ECE459: Programming for Performance	Winter 2024
Lecture 28 — Causal and Simulation Profiling	g
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Causal Profiling

At this point we've got some experience in identifying areas of the program that we think are slow or are limiting the maximum performance of our program. If we are presented with more than one thing, how do we know which of those would yield the most benefit? Is it possible that optimizing something would actually have no effect or even a negative effect? The scientific approach would be to do an experiment and find out. That is, change the code, see the impact, re-evaluate. What causal profiling offers us is a way to run those experiments without changing any code. That could be a significant savings of time and effort.

One such causal profiler is called Coz (pronounced like "cause") [CB15]. It does a what-if analysis that says: what would be the impact of speeding up this particular part of the code?

A very simple approach would just look at the time of the program and just calculate what happens if the runtime of function work() is reduced by, say, 10%. But that isn't a realistic approach, because speeding up that function might have no overall impact or change the execution time by increasing lock contention or some other mechanism. No, we actually need a simulation.

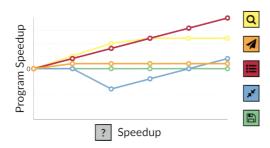
The key observation of the Coz profiler authors is the idea that speeding up some area of code is fundamentally the same as slowing down every other part of the code. It's all relative! This is what we would call a virtual speedup. How is the other code slowed down? Adding some pauses to (stopping the execution of) the other threads. That certainly makes them run slower. Maybe you're not convinced that slowing down everything else is equivalent?

Shown below is the argument from [CB15] in visual form. The original runtime is shown as (a). Hypothetically, say we make function f faster by some factor d=40% that gives us (b). But, if instead of actually making function f faster, let's pause other threads for $0.4 \times t(f)$ where t(f) is the original execution time of f. Then we get an equivalent effect to that of optimizing f by d.

The tool provides some graphs of potential program speedup. From the recorded presentation, it might look something like the diagram below, where the boxes on the right correspond to different theoretical actions in the

application being examined:





This pretend application shows all the possible outcomes, from continuous linear speedup, to speedup capped at some point, to no effect, and finally to where optimizing something makes the overall program runtime worse.

It's easy to imagine scenarios corresponding to each of those. If we're computing the n-body problem, anything that improves the calculation of forces will certainly make things better. And it's easy to imagine that sometimes optimizing a part of the program does not improve anything because that code is not on the critical path. We can also easily imagine that improving something works up to a point where it ceases to be the limiting factor. But making things worse? We already covered that idea: speeding up a thread may increase lock contention or add something to the critical path. At some point, things may recover and be a net benefit.

It is important to remember that just because hypothetically speeding up a particular part of the program would be beneficial, doesn't mean that it's possible to speed up that part. And almost certainly not possible to do so to an arbitrary degree. We still have to make an assessment of what optimizations we can make and how difficult it would be to actually realize those improvements.

Once we've made a change to the program, then it's time to run an experiment again with the new baseline to see what else we can do.

The paper has a table summarizing the optimizations they applied to a few different programs, which seems to support the idea that the tool can be used effectively to get a meaningful speedup with relatively few lines of code [CB15]:

	Summary of optimization results		
Application	Speedup	Diff size	Source lines
Memcached	9.39% ± 0.95%	-6, +2	10,475
SQLite	$25.60\% \pm 1.00\%$	-7, +7	92,635
blackscholes	$2.56\% \pm 0.41\%$	-61, +4	342
dedup	$8.95\% \pm 0.27\%$	-3, +3	2,570
ferret	$21.27\% \pm 0.17\%$	-4, +4	5,937
fluidanimate	$37.5\% \pm 0.56\%$	-1, +0	1,015
streamcluster	$68.4\% \pm 1.12\%$	-1, +0	1,779
swaptions	$15.8\% \pm 1.10\%$	-10, +16	970

There are potentially some limitations to this, of course. Putting pauses in the execution of the code can work when the execution of the program is all on the same machine and we have control over all the threads; it would need some meaningful extension to work for a distributed system where coordinating things across many servers would be needed.

Using some benchmarking workload, the authors estimate a 17.6% overhead for this tool, which is broken down into 2.6% for startup debug information collection, sampling at 4.8%, and 10.2% is the delay that's caused by slowing down other threads to create a virtual speedup [CB15].

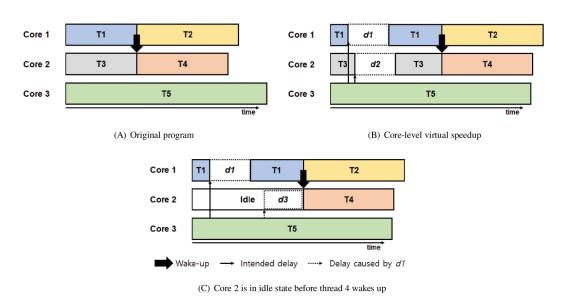
If you'd like to see some more details of the tool, you can see the author presentation at the ACM symposium here: https://www.youtube.com/watch?v=jE0V-plodPg

The Next Generation: SCOZ

A few years later, another group of researchers worked to extend the Coz profiler to account for some limitations: inability to look at multi-process applications (which we just talked about), but also cases where the OS itself becomes a bottleneck [AKNJ21]. You may recall that looking into the kernel is not always permitted for a given profiling tool – depending on permissions. It is therefore obvious to imagine that if one cannot look, then one cannot touch.

If, indeed, the kernel is a bottleneck, it may or may not be possible to do very much about it. Avoiding system calls is one of the "do less work" strategies that you have likely already considered; oftentimes doing the system call is because we must. In an open-source OS or a kernel module we control, then we would have the ability to do something about it, if coz could give some recommendations.

The approach of [AKNJ21] is to move from a thread-based system to a core-based one. So where, previously, to simulate speedup of a particular section of code the tool would pause all other threads, now it pauses execution on all other cores. There are some details to consider about what to do when there are idle cores to make sure that the delay is charged to the "right" core when one is woken up by another. The diagram the authors provides helps to explain it well:



The implementation involves one profiler thread for each core to manage its behaviour. The thread is pinned to the core, and its purpose is primarily to call the ndelay interface (with preemption temporarily disabled) to stop execution of code on that specific core [AKNJ21].

This extension does allow scoz to do more than coz, but it does require running within the kernel, which imposes certain limitations to where and how it can be applied. That's an interesting tradeoff!

1 Simulations

In a related idea,

Cachegrind

Cachegrind is another tool in the Valgrind package and this one is much more performance oriented than the other two tools. Yes, memcheck and Helgrind look for errors in your program that are likely to lead to slowdowns (memory leaks) or make it easier to parallelize (spawn threads) without introducing errors. Cachegrind, however, does a simulation of how your program interacts with cache and evaluates how your program does on branch prediction. As we discussed earlier, cache misses and branch mispredicts have a huge impact on performance.

Recall that a miss from the fastest cache results in a small penalty (perhaps, 10 cycles); a miss that requires going to memory requires about 200 cycles. A mispredicted branch costs somewhere between 10-30 cycles. All figures & estimates from the cachegrind manual [Dev15].

Cachegrind reports data about the First Level Instruction Cache (I1) [L1 Instruction Cache], the First Level Data Cache (D1) [L1 Data Cache], and the Last Level Cache (LL) [L3 Cache].

Unlike the normal Valgrind operation, you probably want to turn optimizations on (compile the release version). You still want debugging symbols, of course, but enabling optimizations will tell you more about what is going to happen in the released version of your program.

If I instruct cachegrind to run on a simple ECE 252-type example using the -branch-sim=yes option (because by default it won't show it):

```
jz@Loki:~/ece254$ valgrind --tool=cachegrind --branch-sim=yes ./search
==16559== Cachegrind, a cache and branch-prediction profiler
==16559== Copyright (C) 2002-2013, and GNU GPL'd, by Nicholas Nethercote et al.
==16559== Using Valgrind-3.10.0.SVN and LibVEX; rerun with -h for copyright info
==16559== Command: ./search
==16559==
--16559-- warning: L3 cache found, using its data for the LL simulation.
Found at 11 by thread 1
Found at 22 by thread 3
==16559==
==16559== I
                        310.670
             refs:
==16559== I1 misses:
                           1,700
==16559== LLi misses:
                           1,292
==16559== I1 miss rate:
                           0.54%
==16559== LLi miss rate:
                           0.41%
==16559==
==16559== D
                         114,078 (77,789 rd
                                              + 36,289 wr)
             refs:
==16559== D1 misses:
                           4.398
                                 ( 3.360 rd
                                              + 1.038 wr)
==16559== LLd misses:
                           3,252 ( 2,337 rd
                                                    915 wr)
==16559== D1 miss rate:
                            3.8% (
                                     4.3%
                                                    2.8%)
==16559== LLd miss rate:
                            2.8% (
                                     3.0%
                                                    2.5%
==16559==
==16559== LL refs:
                           6,098 (5,060 rd
                                                 1.038 wr)
==16559== LL misses:
                           4,544 (3,629 rd
                                                    915 wr)
                            1.0% (
                                                    2.5%)
==16559== LL miss rate:
                                     0.9%
==16559==
==16559== Branches:
                          66,622 (65,097 cond +
                                                 1.525 ind)
==16559== Mispredicts:
                          7,202 (6,699 cond +
                                                   503 ind)
==16559== Mispred rate:
                           10.8% ( 10.2%
                                                   32.9%
```

So we see a breakdown of the instruction accesses, data accesses, and how well the last level of cache (L3 here) does. Why did I say enable optimization? Well, here's the output of the search program if I compile with the -02 option. Yes, this was a C program, but the idea is the same.

```
jz@Loki:\sim/ece254$ valgrind --tool=cachegrind --branch-sim=yes ./search ==16618== Cachegrind, a cache and branch-prediction profiler
```

```
==16618== Copyright (C) 2002-2013, and GNU GPL'd, by Nicholas Nethercote et al.
==16618== Using Valgrind-3.10.0.SVN and LibVEX; rerun with -h for copyright info
==16618== Command: ./search
==16618==
--16618-- warning: L3 cache found, using its data for the LL simulation.
Found at 11 by thread 1
Found at 22 by thread 3
==16618==
==16618== T
            refs:
                       306 169
==16618== I1 misses:
                        1,652
                         1,286
==16618== LLi misses:
==16618== I1 miss rate:
                         0.53%
==16618== LLi miss rate:
                          0.42%
==16618==
                                           + 35,493 wr)
==16618== D refs:
                       112,015 (76,522 rd
==16618== D1 misses:
                         4,328 (3,353 rd +
                                                 975 wr)
==16618== LLd misses:
                         3,201 (2,337 rd +
                                                 864 wr)
==16618== D1 miss rate:
                           3.8% (
                                    4.3%
                                            +
                                                 2.7% )
==16618== LLd miss rate:
                          2.8% ( 3.0%
                                                 2.4% )
==16618==
==16618== LL refs:
==16618== LL misses:
                         5,980 (5,005 rd
                                                 975 wr)
                         4,487 ( 3,623 rd
                                                 864 wr)
==16618== LL miss rate:
                         1.0% ( 0.9%
                                                 2.4% )
==16618==
==16618== Branches:
                        65,827 (64,352 cond + 1,475 ind)
==16618== Mispredicts:
                        7,109 ( 6,596 cond +
                                                513 ind)
                          10.7% ( 10.2%
==16618== Mispred rate:
                                                34.7%
```

Interesting results: our data and instruction miss rates went down marginally but the branch mispredict rates went up! Well sort of – there were fewer branches and thus fewer we got wrong as well as fewer we got right. So the total cycles lost to mispredicts went down. Is this an overall win for the code? Yes.

In some cases it's not so clear cut, and we could do a small calculation. If we just take a look at the LL misses (4 544 vs 4 487) and assume they take 200 cycles, and the branch miss penalty is 200 cycles, it went from 908 800 wasted cycles to 897 400; a decrease of 11 400 cycles. Repeat for each of the measures and sum them up to determine if things got better overall and by how much.

Cachegrind also produces a more detailed output file, titled cachegrind.out.<pid>(the PID in the example is 16618). This file is not especially human-readable, but we can ask the associated tool cg_annotate to break it down for us, and if we have the source code available, so much the better, because it will give you line by line information. That's way too much to show even in the notes, so it's the sort of thing I can show in class (or you can create for yourself) but here's a small excerpt from the search.c example:

```
-- Auto-annotated source: /home/jz/ece254/search.c
Ir Ilmr ILmr Dr Dlmr DLmr Dw Dlmw DLmw Bc Bcm Bi Bim
         1 96 3 0 4 0 0 23 11 0 0
                                                 for ( int i = arg->startIndex; i < arg->endIndex; ++i
127
   1
   ) {
                                                     if ( array[i] == arg->searchValue ) {
147
                               0 21 9 0 0
          0 84
                    2 0
     0
                3
                           Θ
 6
          0 4 0 0 2
                           0
                               0 0 0 0
                                                        *result = i;
 2
     0
          0 0
                0
                    0 0
                           0
                               0 0 0 0
                                                        break;
                                                     }
                                  .
                                                 }
```

Cachegrind is very... verbose... and it can be very hard to come up with useful changes based on what you see... assuming your eyes don't glaze over when you see the numbers. Probably the biggest performance impact is last level cache misses (those appear as DLmr or DLmw). They have the highest penalty. You might also try to look at the Bcm and Bim (branch mispredictions) to see if you can give some better hints about what the likelihood of branch prediction is [Dev15].

References

- [AKNJ21] Minwoo Ahn, Donghyun Kim, Taekeun Nam, and Jinkyu Jeong. Scoz: A system-wide causal profiler for multicore systems. Software: Practice and Experience, 51(5):1043–1058, 2021. URL: https://onlinelibrary.wiley.com/doi/abs/10.1002/spe.2930, arXiv:https://onlinelibrary.wiley.com/doi/pdf/10.1002/spe.2930, doi:10.1002/spe.2930.
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