

Jonathan E. Zarger

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Objective	Obtain an Electrical Engineering internship working in embedded systems and control systems	
Education	University of Michigan [Ann Arbor, MI]	Expected Graduation - May 2018
	<ul style="list-style-type: none">• MSE Electrical Engineering: Systems (Sept. 2017-May 2018)• BSE Electrical Engineering – Current GPA: 3.625 / 4.000 (Sept. 2013-May 2017)• Courses: Linear System Theory, Embedded Control Systems, Control System Design & Analysis, Digital Signal Processing, Microprocessor Systems, Navigation & Guidance, Hands on Robotics, Programming and Data Structures, Flight Software, Computer Organization	
Work Experience	Delphi Electronics and Safety [Kokomo, IN] – Engineering Intern	May - August 2016
	<ul style="list-style-type: none">• Designed, fabricated and tested equipment for frequency based signals in radiated immunity validation testing, including analog circuit design and RF immunity design• Assessed functionality of prototypes and assisted with failure analysis• Performed signal integrity analysis on high speed signal printed circuit board traces	
	BWI Group [Brighton, MI] – Engineering Intern	May - August 2015
	<ul style="list-style-type: none">• Led functional and failsafe benchmarking on brake systems to aid project development• Helped develop platform for control unit validation, including electric motor analysis	
	Honda R&D Americas [Southfield, MI] – Engineering Intern	May - August 2014
Team and Project Experience	<ul style="list-style-type: none">• Led project to design and fabricate remote controlled obstacles for demonstrating collision detection systems at the Intelligent Transportation Systems World Congress	
	Michigan Aeronautical Science Association – Avionics Team	September 2014 - Present
	<ul style="list-style-type: none">• Avionics Team Lead (2015-2016), Active Control Sub-Team Co-Lead (2016-2017)• Led team of ten students to design, implement, and test electrical systems• Co-Led project to prototype active roll control hardware and algorithms for a rocket• Led project to design, fabricate, and program a recovery control and telemetry device	
	MHacks Coordinator Team – Hardware	November 2015 - October 2016
	<ul style="list-style-type: none">• Designed microcontroller development boards to distribute to event participants• Planned and ran Introduction to Hardware and Arduino Workshops	
	EECS 452 Digital Signal Processing Capstone Project	Fall 2016
	<ul style="list-style-type: none">• Worked on team to design robot that uses image tracking to follow a laser pointer• Designed and built mechanical and electrical hardware for project• Designed and implemented closed-loop controller for laser following	
	Major Control Systems Projects	2015 - 2016
	<ul style="list-style-type: none">• Implemented simulated adaptive cruise control and lane-keep system with Simulink• Wrote control and guidance software to fly a quadcopter autonomously through a 3D path• Developed real-time embedded software to control tabletop satellite simulator• Implemented FPGA design with Verilog HDL to communicate with a video game controller	
Technical Skills	Electrical Hardware Related	
	<ul style="list-style-type: none">• Proficient with soldering and wiring harness manufacture, including surface mount• Proficient with EAGLE and Altium CircuitMaker for schematic design and ECAD• Proficient with reading electrical schematics and component datasheets• Significant experience with microcontrollers and embedded systems	
	Software Related	
	<ul style="list-style-type: none">• Proficient with C, C++, MATLAB, Python; experience with Simulink, Stateflow, Verilog HDL• Proficient with Windows, experience with Linux• Proficient with NI Multisim (SPICE), LTSpice, and Synopsys Saber for circuit modeling	