### **Distributed Systems**

(4th edition, version 01)

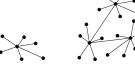
Chapter 01: Introduction

Introduction From networked systems to distributed systems

Distributed versus Decentralized

## What many people state

Centralized







Distributed

#### When does a decentralized system become distributed?

- Adding 1 link between two nodes in a decentralized system?
- Adding 2 links between two other nodes?
- In general: adding k > 0 links....?

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Distributed versus decentralized systems 2 / 53 Distributed versus decentralized systems 2 / 53

Introduction From networked systems to distributed systems and introduction From networked systems to distributed systems and the control of the control of

#### Two views on realizing distributed systems

- Integrative view: connecting existing networked computer systems into a larger a system.
- Expansive view: an existing networked computer systems is extended with additional computers

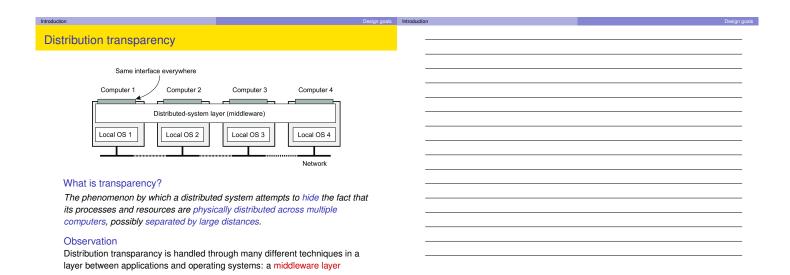
#### Two definitions

Distributed versus decentralized systems

- A decentralized system is a networked computer system in which processes and resources are necessarily spread across multiple computers.
- A distributed system is a networked computer system in which processes and resources are sufficiently spread across multiple computers.

Some common misconceptions			
Centralized solutions do not scale  Make distinction between logically and physically centralized. The root of the Domain Name System:  logically centralized  physically (massively) distributed  decentralized across several organizations  Centralized solutions have a single point of failure  Generally not true (e.g., the root of DNS). A single point of failure is often:  easier to manage  easier to make more robust  Important  There are many, poorly founded, misconceptions regarding scalability, fault tolerance, security, etc. We need to develop skills by which distributed systems can be readily understood so as to judge such misconceptions.			
Distributed versus decentralized systems 4/	53 Distributed versus decentraliz	ed systems	4/53
Perspectives on distributed systems  Distributed systems are complex: take persepctives  Architecture: common organizations Process: what kind of processes, and their relationships Communication: facilities for exchanging data Coordination: application-independent algorithms Naming: how do you identify resources? Consistency and replication: performance requires of data, which need to be the same Fault tolerance: keep running in the presence of partial failures Security: ensure authorized access to resources	Introduction		From networked systems to distributed systems
Introduction  Design go  What do we want to achieve?  Overall design goals  Support sharing of resources Distribution transparency	53 Studying distributed systems		5 / 53  Design goals
<ul><li>Openness</li><li>Scalability</li></ul>			

 Resource sharing
 7/53
 Resource sharing
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Distribution transparency

Design goals

Introduction

Design goals

Transparency	Description
Access	Hide differences in data representation and how an
	object is accessed
Location	Hide where an object is located
Relocation	Hide that an object may be moved to another location
	while in use
Migration	Hide that an object may move to another location
Replication	Hide that an object is replicated
Concurrency	Hide that an object may be shared by several
	independent users
Failure	Hide the failure and recovery of an object

Types

Distribution transparency 9/53 Distribution transparency 9/53 Distribution transparency 9/53

Degree of transparency
Aiming at full distribution transparency may be too much
There are communication latencies that cannot be hidden
<ul> <li>Completely hiding failures of networks and nodes is (theoretically and practically) impossible</li> </ul>
<ul> <li>You cannot distinguish a slow computer from a failing one</li> <li>You can never be sure that a server actually performed an operation before a crash</li> </ul>
<ul> <li>Full transparency will cost performance, exposing distribution of the system</li> </ul>
<ul> <li>Keeping replicas exactly up-to-date with the master takes time</li> <li>Immediately flushing write operations to disk for fault tolerance</li> </ul>
Distribution transparency

Degree of transparency

Exposing distribution may be good

• Making use of location-based services (finding your nearby friends)

• When dealing with users in different time zones

• When it makes it easier for a user to understand what's going on (when e.g., a server does not respond for a long time, report it as failing).

Conclusion

Distribution transparency is a nice goal, but achieving it is a different story, and it should often not even be aimed at.

xion	Design goals	Introduction	Design goals
penness of distributed systems			
Open distributed system A system that offers components that car other systems. An open distributed syste components that originate from elsewher	m itself will often consist of		
What are we talking about?  Be able to interact with services from other underlying environment:	er open systems, irrespective of the		
<ul> <li>Systems should conform to well-defi</li> <li>Systems should easily interoperate</li> <li>Systems should support portability</li> <li>Systems should be easily extensible</li> </ul>	of applications		

Op

Introduction	Design goals	Introduction	Design goals
Policies versus mechanisms			
Implementing openness: policies  • What level of consistency do we reaction with the work of the work	wnloaded code to perform?  Idjust in the face of varying bandwidth?  Ire for communication?  In the face of varying bandwidth?  Ire for communication?		
Provide adjustable QoS parameter			
<ul> <li>Offer different encryption algorith</li> </ul>	ms		
Openness	13 / 53	Openness	13/53

Observation

Observation

The stricter the separation between policy and mechanism, the more we need to ensure proper mechanisms, potentially leading to many configuration parameters and complex management.

Finding a balance

Hard-coding policies often simplifies management, and reduces complexity at the price of less flexibility. There is no obvious solution.

Introduction	Design goals	Introduction	Design goals
Dependability			
Basics A component provides services to clients may require the services from other com on some other component.	· · · · · · · · · · · · · · · · · · ·		
Specifically A component $C$ depends on $C^*$ if the cothe correctness of $C^*$ 's behavior. (Comp			

Dependability 16/53 Dependability

Reliability versus availability

Reliability R(t) of component C
Conditional probability that C has been functioning correctly during [0, t) given C was functioning correctly at the time T = 0.

Traditional metrics

• Mean Time To Failure (MTTF): The average time until a component fails.

• Mean Time To Repair (MTTF): The average time needed to repair a component.

• Mean Time Between Failures (MTBF): Simply MTTF + MTTR.

Terminology Introduction Design goals Introduction

Failure, error, fault

Term	Description	Example
Failure	A component is not living up to its specifications	Crashed program
Error	Part of a component that can lead to a failure	Programming bug
Fault	Cause of an error	Sloppy programmer

Dependability 18/53 Dependability 18/53

### Terminology

#### Handling faults

Term	Description	Example
Fault prevention	Prevent the occurrence of a fault	Don't hire sloppy programmers
Fault tolerance	Build a component and make it mask the occurrence of a fault	Build each component by two independent programmers
Fault removal	Reduce the presence, number, or seriousness of a fault	Get rid of sloppy programmers
Fault forecasting	Estimate current presence, future incidence, and consequences of faults	Estimate how a recruiter is doing when it comes to hiring sloppy programmers

Introduction	Design goals	Introduction	Design goals
On security			
Observation			

A distributed system that is not secure, is not dependable

#### What we need

- Confidentiality: information is disclosed only to authorized parties
- Integrity: Ensure that alterations to assets of a system can be made only in an authorized way

#### Authorization, Authentication, Trust

- Authentication: verifying the correctness of a claimed identity
- Authorization: does an identified entity has proper access rights?
- Trust: one entity can be assured that another will perform particular actions according to a specific expectation

Introduction	Design goals	Introduction	Design goals
Security mechanisms			
Keeping it simple It's all about encrypting and decrypting of	data using security keys.		
Notation $K(data)$ denotes that we use key $K$ to each $K(data)$	ncrypt/decrypt <i>data</i> .		

Security mechanisms Secure hashing

In practice, we use secure hash functions: H(data) returns a fixed-length

- string.
  Any change from data to data\* will lead to a completely different string H(data\*).
  - Given a hash value, it is computationally impossible to find a data with h = H(data)

Practical digital signatures

Sign message for Bob by Alice:

$$[\textit{data}, \underbrace{\textit{H(data)} \overset{?}{=} \textit{PK}_{\textit{alice}}(\textit{sgn})}_{\textit{Check by Bob}}] = \underbrace{[\textit{data}, \textit{H}, \textit{sgn} = \textit{SK}_{\textit{alice}}(\textit{H(data)})]}_{\textit{Sent by Alice}}$$

Scale in distributed systems Observation

Many developers of modern distributed systems easily use the adjective "scalable" without making clear why their system actually scales.

At least three components

- Number of users or processes (size scalability)
- Maximum distance between nodes (geographical scalability)
- Number of administrative domains (administrative scalability)

Observation

Most systems account only, to a certain extent, for size scalability. Often a solution: multiple powerful servers operating independently in parallel. Today, the challenge still lies in geographical and administrative scalability.

#### Size scalability

#### Root causes for scalability problems with centralized solutions

- The computational capacity, limited by the CPUs
- The storage capacity, including the transfer rate between CPUs and disks
- The network between the user and the centralized service

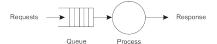
O - - I - I-Tr

/ 53 Scalability

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Formal analysis

A centralized service can be modeled as a simple queuing system



#### Assumptions and notations

- The queue has infinite capacity ⇒ arrival rate of requests is not influenced by current queue length or what is being processed.
- Arrival rate requests:  $\lambda$
- $\bullet$  Processing capacity service:  $\mu$  requests per second

Fraction of time having k requests in the system

$$p_k = (1 - \frac{\lambda}{\mu}) (\frac{\lambda}{\mu})^k$$

Scalability

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Introduction

# Formal analysis

Utilization U of a service is the fraction of time that it is busy

$$U = \sum_{k>0} p_k = 1 - p_0 = \frac{\lambda}{\mu} \Rightarrow p_k = (1 - U)U^k$$

Average number of requests in the system

$$\overline{N} = \sum_{k \ge 0} k \cdot p_k = \sum_{k \ge 0} k \cdot (1 - U) U^k = (1 - U) \sum_{k \ge 0} k \cdot U^k = \frac{(1 - U)U}{(1 - U)^2} = \frac{U}{1 - U}$$

Average throughput

$$X = \underbrace{U \cdot \mu}_{\text{server at work}} + \underbrace{(1 - U) \cdot 0}_{\text{server idle}} = \frac{\lambda}{\mu} \cdot \mu = \lambda$$

#### Formal analysis

Response time: total time take to process a request after submission

$$R = \frac{\overline{N}}{X} = \frac{S}{1 - U} \Rightarrow \frac{R}{S} = \frac{1}{1 - U}$$

with  $S = \frac{1}{\mu}$  being the service time.

#### Observations

- If U is small, response-to-service time is close to 1: a request is immediately processed
- If *U* goes up to 1, the system comes to a grinding halt. Solution: decrease S.

Problems with geographical scalability

- - Cannot simply go from LAN to WAN: many distributed systems assume synchronous client-server interactions: client sends request and waits for an answer. Latency may easily prohibit this scheme.
  - WAN links are often inherently unreliable: simply moving streaming video from LAN to WAN is bound to fail.
  - · Lack of multipoint communication, so that a simple search broadcast cannot be deployed. Solution is to develop separate naming and directory

Services (naving their own scalability problems).	

Problems with administrative scalability

#### Essence

Conflicting policies concerning usage (and thus payment), management, and security

#### Examples

- Computational grids: share expensive resources between different
- Shared equipment: how to control, manage, and use a shared radio telescope constructed as large-scale shared sensor network?

#### Exception: several peer-to-peer networks

- File-sharing systems (based, e.g., on BitTorrent)
- Peer-to-peer telephony (early versions of Skype)

Peer-assisted audio streaming (Spotify)

Note: end users collaborate and not administrative entities.

Techniques for scaling

Facilitate solution by moving computations to client

| First name | MAARTEN | LAST NAME |

Techniques for scaling

Partition data and computations across multiple machines

• Move computations to clients (Java applets and scripts)

• Decentralized naming services (DNS)

• Decentralized information systems (WWW)

Introduction	1	Design goals Introd	luction	Design goals
Techniques for scaling				
Deplication and eaching, Make con	ion of data available at different			
Replication and caching: Make cop machines	nes of data available at different			
<ul> <li>Replicated file servers and database</li> </ul>	ases			
Mirrored Websites				
<ul><li>Web caches (in browsers and pro:</li><li>File caching (at server and client)</li></ul>	*			
• The Caching (at server and cheft)				
				-

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# Scaling: The problem with replication

#### Applying replication is easy, except for one thing

- Having multiple copies (cached or replicated), leads to inconsistencies: modifying one copy makes that copy different from the rest.
- Always keeping copies consistent and in a general way requires global synchronization on each modification.
- Global synchronization precludes large-scale solutions.

#### Observation

If we can tolerate inconsistencies, we may reduce the need for global synchronization, but tolerating inconsistencies is application dependent.

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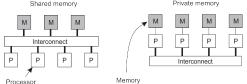
Scalabity 35/53 Scalabity 35/53 Scalabity 35/53

# Introduction A simple classification of distributed systems Parallel computing A simple classification of distributed systems Introduction A simple classification of distributed systems A simple classification of distributed systems A simple classification of distributed systems

#### Observation

High-performance distributed computing started with parallel computing

#### Multiprocessor and multicore versus multicomputer



Distributed shared mem	ory systems	<del></del>	
multicomputers, yet have pr (or cores). Solution: Try to i multicomputer.  Example through virtual-Map all main-memory page address space. If a process processor <i>B</i> , the OS at <i>A</i> tr been located on local disk.  Problem  Performance of distributed	s (from different processors) into one single virtual s at processor A addresses a page P located at aps and fetches P from B, just as it would if P had shared memory could never compete with that of to meet the expectations of programmers. It has		
High-performance distributed computing		B7 / 53 High-performance distributed compu	puting 37/53
Introduction	A simple classification of distributed sy	ratems. Introduction	A simple classification of distributed systems
Cluster computing			
	Management	High-performance distributed compu	puling 38/53
Grid computing	A simple classification of distributed sy	stems Introduction	A simple classification of distributed systems
Gha computing			
The next step: plenty of	nodes from everywhere		
<ul> <li>Heterogeneous</li> </ul>			

Can easily span a wide-area network

• Dispersed across several organizations

High-performance distributed computing 40 /53 High-performance distributed computing 40 /

applications in a single organization.

Integrating applications

Situation
Organizations confronted with many networked applications, but achieving interoperability was painful.

Basic approach
A networked application is one that runs on a server making its services available to remote clients. Simple integration: clients combine requests for (different) applications; send that off; collect responses, and present a coherent result to the user.

Next step
Allow direct application-to-application communication, leading to Enterprise
Application Integration.

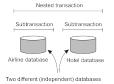
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Distributed information systems
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# Example EAI: (nested) transactions A simple classification of distributed systems A simple classification of distributed systems A simple classification of distributed systems A simple classification of distributed systems

#### Transaction

Primitive	Description
BEGIN_TRANSACTION	Mark the start of a transaction
END_TRANSACTION	Terminate the transaction and try to commit
ABORT_TRANSACTION	Kill the transaction and restore the old values
READ	Read data from a file, a table, or otherwise
WRITE	Write data to a file, a table, or otherwise

#### Issue: all-or-nothing

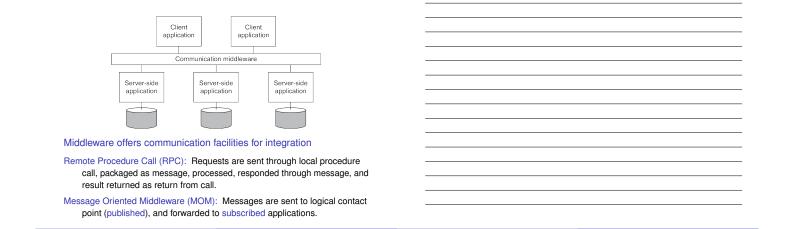


- Atomic: happens indivisibly (seemingly)
- Consistent: does not violate system invariants
- Isolated: not mutual interference
- Durable: commit means changes are permanent

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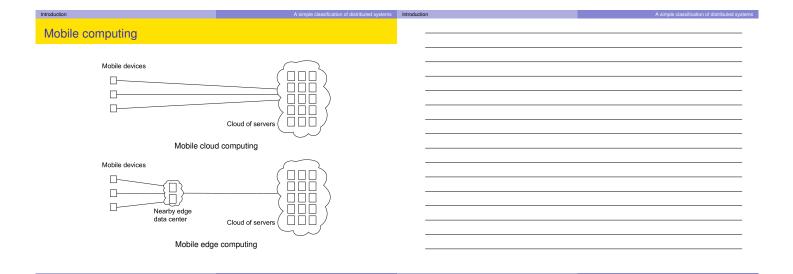
Middleware and EAI



v to integrate applications
File transfer: Technically simple, but not flexible:
Figure out file format and layout
Figure out file management
<ul> <li>Update propagation, and update notifications.</li> </ul>
Shared database: Much more flexible, but still requires common data scheme next to risk of bottleneck.
Remote procedure call: Effective when execution of a series of actions is needed.
Messaging: RPCs require caller and callee to be up and running at the same time. Messaging allows decoupling in time and space.

Distributed pervasive systems	
Observation Emerging next-generation of distributed systems in which nodes are small, mobile, and often embedded in a larger system, characterized by the fact that the system naturally blends into the user's environment.  Three (overlapping) subtypes  • Ubiquitous computing systems: pervasive and continuously present, i.e., there is a continuous interaction between system and user.  • Mobile computing systems: pervasive, but emphasis is on the fact that devices are inherently mobile.  • Sensor (and actuator) networks: pervasive, with emphasis on the actual (collaborative) sensing and actuation of the environment.	Pervasive systems 45/53
Introduction A simple classification of distributed systems	Introduction A simple classification of distributed systems
Core elements  1. (Distribution) Devices are networked, distributed, and accessible transparently 2. (Interaction) Interaction between users and devices is highly unobtrusive 3. (Context awareness) The system is aware of a user's context to optimize interaction 4. (Autonomy) Devices operate autonomously without human intervention, and are thus highly self-managed 5. (Intelligence) The system as a whole can handle a wide range of dynamic actions and interactions	Pervasive systems 47/53
Introduction A simple classification of distributed systems	Introduction A simple classification of distributed systems
Distinctive features     • A myriad of different mobile devices (smartphones, tablets, GPS devices, remote controls, active badges).     • Mobile implies that a device's location is expected to change over time ⇒ change of local services, reachability, etc. Keyword: discovery.     • Maintaining stable communication can introduce serious problems.	
<ul> <li>For a long time, research has focused on directly sharing resources between mobile devices. It never became popular and is by now considered to be a fruitless path for research.</li> </ul>	

Mobile devices set up connections to stationary servers, essentially bringing mobile computing in the position of clients of cloud-based services.



Sensor networks

Characteristics
The nodes to which sensors are attached are:

• Many (10s-1000s)

• Simple (small memory/compute/communication capacity)

• Often battery-powered (or even battery-less)

Sensor networks as distributed databases

Two extremes

Sensor data is sent directly to operator's site

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Developing distributed systems: Pitfalls

Observation
Many distributed systems are needlessly complex, caused by mistakes that required patching later on. Many false assumptions are often made.

False (and often hidden) assumptions

• The network is reliable

• The network is secure

• The network is homogeneous

• The topology does not change

Latency is zeroBandwidth is infiniteTransport cost is zero

There is one administrator