

Physics 226

Sept. 21, 2021

0 Review of Differential Geometry

Non-Euclidean Geometries

- Consider Euclidean coord's (ξ^1, ξ^2) and some other coord. sys. (x^1, x^2) . What is the distance bet. two neighbouring points in the new sys.?

We explicitly evaluate $d\xi^1$ & $d\xi^2$ in the terms of the new coord's

0 Orientation

- Do other's book for cosmology part
- Perturbations of Schwarzschild - (ideal) basis of LISA
- Difference bet. a tensor and a its components
- Connection bet. geodesics and the equivalence principle
- Lie derivatives
- Killing vectors \rightarrow symmetries
- Metric Metrics in manifolds \rightarrow sense of distance and angle
 - \hookrightarrow isomorphism (one to one corres.) vectors & dual vectors
 - \hookrightarrow geodesics - extremal path
- Auto-parallel path - path by parallel transport
- Connection coefficients - imposes a parallel transport rule on a manifold
 - \hookrightarrow Levi-Civita connection - preserves the length of the vector as you parallel transport it
 - \hookrightarrow affine connections
- Anubony \leftarrow curvature
- Physical aspects of curvature - measured by the difference bet. the relative
 - \hookrightarrow given by geodesic deviation eqn acceleration of diff. objects
- Physical measurements in curved spacetime
 - \hookrightarrow go to an orthonormal frame (local frame of the observer) / rest frame, and represent the geometric ~~component~~ object into the orthonormal basis. The components of the represented object are what are measured by the observer
- Symmetry arguments to reduce the ansatz
 - Apply symmetry (vacuum soln, time symmetry, spherical sym.)
 - Get reduced metric
 - Plug in to Einstein tensor

* Special relativity in General frames

Sept. 23, 2021

1 Review of Differential Geometry (cont.)

- GR: All gravitational phenomena are the result of stuff moving in spacetime
 - tensors \rightarrow matter (matterworld)
 - \rightarrow Curved Lorentzian Manifold of events
- Tensors: fancy name for the geometric objects on the manifold
 - does not depend on coordinate sys.
- Manifolds: smooth in context of physics
 - \hookrightarrow topological space that is locally coordinatizable (locally \mathbb{R}^n)
 - set on which you have open sets

1 Review of the Schwarzschild Solution

The Schwarzschild soln / geometry takes the form of

$$ds^2 = -\left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2 d\Omega^2$$

$$d\Omega^2 = d\theta^2 + \sin^2\theta d\phi^2$$

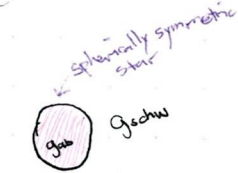
(solid angle)

in Schwarzschild coords $\{t, r, \theta, \phi\}$.

- unique, static, spherically symmetric soln to the vacuum Einstein equation
- peculiar since its non-trivial even if it's in vacuum
- reasonable approx. for spherically symmetric stars

(no matter fields)

$$G_{ab} = 8\pi T_{ab} \rightarrow T_{ab} = 0$$



uses the convention: $(- + + +)$

Stationary spacetime

→ static spacetime

add condition

$\exists k^a$ (Killing vector) where $g_{ab} k^a k^b < 0$ (timelike)

k^a must be hypersurface-orthogonal

Killing vector: If I differentiate the metric wrt the Killing flow, it doesn't change; vector field that corres. to symmetry

Lie derivative

$$\mathcal{L}_k g = 0$$

$$\nabla_a k_b = 0 \text{ (Killing's eqn)}$$

* Symmetrization symbol

$$\nabla_{(a} k_{b)} := \frac{1}{2} (\nabla_a k_b + \nabla_b k_a) = 0$$

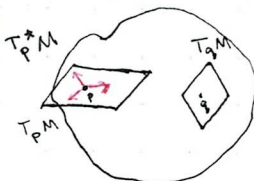
* Anti-symmetrization symbol

$$\nabla_{[a} k_{b]} := \frac{1}{2} (\nabla_a k_b - \nabla_b k_a)$$

- If a vector field satisfies the Killing's eqn, then that Killing flow is a symmetry of your given spacetime

Lie derivative: $\mathcal{L}_v T$ - use vector field v to bring tensor T at a diff. point connected by the curves

tangent space corres. to $T_p M$



Here, we can't simply compare objects in $T_p M$ with $T_q M$ (like vector subtraction between the two tangent spaces). We can establish a connection to do so. Another way is with the use of an arbitrary vector field which gives rise to integral

an arbitrary choice for the sake of comparing geometric objects

$$\Phi_\lambda: M \rightarrow M$$

(integral curves) v^a



curves. The flow Φ generated by v^a can be thought of as a mapping of the manifold onto itself. For example, it can map a point to another point lying on the same integral curve with a distance parameter λ away from the orig. point. Thus, since p and q lie on the same curve, the object living in their corres. tangent spaces are related through the said curve. The comparison of these objects makes use of pull backs & push forwards.

The dual of a vector is given by:

$$k_a = g_{ab} k^b$$

Hypersurface-orthogonality

→ There exists two scalar functions Φ, f (where $\Phi, f: M \rightarrow \mathbb{R}$) such that k_a can be expressed as $k_a = -f \nabla_a \Phi$

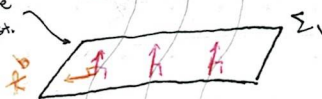
dual of the Killing vector field

$$\nabla_a \Phi = (\partial_a \Phi) dx^a$$

→ gradient one-form / covariant derivative of a scalar

flowing in the manifold k^a

hypersurface $\Phi(x^a) = \text{const.}$



This definition means that for k_a , \exists hypersurfaces $\Phi(x^a) = \text{const.}$ s.t. the congruence of the worldlines / integral curves generated by k^a is perpendicular to each point in these hypersurfaces. We can then say that k^a is hypersurface-orthogonal

$$\frac{dx^a}{d\lambda} = k^a(x)$$

Each worldline in the congruence is a solution to this eqn

$$x^a(\lambda) = \{t(\lambda), r(\lambda), \theta(\lambda), \phi(\lambda)\}$$

bundle of integral curves



coordinate expressions of worldline

Foliation: splitting of a manifold into non-intersecting parts

Orthogonality: If I take an arbitrary tangent vector t^b lying on a specific hypersurface Σ . It is orthogonal if $g_{ab} k^a t^b = 0$ (inner product bet. k^a & t^b using the metric vanishes)

Note: $\nabla \Phi$ - the normal vector corres. to Φ in usual connotation

We demand this for all points in all our hypersurfaces described by const. Φ

implies that k^a is the normal vector wrt the hypersurface

- implies that Killing vector fields generate foliation in your manifold



Consider one of the hypersurfaces Σ_i and imagine a curve σ_i lying on it. In an arbitrary coord. sys., σ is described by $\sigma: x^\mu$ (are length parameter along the curve). We can compute how Φ changes along the curve:

$$\frac{d\Phi}{ds} = 0 \quad \text{— since the curve lies on the hyper surface}$$

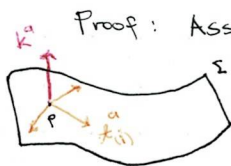
Note that this can be written as:

$$0 = \frac{d\Phi(x^\mu(s))}{ds} \stackrel{\text{chain rule}}{=} \frac{d\Phi}{dx^\mu} \frac{dx^\mu}{ds} = \Phi_{,\mu} \dot{x}^\mu \quad \text{— expression for arbitrary tangent vector}$$

From this, we can see that if

$$k_\mu = -f \Phi_{,\mu} \quad \xrightarrow{\text{then}} \quad k_\mu \dot{x}^\mu = 0$$

- The reverse is harder to prove: We can write $k_\mu = -f \Phi_{,\mu}$ if it is orthogonal to all tangent vectors



Proof: Assume $k_a \dot{x}^a \neq 0 \forall$ tangent vectors \dot{x}^a of Σ . This means that k^a is \perp to Σ . Since k^a is orthogonal to the hypersurface, there must exist three indep. tangent vectors. Then, we can write down 3 conditions:

$$\dot{x}^a_{(i)} k_a = 0 \quad i=1,2,3$$

In component form: $\dot{x}^a_{(i)} k_a = 0$ (3 linear eqns w/ 4 unknowns)

$$k_\mu = (k_0, k_1, k_2, k_3) = k_0(1, k_i/k_0)$$

This means that the orthogonality condition of k^a determines its components up to an over-all scaling we can't specify.

Thus, we have

$$\dot{x}^a_{(i)} k_\mu = 0$$

and

$$\dot{x}^a_{(i)} \Phi_{,\mu} = 0$$

$$\left. \begin{array}{l} \dot{x}^a_{(i)} k_\mu = 0 \\ \dot{x}^a_{(i)} \Phi_{,\mu} = 0 \end{array} \right\} k_\mu \propto \Phi_{,\mu}$$

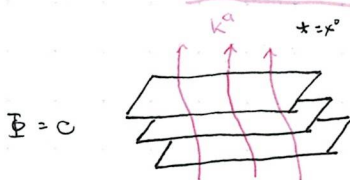
We can also say that "-f" is the ratio bet. k_μ and $\Phi_{,\mu}$ at point p:

$$f_p = - \frac{(k_a)_{\text{p}}}{(\nabla_a \Phi)_{\text{p}}}$$

from an earlier calculation. Then, this implies that the only difference bet.

k_μ & $\Phi_{,\mu}$ is some scaling factor which we can call "-f". Therefore, we can express k_a as $k_a = -f \nabla_a \Phi$

- This is important since it turns out that there is a convenient set of coordinates for a static space time.



How do we choose our coordinate system?

- Choose one of the coordinates x^0 s.t.

$$k^a \propto \frac{\partial}{\partial x^0} = \frac{\partial}{\partial t}$$

In other words, x^0 should be a parameter that runs along the integral curve of k^a and that the other coordinates $\{x^i\}$ should not change on this curve.

- x^0 : coord. along curve

$\{x^i\}$: labels the curve

- Choose $\{x^i\}$ such that:

$$\frac{\partial}{\partial x^i} \longrightarrow \text{tangent to } \Sigma$$

- What insight does the existence of the hypersurfaces give us?

$$x^0 = 1 \quad \int \dots \int_{x^i} x^0 = 2.5$$

Here, λ & x^i are parametrizations of the integral curves. We see that there is no need to have a common parametrization among these integral curves, as they are diff. curves from one another.

However, we can use hypersurfaces to relate them. For example, if points among different integral curves share the same hypersurface, we could give them the same x^0

- * Φ serves as some sort of "connection" between these diff. integral curves (could be w/ diff. coord. systems)

- What does this imply?

Consider the components of our metric. For instance, we can infer that

$$g_{00} = g(\partial_0, \partial_0) < 0$$

since we assumed that k^a is timelike

$$g_{0i} = g(\partial_0, \partial_i) = 0$$

since $\partial_0 \perp \partial_i$; $\{\frac{\partial}{\partial x^i}\}$ are tangent vectors to Σ which are orthogonal to k^a

$$= g_{ab} \underbrace{\left(\frac{\partial}{\partial x^0}\right)^a}_{k^a} \underbrace{\left(\frac{\partial}{\partial x^i}\right)^b}_{x^b} = 0$$

Because of this, we can write the line element of our static spacetime to be

$$ds^2 = g_{00}(x^a)(dx^0)^2 + g_{ij}(x^a) dx^i dx^j + g_{0i} dx^0 dx^i$$

In other words, with the use of symmetries and the way we adopted our coordinates to match these symmetries, we can reduce our line element generally of the form $ds^2 = g_{\mu\nu} dx^\mu dx^\nu$ to the form above which has no cross terms.

Recall condition for orthogonality discussed in pg. 1