3月16日 第三周周一作业

Section 1.5 긔. 解.

row0x(-1) - row0 [YOW B X I

now 0 x 4 1000 @ x(-1)

POWG X (-1) \$ 10WB row@x & MOWO X (-3) \$ nows

即原矩阵的逆为

Section 1.6

$$1000 = 2 \quad 1000 + 1000$$
 $1000 = 2 \quad 1000 + 1000$

$$b_2 = 2b_3 + b_4$$

22. Proof. 0. If
$$(QA)\vec{n} = \vec{0}$$
 has just the trivial solution:

Since Q is an invertible nxn matrix, we have Q^{-1}

Left multiply a^{-1} to $(aA)\vec{3} = \vec{0}$.

Then we have $\Omega^{1}(\Omega A)\vec{s}=\vec{\delta}$,

$$\alpha^{\dagger} \alpha = \ln \quad \text{Then } \quad A\vec{\beta} = \vec{0} \quad \text{has just the trivial solution.}$$

Since Q is an invertible $n \times n$ matrix, Q doesn't have zero line. Then, left multiply Q to $A\vec{x} = \vec{\sigma}$. We get $(QA)\vec{x} = \vec{\sigma}$ also has just

the trivial solution.

Section 1.1

10.
$$A = \begin{bmatrix} -b & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$\begin{bmatrix} -6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$A^{2} = \begin{bmatrix} 3b & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 15 \end{bmatrix} \qquad A^{-2} = \begin{bmatrix} \frac{1}{36} & 0 & 0 \\ 0 & \frac{1}{9} & 0 \\ 0 & 0 & \frac{1}{16} \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} \frac{1}{36} & 0 & 0 \\ 0 & 0 & \frac{1}{16} \end{bmatrix}$$

3月18日 第三周 周三作业

Section 17

32. (ω. Since A is an nxn symmetric matrin. According to Theorm 17.3: If A and b are nxn symmetric matrices, AB is also an nxn symmetric matrin.

A=AA such that A is symmetric.

 $(A^2)^T = (AA)^T = A^TA^T = AA = A^2$

(b). Since A is an nxn symmetric matrix. We have $A^{T} = A$ $(2A^{2} - 3A + 1)^{T} = (2A^{2})^{T} - (3A)^{T} + L^{T} = 2(A^{2})^{T} - 3A^{T} + L^{T}$ $= 2A^{2} - 3A + 1$

So 2A²-3A+1 is symmetric

34. Assume
$$A = \begin{bmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{bmatrix} \qquad A^2 = \begin{bmatrix} a_1^2 & 0 & 0 \\ 0 & a_2^2 & 0 \\ 0 & 0 & a_3^2 \end{bmatrix}$$

$$A^{2}-3A-41 = \begin{bmatrix} a_{1}^{2}-3a_{1}-4 & o & o \\ o & a_{2}^{2}-3a_{3}-4 & o \\ o & o & a_{3}^{2}-3a_{3}-4 \end{bmatrix} = \vec{0}$$

 $B_1 = \frac{1}{3} \cdot 3a_1 - 4 = 0 \qquad a_2^2 - 3a_2 - 4 = 0 \qquad a_3^2 - 3a_3 - 4 = 0$

$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 4 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

- - (a). $M_{13} = \begin{vmatrix} 0 & 0 & 3 \\ 4 & 1 & 14 \end{vmatrix} = 12 12 = 0$

 - $C_{13} = (-1)^{1+3} M_{13} = 0$

C23 = (-1)2+3 M23 = 96

C22 = (-1)2+2 M22 = -48

 $C_{21} = (-1)^{2+1} M_{21} = -72$

- (b). $M_{23} = \begin{vmatrix} 4 & -1 & 6 \\ 4 & 1 & 14 \\ 4 & 1 & 2 \end{vmatrix} = 8 56 + 24 24 (-8) 56 = -96$
- (c). $M_{22} = \begin{vmatrix} 4 & 1 & 6 \\ 4 & 0 & 14 \end{vmatrix} = 0 + 36 + 72 0 168 8 = -48$

$$det(A) = (-3)(-1)^{3+3} \begin{vmatrix} 3 & 3 & 5 \\ 2 & 2 & -2 \\ 2 & 0 & 2 \end{vmatrix} + 3 \cdot (-1)^{9+3} \begin{vmatrix} 3 & 3 & 5 \\ 2 & 2 & -2 \\ 4 & 1 & 0 \end{vmatrix}$$

$$\begin{vmatrix} 2 & 2 & -2 \\ 2 & 10 & 2 \end{vmatrix} \begin{vmatrix} 2 & 2 & -2 \\ 4 & 1 & 0 \end{vmatrix}$$

$$= -3 \cdot \left[12 + (-12) + 100 - 20 - (-60) - 12 \right] - 3 \cdot \left[0 + (-24) + 10 - 40 - (-6) - 0 \right]$$

= - 384 + 144

= - 140

即 det(A) = -240

The determinat is independent of θ .

 $\begin{vmatrix} \sin \theta & \cos \theta & 0 \end{vmatrix} = \begin{vmatrix} \cdot \cdot \cdot - \end{vmatrix}^{3+3} \begin{vmatrix} \sin \theta & \cos \theta \end{vmatrix} = \begin{vmatrix} \sin \theta - (-\cos \theta) = \sin \theta + \cos \theta = \end{vmatrix}$ $\begin{vmatrix} -\cos \theta & \sin \theta + \cos \theta \end{vmatrix} \begin{vmatrix} -\cos \theta & \sin \theta \end{vmatrix}$











