

# **Chapter 8. Optimization (Part 4)**

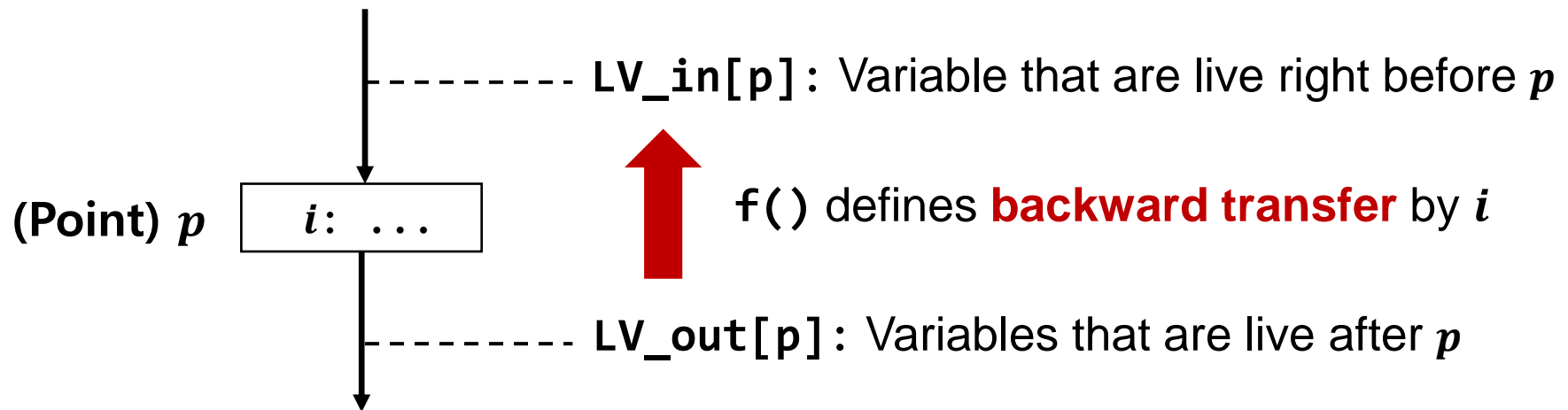
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# Liveness Analysis: Transfer Function

- Note that liveness analysis must be performed backward
  - Start from the exit node and goes backward
- Therefore, the transfer function must define the input live variables in terms of the output live variables
  - For point  $p$  with instruction  $i$ :  $LV\_in[p] = f(LV\_out[p], i)$

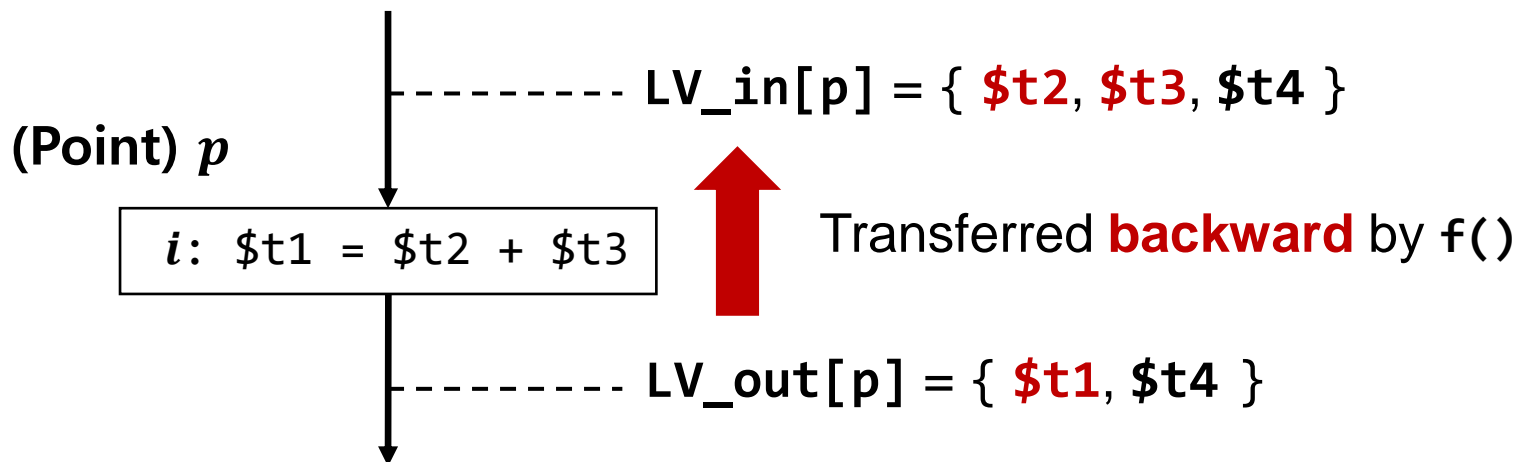


# Liveness Analysis: Transfer Function

## ■ For instruction $i$ , let's introduce the following two sets:

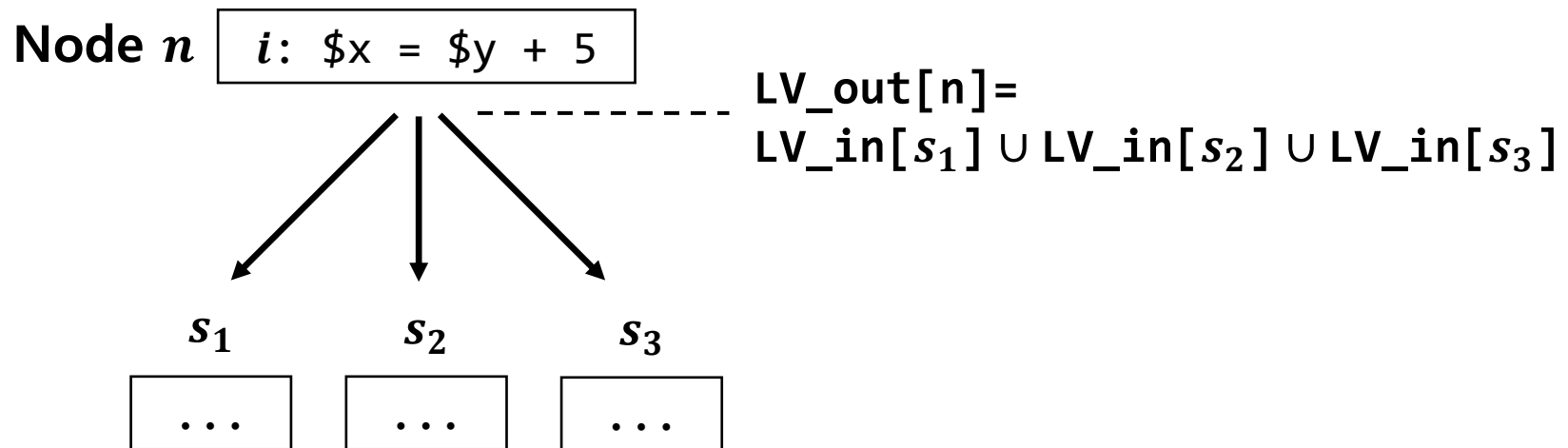
- $\text{def}(i)$  denotes the set of registers defined by  $i$
- $\text{use}(i)$  denotes the set of registers used by  $i$
- Ex)  $\text{def}("\$t1 = \$t2 + \$t3") = \{ \$t1 \}$
- Ex)  $\text{use}("\$t1 = \$t2 + \$t3") = \{ \$t2, \$t3 \}$

## ■ Now we can define: $f(\text{LV}, i) = \text{LV} - \text{def}(i) \cup \text{use}(i)$



# Liveness Analysis: Propagation

- If a variable is *live before* a certain node, then it is also *live after* its predecessors
- Therefore, live variables after node  $n$  can be obtained by joining the live variables before the successors of  $n$ 
  - These live variables must be joined with **union** ( $\cup$ )



# Liveness Analysis: Iterative Algorithm

- Now we can put things together and run the following iterative algorithm (a.k.a. fixpoint algorithm)
  - There can be variations of algorithm, but the basic idea is same

```
for each node  $n$  {  $LV\_in[n] = \emptyset$ ; }

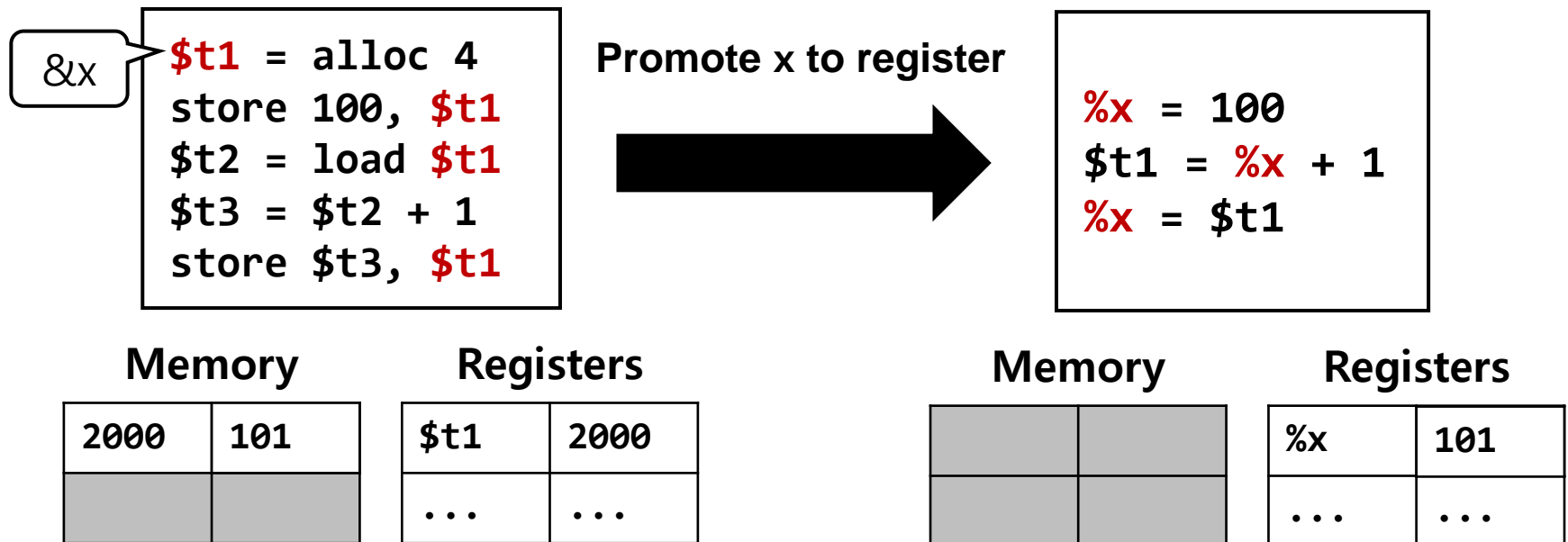
while (there is any change to  $LV\_in[]$ ) {
    for each node  $n$  and its instruction  $i$  {
         $LV\_out[n] = \bigcup_{s \in succ(n)} LV\_in[s]$ ;
         $LV\_in[n] = f(LV\_out[n], i)$ ;
    }
}
```

# Optimization with Memory?

- Recall that compilers **focus on optimizing register computations**, and usually **ignore variables in memory**
- For example, let's consider *dead-store elimination*:
  - Why don't we remove a **store** instruction if it is dead?
  - Unfortunately, it is not trivial to decide whether a **store** updates a variable that is not going to be used anymore
  - It requires the compiler to analyze which memory addresses can be accessed by each **load** and **store**
- As a result, real-world compilers usually perform only **limited form of dead-store elimination**
  - By targeting trivial and obvious patterns

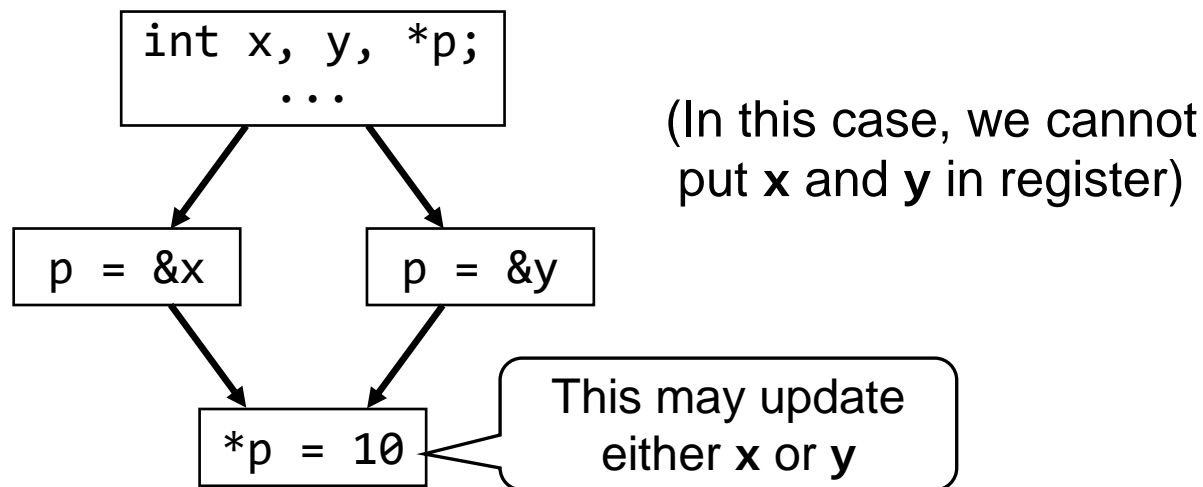
# Mem2Reg Optimization

- Mem2Reg optimization moves some variables from the memory to register (a.k.a., *promotion to register*)
  - Once it is promoted, various optimizations can be applied
  - Ex) Consider C code "int x = 100; x = x + 1;"



# Mem2Reg Optimization

- Of course, not all variables can be promoted to register
  - Compiler must carefully decide which variables can be promoted
- Array type variables cannot be promoted to register
  - Ex) `int arr[16];` // We cannot put this in register
- Pointer operations also disqualify some variables from the promotion to register





# Appendix

# Constant Folding + Propagation

- Part 1 slide mentioned advanced form of optimization for "constant folding + constant propagation" at once

- Unfortunately, we don't have time to discuss it in this course
- If you are interested, read Chapter 9.4 of our textbook\*

- Sometimes, we can reduce the number of repetition by making each optimization pass smarter

- For example, we may perform constant folding and constant propagation at once (we will see such optimization later)

