

Chapter 8. Optimization (Part 3)

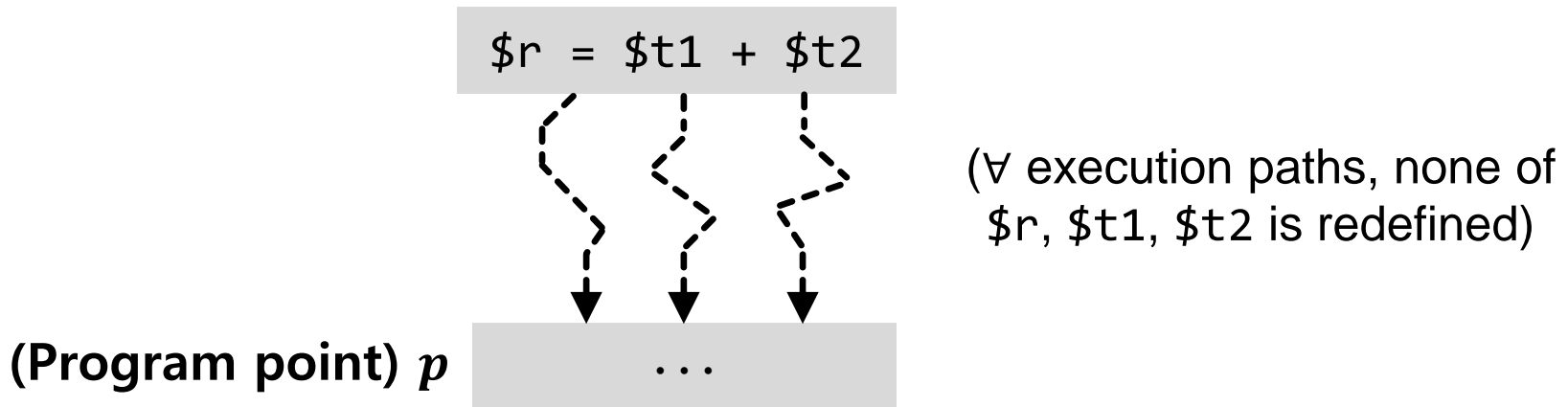
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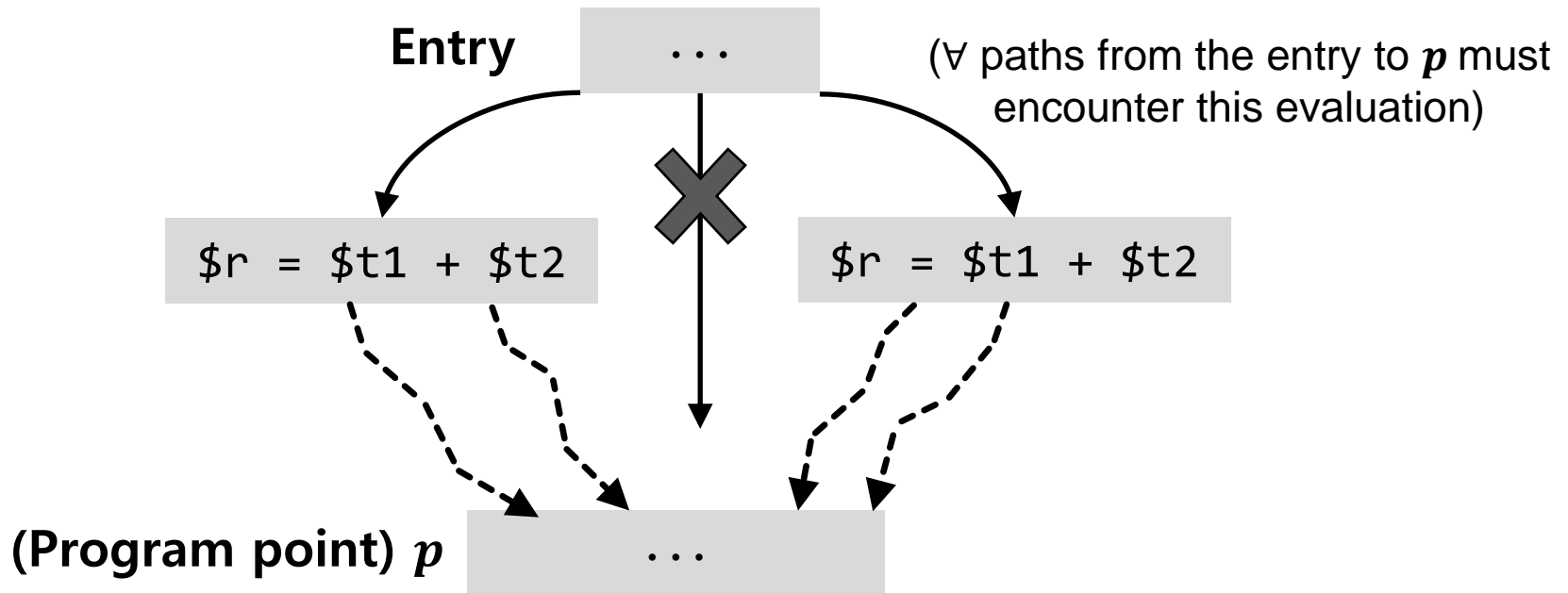
Available Expression (AE) Analysis

- Consider an expression e and program point p
 - e can have various forms: "\$t1", "\$t1 + \$t2", "4 * \$t1"
 - We can choose the scope of expression to trace
- Intuitively, e is available at p in register $\$r$ if the re-computation of e at p produces a value stored in $\$r$
 - Note the difference with reaching definition



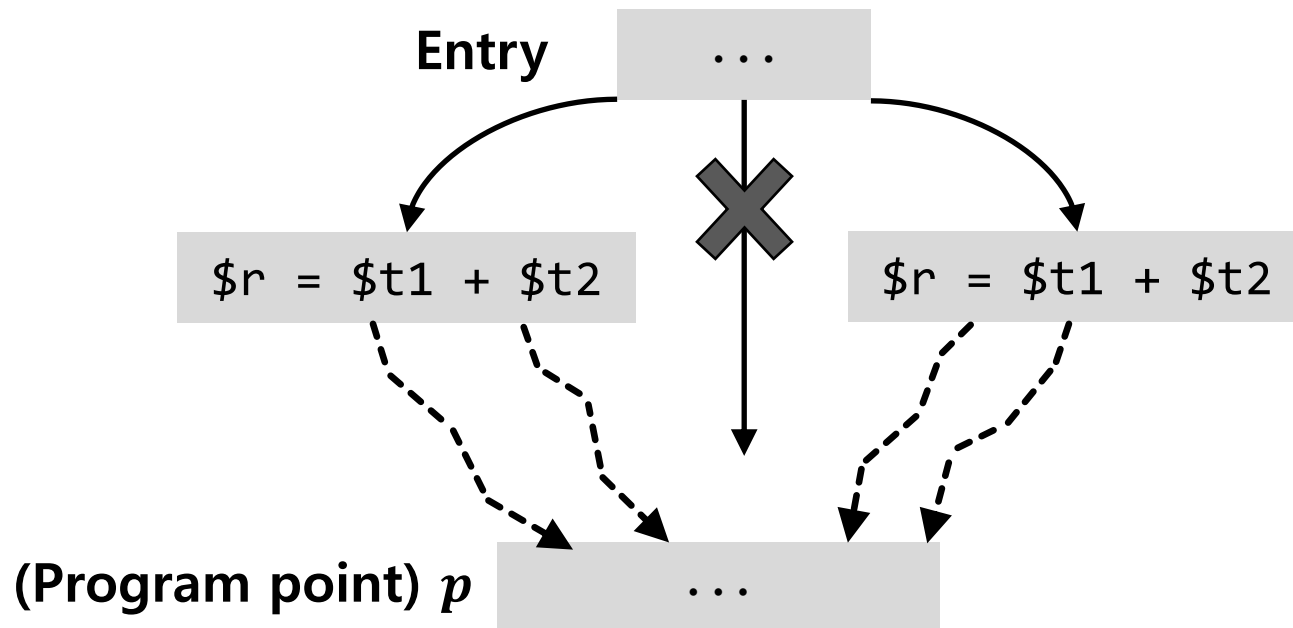
Available Expression (AE) Analysis

- In addition, all the paths from the (function) entry to p must evaluate e and store the result in $\$r$
 - In other words, if there is any path that can arrive at p without such evaluation, e is not available at p



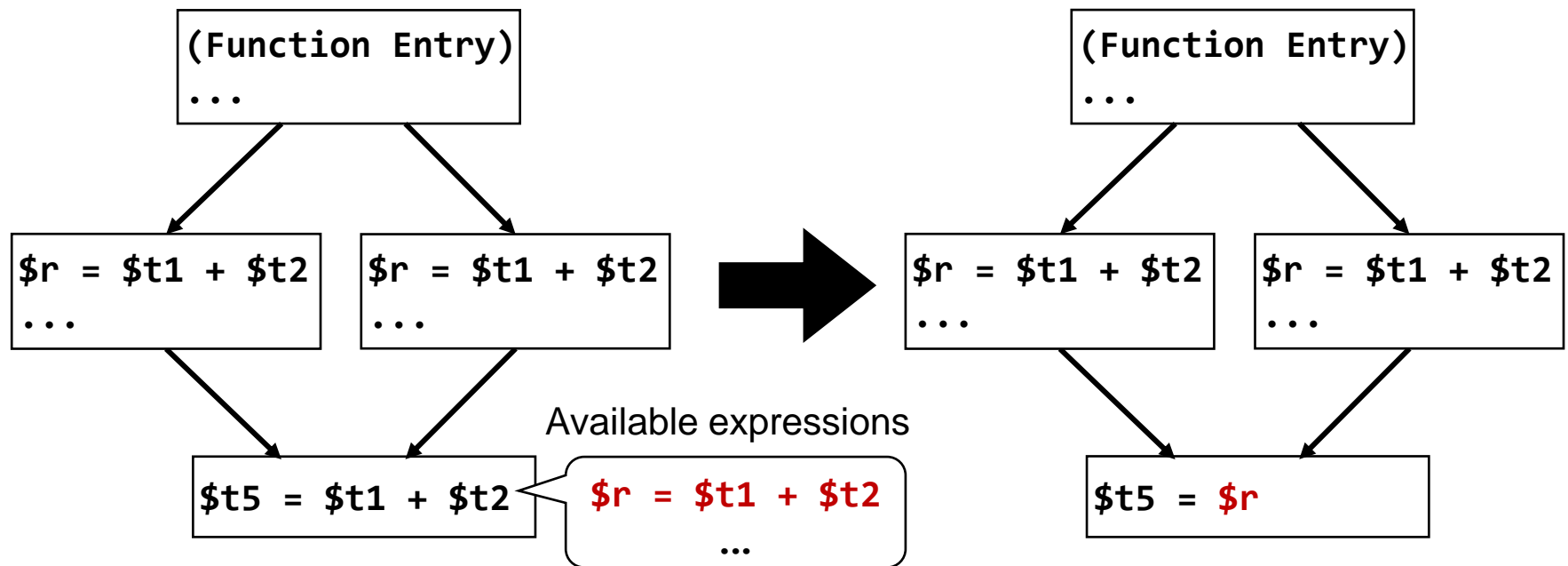
Available Expression (AE) Analysis

- Now, formally speaking: *e* is available at *p* in register *\$r* if every path from the entry to *p* evaluates *e* and stores the result in *\$r*, and after such last evaluation, there is no subsequent update to *\$r* or registers used in *e*



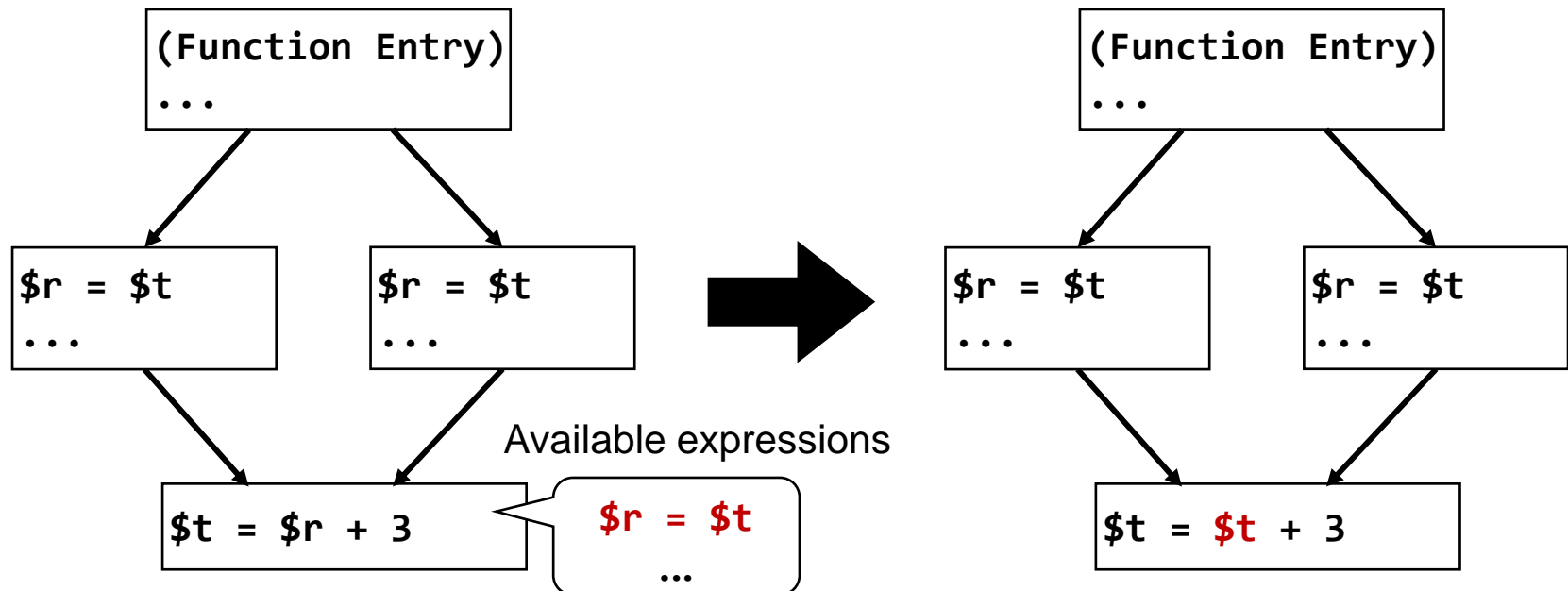
Use of Available Expression (AE)

- From the definition of AE, it is straightforward to perform common subexpression elimination (CSE)
 - If the RHS expression of an assign statement is available in register $\$r$, that RHS can be substituted with $\$r$



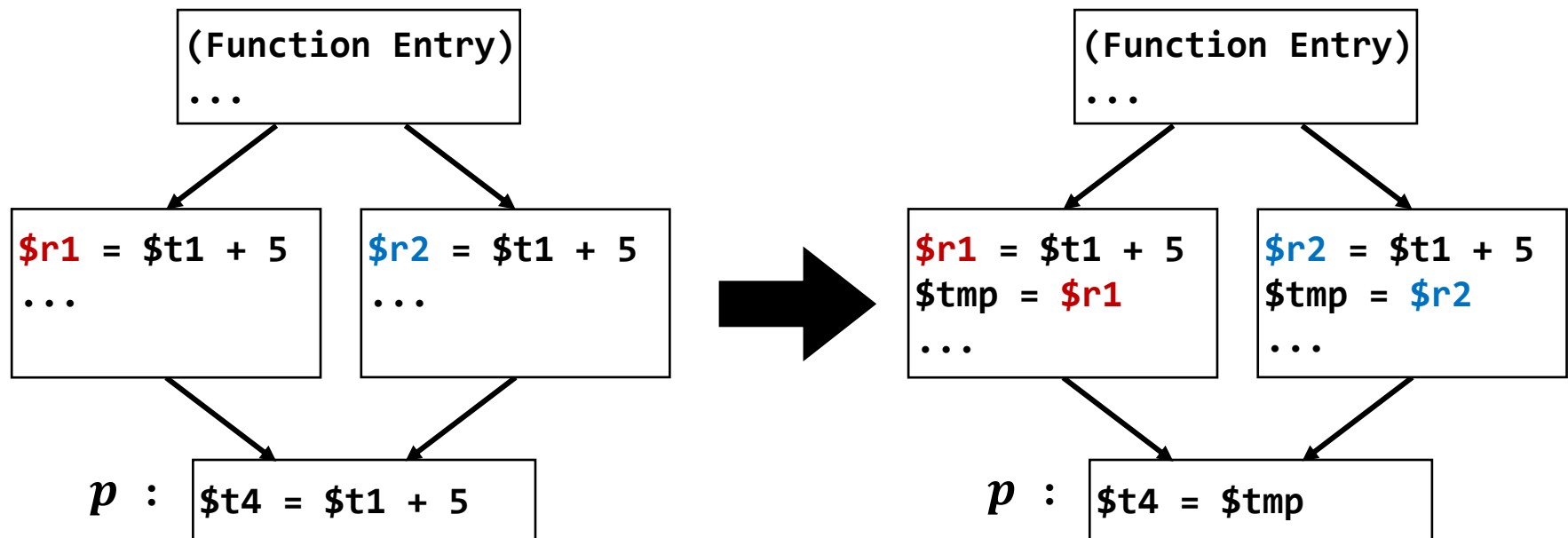
Use of Available Expression (AE)

- Also, if the available expression e has the form of a single variable, we can use it for copy propagation
 - If expression $\$t$ is available in register $\$r$, then these two registers can be used interchangeably
 - This time, we will replace $\$r$ with $\$t$, for copy propagation



Note: Other Form of AE Analysis

- In most textbooks, AE analysis does not care about the register that stores the evaluation result
 - Such textbook will say that $\$t1 + 5$ is available at p
 - Why? Because CSE is still possible by introducing a new registers in such cases (but we will not do this in our course)

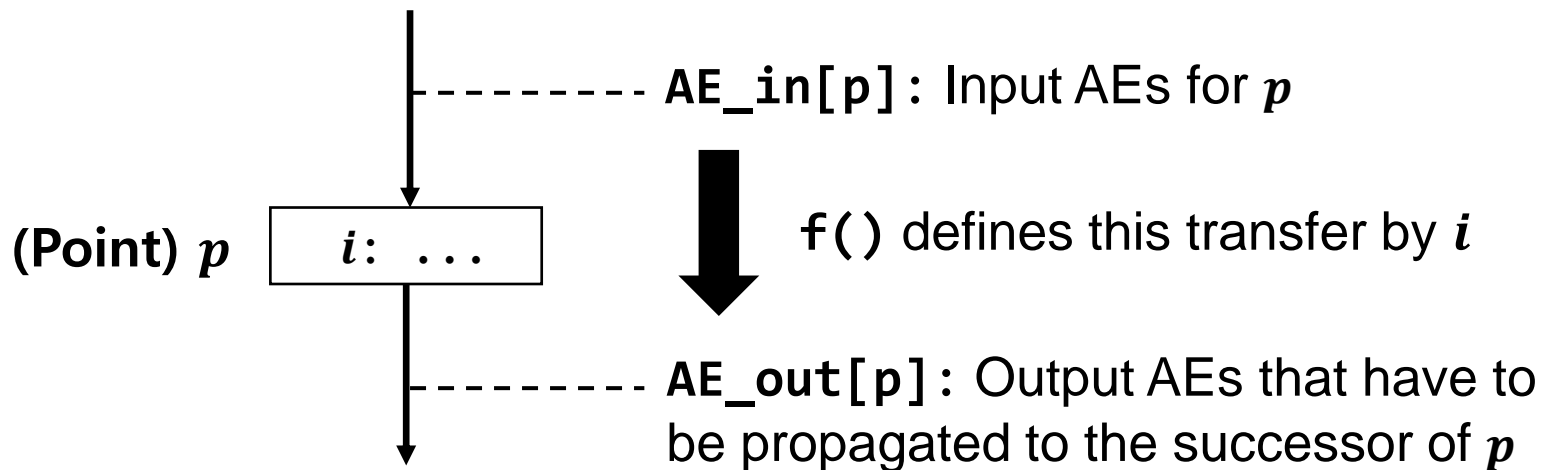


Remind: Conservativeness

- **The analysis and optimization must be conservative**
 - This time, the definition of "**conservative**" is different
 - For CSE, the analysis result must only contain AEs that are always available at runtime (no false positive allowed)
 - Instead, it is okay (and inevitable) to under-approximate the AEs
- **Again, if we have false positives in the result of AE analysis, we may end up with a wrong optimization**

AE Analysis: Transfer Function

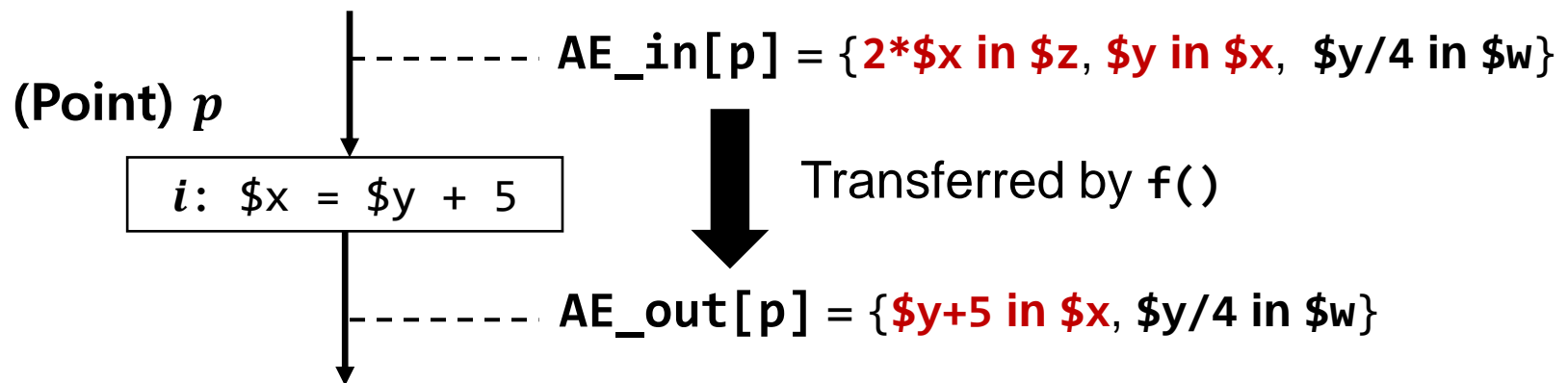
- As before, we must define how the AE set will change by the execution of a single instruction
- Assume that program point p contains instruction i
 - Transfer function f defines output AE in terms of input AE and i
 - $AE_out[p] = f(AE_in[p], i)$



AE Analysis: Transfer Function

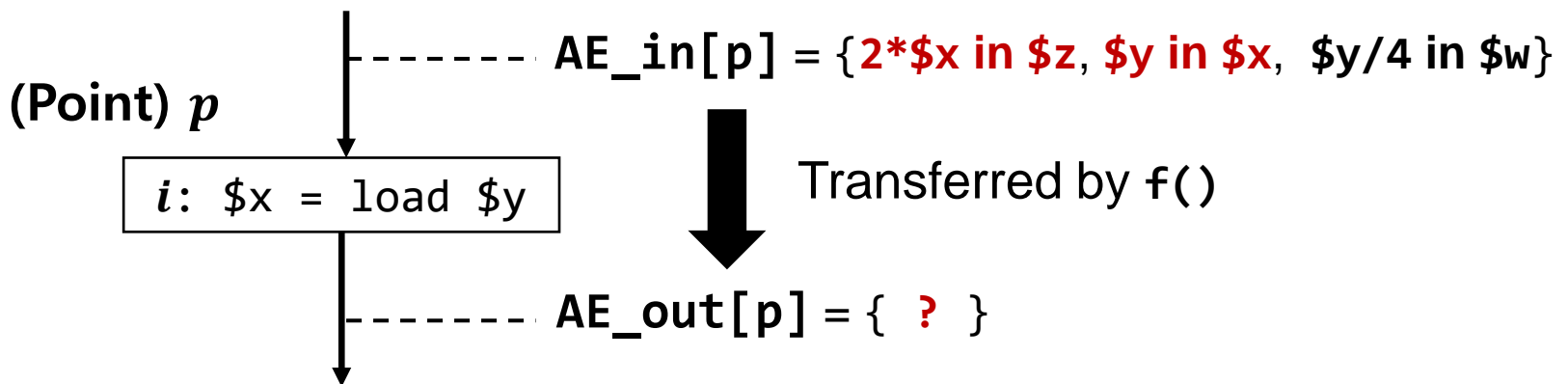
■ If instruction i has the form of " $\$r = e$ ", where e is a register or binary/unary operation:

- $f(IN, i) = IN - \{ AE \in IN \mid AE \text{ contains } \$r \} \cup \{ e \text{ in } \$r \}$
- Ex) " $2 * \$x$ stored in $\$z$ " is an AE that contain $\$x$
- Ex) " $\$y$ stored in $\$x$ " is also an AE that contain $\$x$
- Corner case: what should happen when i is " $\$x = \$x + 1$ "?
 - Actually, we must add $\{ e \text{ in } \$r \}$ only if e does not contain $\$r$



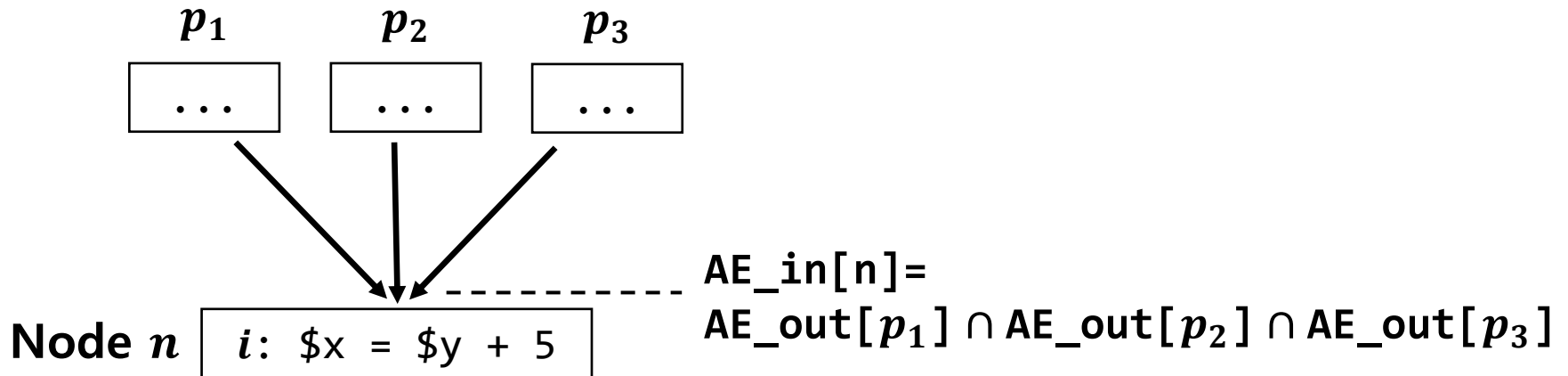
AE Analysis: Transfer Function

- Note that "\$r = alloc(N)" must not generate any AE
 - $f(IN, i) = IN - \{ AE \in IN \mid AE \text{ contains } \$r \}$
- For other instructions that does not define any register:
 - $f(IN, i) = IN$
- Q. What about the load instruction, "\$r = load \$t"?
 - To support this form of expression in AE, we must also consider the effect of **store** instruction (I will leave this as your exercise)



AE Analysis: Propagation

- How should we propagate AEs along the control-flows?
- An expression is available at a program point if that expression is available after all of the predecessors
- For node n , the output AEs of n 's predecessors must be joined with intersection (\cap) and used as n 's input



AE Analysis: Iterative Algorithm

■ Now we can put things together and run the following iterative algorithm (a.k.a. fixpoint algorithm)

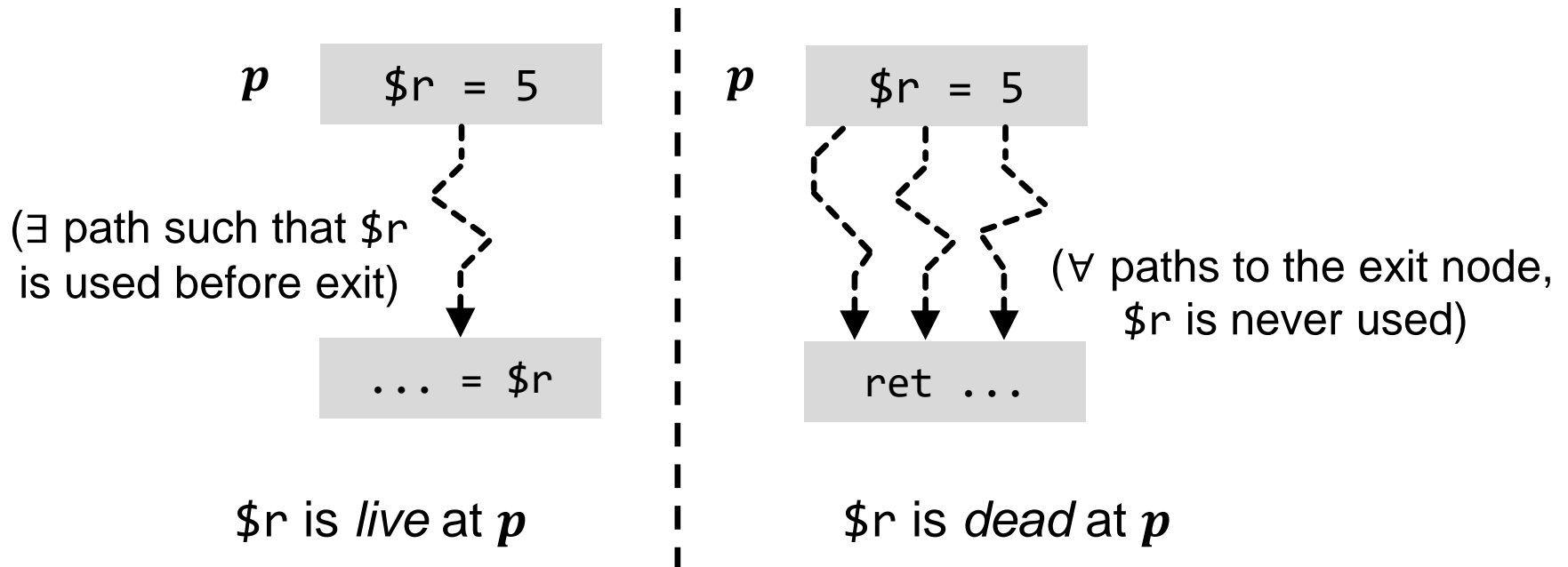
- There can be several variations, but the basic idea is same
- In the algorithm below, U denotes the universal set of all the expressions that can appear in the program

```
for each node  $n$  {  $AE\_out[n] = U$ ; }

while (there is any change to  $AE\_out[]$ ) {
  for each node  $n$  and its instruction  $i$  {
     $AE\_in[n] = \bigcap_{p \in pred(n)} AE\_out[p]$ ;
     $AE\_out[n] = f(AE\_in[n], i)$ ;
  }
}
```

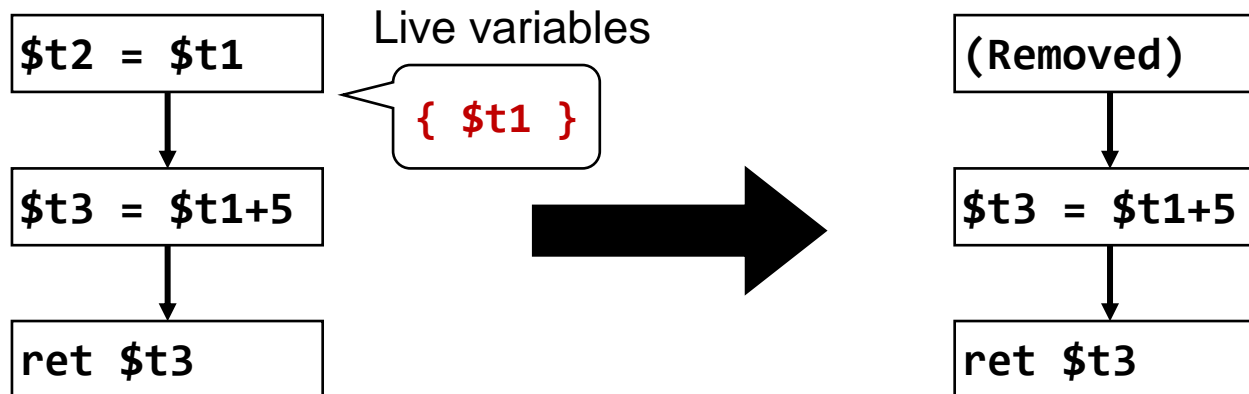
Liveness Analysis

- A variable/register $\$r$ is live at (after) program point p if its value can be used after the execution of p
- *Live variable analysis*, or *liveness analysis*, computes the set of live variables at each program point



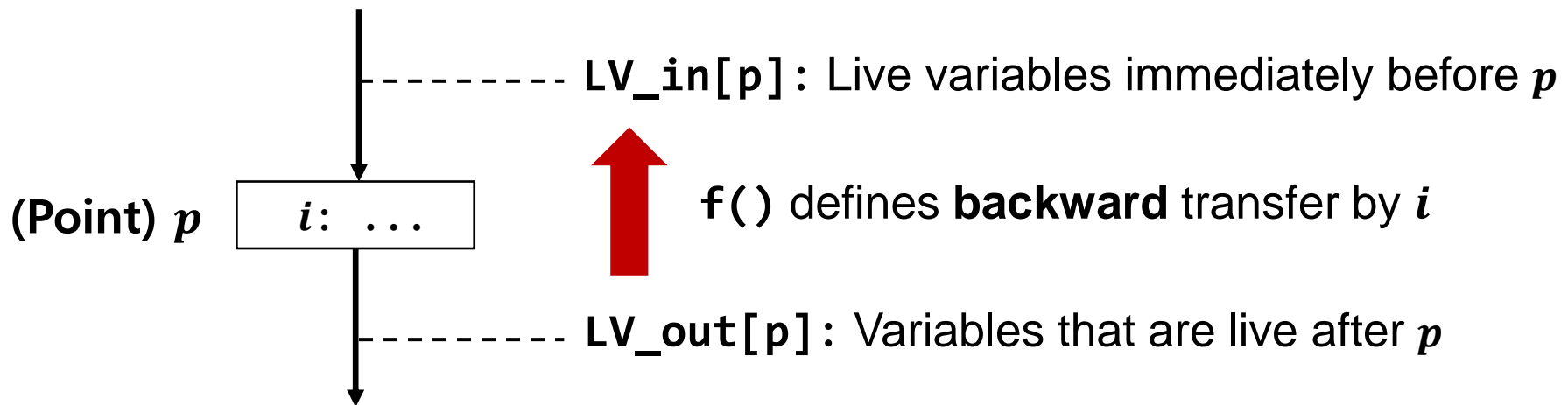
Use of Liveness Analysis

- We can perform dead code elimination (DCE) with the result of liveness analysis
 - If an instruction is defining a register that is **not live** after that instruction, we can remove such dead instruction
- Again, remember that we have to be conservative
 - The analysis result can over-approximate the live variables, but should not under-approximate them



Liveness Analysis: Transfer Function

- Note that liveness analysis must be performed backward
 - Start from the exit node and goes backward
- Therefore, the transfer function must define the input live variables in terms of the output live variables
 - For point p with instruction i : $LV_in[p] = f(LV_out[p], i)$



(Continued in Part 4)