d}{dt} |\psi_I(t)\rangle = \hat{V}_I(t) |\psi_I(t)\rangle.$$

取一阶近似, 有:

$$|\psi_I(t)\rangle = \hat{U}_I(t, 0) |\psi_I(0)\rangle = \left(1 + \frac{1}{i\hbar} \int_0^t \hat{V}_I(t') dt'\right) |\psi_I(0)\rangle.$$

其中 $|\psi_I(0)\rangle = |\psi(0)\rangle = |0\rangle$ 。从而可以计算:

$$\begin{aligned} |\psi_I(t)\rangle &= |0\rangle + \frac{1}{i\hbar} \int_0^t e^{i\omega t(\hat{n}+1/2)} \sqrt{2}g\hbar\hat{x}e^{-i\omega t(\hat{n}+1/2)} |0\rangle \\ &= |0\rangle - ig \int_0^t e^{i\omega t'} dt' |1\rangle \\ &= |0\rangle - \frac{g}{\omega} (e^{i\omega t} - 1) |1\rangle. \end{aligned}$$

对于三个算符可以计算:

$$\begin{aligned} i\hbar \frac{d\hat{n}_I(t)}{dt} &= [\hat{n}_I(t), \hat{H}_0] = 0; \\ i\hbar \frac{d\hat{x}_I(t)}{dt} &= [\hat{x}_I(t), \hat{H}_0] = i\hbar\omega\hat{p}_I(t); \\ i\hbar \frac{d\hat{p}_I(t)}{dt} &= [\hat{p}_I(t), \hat{H}_0] = -i\hbar\omega\hat{x}_I(t). \end{aligned}$$

则有:

$$\begin{aligned} \hat{n}_I(t) &= \hat{n}_I(0) = \hat{n}; \\ \hat{x}_I(t) &= \hat{A}_1 \sin(\omega t) - \hat{A}_2 \cos(\omega t); \\ \hat{p}_I(t) &= \hat{A}_1 \cos(\omega t) + \hat{A}_2 \sin(\omega t). \end{aligned}$$

利用 $\hat{x}_I(0) = \hat{x}$, $\hat{p}_I(0) = \hat{p}$, 可得: $\hat{A}_1 = \hat{p}$, $\hat{A}_2 = -\hat{x}$ 。即:

$$\begin{aligned} \hat{x}_I(t) &= \hat{p} \sin(\omega t) + \hat{x} \cos(\omega t); \\ \hat{p}_I(t) &= \hat{p} \cos(\omega t) - \hat{x} \sin(\omega t). \end{aligned}$$

则可以计算三个算符的平均值为:

$$\begin{aligned} \langle \psi_I(t) | \hat{n}_I(t) | \psi_I(t) \rangle &= \frac{2g^2}{\omega^2} (1 - \cos(\omega t)); \\ \langle \psi_I(t) | \hat{x}_I(t) | \psi_I(t) \rangle &= \frac{\sqrt{2}g}{\omega} (\cos(\omega t) - 1); \\ \langle \psi_I(t) | \hat{p}_I(t) | \psi_I(t) \rangle &= -\frac{\sqrt{2}g}{\omega} \sin(\omega t). \end{aligned}$$

习题 2 利用路径积分推导一维谐振子的传播子表达式

传播子为:

$$\begin{aligned} K(x_f, t_f; x_i, t_i) &= \prod_{k=1}^{N-1} \sqrt{\frac{m}{2\pi i \hbar \tau}} \int dx_k \prod_{j=0}^{N-1} e^{\frac{i}{\hbar} \tau \left[\frac{m}{2} \left(\frac{x_{j+1} - x_j}{\tau} \right)^2 - V(x_j) \right]} \\ &= \prod_{k=1}^{N-1} \int dx_k \prod_{j=0}^{N-1} K(x_{j+1}, x_j, \tau) \end{aligned}$$

其中

$$K(x_{j+1}, x_j, \tau) = K(x_{j+1}, t_{j+1}, x_j, t_j) = \sqrt{\frac{m}{2\pi i \hbar \tau}} e^{\frac{i}{\hbar} \tau \left[\frac{m}{2} \left(\frac{x_{j+1} - x_j}{\tau} \right)^2 - V(x_j) \right]}$$

当 $\tau \rightarrow 0$ 时, 可以做如下近似:

$$V(x_j) \approx \frac{1}{2}(V(x_{j+1}) + V(x_j))$$

则短时传播子为:

$$\begin{aligned} K(x_{j+1}, x_j, \tau) &= \sqrt{\frac{m}{2\pi i \hbar \tau}} e^{\frac{i}{\hbar} \tau \left[\frac{m}{2} \left(\frac{x_{j+1} - x_j}{\tau} \right)^2 - \frac{1}{2}(V(x_{j+1}) + V(x_j)) \right]} \\ &= \sqrt{\frac{m}{2\pi i \hbar \tau}} e^{\frac{im}{2\hbar} \frac{1}{\tau} \left[\left(\frac{x_{j+1} - x_j}{\tau} \right)^2 - \frac{\omega^2 \tau^2}{2} (x_{j+1}^2 + x_j^2) \right]} \\ &= \sqrt{\frac{m\omega}{2\pi i \hbar}} \sqrt{\frac{1}{\omega \tau}} e^{\frac{im\omega}{2\hbar} \frac{1}{\omega \tau} \left[\left(1 - \frac{\omega^2 \tau^2}{2} \right) (x_{j+1}^2 + x_j^2) - 2x_{j+1}x_j \right]} \end{aligned}$$

可以做变量替换:

$$\sin \phi = \omega \tau.$$

当 $\tau \rightarrow 0$ 时, 有: $\phi \approx \sin \phi = \omega \tau$, $\cos \phi = \sqrt{1 - \omega^2 \tau^2} \approx 1 - \omega^2 \tau^2 / 2$, 则有:

$$F(\eta, \eta'; \phi) = K(\eta, \eta'; \frac{\sin \phi}{\omega}) = \sqrt{\frac{m\omega}{2\pi i \hbar}} \sqrt{\frac{1}{\sin \phi}} e^{\frac{im\omega}{2\hbar} \frac{1}{\sin \phi} [(\eta^2 + \eta'^2) \cos \phi - 2\eta\eta']}$$

可以计算:

$$\begin{aligned} \int d\eta F(\eta'', \eta; \phi) F(\eta, \eta'; \phi) &= \frac{m\omega}{2\pi i \hbar} \frac{1}{\sin \phi} e^{\frac{im\omega}{2\hbar} \frac{\cos \phi}{\sin \phi} (\eta''^2 + \eta'^2)} \int d\eta e^{\frac{im\omega}{\hbar} \frac{1}{\sin \phi} [\eta^2 \cos \phi - \eta(\eta'' + \eta')]} \\ &= \frac{m\omega}{2\pi i \hbar} \frac{1}{\sin \phi} \sqrt{\frac{\pi i \hbar \sin \phi}{m\omega \cos \phi}} e^{\frac{im\omega}{2\hbar} \frac{1}{\sin \phi} [(\eta''^2 + \eta'^2) \cos \phi - \frac{(\eta'' + \eta')^2}{2 \cos \phi}]} \\ &= \sqrt{\frac{m\omega}{2\pi i \hbar}} \sqrt{\frac{1}{\sin 2\phi}} e^{\frac{im\omega}{2\hbar} \frac{1}{\sin 2\phi} [(\eta''^2 + \eta'^2) \cos 2\phi - 2\eta''\eta']} \\ &= F(\eta'', \eta'; 2\phi). \end{aligned}$$

利用此性质, 可以计算传播子如下:

$$\begin{aligned} K(x_f, t_f; x_i, t_i) &= \prod_{k=1}^{N-1} \int dx_k \prod_{j=0}^{N-1} F(x_{j+1}, x_j, \phi) \\ &= F(x_f, x_i, T) \end{aligned}$$

$$= \left(\frac{m\omega}{2\pi i \hbar \sin \omega(t_f - t_i)} \right)^{1/2} e^{\frac{i}{\hbar} \frac{m\omega}{2 \sin \omega(t_f - t_i)} [(x_f^2 + x_i^2) \cos \omega(t_f - t_i) - 2x_f x_i]}.$$

习题 3 SSH model 的哈密顿量可以写为:

$$\hat{H}_{SSH}(k) = (t_1 + t_2 \cos k) \hat{\sigma}_x + t_2 \hat{\sigma}_y.$$

计算:

$$\gamma = \int_{-\pi}^{\pi} \sum_i \langle n_i(k) | i \frac{\partial}{\partial k} | n_i(k) \rangle dk.$$

系统哈密顿量可以写为:

$$H = \begin{pmatrix} 0 & t_1 + t_2 e^{-ik} \\ t_1 + t_2 e^{ik} & 0 \end{pmatrix}$$

将其对角化可得两个本征态分别为:

$$|u_1\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} \frac{t_1 + t_2 e^{-ik}}{\sqrt{t_1^2 + t_2^2 + 2t_1 t_2 \cos k}} & 1 \end{pmatrix}^T; \quad |u_2\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} -\frac{t_1 + t_2 e^{-ik}}{\sqrt{t_1^2 + t_2^2 + 2t_1 t_2 \cos k}} & 1 \end{pmatrix}^T.$$

则可以计算 Berry Phase 为:

$$\begin{aligned} \gamma_1 &= \int_{-\pi}^{\pi} \langle u_1(k) | i \frac{d}{dk} | u_1(k) \rangle dk \\ &= \frac{i}{2} \int_{-\pi}^{\pi} \frac{t_1 + t_2 e^{ik}}{\sqrt{t_1^2 + t_2^2 + 2t_1 t_2 \cos k}} \frac{d}{dk} \frac{t_1 + t_2 e^{-ik}}{\sqrt{t_1^2 + t_2^2 + 2t_1 t_2 \cos k}} dk \\ &= \frac{i}{2} \int_{-\pi}^{\pi} \frac{t_1 + t_2 e^{ik}}{\sqrt{t_1^2 + t_2^2 + 2t_1 t_2 \cos k}} \left(\frac{-it_2 e^{-ik}}{\sqrt{t_1^2 + t_2^2 + 2t_1 t_2 \cos k}} + \frac{(t_1 + t_2 e^{-ik})t_1 t_2 \sin k}{(t_1^2 + t_2^2 + 2t_1 t_2 \cos k)^{3/2}} \right) dk \\ &= \frac{1}{2} \int_{-\pi}^{\pi} \frac{t_2^2 + t_1 t_2 e^{-ik} + it_1 t_2 \sin k}{t_1^2 + t_2^2 + 2t_1 t_2 \cos k} dk \\ &= \frac{1}{2} \int_{-\pi}^{\pi} \frac{t_2^2 + t_1 t_2 \cos k}{t_1^2 + t_2^2 + 2t_1 t_2 \cos k} dk \\ &= \frac{1}{4} \int_{-\pi}^{\pi} \left(1 + \frac{t_2^2 - t_1^2}{t_1^2 + t_2^2 + 2t_1 t_2 \cos k} \right) dk \\ &= \frac{\pi}{2} + \frac{1}{4} \int_{-\pi}^{\pi} \frac{t_2^2 - t_1^2}{t_1^2 + t_2^2 + 2t_1 t_2 \cos k} dk \end{aligned}$$

其中, 可以利用 Mathematica 计算上述积分, 当 $t_2 > t_1$ 时, 积分等于 2π , 此时 $\gamma_1 = \pi$; 当 $t_2 < t_1$ 时, 积分等于 -2π , 此时 $\gamma_1 = 0$.

同样地, 我们可以计算:

$$\gamma_2 = \int_{-\pi}^{\pi} \langle u_2(k) | i \frac{d}{dk} | u_2(k) \rangle = \begin{cases} \pi, & t_2 > t_1; \\ 0, & t_2 < t_1. \end{cases}$$