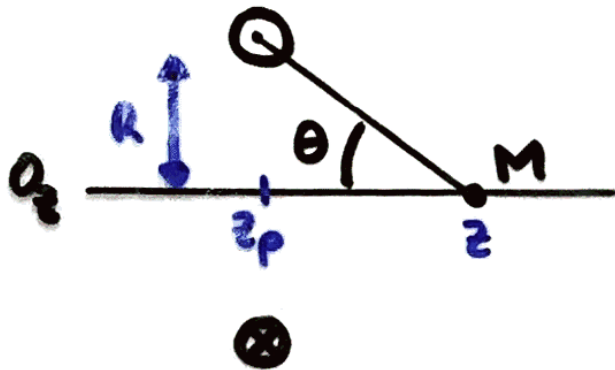


CALCUL DU CHAMP \vec{B}

* Les plans passant par Oz sont des plans d'antisymétrie pour \vec{B} : $\vec{B} = B_z \vec{e}_z$ (SUR L'AXE)

* invariance par rotation : $B(r, \theta, z) = B(r, z)$

* champ d'une spire : $dB_z(M) = \frac{\mu n I}{2R} \sin^3(\theta) d\ell$ I



$$z - z_p = \frac{R}{\tan \theta} \Rightarrow d\ell = dz_p = \frac{R}{\sin^2 \theta} d\theta \quad \text{II}$$

$$\text{I et II} \Rightarrow dB_z(M) = \frac{\mu n I}{2} \sin \theta d\theta$$

$$\Rightarrow B_z(M) = \frac{\mu n I}{2} (\cos \theta_2 - \cos \theta_1)$$

RELATION

CHAMP AXIAL / RADIAL

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\frac{1}{r} \frac{\partial r B_r}{\partial r} + \frac{1}{r} \cancel{\frac{\partial B_\theta}{\partial \theta}} + \frac{\partial B_z}{\partial z} = 0$$

$$\partial(r B_r) = \frac{dB_z}{dz} \cdot (-r dr)$$

$$B_r = -\frac{r}{2} \frac{dB_z}{dz}$$

$$B_z = \frac{\mu n I}{2} (\cos \theta_2 - \cos \theta_1)$$

$$\theta_{12} = \frac{\pi}{2} - \text{Atan}\left(\frac{z + L/2}{R}\right)$$

$$\frac{z}{R} + \frac{L}{2R} = \tan\left(\frac{\pi}{2} - \theta_{12}\right)$$

$$dz = \frac{-R}{\sin^2 \theta_{12}} d\theta_{12}$$

$$\frac{dB_z}{dz} = \frac{\mu n I}{2} \left(\frac{\cos \theta_2}{d\theta} \frac{d\theta}{dz} - \frac{\cos \theta_1}{d\theta} \frac{d\theta}{dz} \right)$$

$$\frac{dB_z}{dz} = \frac{\mu n I}{2R} (\sin^3 \theta_1 - \sin^3 \theta_2)$$

$$B_r = \frac{\mu n I r}{2R} (\sin^3 \theta_2 - \sin^3 \theta_1)$$

CALCUL DU COURANT INDUIT

* On cherche \vec{A} tq: $\vec{\nabla} \wedge \vec{A} = \vec{B}$

$$\rightarrow \boxed{\vec{A} = (\vec{B} \cdot \vec{e}_z) \frac{r}{2} \vec{e}_\theta} *$$

$$* \vec{j} = \sigma \vec{E} = -\sigma \frac{\partial \vec{A}}{\partial t}$$

$$= -\frac{\sigma r}{2} \frac{\partial B_z}{\partial t} \vec{e}_\theta$$

$$\boxed{\vec{j} = -\sigma \frac{\mu n I' r}{4} (\cos \alpha_1 - \cos \alpha_2) \vec{e}_\theta}$$

$$\vec{\nabla} \wedge \vec{A} = -\frac{\partial A_\theta}{\partial z} \vec{e}_r + \frac{1}{r} \frac{\partial r A_\theta}{\partial r} \vec{e}_z$$

$$= -\frac{r}{2} \frac{dB_z}{dz} \vec{e}_r + B_z \vec{e}_z$$

$$= B_r \vec{e}_r + B_z \vec{e}_z$$

$$\boxed{\vec{\nabla} \wedge \vec{A} = \vec{B}}$$

EQUATION DU MOUVEMENT

$$d\vec{F} = \vec{j} \, dz \wedge \vec{B}$$

$$\begin{aligned} d\vec{F} &= j_0 \, dr \, dx \, (2\pi r) \cdot B_r \cdot (\vec{e}_\theta \wedge \vec{e}_r) \\ &= \frac{\mu n I \pi r^2}{2R} (\sin^3 \alpha_1 - \sin^3 \alpha_2) \cdot j \, dr \, dx \, \vec{e}_z \end{aligned}$$

$$d\ddot{z} = \frac{(\mu n)^2 \pi r^3}{8 R m} \cdot I(t) \cdot I'(t) \cdot (\cos \alpha_1 - \cos \alpha_2) (\sin^3 \alpha_1 - \sin^3 \alpha_2)$$

$$\ddot{z} = K \cdot I(t) \cdot I'(t) \cdot \underbrace{\int_{z-L/2}^{z+L/2} (\cos \alpha_1 - \cos \alpha_2) (\sin^3 \alpha_1 - \sin^3 \alpha_2) \, dx}_{g(z)}$$

$$\alpha_1 = \frac{\pi}{2} - A \tan\left(\frac{z+L/2}{R}\right)$$

$$\alpha_2 = \frac{\pi}{2} - A \tan\left(\frac{z-L/2}{R}\right)$$

