Algorithm Library

magic::team.getname()

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Contents

一切的开始

宏定义

- 需要 C++11

```cpp
#include <bits/stdc++.h>
using namespace std;
using LL = long long;
#define FOR(i, x, y) for (decay<decltype(y)>::type i = (x), _##i = (y); i < _##i; ++i)
#define FORD(i, x, y) for (decay<decltype(x)>::type i = (x), _##i = (y); i > _##i; --i)
#ifdef zerol
#define dbg(x...) do { cout << "\033[32;1m" << #x << " -> "; err(x); } while (0)
void err() { cout << "\033[39;0m" << endl; }
template<template<typename...> class T, typename t, typename... A>
void err(T<t> a, A... x) { for (auto v: a) cout << v << ' '; err(x...); }
template<typename T, typename... A>
void err(T a, A... x) { cout << a << ' '; err(x...); }
#else
#define dbg(...)
#endif
// --------------------------------------------------------------------------
```

计算几何

二维几何：点与向量

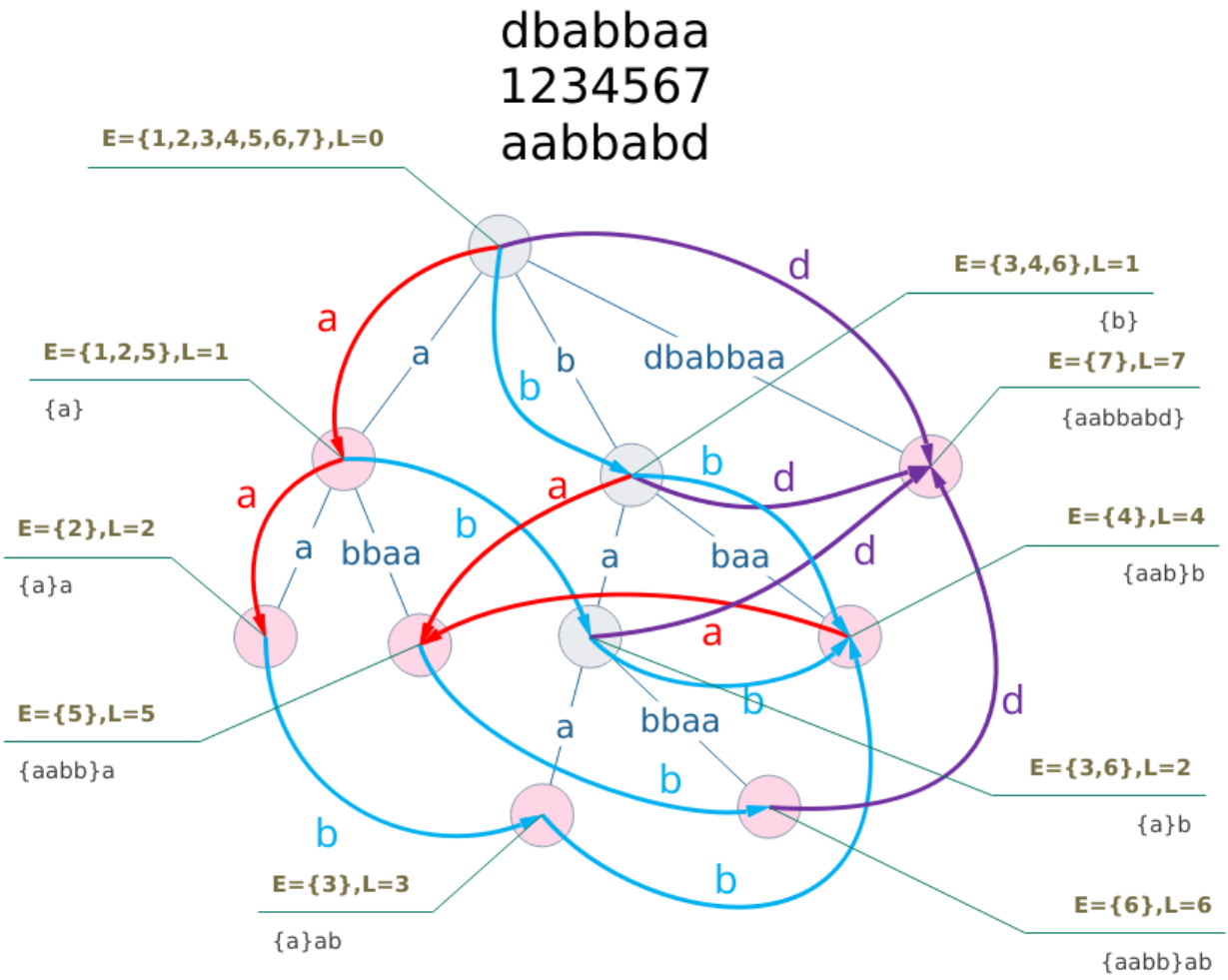
```cpp
#define y1 yy1
#define nxt(i) ((i + 1) % s.size())
typedef double LD;
const LD PI = 3.14159265358979323846;
const LD eps = 1E-10;
int sgn(LD x) { return fabs(x) < eps ? 0 : (x > 0 ? 1 : -1); }
struct L;
struct P;
typedef P V;
struct P {
    LD x, y;
    explicit P(LD x = 0, LD y = 0): x(x), y(y) {}
    explicit P(const L& l);
};
struct L {
    P s, t;
    L() {}
    L(P s, P t): s(s), t(t) {}
};

P operator + (const P& a, const P& b) { return P(a.x + b.x, a.y + b.y); }
P operator - (const P& a, const P& b) { return P(a.x - b.x, a.y - b.y); }
P operator * (const P& a, LD k) { return P(a.x * k, a.y * k); }
P operator / (const P& a, LD k) { return P(a.x / k, a.y / k); }
inline bool operator < (const P& a, const P& b) {
    return sgn(a.x - b.x) < 0 || (sgn(a.x - b.x) == 0 && sgn(a.y - b.y) < 0);
}
bool operator == (const P& a, const P& b) { return !sgn(a.x - b.x) && !sgn(a.y - b.y); }
P::P(const L& l) { *this = l.t - l.s; }
ostream &operator << (ostream &os, const P &p) {
    return (os << "(" << p.x << "," << p.y << ")");
}
istream &operator >> (istream &is, P &p) {
    return (is >> p.x >> p.y);
}

LD dist(const P& p) { return sqrt(p.x * p.x + p.y * p.y); }
LD dot(const V& a, const V& b) { return a.x * b.x + a.y * b.y; }
LD det(const V& a, const V& b) { return a.x * b.y - a.y * b.x; }
LD cross(const P& s, const P& t, const P& o = P()) { return det(s - o, t - o); }
// --------------------------------------------
```

字符串

后缀自动机



杂项

STL

- copy

```
template <class InputIterator, class OutputIterator>
  OutputIterator copy (InputIterator first, InputIterator last, OutputIterator result);
```