Models for clustered data

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· Re-intro to GLMs

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- · Why?

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- · Radon!

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- · Self-assessments.

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- Gives flexibility in the types of outcomes and inputs we can model.
- Model non-linear response using linear predictors

Advanced GLM tricks

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- Represent hierarchical/multi-level structure
- Model spatial autocorrelation
- Allow variance parameters to change with individual-level covariates to acommodate heteroskedasticity

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- Linear relationship between X and Y quantified by regression coefficients $\boldsymbol{\beta}$
- Outcome assumed to have distribution with mean determined by regression coefficients.
- Link function, g(), translates between linear predictor and the mean of the distribution function.

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- \cdot Conditional mean for individual i denoted by $\hat{y}_i = g(y_i^*)$

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And others:

· Gamma, Exponential, Negative Binomial...

GLM with Normally-distributed errors

GLM with normally distributed errors pprox OLS regression

What are assumptions of ordinary least squares regression?

Linear predictor for individual i is a function of her covariates:

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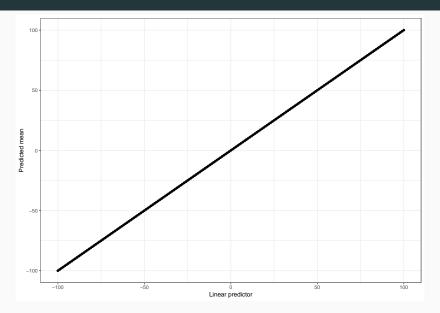
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- $\cdot \epsilon_i \sim Normal(0, \sigma^2)$

Identity link function maps real numbers to real numbers



 $\cdot \alpha$ mean of y_i when $x_i = 0$

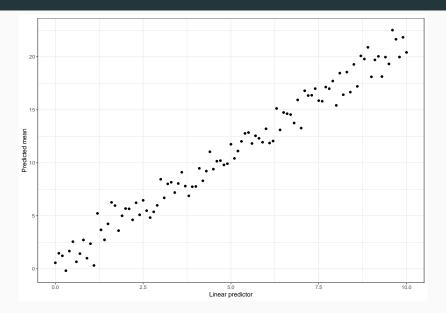
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- \cdot β is change in mean of y_i for each one-unit change in x_i
- Just like in Merlo example, we also estimate the value of σ^2 that measures the amount of individual-level variability in outcomes

Generate some fake data in R

```
## Predictors
x \leftarrow seq(from = 0.0, to = 10.0, by = 0.1)
## Regression coefficient
b < -2.1
## Intercept
a < -0.4
## Variance
sd < -1.0
## The Data
y \leftarrow a + b * x + rnorm(length(x), 0, sd)
```

The Data



Recover the parameters

$$m \leftarrow glm(y \sim x, data = df)$$

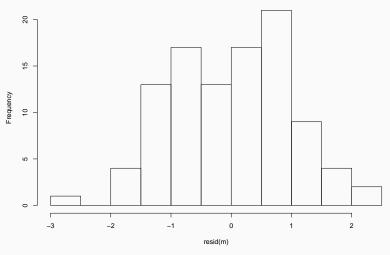
Parameter estimates

Table 1: Fitting generalized (gaussian/identity) linear model: $y \sim x$

	Estimate	Std. Error	t value	Pr(> t)
(Intercept)	0.55	0.2	2.7	0.0071
Х	2.1	0.035	60	1.6e-79

Model Residuals

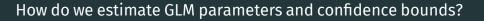




Residual variance

Table 2: Analysis of Variance Model

		Sum	Mean		
	Df	Sq	Sq	F value	Pr(>F)
Х	1	3721	3721	3579	1.6e-79
Residuals	99	103	1	NA	NA



Maximum likelihood estimation

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- Both of these necessitate calculating the likelihood of the data.

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For Gaussian GLM, f = Normal distribution, $\theta = \{\alpha, \beta, \sigma^2\}$

Motivations for Multilevel

Modeling

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- When might you want model slopes to vary and intercepts to be fixed?
- When might you want them to both vary?

Linear Models (GLMs) for clustered data

A re-introduction to Generalized

Going to be seeing a lot of this:

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- y_i is continuous outcome measure: height, BMI, etc.
- \cdot β is risk associated with some kind of exposure
- $\cdot x_i \in [0,1]$ is an indicator of exposure.
- · α is expected outcome when x_i = 0
- \cdot ϵ_i are independently and identically distributed (i.i.d.) errors

Independent errors

Classic assumption is that:

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In plain-ish English:

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Another way of writing it:

$$y_i \sim N(\alpha + \beta x_i, \sigma^2)$$

Three Approaches to Modeling Clustered Data



Which door will you choose?

Door #1: Ignore clustering and fit a normal GLM

- · Pool data across all units, i.e. ignore clustering.
- · i.e. fit model $y_{ij} = \alpha + \beta x_i + \epsilon_i$

Is this a good idea? Why or why not?

NO!



Complete pooling ignores potential sources of *observed* and *unobserved*. unit-level confounding.

Pooling clustered data violates assumption of independent errors

A pooled model:

$$y_i = \alpha + \beta x + \epsilon_i \tag{1}$$

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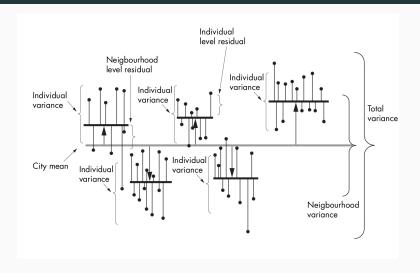
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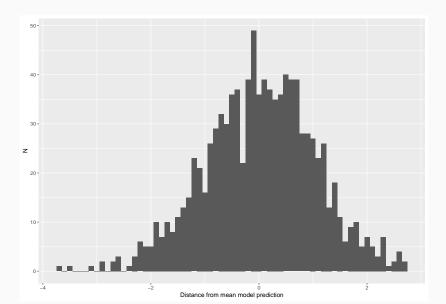
• y_i is a combination of systematic variation $(\alpha + \beta x)$ and uncorrelated random noise (ϵ_i) where:

$$i.i.d. \ \epsilon \sim Normal(0, \sigma^2)$$
 (2)

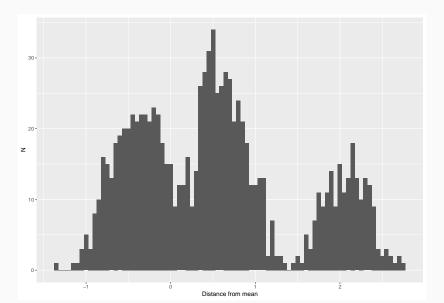
Clustering may result in correlation between average differences from mean



Your residuals should look like this



When you ignore clustering you may see something like:



Door #2: Fit a different model to each cluster

Fit $unpooled \mod 1$ to each unit (j), assuming outcomes in each unit are independent:

$$\cdot \ y_{ij} = \alpha_j + \beta_j x_i + \epsilon_{ij}$$

$$\cdot \ \epsilon_{ij} \sim N(0,\sigma_j^2)$$

More danger!



Totally unpooled models run the risk of overfitting the data, particularly in small samples.

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What else could go wrong here?

- Some units (e.g. counties) may have few observations, making unpooled models impractical
- We may want to allow some effect of exposure (e.g. having a basement) to be consistent across counties.

Door #3: Partial Pooling!

 Allow effects to vary across clusters, but constrain them with a prior distribution.

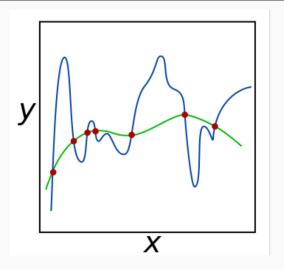
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- Allow effects to vary across clusters, but constrain them with a prior distribution.
- This approach accommodates variation across units without assuming they have no similarity.
- More likely to make accurate out-of-sample predictions than the fully-pooled or unpooled examples.

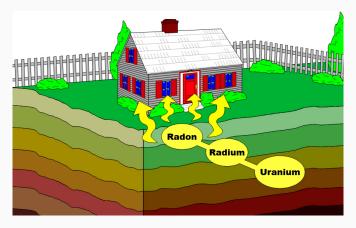
Partial pooling = Regularization



Both functions fit the data perfectly...which one should you prefer?

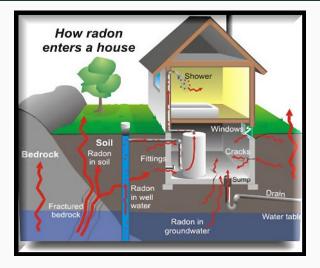
Radon Example

Radon is a carcinogenic gas



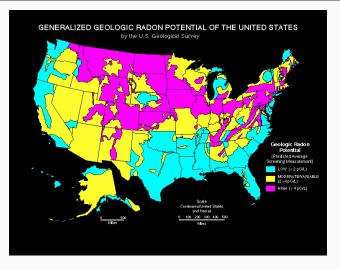
Radon is a byproduct of decaying soil uranium.

Radon enters a house more easily when it is built into the ground



Ann Arbor is a radon hotspot!

Considerable geographic variation in radon potential



Ann Arbor is a radon hotspot!

Trust me on this one...



My very own radon mitigation system.

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- · County-level variation in soil uranium.
- Whether or not the radon measurement was taken in a basement.

Random intercepts account for county-level variation

Gelman [@Gelman2006] proposes a multi-level model to measure household radon in household i in county j, y_{ij} :

$$\cdot \ y_{ij} \sim N(\alpha_j + \beta x_{ij}, \sigma_y^2)$$
 , for $i=1,\dots,n_j, j=1,\dots,J$

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Where:

- $\cdot \ \alpha_j$ is average, non-basement radon measure at county level
- β is fixed effect measuring average change in radon level in houses with a basement.
- \cdot σ_y^2 represents within-county variation in risk

Include predictors of county-level variation in second level

County-level random intercept is a function of county soil uranium measure, u_i :

$$\cdot \ \alpha_j \sim N(\gamma_0 + \gamma_1 u_j, \sigma_\alpha^2)$$
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Where:

- $\cdot \ \gamma_0$ is expected household radon measure when $u_i=0$
- · γ_1 scales expected county-level uranium with u_i
- σ_{α}^2 is between-county variation in radon risk not measured by u_{j} .

Putting it all together

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Putting it all together

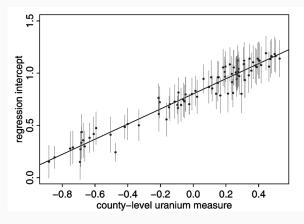
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Household-level radon measure is a function of having a basement and county-level intercept:

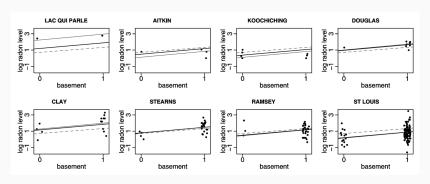
$$\cdot y_{ij} \sim N(\alpha_j + \beta x_{ij}, \sigma_y^2)$$

County-level radon levels vary with soil uranium measures



County-level intercept, α_j , (± 1 standard error) as a function of county-level uranium.

Model predictions vs. radon measures by county



Multi-level regression line, $y=\alpha_j+\beta x$, from 8 Minnesota counties. Unpooled estimates = light grey line; Totally pooled estimates = dashed grey line.

Next Time

 \cdot Hands-on with the Radon example

References

References i