

基态性质：存在相互作用时，基态满足对称性， $b_{\alpha}^{\dagger} |G\rangle = 0$ ；关注基态中和- π 两个模式， $|G\rangle = \sum_{i,j} C_{ij} |i,j\rangle$ ， i, j 分别表示质子、反粒子数。 $b_{\alpha} = U_m a_m + U_n a_n^{\dagger}$ ，则有 $\sum_{i,j} U_m U_n C_{ij} |i-1,j+1\rangle + U_m U_n |j+1,j\rangle = 0 \Rightarrow C_{m,n+1} = -\frac{U_m}{U_n} \sqrt{\frac{n+1}{m+1}} C_{ij}$ 。则有 $C_{ij} = C_{i,j+1}$ ， $C_{m+1,n+1} = -\frac{U_m}{U_n} C_{mn} \Rightarrow |G\rangle = \sum_{i,j} (-\frac{U_m}{U_n})^{i-1} C_{i,j} |i,j\rangle$ ， $\beta = \frac{1}{U_m} (U_m - U_n)$ ， $n_{\alpha} = \langle G | n_{\alpha} | G \rangle = \frac{\pi}{\beta} = \frac{\cos(\pi\beta)}{\pi} = \frac{1 - \sin^2(\pi\beta)}{\pi} = \frac{1 - \sin^2(2\pi\omega_0)}{2\pi}$ ，模态的粒子数， $n_{\alpha} = < G | n_{\alpha} | G >$ 。

相对论量子力学：61 KLEIN-GORDON 方程 $E^2 = c^2 p^2 + m^2 c^4$, $E \rightarrow \sqrt{E^2 - p^2}$, $p \rightarrow \gamma v$

$\frac{1}{c^2} \frac{\partial^2}{\partial t^2} \psi = V^2 \psi + \frac{m^2 c^2}{\hbar^2} \psi \Rightarrow \frac{1}{c^2} \frac{\partial}{\partial t} (\psi^2 \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2} \psi) = \nabla \cdot (\psi^2 \nabla \psi - 4\psi \nabla^2 \psi) ; \frac{\partial}{\partial t} \frac{1}{c^2} (\psi^2 \nabla^2 \psi) \Rightarrow \frac{\partial \psi}{\partial t} + \nabla^2 \psi = 0$ ，平面波解： $\psi(t, \vec{x}) = C e^{i(\vec{k} \cdot \vec{x} - \omega t)}$

非相对论极限： $E = \sqrt{p^2 + m^2 c^2} = mc^2 (1 + \frac{p^2}{mc^2})^{\frac{1}{2}} \approx mc^2 + \frac{p^2}{2mc^2} - \frac{1}{8} \frac{p^4}{mc^2} + \dots$

全 $\Psi(P, t) = e^{-imc^2 t/\hbar} \varphi(P, t)$, $\frac{\partial^2}{\partial t^2} \Psi(P, t) = \left(\frac{\partial}{\partial t} \varphi(P, t) \right)^2 - 2 \frac{imc^2}{\hbar} \frac{\partial}{\partial t} \varphi(P, t) - \frac{m^2 c^2}{\hbar^2} \varphi(P, t)$

忽略第一项，代入 K-G 方程 $\rightarrow -2 \frac{im}{\hbar} \frac{\partial}{\partial t} \varphi(P, t) - \frac{m^2 c^2}{\hbar^2} \varphi(P, t) \Rightarrow i \hbar \frac{\partial}{\partial t} \varphi(P, t) = -\frac{\hbar^2}{mc^2} \nabla^2 \varphi$

在电磁场中， $E \rightarrow i \hbar \frac{\partial}{\partial t} - q\vec{A}$, $\vec{p} \rightarrow -i\hbar \nabla - \frac{q}{c} \vec{A}$; $(i\hbar \frac{\partial}{\partial t} - q\vec{A})^2 \psi = c^2 (-i\hbar \nabla - \frac{q}{c} \vec{A})^2 \psi + m^2 c^4 \psi$

类似地， $\Psi(P, t) = \varphi(P, t) e^{-imc^2 t/\hbar}$ 得非相对论近似： $i \hbar \frac{\partial}{\partial t} \varphi(P, t) = \left[\frac{1}{mc} (-i\hbar \nabla - \frac{q}{c} \vec{A})^2 \right] \varphi(P, t)$

规范不变性， $\vec{A} \rightarrow \vec{A}' = \vec{A} + \nabla f$; $\psi \rightarrow \psi' = \psi - \frac{1}{c} \frac{\partial}{\partial t} f$ ，则有 $\psi \rightarrow \psi' = e^{i\theta} \psi$; $\theta = i \frac{\partial f}{\partial c}$

考虑负能解情形： $(i\hbar \frac{\partial}{\partial t} - q\vec{A})^2 \psi = C^2 (-i\hbar \nabla - \frac{q}{c} \vec{A})^2 \psi^- + m^2 c^4 \psi_c^-$ ；有 $\psi_c^- = \psi'^*$ ，其中 ψ_c^- 为正能 KG 态，电荷为 $-q$ ，在相同势场下的波函数。

协变形式及 Lorentz 变换：def: $x^{\mu} = (x^0, x^1, x^2, x^3) = (ct, \vec{x}, \vec{y}, \vec{z})$; $\eta_{\mu\nu} = (ct, -\vec{x}, -\vec{y}, -\vec{z})$

矩阵张量 $g = (g_{\mu\nu}) = (g^{\mu\nu}) = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & & \\ & & & 1 & \end{pmatrix}$; $g^{\mu\nu} g^{\rho\sigma} = \delta_{\mu}^{\rho} \delta_{\nu}^{\sigma} = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & & \\ & & & 1 & \end{pmatrix}$ 逆变 x^{μ} ，协变 $\eta_{\mu\nu}$

$\partial_{\mu} = \frac{\partial}{\partial x^{\mu}} = (\partial_0, \nabla)$; 四动量： $P^{\mu} = (\frac{E}{c}, \vec{p})$, $P_{\mu} = (\frac{E}{c}, -\vec{p})$

$\partial_{\mu} \partial^{\mu} = g^{\mu\nu} \partial_{\mu} \partial_{\nu} = g_{\mu\nu} a^{\mu} b^{\nu} = a^0 b^0 - \vec{a} \cdot \vec{b}$; $\partial_{\mu} \partial^{\mu} = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2$; $P_{\mu} P^{\mu} = \frac{E^2}{c^2} - \vec{p}^2 = g_{\mu\nu} \partial_{\mu} \partial^{\nu}$

KG 方程 $\left[\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 - \frac{m^2 c^2}{\hbar^2} \right] \psi = 0 \Rightarrow \left[g_{\mu\nu} \partial^{\mu} + \frac{m^2 c^2}{\hbar^2} \right] \psi = 0$ D'Alembert 方程 $\square = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2$

Lorentz 变换： $ct' = \frac{ct + \beta x}{\sqrt{1 - \beta^2}}$, $x' = \frac{x - \beta ct}{\sqrt{1 - \beta^2}}$; $ct = \frac{ct' + \beta x'}{\sqrt{1 - \beta^2}}$, $x = \frac{x' + \beta ct'}{\sqrt{1 - \beta^2}}$

逆变向量： $x^{\mu} = x^0 \cosh \eta + x^1 \sinh \eta$ 协变张量 $\eta^{\mu} = \eta_0 \cosh \eta + \eta_1 \sinh \eta$

$x^1 = -x^0 \sinh \eta + x^1 \cosh \eta$ $\eta_1' = \eta_0 \sinh \eta + \eta_1 \cosh \eta$

$x^0 = x^0$ $\eta_0' = \eta_0$

$x^1 = x^1$ $\eta_1' = \eta_1$

$x^{\mu} = L^{\mu}_{\nu} x^{\nu}$; $L^{\lambda}_{\mu} g^{\mu\nu} L^{\nu}_{\nu} = g^{\lambda\mu}$; $L g L^T = g$

6.2 Dirac 方程 将能量写作 $E = c \alpha \cdot \vec{p} + \beta mc^2$ ；满足 $E^2 = p^2 c^2 + m^2 c^4$ 时有 $\boxed{g_{\mu}^{\nu} (\frac{\partial}{\partial x^{\nu}})}$

$\{a^{\mu}, a^{\nu}\} = 2\delta_{\mu\nu}$, $\{a^{\mu}, \beta\} = 0$, $\beta^2 = 1$; $i \hbar \frac{\partial}{\partial x^{\mu}} = (c \alpha \cdot \vec{p} + \beta mc^2) \psi$; \vec{p}, β 未来, $a^{\mu} = \begin{pmatrix} 0 & \alpha^{\mu} \\ \alpha^{\mu} & 0 \end{pmatrix}$, $\beta = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

Dirac 方程 可重新写作 $\frac{1}{c} \frac{\partial \psi}{\partial t} + \frac{1}{2} \alpha^{\mu} \frac{\partial \psi}{\partial x^{\mu}} + i \frac{mc}{\hbar} \beta \psi = 0 \Rightarrow \frac{d}{dt} (\psi^2) + \frac{1}{2} \frac{\partial^2 \psi}{\partial x^{\mu} \partial x^{\mu}} = 0$

$j^{\mu} = c \psi^{\dagger} a^{\mu} \psi$, 全 $j^0 = cP$. 则 $\partial_{\mu} j^{\mu} = 0$

$H = -i \hbar c \vec{a} \cdot \nabla + mc^2$, $\frac{1}{i\hbar} \eta_{\mu k} = \frac{1}{i\hbar} [\eta_{\mu 0}, H] = \frac{1}{i\hbar} [\eta_{\mu 0}, C \vec{a} \cdot \nabla P] = C a^k \vec{a} \cdot \nabla P$, $V_k = \partial_t \eta_{\mu k} = C a^k$

$j^k = \frac{1}{i\hbar} \eta_{\mu k} \psi$. 角动量算符： $\vec{L} = \vec{r} \times \vec{p} = -i\hbar \vec{r} \times \nabla$; $[H, \vec{L}] = -\hbar^2 \vec{r} \times \vec{L} \times \nabla$ ，所以 \vec{L} 不是守恒量。

自旋角动量 $\vec{s} = \frac{1}{2} \vec{a} = \frac{1}{2} \begin{pmatrix} \vec{p} & 0 \\ 0 & \vec{p} \end{pmatrix}$ ，利用等式： $(\vec{2} \vec{a}, \vec{s}) = \begin{pmatrix} 0 & (\vec{2} \vec{a}, \vec{s}) \\ (\vec{2} \vec{a}, \vec{s}) & 0 \end{pmatrix}$ 有 $(\vec{2} \vec{a}, \vec{s}) = 2i \vec{a} \vec{s} \vec{a}$

则有 $[H, \vec{s}] = -\hbar c [2 \vec{a}, \vec{s}] = 2 \hbar c \vec{a} \times \vec{s}$ ，则总角动量 $\vec{j} = \vec{L} + \vec{s} = \vec{L} + \vec{s}$ 满足 $[H, \vec{j}] = 0$ 为守恒量。

螺旋度算符 $\hat{h} = \vec{s} \cdot \vec{p} = \frac{p}{m}$ 也与 H 对易, $[H, \hat{h}] = 0$

$L(H, \vec{Z}, \vec{P}) = 0$

Dirac 方程 协变形式 $\partial^{\mu} \psi = (\rho, \beta \vec{a}^{\mu}) \Rightarrow (i \hbar \partial_{\mu} - \frac{mc}{\hbar}) \psi = (i \hbar \frac{\partial}{\partial t} - \frac{mc}{\hbar}) \psi = 0$

$\rho^{\mu} = (ia_0, \vec{p})$, $\rho_{\mu} = (i\partial_0, -\vec{p})$, $\partial_{\mu} = \frac{\partial}{\partial x^{\mu}}$, $\partial^{\mu} = \begin{pmatrix} 0 & \partial^{\mu} \\ \partial^{\mu} & 0 \end{pmatrix}$, $\{ \partial^{\mu}, \partial^{\nu} \} = 2 g^{\mu\nu}$

\vec{a}^2 未来, \vec{a}^2 反未来。协变形式 $\partial^{\mu} \psi = g_{\mu\nu} \partial^{\nu} \psi$, $i \partial^{\mu} \partial^{\nu} \psi = m \psi$

在 Pauli 度规下, $\eta_{\mu\nu} = (x_1, x_2, x_3, x_4) = (x, y, z, ict)$; $\partial_{\mu} = (\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}, -\frac{i}{c} \frac{\partial}{\partial t})$; $\partial_{\mu} = -i \beta \vec{a}^{\mu}$, $\partial_{\mu} = \beta \vec{a}^{\mu}$

$\eta_{\mu\nu} = \eta_{\nu\mu} = \eta_{\mu\nu}$, 此时 \vec{a} 未来。且 $\{\partial_{\mu}, \partial_{\nu}\} = 2 \delta_{\mu\nu} \Rightarrow$ Dirac 方程 $(\partial_{\mu} \partial_{\nu} + \frac{mc}{\hbar}) \psi = 0$

Dirac 粒子密度 $H = c \vec{a} \cdot \vec{p} + \beta mc^2$ ，系统角动量算符为 L ，求 $[H, L] = -\hbar^2 \vec{r} \times \vec{L}$